1. Matrix, vector and scalar representation

1.1 Matrix

Example:

$$X = \left[egin{array}{ccc} 4.1 & 5.3 \ -3.9 & 8.4 \ 6.4 & -1.8 \end{array}
ight]$$

 X_{ij} is the element at the i^{th} row and j^{th} column. Here: $X_{11}=4.1, X_{32}=-1.8.$

Dimension of matrix X is the number of rows times the number of columns.

Here $dim(X)=3\times 2$. X is said to be a 3×2 matrix.

The set of all 3×2 matrices is $\mathbb{R}^{3 \times 2}$.

1.2 Vector

Example:

$$x = \left[egin{array}{c} 4.1 \ -3.9 \ 6.4 \end{array}
ight]$$

 $x_i=i^{th}$ element of x. Here: $x_1=4.1, x_3=6.4$.

Dimension of vector x is the number of rows.

Here dim(x)=3 imes 1 or dim(x)=3. x is said to be a 3-dim vector.

The set of all 3-dim vectors is \mathbb{R}^3 .

1.3 Scalar

Example:

$$x = 5.6$$

A scalar has no dimension.

The set of all scalars is \mathbb{R} .

Note: x = [5.6] is a 1-dim vector, not a scalar.

Question 1: Represent the previous matrix, vector and scalar in Python

Hint: You may use numpy library, shape(), type(), dtype.

import numpy as np

#YOUR CODE HERE

```
x = np.array([[ 4.1 ,5.3] ,[-3.9 ,8.4], [ 6.4, -1.8]])

print(x)
print(x.shape)  # size of x
print(type(x))  # type of x
print(x.dtype)  # data type of x

y = np.array([ 4.1, -3.9, 6.4])

print(y)
print(y.shape)  # size of y

z = np.array(5.6)
print(z)
print(z.shape)  # size of z
```

▼ 2. Matrix addition and scalar-matrix multiplication

2.1 Matrix addition

Example:

$$\begin{bmatrix} 4.1 & 5.3 \\ -3.9 & 8.4 \\ 6.4 & -1.8 \end{bmatrix} + \begin{bmatrix} 2.7 & 7.3 \\ 3.5 & 2.4 \\ 6.0 & -1.1 \end{bmatrix} = \begin{bmatrix} 4.1 + 2.7 & 5.3 + 7.3 \\ -3.9 + 3.5 & 8.4 + 2.4 \\ 6.4 + 6.0 & -1.8 - 1.1 \end{bmatrix}$$
$$3 \times 2 + 3 \times 2 = 3 \times 2$$

All matrix and vector operations must satisfy dimensionality properties. For example, it is not allowed to add two matrices of different dimentionalities, such as

$$\begin{bmatrix} 4.1 & 5.3 \\ -3.9 & 8.4 \\ 6.4 & -1.8 \end{bmatrix} + \begin{bmatrix} 2.7 & 7.3 & 5.0 \\ 3.5 & 2.4 & 2.8 \end{bmatrix} = \text{Not allowed}$$
$$3 \times 2 + 2 \times 3 = \text{Not allowed}$$

2.1 Scalar-matrix multiplication

Example:

import numpy as np

$$3 imes egin{bmatrix} 4.1 & 5.3 \ -3.9 & 8.4 \ 6.4 & -1.8 \end{bmatrix} &= egin{bmatrix} 3 imes 4.1 & 3 imes 5.3 \ 3 imes -3.9 & 3 imes 8.4 \ 3 imes 6.4 & 3 imes -1.8 \end{bmatrix}$$
No dim $+ 3 imes 2 &= 3 imes 2$

Question 2: Add the two matrices, and perform the multiplication scalarmatrix as above in Python

```
#YOUR CODE HERE
X1 = ([[4.1, 5.3],
      [-3.9, 8.4],
      [6.4, -1.8]
X2 = ([[2.7, 3.5],
      [7.3, 2.4],
      [ 5., 2.8]])
X = np.add(X1, X2) # summation of X1 and X2
print(X1)
print(X2)
print(X)
Y1 = 4 * X # X multiplied by 4
Y2 = np.divide(X, 3)  # X divided by 3
print(X)
print(Y1)
print(Y2)
    [[4.1, 5.3], [-3.9, 8.4], [6.4, -1.8]]
     [[2.7, 3.5], [7.3, 2.4], [5.0, 2.8]]
     [[ 6.8 8.8]
      [ 3.4 10.8]
      [11.4 1.]]
     [[ 6.8 8.8]
      [ 3.4 10.8]
      [11.4 1.]]
     [[27.2 35.2]
      [13.6 43.2]
      [45.6 4.]]
     [[2.26666667 2.933333333]
      [1.13333333 3.6 ]
      [3.8]
                  0.3333333311
```

▼ 3. Matric-vector multiplication

3.1 Example

Example:

$$\begin{bmatrix} 4.1 & 5.3 \\ -3.9 & 8.4 \\ 6.4 & -1.8 \end{bmatrix} \times \begin{bmatrix} 2.7 \\ 3.5 \end{bmatrix} = \begin{bmatrix} 4.1 \times 2.7 + 5.3 \times 3.5 \\ -3.9 \times 2.7 + 8.4 \times 3.5 \\ 6.4 \times 2.7 - 1.8 \times 3.5 \end{bmatrix}$$
$$3 \times 2 \qquad 2 \times 1 = \qquad 3 \times 1$$

Dimension of the matric-vector multiplication operation is given by contraction of 3×2 with 2×1 = 3×1 .

3.2 Formalization

$$egin{bmatrix} [A] & imes & m{x} \end{bmatrix} & = & m{y} \ m imes n & m imes 1 & = & m imes 1 \end{bmatrix}$$

Element y_i is given by multiplying the i^{th} row of A with vector x:

$$egin{array}{lll} y_i &=& A_i & & x \ 1 imes 1 &=& 1 imes n & imes n imes 1 \end{array}$$

It is not allowed to multiply a matrix A and a vector x with different n dimensions such as

$$\begin{bmatrix} 4.1 & 5.3 \\ -3.9 & 8.4 \\ 6.4 & -1.8 \end{bmatrix} \times \begin{bmatrix} 2.7 \\ 3.5 \\ -7.2 \end{bmatrix} = ?$$

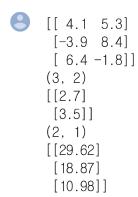
$$3 \times 2 \times 3 \times 1 = \text{not allowed}$$

▼ Question 3: Multiply the matrix and vector above in Python

```
import numpy as np

#YOUR CODE HERE

A = np.array([[ 4.1, 5.3],
      [-3.9, 8.4],
      [ 6.4, -1.8]])
x = np.array([[ 2.7],
      [ 3.5]])
y = np.dot(A, x)  # multiplication of A and x
print(A)
print(A.shape)  # size of A
print(x)
print(x.shape)  # size of x
print(y)
print(y.shape)  # size of y
```



(3, 1)

4. Matrix-matrix multiplication

4.1 Example

$$\begin{bmatrix} 4.1 & 5.3 \\ -3.9 & 8.4 \\ 6.4 & -1.8 \end{bmatrix} \times \begin{bmatrix} 2.7 & 3.2 \\ 3.5 & -8.2 \end{bmatrix} = \begin{bmatrix} 4.1 \times 2.7 + 5.3 \times 3.5 & 4.1 \times 3.2 + 5 \\ -3.9 \times 2.7 + 8.4 \times 3.5 & -3.9 \times 3.2 + 8 \\ 6.4 \times 2.7 - 1.8 \times 3.5 & 6.4 \times 3.2 - 1 \end{bmatrix}$$

$$3 \times 2 \times 2 \times 2 = 3 \times 2$$

Dimension of the matrix-matrix multiplication operation is given by contraction of 3×2 with 2×2 = 3×2 .

4.2 Formalization

$$egin{bmatrix} m{A} & m{X} & m{X} & = & m{Y} \ m imes n & m imes p & = & m imes p \end{bmatrix}$$

Like for matrix-vector multiplication, matrix-matrix multiplication can be carried out only if A and X have the same n dimension.

4.3 Linear algebra operations can be parallelized/distributed

Column Y_i is given by multiplying matrix A with the i^{th} column of X:

$$egin{array}{lll} Y_i &=& A & imes & X_i \ 1 imes 1 &=& 1 imes n & imes & n imes 1 \end{array}$$

Observe that all columns X_i are independent. Consequently, all columns Y_i are also independent. This allows to vectorize/parallelize linear algebra operations on (multi-core) CPUs, GPUs, clouds, and consequently to solve all linear problems (including linear regression) very efficiently, basically with one single line of code (Y=AX for millions/billions of data). With Moore's law (computers speed increases by 100x every decade), it has introduced a computational revolution in data analysis.

Question 4: Multiply the two matrices above in Python

```
import numpy as np

#YOUR CODE HERE

A = np.array([[ 4.1, 5.3],
     [-3.9, 8.4],
     [ 6.4, -1.8]])

X = np.array([[ 2.7, 3.2],
     [ 3.5, -8.2]])

Y = np.dot(A, X)  # matrix multiplication of A and X print(A)

print(A.shape)  # size of A

print(X)

print(X.shape)  # size of X

print(Y)

print(Y.shape)  # size of Y
```

▼ 5. Some linear algebra properties

5.1 Matrix multiplication is *not* commutative

5.2 Scalar multiplication is associative

5.3 Transpose matrix

$$egin{array}{lll} X_{ij}^T & = & X_{ji} \ egin{array}{lll} 2.7 & 3.2 & 5.4 \ 3.5 & -8.2 & -1.7 \end{array} igg|^T & = & egin{bmatrix} 2.7 & 3.5 \ 3.2 & -8.2 \ 5.4 & -1.7 \end{array} igg|$$

5.4 Identity matrix

$$I=I_n=Diag([1,1,\ldots,1])$$

such that

$$I \times A = A \times I$$

Examples:

$$I_2 = egin{bmatrix} 1 & 0 \ 0 & 1 \end{bmatrix}$$
 $I_3 = egin{bmatrix} 1 & 0 & 0 \ 0 & 1 & 0 \ 0 & 0 & 1 \end{bmatrix}$

5.5 Matrix inverse

For any square n imes n matrix A, the matrix inverse A^{-1} is defined as

$$AA^{-1} = A^{-1}A = I$$

Example:

$$\begin{bmatrix} 2.7 & 3.5 \\ 3.2 & -8.2 \end{bmatrix} \times \begin{bmatrix} 0.245 & 0.104 \\ 0.095 & -0.080 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$A \times A^{-1} = I$$

Some matrices do not hold an inverse such as zero matrices. They are called degenerate or singular.

Question 5: Compute the matrix transpose as above in Python. Determine also the matrix inverse in Python.

```
import numpy as np

#YOUR CODE HERE

A = np.array([[ 2.7,  3.5,  3.2]
   ,[-8.2,  5.4, -1.7]])

AT = A.T  # transpose of A

print(AT)
```

```
print(A.shape) # size of A
print(AT.shape) # size of AT

A = np.array([[ 2.7,  3.5],
  [ 3.2, -8.2]])
Ainv = np.linalg.inv(A) # inverse of A
AAinv = np.dot(A, Ainv) # multiplication of A and A inverse
print(A)
print(A.shape) # size of A
print(Ainv)
print(Ainv.shape) # size of Ainv
print(AAinv.shape) # size of AAinv
```



```
[[ 2.7 -8.2]
 [ 3.5 5.4]
 [ 3.2 -1.7]]
(2, 3)
(3, 2)
 [[ 2.7 3.5]
 [ 3.2 -8.2]]
(2, 2)
 [[ 0.24595081  0.104979 ]
 [ 0.0959808  -0.0809838 ]]
(2, 2)
 [[1.000000000e+00  1.11022302e-16]
 [ 0.000000000e+00  1.00000000e+00]]
(2, 2)
```