Solutions of exercises for Sasamoto's course. TA1

Problem 0.i

Recall that for any cylindric function f we have

$$\frac{d}{dt}\mathbb{E}[f] = \mathbb{E}[Lf],$$

with

$$Lf(\eta) = \sum_{j \in \mathbb{Z}} \left(p\eta_j (1 - \eta_{j+1}) + q\eta_{j+1} (1 - \eta_j) \right) \left(f(\eta^{j,j+1}) - f(\eta) \right). \tag{1}$$

We now set $f(\eta) = \eta_k$ for a fixed integer k. With this choice the summation (1) reduces to

$$Lf(\eta) = \left(p\eta_k(1 - \eta_{k+1}) + q\eta_{k+1}(1 - \eta_k)\right)(\eta_{k+1} - \eta_k) + \left(p\eta_{k-1}(1 - \eta_k) + q\eta_k(1 - \eta_{k-1})\right)(\eta_{k-1} - \eta_k).$$

Notice that

$$\left(p\eta_k(1 - \eta_{k+1}) + q\eta_{k+1}(1 - \eta_k) \right) (\eta_{k+1} - \eta_k) = \begin{cases} q\eta_{k+1}(1 - \eta_k) & \text{if } \eta_{k+1} = 1, \ \eta_k = 0 \\ -p\eta_k(1 - \eta_{k+1}) & \text{if } \eta_{k+1} = 0, \ \eta_k = 1 \\ 0 & \text{otherwise.} \end{cases}$$

Analogously

$$\left(p\eta_{k-1}(1-\eta_k) + q\eta_k(1-\eta_{k-1}) \right) (\eta_{k-1} - \eta_k) = \begin{cases} -q\eta_k(1-\eta_{k-1}) & \text{if } \eta_k = 1, \ \eta_{k-1} = 0 \\ p\eta_{k-1}(1-\eta_k) & \text{if } \eta_k = 0, \ \eta_{k-1} = 1 \\ 0 & \text{otherwise.} \end{cases}$$

In conclusion we have

$$\frac{d}{dt}\mathbb{E}[\eta_k] = p\Big(\mathbb{E}[\eta_{k-1}(1-\eta_k)] - \mathbb{E}[\eta_k(1-\eta_{k+1})]\Big) + q\Big(\mathbb{E}[\eta_{k+1}(1-\eta_k)] - \mathbb{E}[\eta_k(1-\eta_{k-1})]\Big).$$

Problem 0.ii

Here we proof what is sometimes called the Andreief identity. Expanding the determinants $\det\{\phi_i(x_j)\}\$ and $\det\{\psi_i(x_j)\}\$ we can write their product as

$$\det\{\phi_i(x_j)\}\det\{\psi_i(x_j)\} = \sum_{\sigma,\tau \in S_N} \epsilon(\sigma)\epsilon(\tau) \prod_{i=1}^N \phi_{\sigma(i)}(x_i)\psi_{\tau(i)}(x_i).$$

Assuming the convergence of the integrals of functions ϕ, ψ we can exchange summations and integrals, obtaining

$$\int_{\mathbb{R}^{N}} \det\{\phi_{i}(x_{j}) \det\{\psi_{i}(x_{j})\} \prod_{i} dx_{i} = \sum_{\sigma, \tau \in S_{N}} \epsilon(\sigma) \epsilon(\tau) \prod_{i=1}^{N} \int_{\mathbb{R}} \phi_{\sigma(i)}(x) \psi_{\tau(i)}(x) dx$$

$$= \sum_{\tau \in S_{N}} \sum_{\sigma \in S_{N}} \epsilon(\tau \circ \sigma) \epsilon(\sigma) \prod_{i=1}^{N} \int_{\mathbb{R}} \phi_{\sigma(i)} \psi_{\tau \circ \sigma(i)}(x) dx, \tag{2}$$

where in the second equality we performed a change of summation index $\tau \to \tau \circ \sigma$. Since $\epsilon(\sigma \circ \tau)\epsilon(\sigma) = \epsilon(\tau)$ we see that each addend in the summation is constant in σ and therefore the right hand side of (2) becomes

$$N! \sum_{\tau \in S_n} \epsilon(\tau) \prod_{i=1}^N \int_{\mathbb{R}} \phi_i(x) \psi_{\tau(i)}(x) dx = N! \det \left(\int_{\mathbb{R}} \phi_i(x) \psi_j(x) dx \right).$$

Problem 1.i.a

The integrand in the expression of F_n only has poles at 0 and 1 and therefore the complex contour can be chosen to be a disk arbitrary large large radius R, that we denote with D_R

$$F_{n+1}(x,t) = \frac{1}{2\pi i} \int_{D_R} dz \frac{1}{z^{x+1}} \left(1 - \frac{1}{z} \right)^{-n-1} e^{-(1-z)t}.$$
 (3)

When |z| > 1 we can safely exchange the infinite summation sign with the integral sign and take the geometric summation obtaining

$$\sum_{y=x}^{\infty} F_n(y,t) = \frac{1}{2\pi i} \int_{D_R} dz \left(\sum_{y=x}^{\infty} \frac{1}{z^{x+1}} \right) \left(1 - \frac{1}{z} \right)^{-n} e^{-(1-z)t}$$

$$= \frac{1}{2\pi i} \int_{D_R} dz \frac{1}{z^{x+1}} \left(1 - \frac{1}{z} \right)^{-n-1} e^{-(1-z)t}$$

$$= F_{n+1}(x,t). \tag{4}$$

Problem 1.i.b

This simply follows by integrating the t dependent factor in the integrand function. We have

$$\int_{0}^{t} F_{n}(x, t') dt' = \frac{1}{2\pi i} \int_{D_{R}} dz \frac{1}{z^{x+1}} \left(1 - \frac{1}{z} \right)^{-n} \left[-\frac{e^{-(1-z)t'}}{(1-z)} \right]_{t'=0}^{t'=t}$$

$$= \frac{1}{2\pi i} \int_{D_{R}} dz \frac{1}{z^{x+1}} \left(1 - \frac{1}{z} \right)^{-n-1} \left(1 - e^{-(1-z)t} \right)$$

$$= F_{n+1}(x, t) - F_{n+1}(x, 0)$$
(5)

Problem 1.ii

We write down the time derivative of the function G using the multilinearity property of the determinant

$$\frac{d}{dt}G(x_1, x_2; t) = \begin{vmatrix} \frac{d}{dt}F_0(x_1 - y_1; t) & F_1(x_2 - y_1; t) \\ \frac{d}{dt}F_{-1}(x_1 - y_2; t) & F_0(x_2 - y_2; t) \end{vmatrix} + \begin{vmatrix} F_0(x_1 - y_1; t) & \frac{d}{dt}F_1(x_2 - y_1; t) \\ F_{-1}(x_1 - y_2; t) & \frac{d}{dt}F_0(x_2 - y_2; t) \end{vmatrix}.$$
(6)

By using relations of the function F we have

$$\begin{vmatrix} \frac{d}{dt}F_0(x_1 - y_1; t) & F_1(x_2 - y_1; t) \\ \frac{d}{dt}F_{-1}(x_1 - y_2; t) & F_0(x_2 - y_2; t) \end{vmatrix} = \begin{vmatrix} F_0(x_1 - y_1 - 1; t) - F_0(x_1 - y_1; t) & F_1(x_2 - y_1; t) \\ F_{-1}(x_1 - y_2 - 1; t) - F_{-1}(x_1 - y_2; t) & F_0(x_2 - y_2; t) \end{vmatrix} = G(x_1 - 1, x_2; t) - G(x_1, x_2; t).$$

$$(7)$$

and analogously we write

$$\begin{vmatrix} F_0(x_1 - y_1; t) & \frac{d}{dt} F_1(x_2 - y_1; t) \\ F_{-1}(x_1 - y_2; t) & \frac{d}{dt} F_0(x_2 - y_2; t) \end{vmatrix} = G(x_1, x_2 - 1; t) - G(x_1, x_2; t).$$
 (8)

To check the boundary conditions we use again recurrence relations of F. We write

$$G(x_{1}, x_{1} + 1; t) = \begin{vmatrix} F_{0}(x_{1} - y_{1}; t) & F_{1}(x_{1} - y_{1} + 1; t) \\ F_{-1}(x_{1} - y_{2}; t) & F_{0}(x_{1} - y_{2} + 1; t) \end{vmatrix}$$

$$= \begin{vmatrix} F_{0}(x_{1} - y_{1}; t) & F_{1}(x_{1} - y_{1}; t) - F_{0}(x_{1} - y_{1}; t) \\ F_{-1}(x_{1} - y_{2}; t) & F_{0}(x_{1} - y_{2}; t) - F_{-1}(x_{1} - y_{2}; t) \end{vmatrix}$$

$$= \begin{vmatrix} F_{0}(x_{1} - y_{1}; t) & F_{1}(x_{1} - y_{1}; t) \\ F_{-1}(x_{1} - y_{2}; t) & F_{0}(x_{1} - y_{2}; t) \end{vmatrix}$$

$$= G(x_{1}, x_{1}; t).$$
(9)

Finally we can verify the initial conditions. Through a residue computation we see that

$$G(x_1, x_2; 0) = \begin{vmatrix} \mathbf{1}_{x_1 = y_1} & \mathbf{1}_{y_1 \ge x_2} \\ \mathbf{1}_{x_1 = y_2} - \mathbf{1}_{x_1 = y_2 + 1} & \mathbf{1}_{x_2 = y_2} \end{vmatrix} = \mathbf{1}_{x_1 = y_1} \mathbf{1}_{x_2 = y_2},$$
(10)

since $y_1 < y_2$ and the only region allowed for indices x_1, x_2 is $x_1 < x_2$.