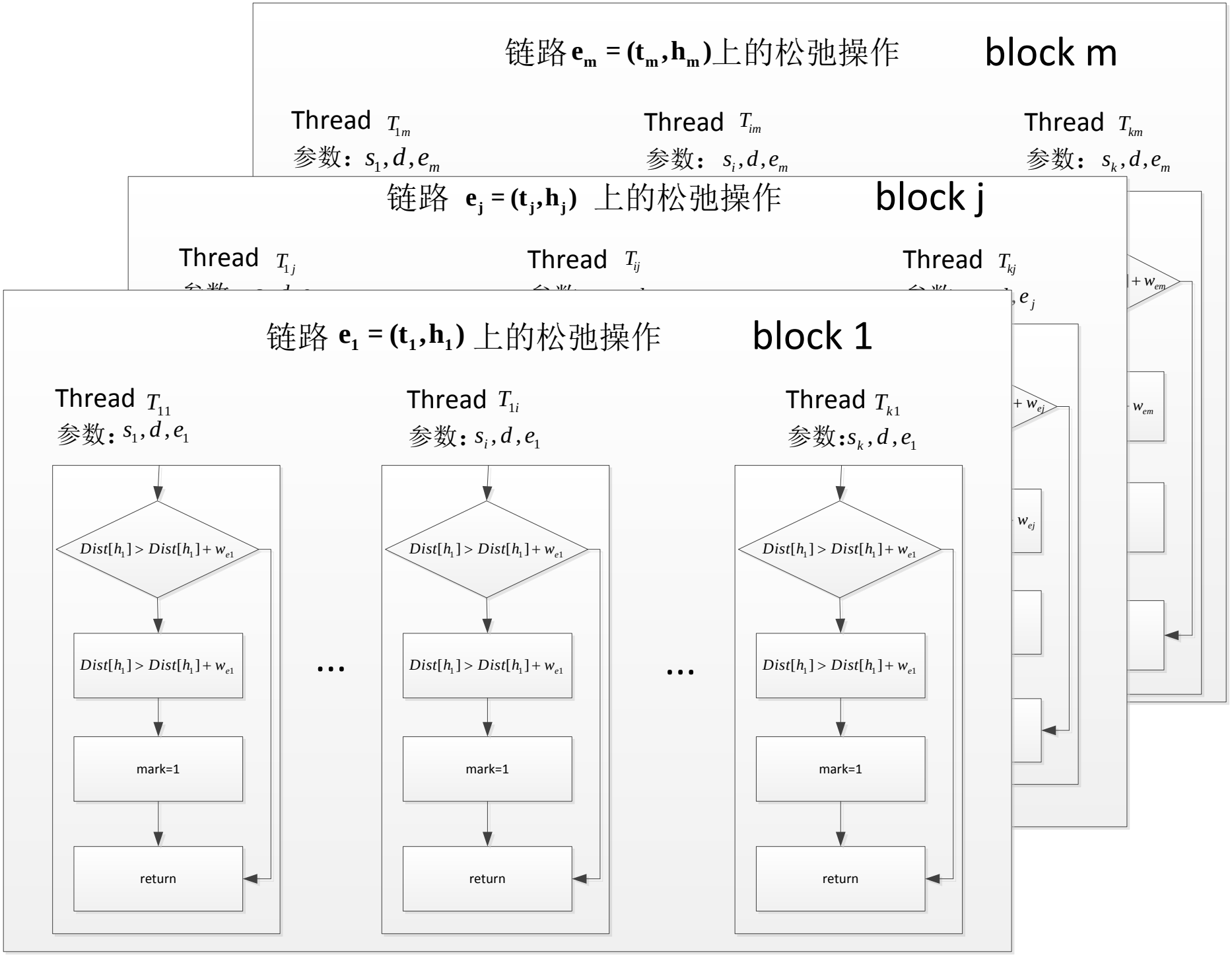
链路 $\mathbf{e_m} = (\mathbf{t_m}, \mathbf{h_m})$ 上的松弛操作
block m
Thread T_{1m}
参数：s_1, d, e_m
Thread T_{im}
参数：s_i, d, e_m
Thread T_{km}
参数：s_k, d, e_m
链路 $\mathbf{e_j} = (\mathbf{t_j}, \mathbf{h_j})$ 上的松弛操作
block j
Thread T_{1j}
Thread T_{ij}
Thread T_{kj}
链路 $\mathbf{e_1} = (\mathbf{t_1}, \mathbf{h_1})$ 上的松弛操作
block 1
Thread T_{11}
参数：s_1, d, e_1
Thread T_{1i}
参数：s_i, d, e_1
Thread T_{k1}
参数：s_k, d, e_1
$Dist[h_1] > Dist[h_1] + w_{e1}$
$Dist[h_1] > Dist[h_1] + w_{e1}$
mark=1
return
...
$Dist[h_1] > Dist[h_1] + w_{e1}$
$Dist[h_1] > Dist[h_1] + w_{e1}$
mark=1
return
...
$Dist[h_1] > Dist[h_1] + w_{e1}$
$Dist[h_1] > Dist[h_1] + w_{e1}$
mark=1
return