

BOAS VINDAS | WELCOME | BIENVENIDAS



FUTURE

O PAPEL DA TECNOLOGIA NA
CONSTRUÇÃO DO AMANHÃ
TECHNOLOGY CREATING TOMORROW

#thedevconf



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TECHNOLOGY CREATING TOMORROW

Autonomous Robots with Deep Learning, Natural Language and Logic

Let's change the world!

Autonomous Robots with Deep Learning, Natural Language and Logic

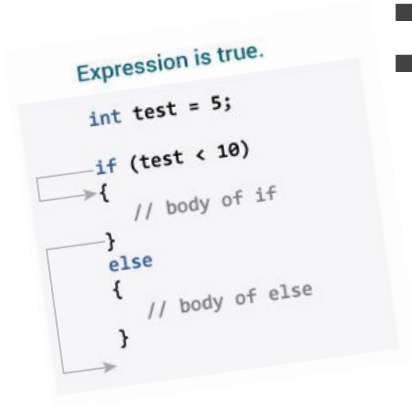
About me... Hobbert Evergreen or Bob ([linkedin](#))

- CEO at EverThink, a StartUP of Smart Robots
- YouTuber at "Inteligência Mil Grau" channel
- Graduated in Psychology at the University of São Paulo (USP)
- Post graduated in Automation Engineering
- Worked with Robotics and Artificial Intelligence since 2012 as a researcher in a Innovation Institute

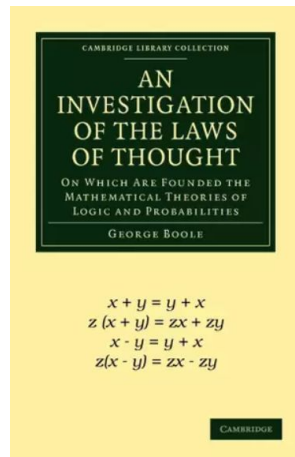


Interests

- Psychologist studying intelligence
- Connections between AI and Psychology
 - Coincidences



- If-Else looks similar to our way of thinking
- George Boole was researching human intelligence when he created his logic
 - * An Investigation of the Laws of Thought on Which are Founded the Mathematical Theories of Logic and Probabilities - 1984



Interests

Real desire to understand our human intelligence in details!

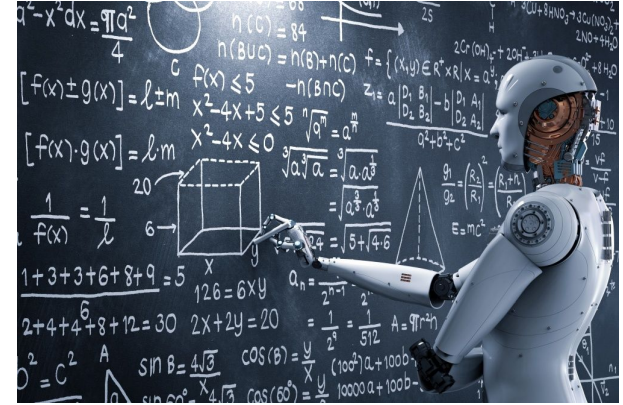
Build a machine able to think!



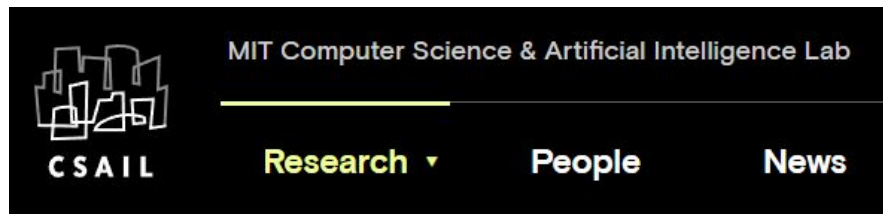
Atlas from Boston Dynamics

Personal Mission

- Research Strong AI
- Encourage Strong AI around the World
- Participate Globally with others Researchers
- Encourage self-knowledge
- Encourage a happy life, intense, full of meaning
- Encourage a dreamy life



We are not dreaming alone



COMMUNITY OF RESEARCH

Embodied Intelligence Community of Research

Our goal is to understand the nature of intelligent behavior in the physical world, through the study of human intelligence and the design and implementation of intelligent robots.

Lead [Ted Adelson](#)



RESEARCH GROUP

Learning and Intelligent Systems

We conduct interdisciplinary research aimed at discovering the principles underlying the design of artificially intelligent robots.

Lead [Leslie Kaelbling](#), [Tomas Lozano-Perez](#)



RESEARCH GROUP

Distributed Robotics Laboratory

We aim to develop the science of autonomy toward a future with robots and AI systems integrated into everyday life, supporting people with cognitive and physical tasks.

Lead [Daniela Rus](#)



What do you expect for the future?

- Intelligent Machines or Intelligents Humanoid Robots?
- Artificial intelligence replacing the human being and us with all the free time in the world or a co-participation
- War between human and IA or a collaborative way?



Can a machine think?

John Searle like answer

- First, we need to understand how the Intelligence happens!
- After, maybe, we can build one!



Robotics Challenges

First

When we play a game using deep reinforcement, we have the score to evaluate performance and the pixels of the screen to create our world

How do you imagine our life score to optimize? We have one?

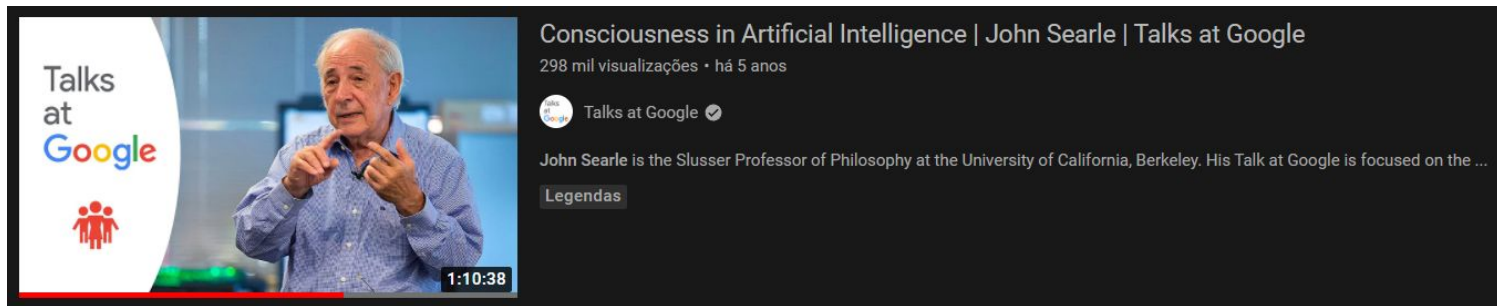
That score is absolute to everyone or relative?



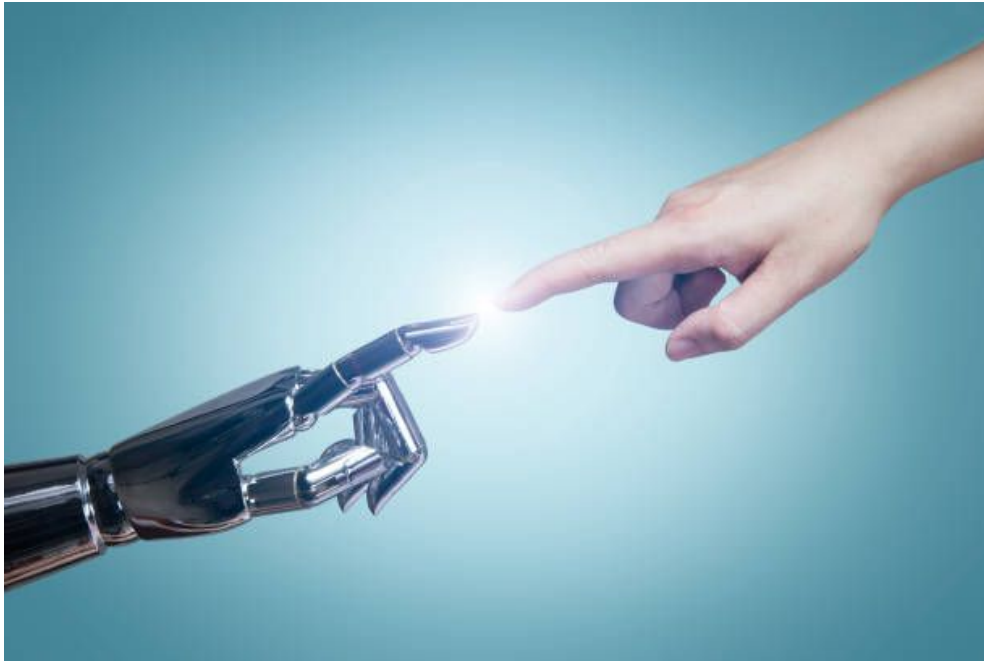
Consciousness

- Chinese Room Argument (John Searle)
 - Just manipulate symbols
 - Machines are syntactical, not semantics
 - Calculator don't understand what a sum is like us

<https://www.youtube.com/watch?v=rHKwIYsPXLg>

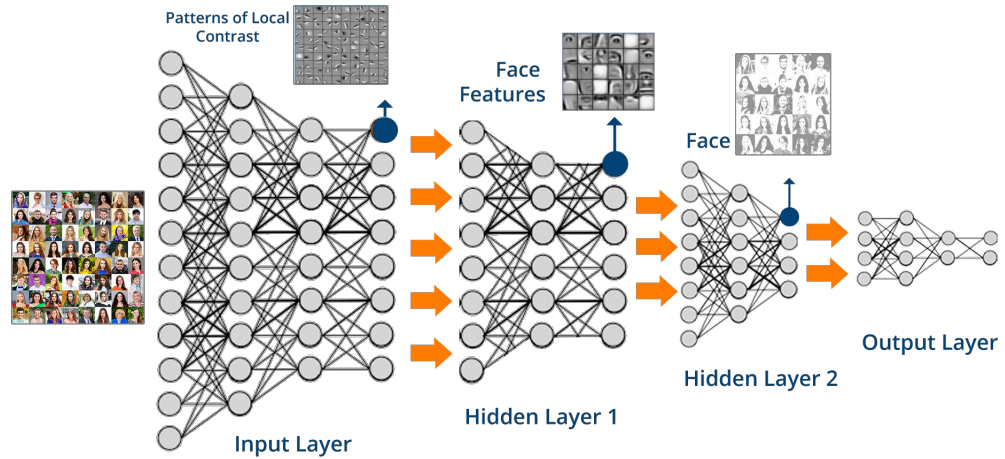
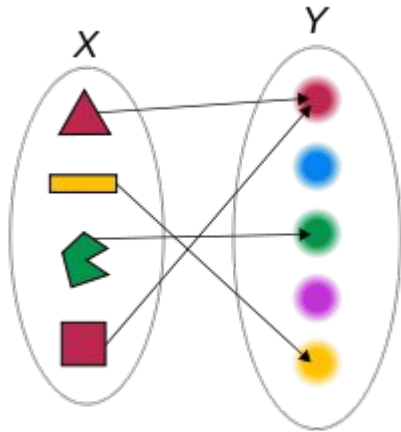


How far we are?



Functions Models

Neural Network

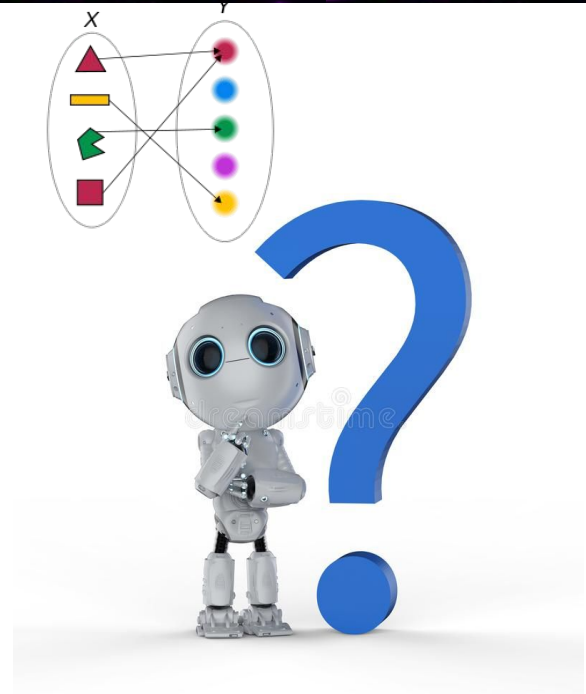


The AI based on “functions”

Our intelligence are a simple connection between sets?

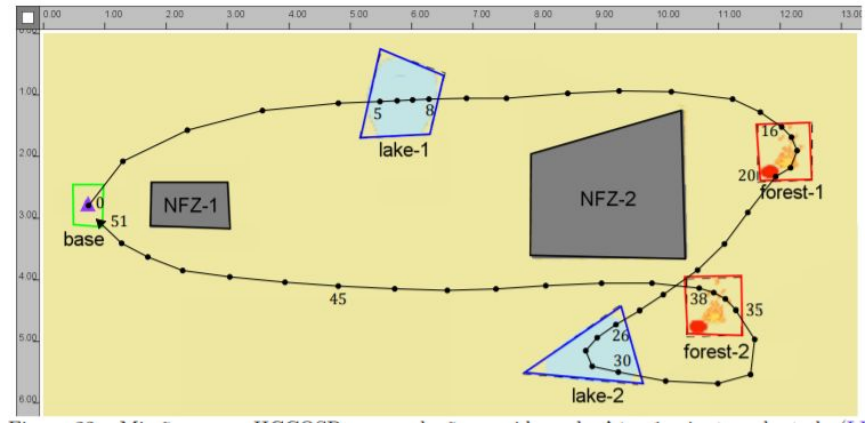
How to think about something if our thoughts are just a “function”?

We can evaluate some possibilities using a “function”?



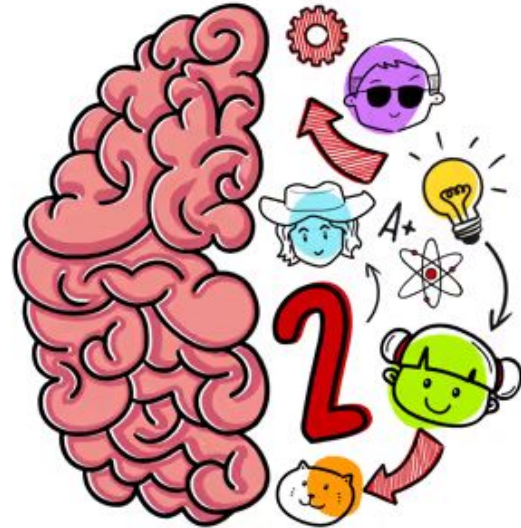
An example solution for AI for drones

- Be guided by goals
- MIT (<https://www.csail.mit.edu/research/cognitive-ai#projects>)
- Use NLP
- Solver
- Computer Vision



AI Approaches

- Human like intelligence based on:
 - biology
 - chemistry
 - nanotechnology
 - psychology
 - philosophy
- Intelligence as a process
 - machine learning



Intelligence and Intelligent

Intelligence is something someone can have

Intelligent is something relative to a solution



Robotics Challenges

Second

Intelligence presumes consciousness?

Intelligence can exist without someone?

Do we need to find consciousness to put into our robots so they can finally think?



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AI Models

- Lots of weak AIs to correspond to an Strong
- Build an one and simples Strong AI (Brain)
- AGI - Artificial General Intelligence
 - Deep Reinforcement with Multi-Agents?



Intelligent Robotics Challenge

- Human Interaction
 - Truly Language Comprehension
 - Complex Long Term Goals
 - Complex Decision Making
 - Self-Living Learning



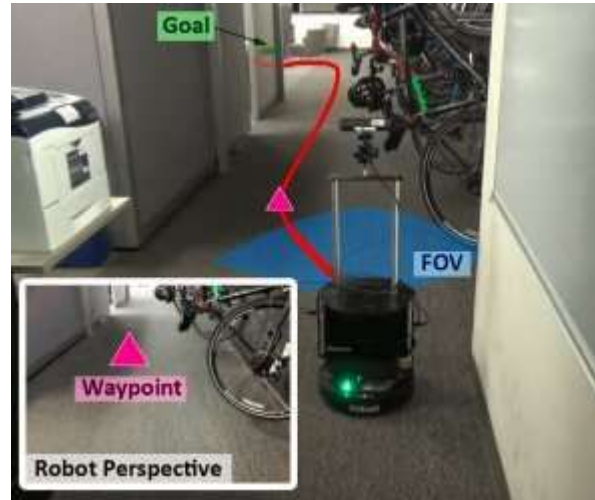
Combining Models

Maths to navigate with a Robot

Deep Learning for object detection

TTS do understand words

NLP to understand Goals



Intelligence versus useful stupidity

We can teach a dog to do something

we can teach a computer to extract emotion from a text...

The dog is smarter, but the computer may be more useful?

Who matters if a autonomous car have consciousness?



Combining Models

Deep Neural to recognize Objects

Reinforcement Learning to define actions on World

Multi-Agent to communicate

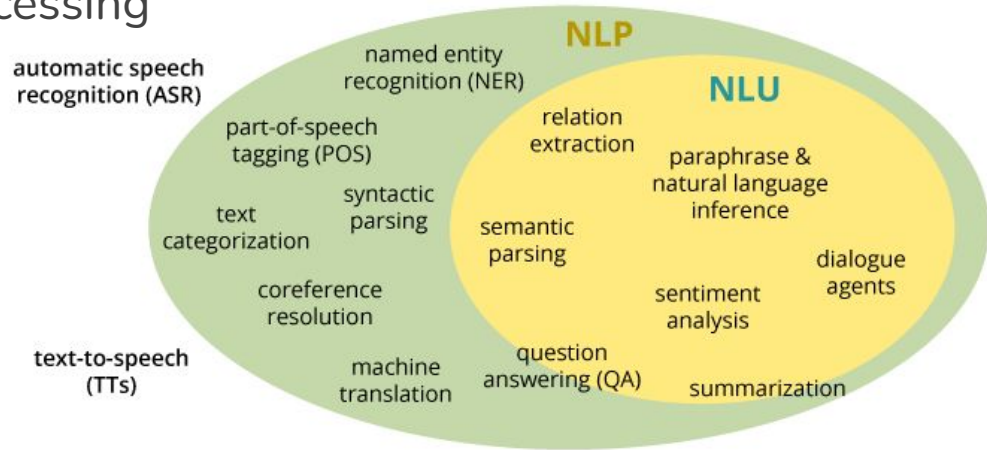


<https://ai.googleblog.com/2021/04/model-based-rl-for-decentralized-multi.html>

Language and Logic

- TTS
- Natural Language Processing
- LISP
- Prolog

Terminology: NLU vs. NLP vs. ASR



Multi-Agent

Agent Speak (Prolog)

Logic and Reasoning

Comunication

LingoDroids https://www.youtube.com/watch?v=E6YZ_qnZsjg



Pay Attention

When we talk about strong AI
We are not talking about something a professor can teach
Or a neuroscientist can explain
Or a psychologist knows what is about
Talking about strong AI is something like a researcher looking for the unknown
To create a truly AI can bring us a real big change in the world
And to ourselves

Is not about get a new job
Maybe we are talking about not have a job anymore
And find another goals to our lives



ROS

WHY ROS?

GETTING STARTED

COMMUNITY

ECOSYSTEM

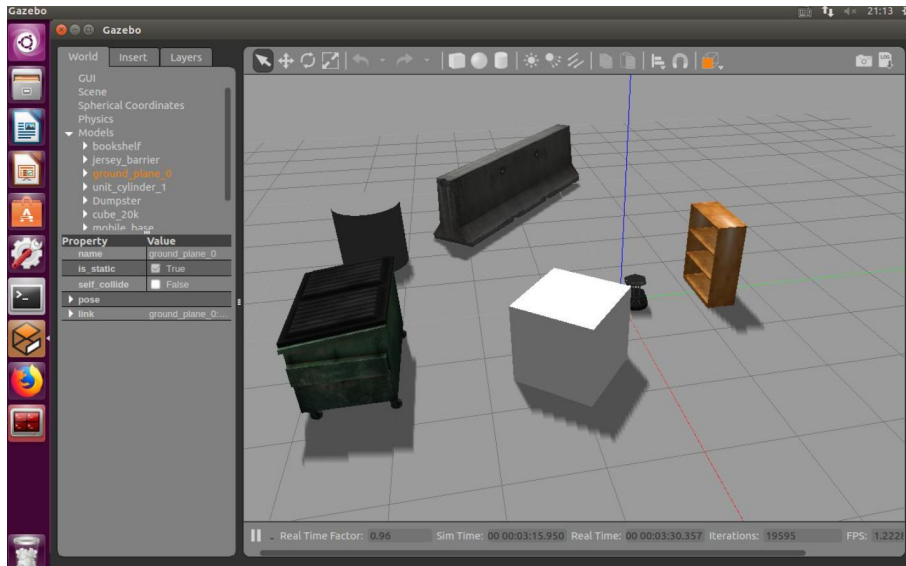
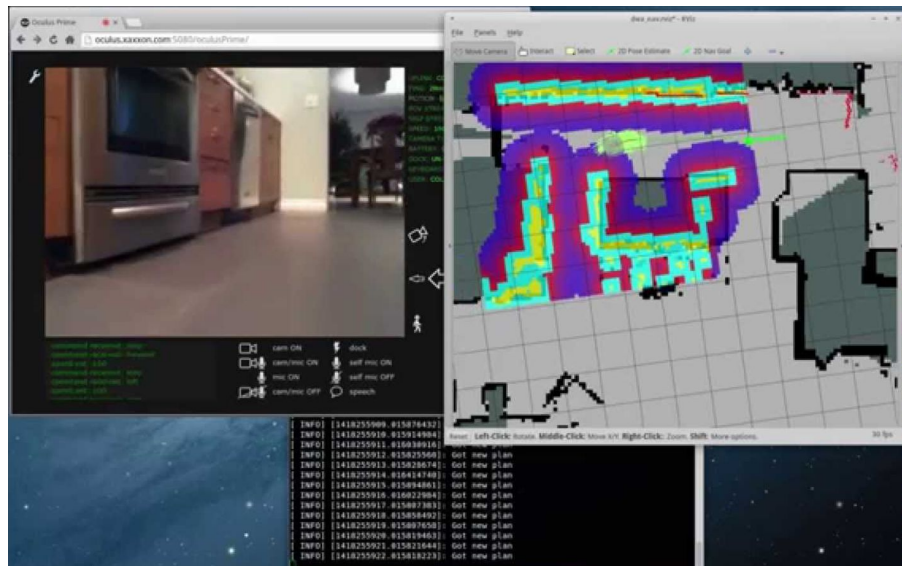
ROS - Robot Operating System

The Robot Operating System (ROS) is a set of software libraries and tools that help you build robot applications. From drivers to state-of-the-art algorithms, and with powerful developer tools, ROS has what you need for your next robotics project. And it's all open source.



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Linux friendly... C++ native and Python portability

No excuses to not start build robots today!!

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ros.org



**Get ROS Noetic
Ninjemys on Ubuntu
Linux**

(Recommended for
Latest ROS 1 LTS)

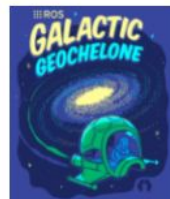
[Install](#)



**Get ROS Foxy Fitzroy on
Ubuntu Linux, macOS, or
Windows 10**

(Recommended for Latest
ROS 2 LTS)

[Install](#)



**Get ROS Galactic
Geckelone on Ubuntu
Linux, macOS, or Windows
10**

(Recommended for Latest
ROS 2)

[Install](#)

Challenges

Sometimes we learn through repetition

And other times using logic and reasoning

But there is a kind of event that we can solve that will occur just one time in life

And you need to use logic and think about this event

For months or years, maybe

We have to keep this in mind



Prototyping Robotics, Maths and Electronics

Prototype with raspberry pi

Wifi

GPS

Camera for vision

Kalman filter for navigation

No excuses to not start build robots today AGAIN!!



AI for Games and Robots

Games can be a simplified version of the world

Games have scores

We can test algorithms against humans

Performance must be in real time

Images are stable without light variation

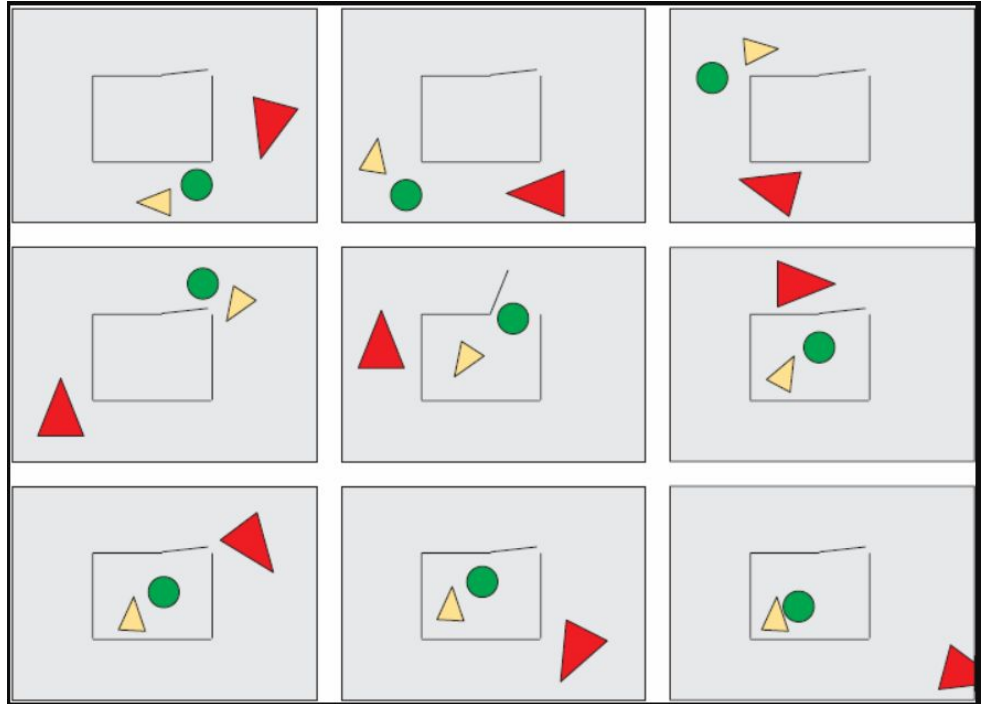


Perception and Abstraction

Heider and Simmel

How much of our understanding
needs a real object to create
emotions and an history?

We can easily build a detector for
every part in this image, but we can
tell a history?



AI Models

- - Based on Maths and Logics
 - Fuzzy Logic
 - Probabilistic Reasoning
- - Based on Life
 - - Rat SLAM - Animals
 - - Genetic Algorithm - Biology - Nature
 - - Reinforcement Learning - Psychology
 - - Neural Networks - Biology - Neuroscience



<https://gym.openai.com/>

AI advances

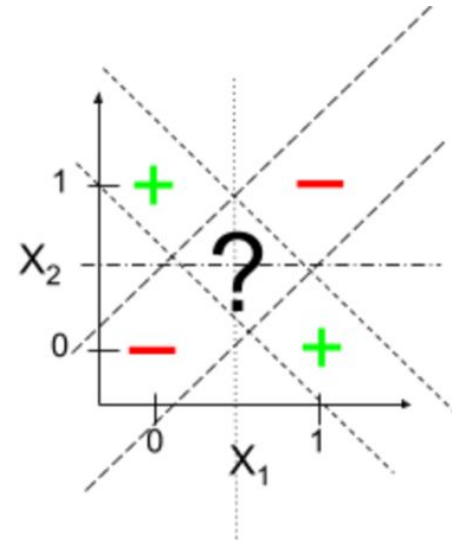
Pay attention

Sometimes AI just improve performance, but keeps the same concept

Sometimes it means to be faster and nothing more

But sometimes, nothing more is everything

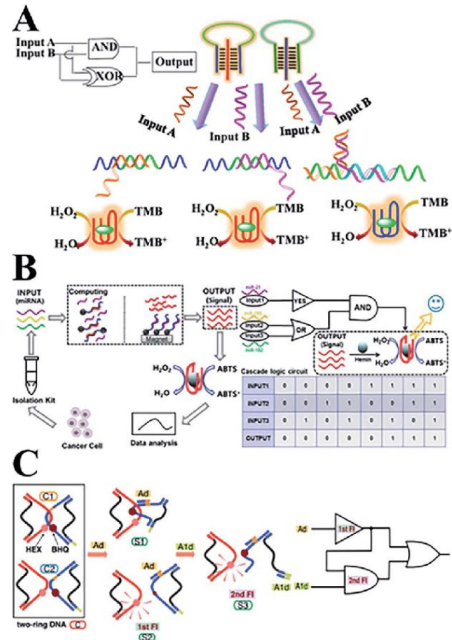
And sometimes we need to change our point of view



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SCIENCE —

The logic units are driven by molecular collisions, not voltage.



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ICUB

<https://icub.iit.it/>

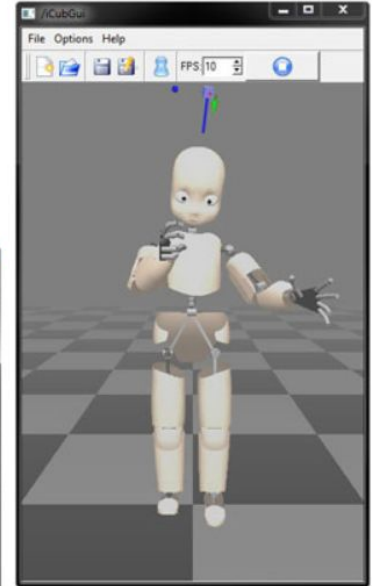


dataSetPlayer

File	Action	Option	Help			
Active	Part	Type	Frames	Sample Rate	Port Name	Status
<input checked="" type="checkbox"/>	head	Bottle	7280	15 ms	/icub/head/state:o	32 %
<input checked="" type="checkbox"/>	images_left	Image:ppm	2208	39 ms	/icub/camcalib/left/out	31 %
<input checked="" type="checkbox"/>	images_right	Image:ppm	2215	39 ms	/icub/camcalib/right/out	31 %
<input checked="" type="checkbox"/>	inertial	Bottle	14404	1 ms	/icub/inertial	32 %
<input checked="" type="checkbox"/>	leftArm	Bottle	7294	18 ms	/icub/left_arm/state:o	31 %
<input checked="" type="checkbox"/>	leftLeg	Bottle	7290	16 ms	/icub/left_leg/state:o	31 %
<input checked="" type="checkbox"/>	rightArm	Bottle	7291	10 ms	/icub/right_arm/state:o	31 %
<input checked="" type="checkbox"/>	rightLeg	Bottle	7291	16 ms	/icub/right_leg/state:o	31 %
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Speed: 1.0x

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No excuses to not start build robots today, AGAIN, AGAIN!!

Intelligent Robotics

this is not a new world

is the same world

with a new comprehension



Bonus Slide - Psychological issues

building a society with autonomous machines will involve intense psychological changes

What humans will do without job? (7 Billion Humans - Game Dilema)

New Objectives?

