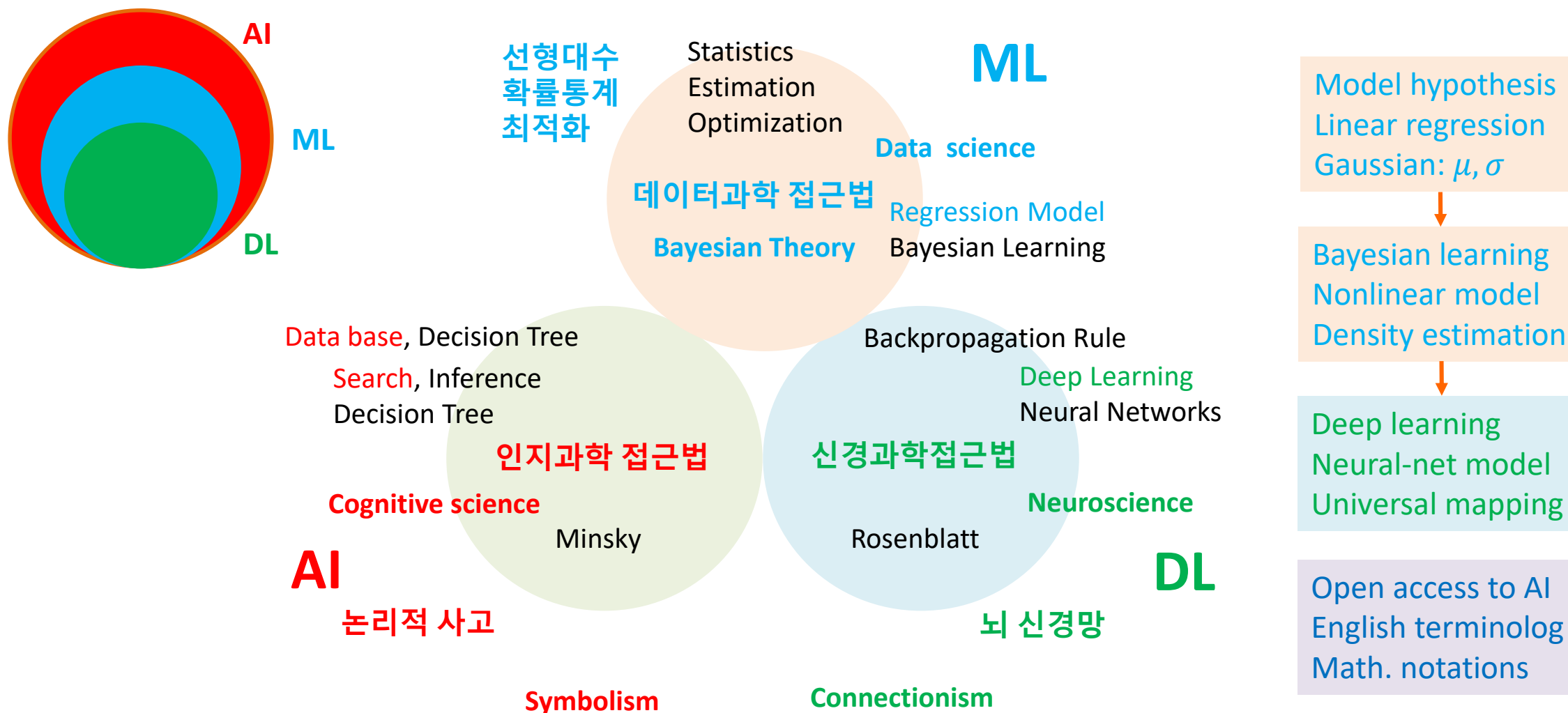


# Artificial Intelligence



# Probability & Random Variable

Jin Young Choi

Seoul National University

“하나님은 주사위 놀이를 할까요?”

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# Outline

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- **Probability**
- **Conditional Probability**
  - Chain Rule, Total Probability, Independence,
- **Random Variable**
- **Distribution of Random Variable**
- **Joint Probability**
- **Bayes Rule**
- **(Joint) Moment**
  - Mean, (Co)Variance, Expectation, Conditional Expectation
- **Weak Law of Large Numbers**
- **Central Limit Theorem**
- **Random Vector**
- **Random Process**
  - Winner Process, Radom Walk, Markov Process, Ergodicity

# Probability

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- relative frequency  $\neq$  probability
- relative frequency: a measured number,  $\hat{p}_i = N_n(O_i)/n$
- probability: a number characterizing an outcome

(cannot be measured)

$$p_i = \lim_{n \rightarrow \infty} N_n(O_i)/n, \quad i = 1; 2, \dots, k$$

- probability is a mathematical model, to define probability, we need
  1. a random experiment
  2. outcomes of the experiment
  3. events, each of which is a set of outcomes

# Probability

---

- Finite sample set  $U$  with uniform distribution

$$p_A = |A|/|U|$$

where  $|A|$  is cardinality of the event set  $A$  and  $|U|$  is that of the sample set.

- Example

- Fair die (uniform)

$$P(A) = P(\{2,4,6\}) = \frac{|\{2,4,6\}|}{|\{1,2,3,4,5,6\}|} = 1/2$$

- Unfair die (not uniform)

$$\begin{aligned} P(A) &= P(\{2\}) + P(\{4\}) + P(\{6\}) \\ &= 1/5 + 1/5 + 1/5 = 3/5 \neq |A|/|U| \end{aligned}$$



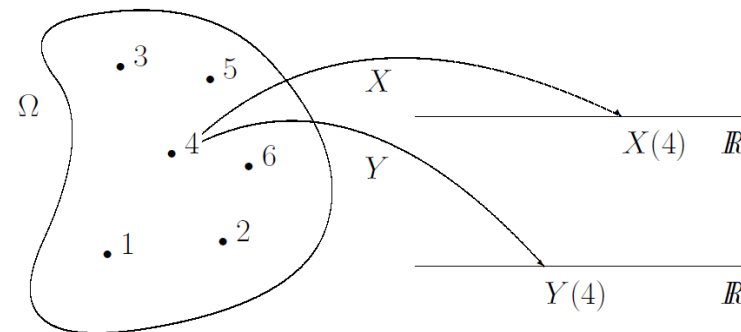
# Random variable (r.v.)

---

- **random variable**: numerical measurements or observations that have uncertain variability each time they are repeated.
- **random variable**: real-valued function defined on  $\Omega$ , given the probability space  $(\Omega; \mathcal{A}; P)$ , i.e.,  $X : \Omega \rightarrow \mathbb{R}, Y : \Omega \rightarrow \mathbb{R}$
- **example**: A coin is tossed 5 times, and if odd number of heads appear, Tom wins \$100, otherwise he loses \$200.

$$\Omega = \{00000, 00001, \dots, 11111\}$$

Tom's net gain is of interest.



# Probability of Random variable

---

- Probability

$$P(X \in B) := P(X^{-1}(B)) = P\{\omega : X(\omega) \in B\}$$

- example:  $\Omega = \{1, 2, 3, 4, 5, 6\}$ , for random variable  $X$ ,

$\omega$	1	2	3	4	5	6
$X$	10	-10	20	-10	30	-10

- find  $P(X \leq 10) = P(\{1, 2, 4, 6\}) = \frac{1}{6} + \frac{1}{6} + \frac{1}{6} + \frac{1}{6} = \frac{2}{3}$

# Discrete random variable

---

- **discrete set**: having finite number of elements
- **example**:  $\Omega = \{\text{students in this class}\}$ , equiprobable selection of a student,  $X(\omega) = \text{final grade points}$

- probability mass function (**pmf**)  
$$p(x) := P(X = x)$$

- $0 \leq p(x) \leq 1$
- $\sum_x p(x) = 1$
- $P(X \in B) = \sum_{x \in B} p(x)$



# Continuous random variable

---

- **continuous set**: defined by a range of continuous values
- **example**:  $\Omega = [0, 24]$  represents the time of a specific day;  
 $X(\omega)$  = amount of UV light coming into a detector

- probability density function (**pdf**)

$$f(x) := \lim_{\Delta x \rightarrow 0} \frac{P(x < X \leq x + \Delta x)}{\Delta x}$$

- $f(x) \geq 0$ ;  $f(x) > 1$  is possible.
- $\int_{-\infty}^{\infty} f(x)dx = 1$
- $P(a < X < b) = P(a < X \leq b) = P(a \leq X < b)$   
 $= P(a \leq X \leq b) = \int_a^b f(x)dx,$
- $P(X \in B) = \int_B f(x)dx$

# Cumulative distribution function

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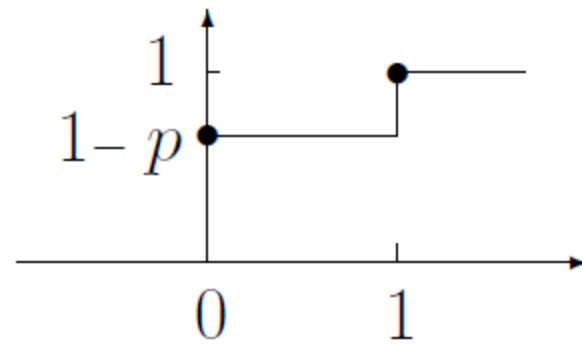
- cumulative distribution function, cdf

$$F(x) := P(X \leq x)$$

for discrete  $X$ ,  $F(x)$  consists of discrete steps.

the step heights are the probability masses.

example:  $Ber(p)$  cdf



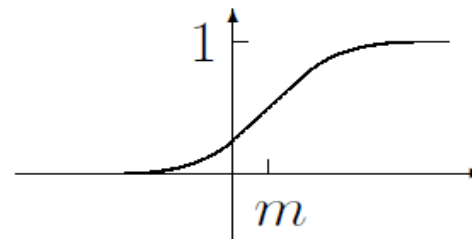
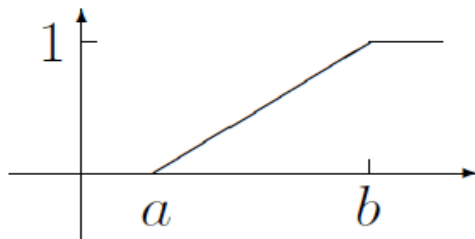
# Cumulative distribution function

---

- If  $X$  is a continuous random variable with density  $f(x)$ , then

$$\begin{aligned}\Rightarrow F(x) &= P(X \leq x) = \int_{-\infty}^x f(v) dv \\ &= F(a) + \int_a^x f(v) dv \\ \Rightarrow 1 - F(x) &= P(X \geq x) = \int_x^{\infty} f(v) dv\end{aligned}$$

- example:  $\text{unif}(a, b)$  and  $N(m, \sigma^2)$  cdf



# Cumulative distribution function

---

- If  $X$  is a *continuous* random variable with density  $f_X$ , then

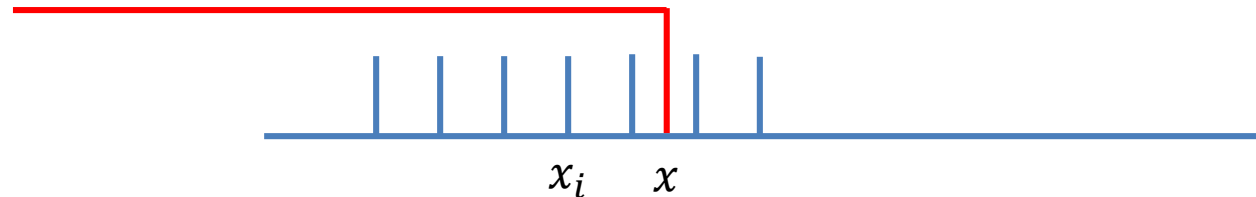
$$F(x) = P(X \leq x) = F(a) + \int_a^x f(v)dv$$

$$\Rightarrow f(x) = \frac{d}{dx} F(x)$$

- If  $X$  is a *discrete* random variable with density  $p$ , then

$$F(x) = \sum_i p(x_i) u(x - x_i)$$

$$\Rightarrow f(x) = \frac{d}{dx} F(x) = \sum_i p(x_i) \delta(x - x_i): \text{generalized pdf } (\leftrightarrow \text{pmf})$$



# Cumulative distribution function (cdf)

---

- properties:

1.  $0 \leq F(x) \leq 1$

2.  $P(a < X \leq b) = F(b) - F(a)$

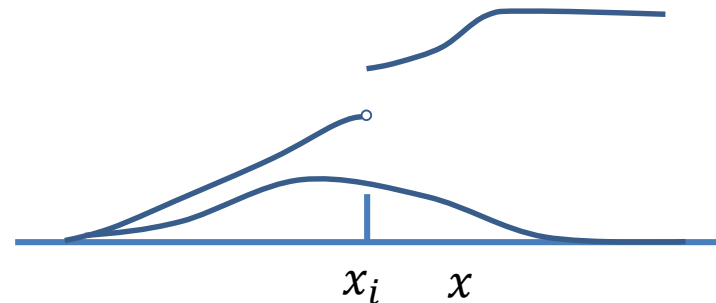
3.  $\lim_{x \rightarrow -\infty} F(x) = 0$

4.  $\lim_{x \rightarrow \infty} F(x) = 1$

5. monotone non – decreasing

6. right continuous:  $\lim_{\varepsilon \rightarrow 0} F(x + \varepsilon) = F(x)$

7.  $\lim_{\varepsilon \rightarrow 0} F(x - \varepsilon) = F(x) - P(X = x)$



# Distribution of discrete r.v.

---

- Bernoulli pmf :  $\Omega = \{0, 1\}$

$$p(k) = \begin{cases} 1 - p, & k=0 \\ p, & k=1 \end{cases}$$

- $Ber(p)$ , two-valued: Bernoulli trial: success= 1, failure= 0  
coin toss: head= 1, tail= 0  
Bernoulli trials: independently repeated Bernoulli trial

# Distribution of discrete r.v.

---

- Uniform pmf :  $\Omega = \{k | k = l, l + 1, \dots, m\}$

$$p(k) = \begin{cases} \frac{1}{(m-l+1)} & k = l, l + 1, l + 2, \dots, m \\ 0 & \text{else} \end{cases}$$

- *unif(l, m)*, equally likely, equiprobable outcomes.  
die toss, random drawing from a deck of 52 cards

# Distribution of discrete r.v.

---

- Geometric pmf :  $\Omega = \{k | k = 0, 1, 2, \dots\}$

$$p(k) = \begin{cases} (1-p)p^k & k = 0, 1, 2, \dots \\ 0 & \text{else} \end{cases}$$

- $\text{geo}(p)$ , first failure after  $k$  successes in Bernoulli trials



# Distribution of discrete r.v.

---

- Binomial pmf :  $\Omega = \{k | k = 0, 1, 2, \dots, n\}$

$$p(k) = \begin{cases} \frac{n!}{k!(n-k)!} p^k (1-p)^{n-k}, & k = 0, 1, \dots, n \\ 0, & \text{else} \end{cases}$$

- Multinomial pmf :  $\Omega = \{k_1, \dots, k_m | k_i = 0, 1, 2, \dots, n\}$

$$p(k_1, \dots, k_m) = \begin{cases} \frac{n!}{k_1! \dots k_m!} p_1^{k_1} \dots p_m^{k_m}, & k_i = 0, 1, \dots, n \\ 0, & \text{else} \end{cases}$$

- $\text{bin}(p)$ ,  $k$  successes among  $n$  Bernoulli trials
- Example: 5 coin tosses; 2 heads;  $P(\text{head}) = p$   
2 heads cases: 00011, 00101, 00110, 01001, 01010,  
01100, 10001, 10010, 10100, 11000

$$\binom{5}{2} p^2 (1-p)^3 = 10 p^2 (1-p)^3$$

# Distribution of discrete r.v.

---

- Negative binomial (Pascal) pmf :  $\Omega = \{k | k = m, m + 1, \dots\}$

$$p(k) = \begin{cases} \binom{k-1}{m-1} p^m (1-p)^{k-m}, & k = m, m+1, m+2, \dots \\ 0, & \text{else} \end{cases}$$

- $Pas(m, p)$ ,  $m$ -th success in  $k$  Bernoulli trial  
a salesman, selling an item with prob  $p$ ,  $m$  items to sell
- Example: 'How many Bernoulli trials ( $k$ ) do you need to get  $m(= 3)$  successes?'

$k \quad p(k)$

3 111:  $p(3) = \binom{2}{2} p^2 (1-p)^0$

4 0111, 1011, 1101:  $p(4) = \binom{3}{2} p^2 (1-p)^1$

5 00111, 01011, 01101, 10011, 10101, 11001:  $p(5) = \binom{4}{2} p^2 (1-p)^2$

# Distribution of discrete r.v.

---

- Poisson pmf:

$$p(k) = \begin{cases} \frac{\lambda^k e^{-\lambda}}{k!}, & k = 0, 1, 2, \dots \\ 0, & \text{else} \end{cases}$$

- $Poi(\lambda)$
- How many customers arrive at a store in time  $t$ ?
- How many neutrinos are detected at a detector in time  $t$ ?
- How many mosquitos are caught at a trap in time  $t$ ?
- How many people are born in Seoul in time  $t$ ?
- How many cars pass a toll gate in time  $t$ ?
- $\lambda$  corresponds to the average number.
- $\lambda \sim np$  (large  $n$  & small  $p$ ),  $bin(n, p) \rightarrow Poi(\lambda)$

# Distribution of continuous r.v.

---

- Uniform pdf :  $\Omega = \{x | a \leq x \leq b\}$

$$f(x) = \begin{cases} \frac{1}{(b-a)}, & a \leq x \leq b \\ 0, & \text{else} \end{cases}$$

- *unif(a, b)*, equally likely, equiprobable outcomes.  
*dart to wheel spinning:  $X \sim \text{unif}(0, 2\pi)$*

# Distribution of continuous r.v.

---

- Exponential pdf :  $\Omega = \{x | x \geq 0\}$

$$f(x) = \begin{cases} \lambda e^{-\lambda x}, & x \geq 0 \\ 0, & \text{else} \end{cases}$$

$\text{exp}(\lambda)$ , time duration, lifetime, interarrival time, cf:  $\text{geo}(p)$

Shorter time is more likely than longer time.

# Distribution of continuous r.v.

---

- Laplace pdf :  $\Omega = R$

$$f(x) = \frac{\lambda}{2} e^{-\lambda|x|}$$

*Lap*( $\lambda$ ), double exponential pdf  
difference between two iid exponential rvs.

# Distribution of continuous r.v.

---

- Gaussian pdf :  $\Omega = R$

$$f(x) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{1}{2}\left(\frac{x-m}{\sigma}\right)^2\right)$$

denoted by  $N(m, \sigma^2)$ ,

- Multivariate Gaussian pdf  $\Omega = R^n$

$$f(x) = \frac{1}{\sqrt{(2\pi)^n} \sqrt{|\Sigma|}} \exp\left(-\frac{1}{2}(x-m)^T \Sigma^{-1}(x-m)\right)$$

# Distribution of continuous r.v.

---

- Cauchy pdf :  $\Omega = R$

$$f(x) = \frac{\lambda}{\pi(\lambda^2 + x^2)}$$

*Cau*( $\lambda$ ), ratio of two iid zero mean Gaussian rvs



# Distribution of continuous r.v.

---

- Rayleigh pdf :  $\Omega = \{x | x \geq 0\}$

$$f(x) = \begin{cases} \frac{x}{\lambda^2} \exp\left(-\frac{x^2}{2\lambda^2}\right), & x \geq 0 \\ 0, & \text{else} \end{cases}$$

*Ray*( $\lambda$ ), square root of an exponential rv ( $X^2 + Y^2$ ),  
 $\sqrt{X^2 + Y^2}$ , where  $X, Y \sim N(0, \sigma^2)$

# Distribution of continuous r.v.

---

- Gamma pdf :  $\Omega = \{x | x \geq 0\}$

$$f(x) = \begin{cases} \lambda \frac{(\lambda x)^{p-1} e^{-\lambda x}}{\Gamma(p)}, & x \geq 0 \\ 0, & \text{else} \end{cases}$$

*Gam(p, λ),*

$p = m$ , positive integer  $\Rightarrow$  Earlang pdf, sum of iid exp( $\lambda$ )

$p = \frac{k}{2}$ ,  $k$  is a positive integer,  $\lambda = \frac{1}{2} \Rightarrow$  chi-squared pdf

# Joint Probability

- **equal:**  $P(X = Y) = 1$
- **Identical:**  $\forall x, p_X(x) = p_Y(x)$
- **example:** three fair-coin tosses;

$X$  = number of heads;  $Y$  = number of tails

$$p_X(0) = p_Y(0) = \frac{1}{8}, p_X(1) = p_Y(1) = \frac{3}{8},$$

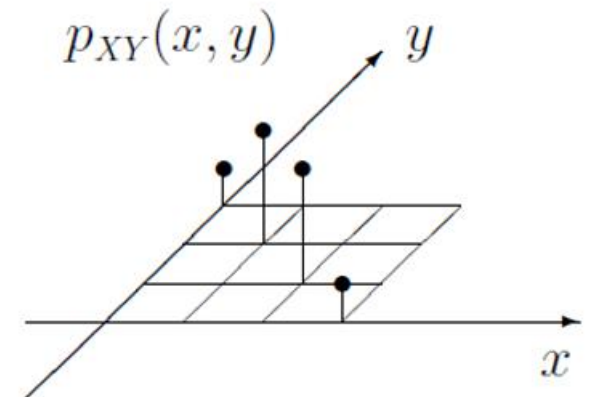
$$p_X(2) = p_Y(2) = \frac{3}{8}, p_X(3) = p_Y(3) = \frac{1}{8}, \rightarrow \text{identical}$$

$$P(X = Y) = 0, \rightarrow \text{not equal}$$

$\omega =$	hhh	hht	hth	htt	thh	tht	tth	ttt
$X(\omega) =$	3	2	2	1	2	1	1	0

$\omega =$	hhh	hht	hth	htt	thh	tht	tth	ttt
$Y(\omega) =$	0	1	1	2	1	2	2	3

$p_{XY}(x, y)$	$x = 0$	$x = 1$	$x = 2$	$x = 3$
$y = 0$	0	0	0	1/8
$y = 1$	0	0	3/8	0
$y = 2$	0	3/8	0	0
$y = 3$	1/8	0	0	0



# Conditional probability

---

- Given an event occurred, just as probability changes to conditional probability.
- **example**:  $X$  is the random variable corresponding to the number on a playing card the opponent is putting face down;  $B$  is the event that my hand consists of  $A(1)$ , 3, 4, 8, and  $Q(12)$ .
- Does the event  $B$  affect the **pmf** of  $X$ ?  
 $P(X = 1|B)$ ?  
 $P(X = 2|B)$ ?

# Conditional probability

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- Conditional probability

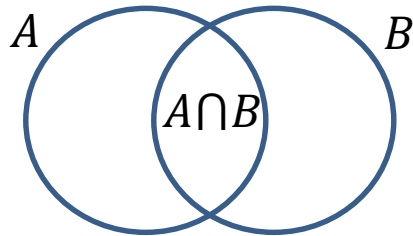
- $P(A|B) = \frac{P(A \cap B)}{P(B)}$

- Chain rule.

- 1.  $P(A \cap B) = P(A|B)P(B)$

- 2.  $P(\cap_{i=1}^n A_i) = P(A_1)P(A_2|A_1)P(A_3|A_1 \cap A_2) \cdots P(A_n | \cap_{i=1}^{n-1} A_i)$

EX) Equally probably (Uniform)



$$P(A|B) = \frac{|A \cap B|}{|B|} = \frac{|A \cap B|/|U|}{|B|/|U|} = \frac{P(A \cap B)}{P(B)}$$

# Total Probability

---

- Total Probability.

1.  $P(A) = \sum_{i=1}^k P(A \cap B_i) = \sum_{i=1}^k P(A|B_i)P(B_i)$   
where  $\{B_i, i = 1, 2, \dots, k\}$  is a partition of  $U$ .

# Independent events

---

- Independent events  $A$  &  $B$ .

- $P(A|B) = P(A)$  if  $P(B) > 0 \Leftrightarrow P(A \cap B) = P(A|B)P(B) = P(A)P(B)$

- $$P(\cap_{i=1}^n A_i) = P(A_1)P(A_2|A_1)P(A_3|A_1 \cap A_2) \cdots P(A_n | \cap_{i=1}^{n-1} A_i)$$
$$= P(A_1)P(A_2)P(A_3) \cdots P(A_n)$$

# Joint Probability

---

- $X$  and  $Y$  are independent:

$$\forall B \text{ and } C \subseteq R, P(X \in B, Y \in C) = P(X \in B)P(Y \in C)$$

- $X_1, X_2, \dots, X_n$  are independent:

$$\forall B_1, B_2, \dots, B_k \subseteq R,$$

$$P(X_i \in B_i, i = 1, 2, \dots, n) = \prod_{i=1}^n P(X_i \in B_i)$$



# Joint Probability

---

- joint probability mass function, **jpmf**

$$p_{XY}(x, y) := P(X = x, Y = y) = P((X, Y) = (x, y)) := p(x, y)$$

1.  $0 \leq p(x, y) \leq 1$
2.  $\sum_{(x,y)} p(x, y) = 1$
3.  $P((X, Y) \in D) = \sum_{(x,y) \in D} p(x, y)$

- extends to multi-variable:

$$p(x_1, \dots, x_k)$$

# Joint Probability

---

- marginal pmf:

$$p(x) = \sum_y p(x, y), \quad p(y) = \sum_x p(x, y)$$

- $X$  and  $Y$  are independent:

$$p(x, y) = p(x)p(y)$$

- $X_1, \dots, X_k$  are independent:

$$p(x_1, \dots, x_k) = \prod_{i=1}^k p(x_i)$$

- independent and identically distributed, iid,  $X_1, \dots, X_k$

$$p(x_1, \dots, x_k) = p(x_1) \cdots p(x_k) \text{ and}$$

$$p(x_i) = p(x_j) \text{ if } x_i = x_j \text{ for } i \neq j.$$

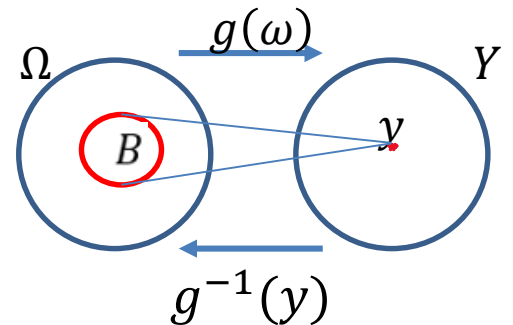
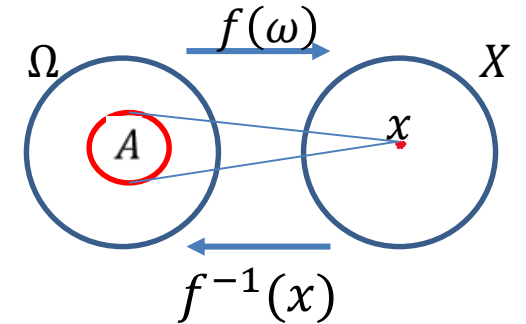
# Bayes Rule

- conditional pmf, cpmf:

$$p(x|y) := \frac{p(x,y)}{p(y)}$$

$$X = x \in \Omega_X, Y = y \in \Omega_Y$$

- $p(x|y)$  is not defined when  $p(y) \neq 0$



A Venn diagram with two overlapping circles labeled  $A$  and  $B$ . The intersection is labeled  $A \cap B$ .

$$p(x|y) = P(A|B) = \frac{|A \cap B|}{|B|} = \frac{|A \cap B| / |U|}{|B| / |U|} = \frac{P(A \cap B)}{P(B)} = \frac{p(x,y)}{p(y)}$$

# Bayes Rule

---

- conditional pmf, cpmf:

$$p(x|y, z) = \frac{p(x, y, z)}{p(y, z)}$$

$$p(x, y|z) = \frac{p(x, y, z)}{p(z)}$$

- independence

$$X, Y \text{ are independent} \rightarrow p(x|y) = p(x)$$

# Bayes Rule

---

- chain rule:

$$p(x, y) = p(x)p(y|x)$$

$$\begin{aligned} p(x_1, \dots, x_k) \\ = p(x_1)p(x_2|x_1)p(x_3|x_1, x_2) \cdots p(x_k|x_1, \dots, x_{k-1}) \end{aligned}$$

$$p(x, y|w) = p(x|w)p(y|w, x)$$

$$p(x, y, z|w) = p(x, y|w)p(z|w, x, y)$$

# Bayes Rule

---

- total probability law:

$$P(X = x) = p(x) = \sum_y p(x, y) = \sum_y p(x|y)p(y)$$

- example:  $X$  : life expectancy of a 70-year-old person.

- blood condition after 70 years old

$H$  : having high blood pressure,  $P(H) = 2/5$

$R$  : having normal blood pressure,  $P(R) = 3/5$

- at every year after 70 years old

survival probability of high blood person:  $9/10$

survival probability of normal blood person:  $19/20$

- what is the probability that a 70 years old person lives until 90 years old ?

# Bayes Rule

---

- example:

- $p(x) = p(x|H)P(H) + p(x|R)P(R)$

- $p(x|H) = \begin{cases} \frac{1}{10} \left(\frac{9}{10}\right)^{x-1}, & x = 1, 2, \dots \\ 0, & \text{else} \end{cases} \sim \text{geo}(1/10)$

- $p(x|R) = \begin{cases} \frac{1}{20} \left(\frac{19}{20}\right)^{x-1}, & x = 1, 2, \dots \\ 0, & \text{else} \end{cases} \sim \text{geo}(1/20)$

- $p(x) = p(x|H)P(H) + p(x|R)P(R)$

$$= \frac{1}{10} \left(\frac{9}{10}\right)^{x-1} \cdot \frac{2}{5} + \frac{1}{20} \left(\frac{19}{20}\right)^{x-1} \cdot \frac{3}{5}$$

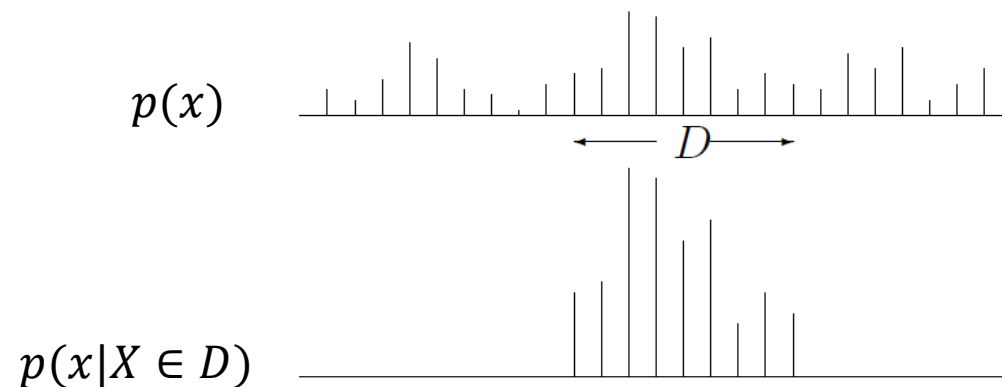
# Bayes Rule

---

- Meaning of conditional probability
- When the conditioning event is of the form  $\{X \in D\}$ ,

$$p(x|X \in D) = \frac{P(X = x, X \in D)}{P(X \in D)}$$

$$= \begin{cases} \frac{P(X = x)}{P(X \in D)}, & X \in D \\ 0, & \text{else} \end{cases}$$





# Bayes Rule

---

- Bayes Rule

- $p(y|x) = \frac{p(x,y)}{p(x)} = \frac{p(x|y) p(y)}{\sum_y p(x|y) p(y)}$

- Learning and Inference ?

Classification

$$p(w_i|x) = \frac{p(x, w_i)}{p(x)} = \frac{p(x|w_i) p(w_i)}{\sum_{w_i} p(x|w_i) p(w_i)}$$

Estimation

$$p(\theta_i|x) = \frac{p(x, \theta_i)}{p(x)} = \frac{p(x|\theta_i) p(\theta_i)}{\sum_{\theta_i} p(x|\theta_i) p(\theta_i)}$$

# Exercise

---

Let  $X$  be the exponential random variable.

Find  $F(x|X > t)$  and  $f(x|X > t)$ . How does  $F(x|X > t)$  differ from  $F(x)$ ?

■ Sol.

✓  $f(x) = \lambda e^{-\lambda x}, x \geq 0.$

✓  $F(x) = \int_0^x \lambda e^{-\lambda v} dv = -e^{-\lambda v} \Big|_0^x = 1 - e^{-\lambda x}$

# Exercise

---

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$$✓ \quad f(x) = \lambda e^{-\lambda x}, x \geq 0.$$

$$✓ \quad F(x) = \int_0^x \lambda e^{-\lambda v} dv = -e^{-\lambda v} \Big|_0^x = 1 - e^{-\lambda x}$$

$$✓ \quad F(x|X > t) = \frac{P[\{X \leq x\} \cap \{X > t\}]}{P[\{X > t\}]} = \begin{cases} 0 & x < t \\ \frac{P[\{t < X \leq x\}]}{P[\{X > t\}]} & x \geq t \end{cases}$$

# Exercise

---

Let  $X$  be the exponential random variable.

Find  $F(x|X > t)$  and  $f(x|X > t)$ . How does  $F(x|X > t)$  differ from  $F(x)$ ?

■ Sol.

$$✓ \quad f(x) = \lambda e^{-\lambda x}, x \geq 0.$$

$$✓ \quad F(x) = \int_0^x \lambda e^{-\lambda v} dv = -e^{-\lambda v} \Big|_0^x = 1 - e^{-\lambda x}$$

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$$✓ \quad \frac{P[\{t < X \leq x\}]}{P[\{X > t\}]} = \frac{F(x) - F(t)}{1 - F(t)} = \frac{e^{-\lambda t} - e^{-\lambda x}}{e^{-\lambda t}} = 1 - e^{-\lambda(x-t)}$$

# Exercise

---

Let  $X$  be the exponential random variable.

Find  $F(x|X > t)$  and  $f(x|X > t)$ . How does  $F(x|X > t)$  differ from  $F(x)$ ?

■ Sol.

$$✓ \quad f(x) = \lambda e^{-\lambda x}, x \geq 0.$$

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$$✓ \quad F(x|X > t) = \frac{P[\{X \leq x\} \cap \{X > t\}]}{P[\{X > t\}]} = \begin{cases} 0 & x < t \\ \frac{P[\{t < X \leq x\}]}{P[\{X > t\}]} & x \geq t \end{cases}$$

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$$✓ \quad f(x|X > t) = \lambda e^{-\lambda(x-t)}$$

# Interim Summary

---

- **Probability**
- **Conditional Probability**
  - Chain Rule, Total Probability, Independence,
- **Random Variable**
- **Distribution of Random Variable**
- **Joint Probability**
- **Bayes Rule**
- **(Joint) Moment**
  - Mean, (Co)Variance, Expectation, Conditional Expectation
- **Weak Law of Large Numbers**
- **Central Limit Theorem**
- **Random Vector**
- **Random Process**
  - Winner Process, Radom Walk, Markov Process, Ergodicity
- **Basic Discrete Structures**
  - Sets, Functions, Sequences, Summations, Recurrence Relations
  - Probability and Counting

# Average

---

- when we **cannot** have the pmf, we need a **statistic**, that characterizes the **sample**, population, or random variable.
- three kinds of **averages**: mean, mode, median
  - **mean**: (arithmetic) average:
$$m := \frac{1}{n} \sum_x x$$
  - **mode**: the most popular value:
$$x_{\text{mod}} := \max^{-1} P(X = x)$$
mode may not be unique; unimodal, bimodal, multimodal.
  - **median**: the center value:
$$P(X < x_{\text{med}}) = P(X > x_{\text{med}})$$
median may not be unique.

# Average

---

- What do you expect for  $X$ ?
- expectation, expected value, mean over universe:

$$EX := \sum_x xp(x) \text{ if } \sum_x |x|p(x) < \infty$$

- expectation is similar to arithmetic average.
- consider  $n$  numbers  $x_1, \dots, x_n$ .

let  $N_x$  be the number of  $x_i$ 's with the value  $x$

$$\frac{1}{n} \sum_{i=1}^n x_i = \frac{1}{n} \sum_x x N_x = \sum_x x \frac{N_x}{n} \rightarrow \sum_x xp(x) \text{ as } n \rightarrow \infty.$$



# Average

---

- expectation of function of random variables

$$EY = \sum_x g(x)p(x)$$

- example:  $X \approx \text{unif}(1,10)$ ,

$X$	1	2	3	4	5	6	7	8	8	10
$Y = g(X)$	5	5	5	5	0	0	0	2	2	3

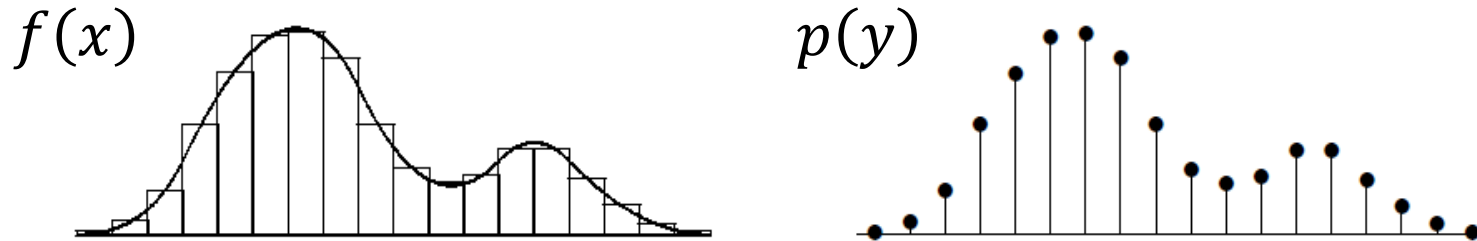
$$\begin{aligned} Eg(X) &= \sum_x g(x)p(x) \\ &= 5 \cdot \frac{1}{10} + 5 \cdot \frac{1}{10} + 5 \cdot \frac{1}{10} + 5 \cdot \frac{1}{10} + 0 \cdot \frac{1}{10} + 0 \cdot \frac{1}{10} + 0 \cdot \frac{1}{10} + 2 \cdot \frac{1}{10} + 2 \cdot \frac{1}{10} + 3 \cdot \frac{1}{10} \\ &= 5 \cdot \frac{4}{10} + 0 \cdot \frac{3}{10} + 2 \cdot \frac{2}{10} + 3 \cdot \frac{1}{10} = \sum_y yp(y) \end{aligned}$$

# Expectation for Continuous r.v.

---

- **expectation:**  $EX := \int_{-\infty}^{\infty} xf(x)dx$ , if  $\int_{-\infty}^{\infty} |x|f(x)dx < \infty$

let  $Y$  be a discrete random variable approximating  $X$ .



$$EX \approx \sum_y yp(y) = \sum_y yf(y)\Delta \approx \int xf(x)dx$$

$$Eg(X) = \int_{-\infty}^{\infty} g(x)f(x)dx$$

This can be justified using approximation with a discrete rv.

# Moment

---

- Moment
  - $n$ -th moment:  $EX^n$
  - $n$ -th central moment:  $E(X - m_X)^n$
- Mean(average): 1-st moment
- Variance: 2-nd central moment
- $n$ -th central moment is a function of  $n$ -th and lower moments.

# Moment

---

- expectation operator is linear.

$$E(aX + b) = aEX + b$$

- variance

$$\begin{aligned} E(X - m_X)^2 &= E(X^2 - 2m_X X + m_X^2) \\ &= EX^2 - 2m_X EX + m_X^2 = EX^2 - m_X^2 \end{aligned}$$

- standard deviation

$$\sigma_X = \sqrt{\text{var}(X)}$$

- variance is not linear

$$\begin{aligned} \text{var}(aX + b) &= E(aX + b)^2 - (E(aX + b))^2 \\ &= E(aX + b)^2 - (am_X + b)^2 = a^2 E(X - m_X)^2 \\ &= a^2 \text{var}(X): \text{ not affected by } b. \end{aligned}$$

# Joint moment

---

- correlation:  $\text{cor}(X, Y) = EXY$

- covariance:

$$\begin{aligned}\text{cov}(X, Y) &= E(X - m_X)(Y - m_Y) \\ &= EXY - m_X m_Y\end{aligned}$$

- correlation coefficient:

$$\begin{aligned}\rho_{XY} &= \frac{\text{cov}(X, Y)}{\sigma_X \sigma_Y} \\ |\rho_{XY}| &\leq 1 \text{ [Schwarz ineq]}\end{aligned}$$

# Joint moment

- uncorrelated  $X$  and  $Y$  :

$$EXY = EXEY, \text{cov}(X, Y) = 0, \text{ or } \rho_{XY} = 0$$

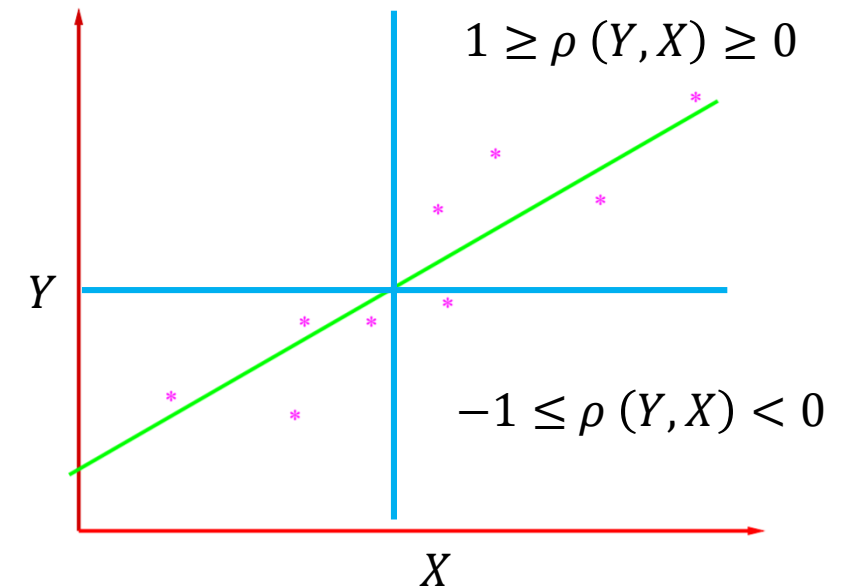
- independent and uncorrelated  
independent  $\Rightarrow$  uncorrelated  
uncorrelated  $\nRightarrow$  independent  
[example]

Let  $p(x) = p(-x)$  and  $Y = X^2$

$$\Rightarrow EX = EX^3 = EX^5 = \dots = 0$$

$$\Rightarrow EXY = EX^3 = 0 = EXEY$$

$\Rightarrow$  uncorrelated but not independent



# Joint moment

---

- **variance of sum** of random variables

$$\text{var}(\sum_{i=1}^k X_i) = \sum_{i=1}^k \text{var}(X_i) + \sum_{i \neq j} \text{cov}(X_i, X_j)$$

$$X_i \text{ uncorrelated} \Rightarrow \text{var}(\sum_{i=1}^k X_i) = \sum_{i=1}^k \text{var}(X_i)$$

$$X_i \text{ i.i.d.} \Rightarrow \text{var}(\sum_{i=1}^k X_i) = k \text{var}(X_i)$$

- **(Cauchy-)Schwarz inequality:**

$$|EXY| \leq \sqrt{EX^2} \sqrt{EY^2},$$

where equality holds if and only if

$X = aY$  for some  $a$ .

$$\Rightarrow |\text{cov}(X, Y)| = |E(X - m_X)(Y - m_Y)| \leq \sigma_X \sigma_Y,$$

$$\Rightarrow |\rho_{XY}| \leq 1$$

$$\text{cf. } |\sum x_i y_i| \leq \sqrt{\sum x_i^2} \sqrt{\sum y_i^2}$$

# Weak law of large numbers

---

- We often estimate the mean of a random variable by averaging its sample values.

$$M_n = \frac{1}{n} \sum_{i=1}^n X_i$$

- **sample mean:**

: unbiased estimator of  $m_X$  if  $EX_i = m_X, i = 1, \dots, n$

$$\leftarrow EM_n = m_X$$

- **weak law of large numbers:**

let  $X_1, \dots, X_n$  be i.i.d.,  $EX_i = m, \text{var}(X_i) = \sigma^2$ ,

$EM_n = m, \text{var}(M_n) = \sigma^2/n \rightarrow 0$  as  $n \rightarrow \infty$

$$\leftarrow X_i \text{ i.i.d.} \Rightarrow \text{var}(M_n) = \text{var}\left(\frac{1}{n} \sum_{i=1}^n X_i\right) = \frac{1}{n^2} \text{var}\left(\sum_{i=1}^n X_i\right) = \frac{1}{n} \text{var}(X_i)$$



# Central Limit Theorem

---

- Let  $X_1, \dots, X_n$  be i.i.d.,  $EX_i = m$ ,  $\text{var}(X_i) = \sigma^2$ ,

$$S_n := \sum_{i=1}^n X_i : \quad \text{mean} = nm, \text{var} = n\sigma^2$$

$$M_n := \frac{1}{n} \sum_{i=1}^n X_i : \quad \text{mean} = m, \text{var} = \frac{\sigma^2}{n}$$

$$Z_n := \frac{1}{\sqrt{n}} \sum_{i=1}^n X_i : \quad \text{mean} = \sqrt{n}m, \text{var} = \sigma^2$$

$$Y_n := \frac{1}{\sqrt{n}} \sum_{i=1}^n \left( \frac{X_i - m}{\sigma} \right) : \quad \text{mean} = 0, \text{var} = 1$$

$$Y_n = \frac{1}{\sqrt{n}} \sum_{i=1}^n \frac{X_i - m}{\sigma} \rightarrow N(0,1) \text{ as } n \rightarrow \infty$$

$$\rightarrow Y_n = \frac{S_n - nm}{\sqrt{n\sigma^2}} \sim N(0,1)$$

# Central Limit Theorem

---

- Example:

Consider the sum  $W$  of the 100 numbers obtained from repeated tossing of a fair die.

$$P(W \leq 200) = \sum_{w=100}^{200} p(w)$$

- Let  $X_1, \dots, X_n$  be i.i.d. repeated tossing of a fair die,  $W = \sum_{i=1}^n X_i$ ,  $EX_i = m$ ,  $\text{var}(X_i) = \sigma^2$

- $W = \sum_{i=1}^n X_i \rightarrow Y = \frac{W - nm}{\sqrt{n\sigma^2}} \sim N(0,1)$

$$\rightarrow P\left(\frac{100 - nm}{\sqrt{n\sigma^2}} \leq Y \leq \frac{200 - nm}{\sqrt{n\sigma^2}}\right) = \sum_{y=y_1}^{y_2} p(y), \quad y_1 = \frac{100 - nm}{\sqrt{n\sigma^2}}, \quad y_2 = \frac{200 - nm}{\sqrt{n\sigma^2}}, \quad n = 100$$

# Central Limit Theorem

---

- Example:

Consider the sum  $W$  of the 100 numbers obtained from repeated tossing of a fair die.

$$P(W \leq 200) = \sum_{w=100}^{200} p(w), W = \sum_{i=1}^n X_i$$

$$\rightarrow P\left(\frac{100-nm}{\sqrt{n\sigma^2}} \leq Y \leq \frac{200-nm}{\sqrt{n\sigma^2}}\right) = \sum_{y=y_1}^{y_2} p(y), y_1 = \frac{100-nm}{\sqrt{n\sigma^2}}, y_2 = \frac{200-nm}{\sqrt{n\sigma^2}}, n = 100$$

- Find  $m$  and  $\sigma^2$

# Central Limit Theorem

---

- Example:

Consider the sum  $W$  of the 100 numbers obtained from repeated tossing of a fair die.

$$P(W \leq 200) = \sum_{w=100}^{200} p(w), W = \sum_{i=1}^n X_i$$

$$\rightarrow P\left(Y \leq \frac{200-nm}{\sqrt{n\sigma^2}}\right) = \sum_{y=y_1}^{y_2} p(y), y_1 = \frac{100-nm}{\sqrt{n\sigma^2}}, y_2 = \frac{200-nm}{\sqrt{n\sigma^2}}, n = 100$$

- Find  $m$  and  $\sigma^2$

$$m = EX_i = \frac{1}{6}(1 + 2 + 3 + 4 + 5 + 6) = 3.5$$

$$EX_i^2 = \frac{1}{6}(1^2 + 2^2 + 3^2 + 4^2 + 5^2 + 6^2) = \frac{91}{6} = 15.1667$$

$$\sigma^2 = \text{var}(X_i) = EX_i^2 - m^2 = 15.17 - 3.5^2 = 2.9167,$$

$$EW = nm = 100 \times 3.5 = 350$$

$$\text{var}(W) = n\sigma^2 = 100 \times 2.9167 = 291.67$$

# Central Limit Theorem

---

- Example:

Consider the sum  $W$  of the 100 numbers obtained from repeated tossing of a fair die.

$$P(W \leq 200) = \sum_{w=100}^{200} p(w), \quad W = \sum_{i=1}^n X_i$$

$$\rightarrow P\left(Y \leq \frac{200 - nm}{\sqrt{n\sigma^2}}\right) = \sum_{y=y_1}^{y_2} p(y), \quad y_1 = \frac{100 - nm}{\sqrt{n\sigma^2}}, \quad y_2 = \frac{200 - nm}{\sqrt{n\sigma^2}}$$

$$P(100 \leq W \leq 200) \approx$$

# Central Limit Theorem

---

- Example:

Consider the sum  $W$  of the 100 numbers obtained from repeated tossing of a fair die.

$$P(W \leq 200) = \sum_{w=100}^{200} P_W(w), W = \sum_{i=1}^n X_i$$

$$\rightarrow P\left(Y \leq \frac{200 - nm}{\sqrt{n\sigma^2}}\right) = \sum_{y=y_1}^{y_2} p_Y(y), y_1 = \frac{100 - nm}{\sqrt{n\sigma^2}}, y_2 = \frac{200 - nm}{\sqrt{n\sigma^2}}$$

$$P(100 \leq W \leq 200) \approx P\left(Y \leq \frac{200 - nm}{\sqrt{n\sigma^2}}\right) = \Phi\left(\frac{200 - nm}{\sqrt{n\sigma^2}}\right) = \Phi\left(\frac{200 - 350}{\sqrt{291.67}}\right) = \Phi(-8.7831) \approx 0$$

# Conditional expectation

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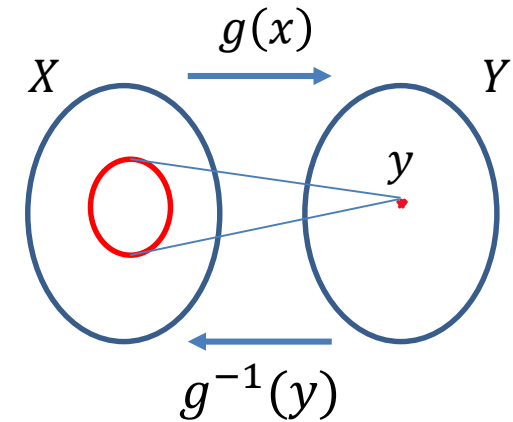
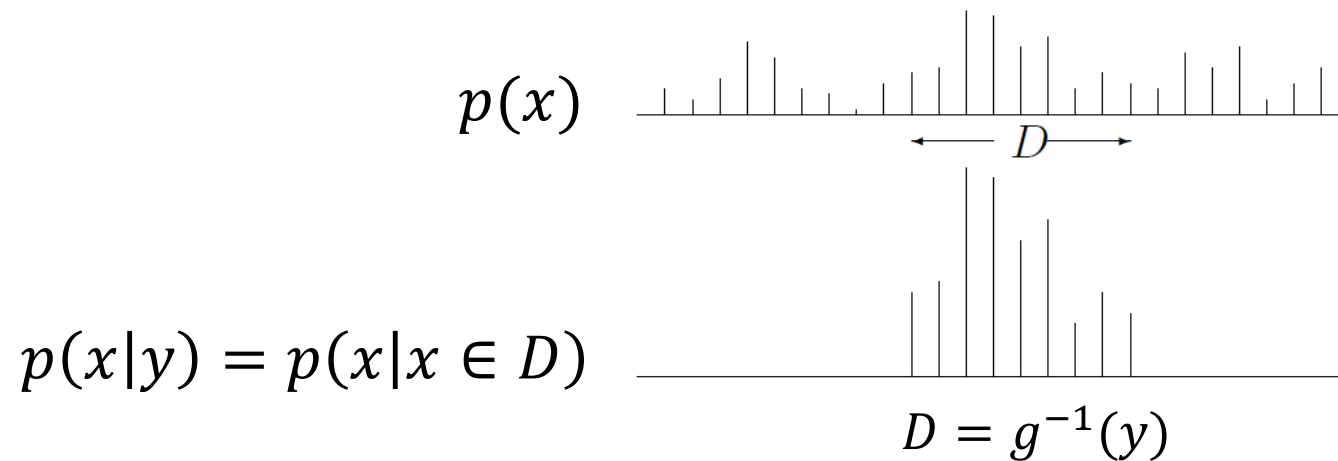
- conditional expectation:

for an event  $A$ ,  $E(X|A) := \sum_x x p(x|A)$

$$E(X|Y = y) := \sum_x x p(x|y)$$

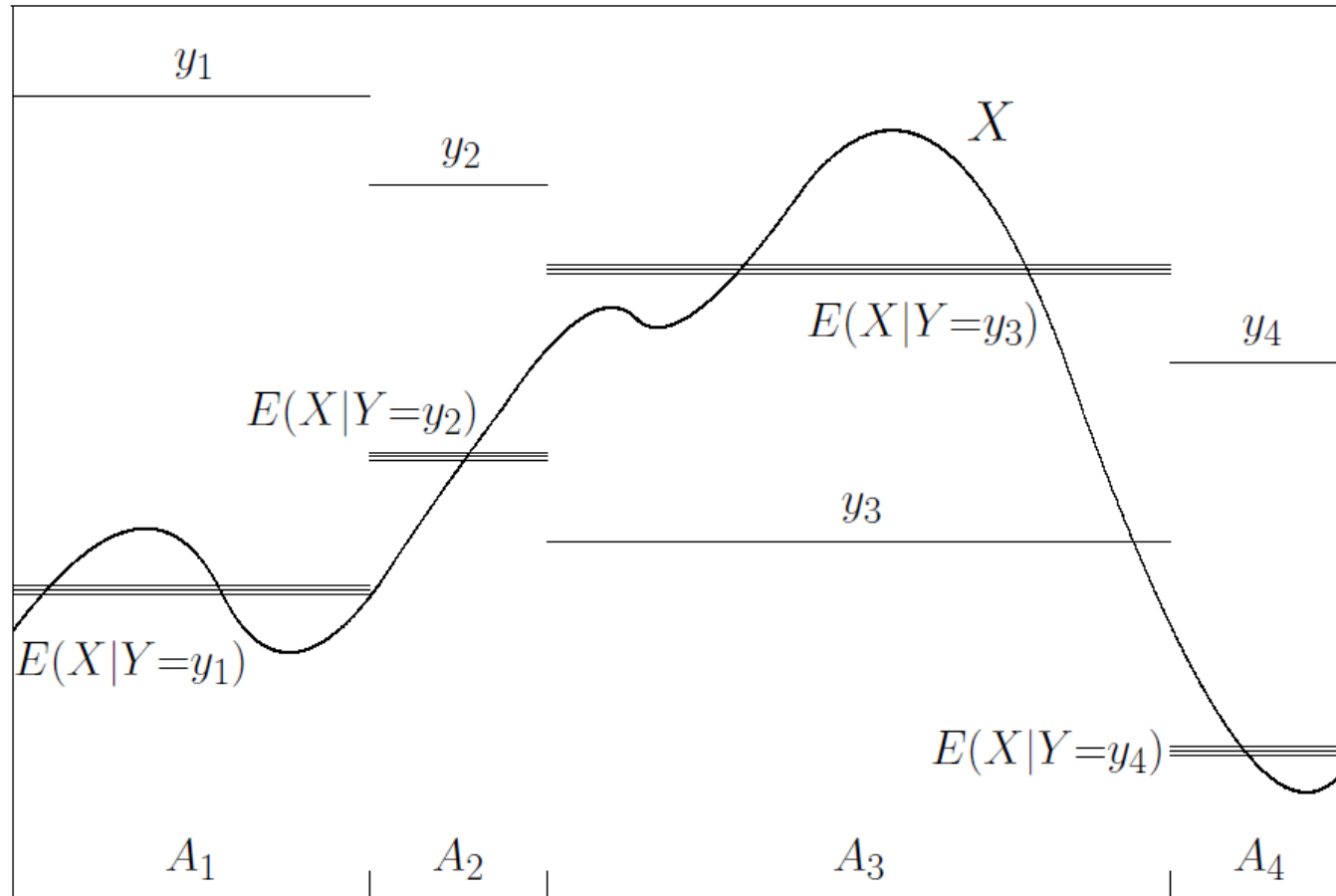
this is a function of  $y$  (for the given  $p(x, y)$ )

$$E(g(X)|Y = y) = \sum_x g(x) p(x|y)$$



# Conditional expectation

---





# Conditional expectation

---

- properties:
1. linear :  $E(aX + bY | Z) = aE(X | Z) + bE(Y | Z)$
  2.  $E(a | X) = a$
  3.  $E(X | a) = EX$
  4.  $X \geq a \Rightarrow E(X | Y) \geq a$ ; likewise for  $>$ ,  $\leq$ , and  $<$ .
  5.  $|E(X | Y)| \leq E(|X| | Y)$
  6.  $E(g(Y)X | Y) = g(Y)E(X | Y)$  [substitution law]
  7.  $X$  and  $Y$  independent  $\Rightarrow E(X | Y) = EX$
  8.  $EE(X | Y) = EX$  [total prob law]
  9.  $g$  is one - to - one  $\Rightarrow E(X | g(Y)) = E(X | Y)$

■  $EE(X|Y) = \sum_y \sum_x xp(x|y)p(y) = \sum_y \sum_x xp(x, y) = \sum_x x \sum_y p(x, y) = \sum_x xp(x) = EX$

# Interim Summary

---

- **Probability**
- **Conditional Probability**
  - Chain Rule, Total Probability, Independence,
- **Random Variable**
- **Distribution of Random Variable**
- **Joint Probability**
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  - Probability and Counting

# Random Vectors

---

- random vector:

$$X = (X_1, \dots, X_k)^T, EX = (EX_1, \dots, EX_k)^T$$

- random matrix:

$$EXX^T = \begin{pmatrix} EX_1X_1 & EX_1X_2 & \cdots & EX_1X_k \\ EX_2X_1 & & & EX_2X_k \\ \vdots & & & \vdots \\ EX_kX_1 & EX_kX_2 & \cdots & EX_kX_k \end{pmatrix}$$

$$E(X - \mathbf{m}_X)(X - \mathbf{m}_X)^T = \begin{pmatrix} E(X_1 - m_1)(X_1 - m_1) & \cdots & E(X_1 - m_1)(X_k - m_k) \\ E(X_2 - m_2)(X_1 - m_1) & \cdots & E(X_2 - m_2)(X_k - m_k) \\ \vdots & \ddots & \cdots \\ E(X_k - m_k)(X_1 - m_1) & \cdots & E(X_k - m_k)(X_k - m_k) \end{pmatrix}$$

# Jointly Gaussian random variables

---

- jointly Gaussian rvs

$$f(x) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{(x-m)^2}{2\sigma^2}\right)$$

$$f(\mathbf{x}) = \frac{1}{\sqrt{(2\pi)^n} \sqrt{|\Sigma|}} \exp\left(-\frac{(\mathbf{x}-\mathbf{m})^T \Sigma^{-1} (\mathbf{x}-\mathbf{m})}{2}\right)$$

$$\Sigma = E[(\mathbf{x} - \mathbf{m})(\mathbf{x} - \mathbf{m})^T]$$

$$= E \begin{bmatrix} (x - m_x)^2 & (x - m_x)(y - m_y) \\ (x - m_x)(y - m_y) & (y - m_y)^2 \end{bmatrix} \text{ for } \mathbf{x}^T = [x, y]$$

$$= \begin{bmatrix} \sigma_x^2 & \rho\sigma_x\sigma_y \\ \rho\sigma_x\sigma_y & \sigma_y^2 \end{bmatrix}, \quad |\Sigma| = \sigma_x^2 \sigma_y^2 (1 - \rho^2)$$

# Jointly Gaussian random variables

---

- conditional probability

$$f(x|y) = \frac{1}{(2\pi)^{\frac{k}{2}} \sqrt{|\Sigma_{X|Y}|}} \exp\left(-\frac{1}{2} (x - m_{X|Y})^t \Sigma_{X|Y}^{-1} (x - m_{X|Y})\right),$$

where

$$m_{X|Y} = A(y - m_Y) + m_X \text{ and}$$

$$\Sigma_{X|Y} = \Sigma_X - AC_{YX}, \text{ where } A\Sigma_Y = \Sigma_{XY}.$$

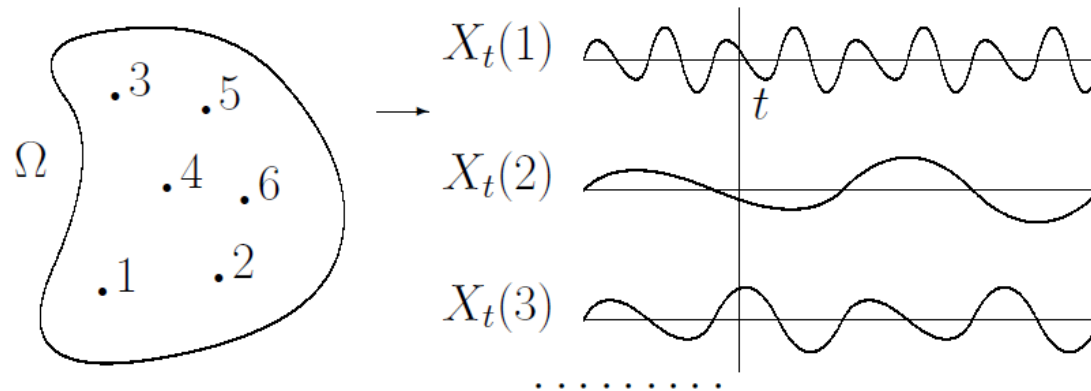
- conditional expectation

$$E(X|Y) = A(Y - m_Y) + m_X$$

# Random process

---

- random process  $X_t(\omega)$ ,  $t \in I$ 
  1. random sequence, random function, or random signal:  $X_t : \Omega \rightarrow$  the set of all sequences or functions
  2. indexed family of infinite number of random variables:  
 $X_t : I \rightarrow$  set of all random variables defined on  $\Omega$



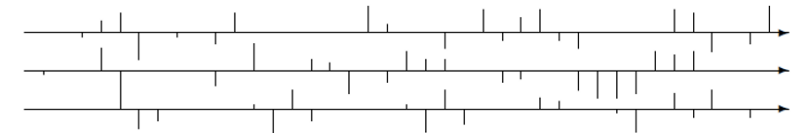
# Random process

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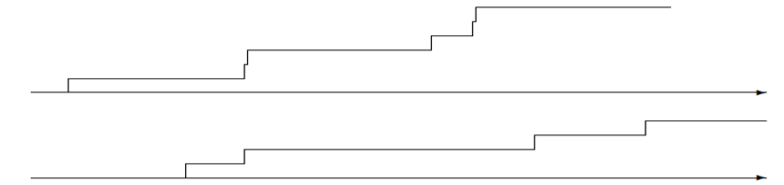
- example:
  - surface temperature of a space shuttle
  - thermal noise of a semiconductor device
  - total number of customers visiting a store up to time  $t$
  - sequence of i.i.d. Bernoulli r. v. : Bernoulli process
  - $X_t = A \cos 2 \pi t, Y_t = B \cos 2 \pi t$   
where  $A$  and  $B$  are independent random variables.
  - $X_t = \cos 2 \pi(t + \Theta), Y_t = \cos 2 \pi(t + \Psi)$   
where  $\Theta, \Psi \sim$  uniform and independent.
  - $X_n, Y_n, Z_n : \text{iid } N(0,1)$

$$f_{X_i, X_j, Y_k}(x_i, x_j, y_k) = \frac{1}{(2\pi)^{\frac{3}{2}}} e^{-\frac{x_i^2 + x_j^2 + y_k^2}{2}}$$

discrete-time, continuous-valued - iid Gaussian



continuous-time, discrete-valued-Poisson process



# Moment

- mean function:

$$m_X(t) := EX_t = \begin{cases} \sum_x xp(x), & \text{disc valued} \\ \int xf(x)dx, & \text{cont valued} \end{cases}$$

- auto-correlation function, acf:

$$R_X(t, s) := EX_t X_s = \begin{cases} \sum_{u \in X_t} \sum_{v \in X_s} uv p(u, v), & \text{disc valued} \\ \int_{X_s} \int_{X_t} uvf(u, v)dudv, & \text{cont valued} \end{cases}$$

$$X = (X_{t_1}, \dots, X_{t_k}) \Rightarrow R_X = \begin{pmatrix} R_X(t_1, t_1) & \cdots & R_X(t_1, t_k) \\ \vdots & & \vdots \\ R_X(t_k, t_1) & \cdots & R_X(t_k, t_k) \end{pmatrix}$$

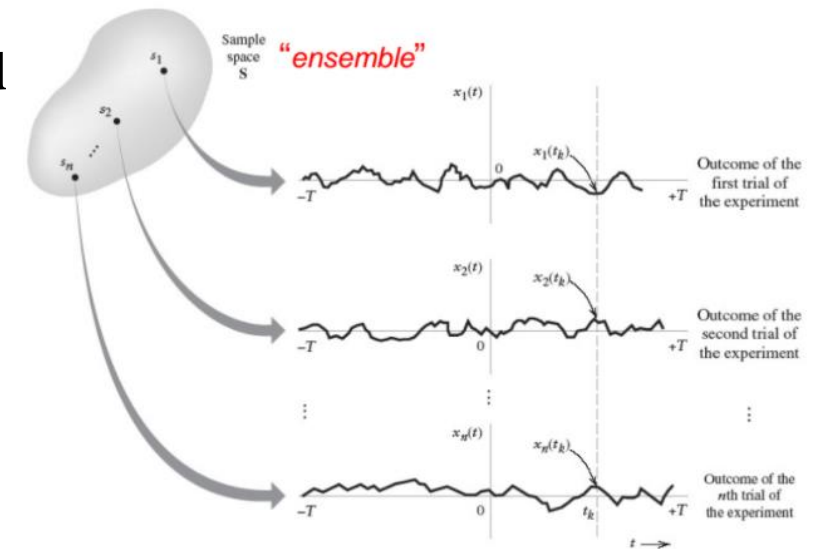


Figure from (Haykin & Moher, 2010)



# Moment

- auto-covariance function, acvf:

$$\begin{aligned} C_X(t, s) &:= E(X_t - m_X(t))(X_s - m_X(s)) \\ &= R_X(t, s) - m_X(t)m_X(s) \end{aligned}$$

$$X = (X_{t_1}, \dots, X_{t_k}) \Rightarrow C_X = \begin{pmatrix} C_X(t_1, t_1) & \cdots & C_X(t_1, t_k) \\ \vdots & & \vdots \\ C_X(t_k, t_1) & \cdots & C_X(t_k, t_k) \end{pmatrix}$$

- cross-correlation function, ccf:

$$R_{XY}(t, s) := EX_t Y_s$$

- cross-covariance function, ccvf:

$$\begin{aligned} C_{XY}(t, s) &:= E(X_t - m_X(t))(Y_s - m_Y(s)) \\ &= R_{XY}(t, s) - m_X(t)m_Y(s) \end{aligned}$$

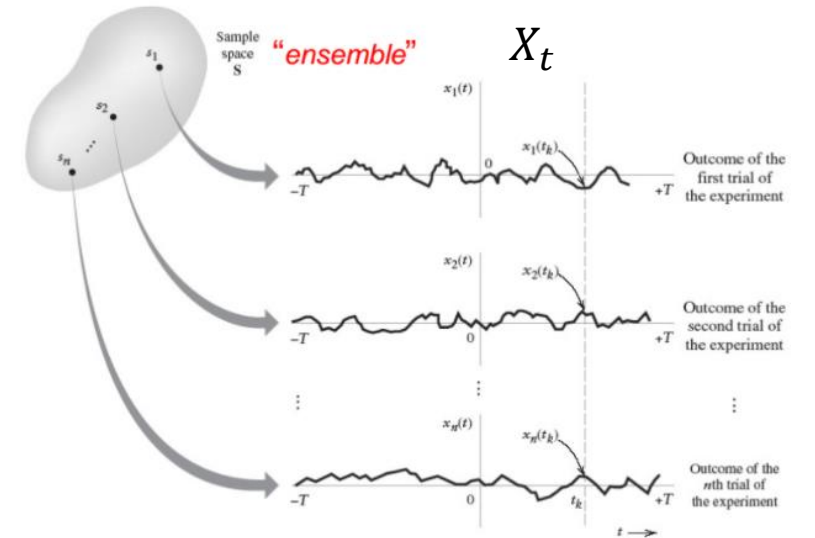


Figure from (Haykin & Moher, 2010)

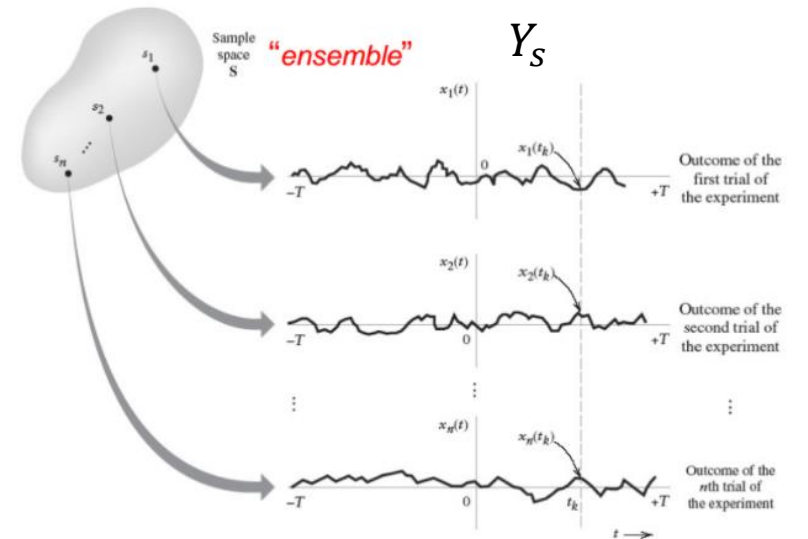


Figure from (Haykin & Moher, 2010)

# Moment

- orthogonal processes  $X_t$  and  $Y_t$ :  $E X_t Y_s = R_{XY}(t, s) = 0$  for any  $t$  and  $s$ .

- uncorrelated processes  $X_t$  and  $Y_t$ :

$$E X_t Y_s = E X_t E Y_s \text{ for any } t \text{ and } s.$$

$$R_{XY}(t, s) = m_X(t) m_Y(s)$$

$$C_{XY}(t, s) = 0$$

- stationarity: shift invariance for any  $d, \tau = s - t$ ,

$$m_X(t) = m_X(t + d) = m_X(0),$$

$$R_X(t, s) = R_X(t + d, s + d) = R_X(\tau),$$

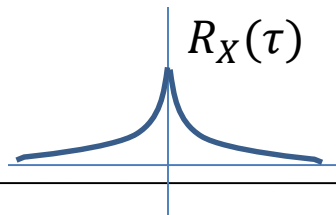
$$C_X(t, s) = C_X(t + d, s + d) = C_X(\tau),$$

$$R_{XY}(t, s) = R_{XY}(t + d, s + d) = R_{XY}(\tau),$$

$$C_{XY}(t, s) = C_{XY}(t + d, s + d) = C_{XY}(\tau).$$

- strictly stationary

pdf is shift invariant



independent  $\Rightarrow$  uncorrelated  
uncorrelated  $\nRightarrow$  independent (except jointly Gaussian proc.)

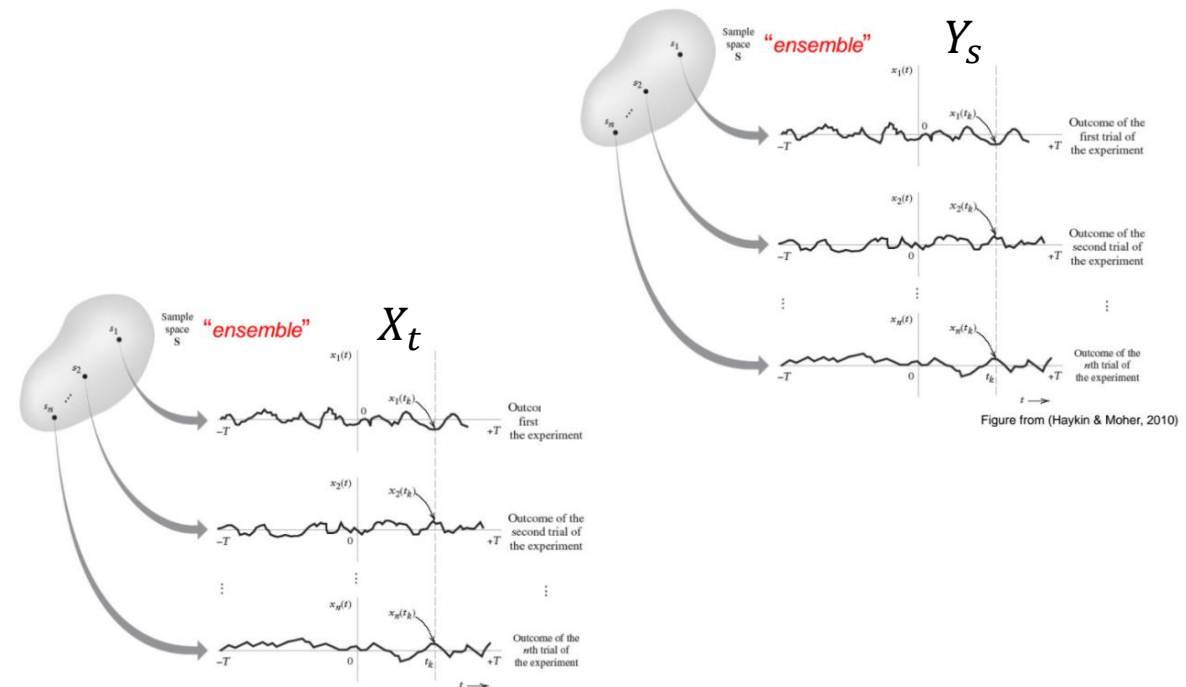


Figure from (Haykin & Moher, 2010)

# Power spectral density

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- Power spectral density, psd,  $S_X(f)$  for wss  $X_t$ :

$$S_X(f) := \begin{cases} \sum_{\tau=-\infty}^{\infty} R_X(\tau) e^{-j2\pi f\tau} & \text{disc - time} \\ \int_{-\infty}^{\infty} R_X(\tau) e^{-j2\pi f\tau} d\tau & \text{cont - time} \end{cases}$$

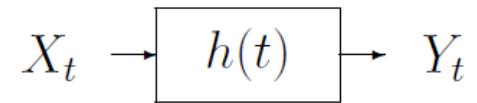
- Fourier inversion:

$$R_X(\tau) = \begin{cases} \int_{-\frac{1}{2}}^{\frac{1}{2}} S_X(f) e^{j2\pi f\tau} df & \text{disc - time} \\ \int_{-\infty}^{\infty} S_X(f) e^{j2\pi f\tau} df & \text{cont - time} \end{cases}$$

# Linear time-invariant system

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- Linear time-invariant system with impulse response  $h(t)$ :



$$Y_t = \int_{-\infty}^{\infty} h(t - \tau) X_{\tau} d\tau$$

- If  $X_t$  is wss,  $Y_t$  is also wss.

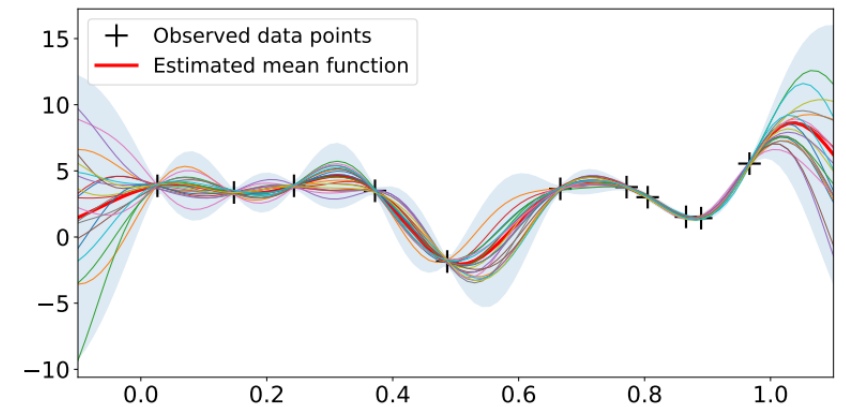
$$R_Y(\tau) = R_X(\tau) * h(\tau) * h(-\tau)$$

$$S_Y(f) = S_X(f) |H(f)|^2$$

# Gaussian process

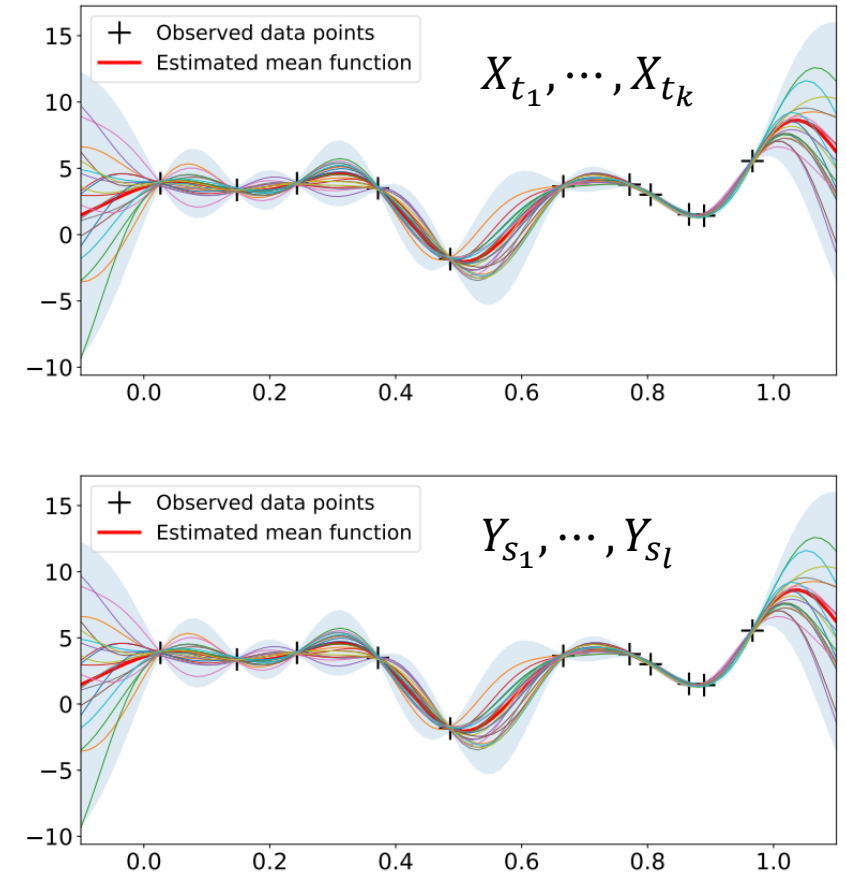
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- Gaussian process: for any choice of  $t_1, \dots, t_k$ ,  $(X_{t_1}, \dots, X_{t_k})^T$  is a Gaussian random vector.
  1. A Gaussian random process is fully characterized by its 1st and 2nd moment, ie, by  $m_X(t)$  and  $R_X(t, s)$ .
  2. Any linear or affine transformation of a Gaussian random process is Gaussian, eg, integral or stable linear filtering.
  3. If samples of a Gaussian random process are uncorrelated, they are independent.
  4. If a Gaussian random process is wss, it is sss.



# Gaussian process

- Jointly Gaussian process: for any choice of  $t_1, \dots, t_k$  and  $s_1, \dots, s_l$ ,  $(X_{t_1}, \dots, X_{t_k}, Y_{s_1}, \dots, Y_{s_l})^T$  is a Gaussian random vector.
  - Jointly Gaussian random processes are fully characterized by their 1st and 2nd moments, ie, by  $m_X(t), m_Y(t), R_X(t, s), R_Y(t, s)$  and  $R_{XY}(t, s)$ .
  - Any linear or affine transformation of a jointly Gaussian random process is Gaussian.
  - If two jointly Gaussian random processes are uncorrelated, they are independent.
  - If jointly Gaussian random processes are jwss, they are jsss.



# White noise

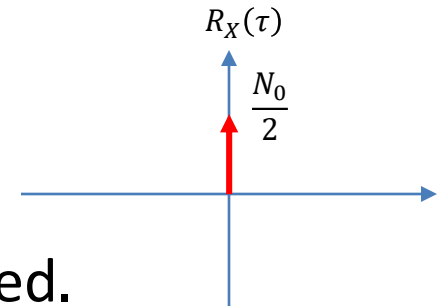
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- White noise : a wss process  $X_t$  with psd  $S_X(f) = \frac{N_0}{2}$

$$\Rightarrow m_X(t) = 0$$

$$\Rightarrow R_X(\tau) = \frac{N_0}{2} \delta(\tau) \quad : \forall \varepsilon > 0, X_t \text{ and } X_{t+\varepsilon} \text{ are uncorrelated.}$$

$$\Rightarrow P_X = EX_t^2 = \int_{-\infty}^{\infty} \frac{N_0}{2} df = \infty : \text{infinite average power}$$

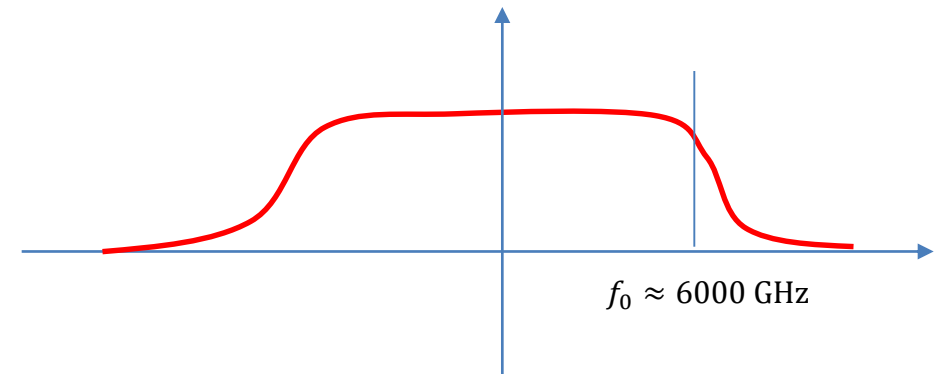


- If  $X_t$  is Gaussian,  $\forall \varepsilon > 0, X_t$  and  $X_{t+\varepsilon}$  are independent.
- In reality what is called a white noise has a psd that is constant up to about 1000 GHz and then gradually tapers off.

# White noise

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- White noise : a wss process  $X_t$  with psd  $S_X(f) = \frac{N_0}{2}$
- Thermal noise model:  $S_X(f) = \frac{N_0}{2} \left( \frac{\frac{|f|}{f_0}}{\exp(\frac{|f|}{f_0}) - 1} \right)$ ,  
 $f_0 \approx 6000$  GHz, Gaussian  $\Rightarrow$  If  $\varepsilon > 0.17$  pico-seconds,  
 $X_t$  and  $X_{t+\varepsilon}$  are considered independent.
- discrete-time white noise: uncorrelated wss process

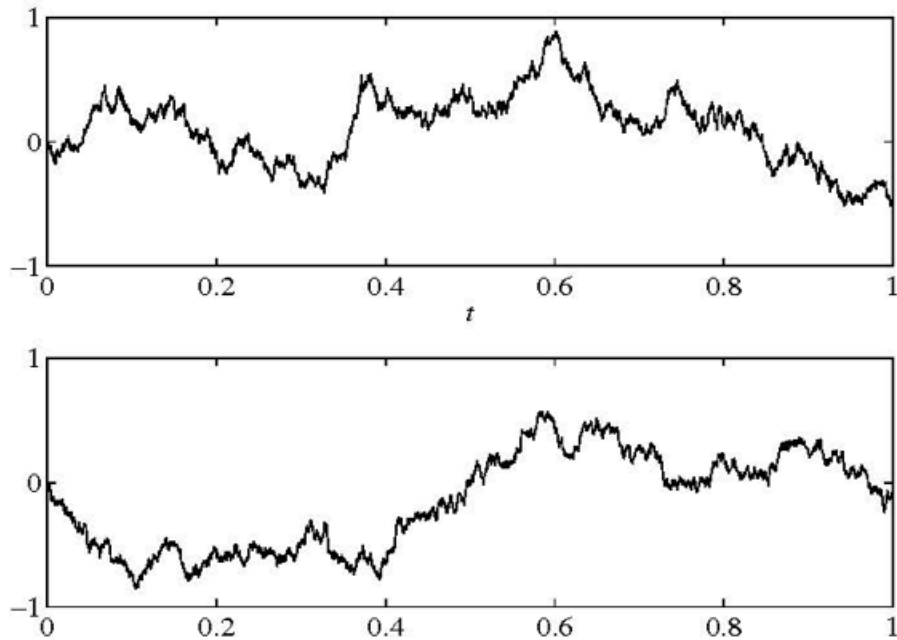




# Wiener process

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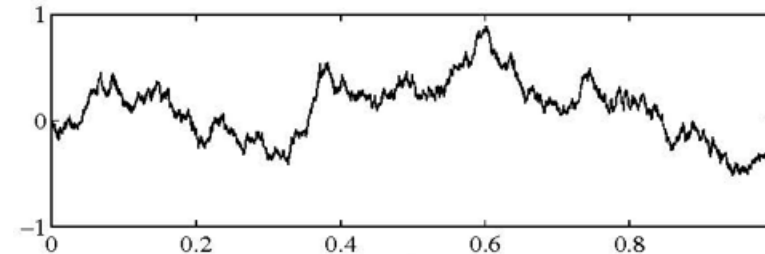
- A **Wiener process**  $W_t$ , also called **Brownian motion**, describes the motion of a **highly excited particle** in a fluid, viewed in one coordinate, that does not drift off in one direction.



# Wiener process

---

- Wiener process for  $t \geq 0$  :
  1.  $W_0 = 0$ .
  2. For  $s < t$ ,  $W_t - W_s$  is a Gaussian random variable with mean zero and variance  $\sigma^2(t - s)$ .
  3. For  $t_1 < t_2 < \dots < t_k$ , the increments  $W_{t_2} - W_{t_1}, W_{t_3} - W_{t_2}, \dots, W_{t_k} - W_{t_{k-1}}$  are independent: independent increment process.
  4. Each sample path is a continuous function of  $t$ .
- $W_t = \int_0^t X_\tau d\tau, t \geq 0$ , where  $X_t$  is a white noise.



# Wiener process

---

- mean, auto-correlation, auto-covariance

$$EW_t = 0, \text{var}(W_t) = \sigma^2 t = E[W_t^2] = \int_0^t E[X_\tau^2] d\tau$$

For  $t > s$ ,  $\text{cov}(W_t, W_s) = ?$

$$\begin{aligned}\text{cov}(W_t, W_s) &= EW_t W_s - EW_t EW_s = EW_t W_s \\ &= E(W_t - W_s + W_s)W_s = E(W_t - W_s)W_s + EW_s^2 \\ &= E(W_t - W_s)EW_s + EW_s^2 = \sigma^2 s\end{aligned}$$

$$\Rightarrow R_W(t, s) = EW_t W_s = \sigma^2 \min(t, s)$$

$$\Rightarrow C_W(t, s) = \text{cov}(W_t, W_s) = \sigma^2 \min(t, s)$$

- Wiener processes are **nonstationary**.

# Random walk approx. of Winner process

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- random walk approximation:

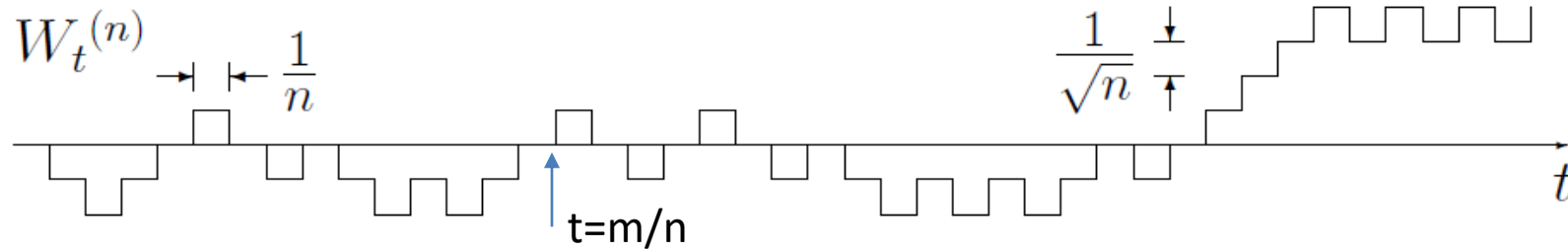
$X_1, X_2, \dots$  is an equiprobable Bernoulli process with values  $+1$  and  $-1$ ,

$$\sigma^2 = p(1 - p).$$

$S_m := \sum_{i=1}^m X_i$ : symmetric random walk

$$W_t^{(n)} := \frac{1}{\sqrt{n}} S_{[nt]} = \frac{1}{\sqrt{n}} S_m,$$

where  $[t]$  is the greatest integer no greater than  $t$ .

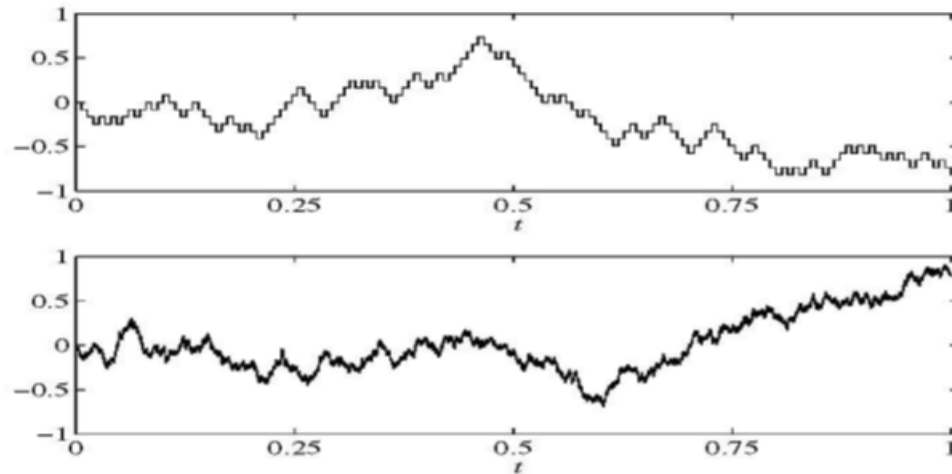


$$W_t^{(n)} := \sum_{i=1}^m \frac{1}{\sqrt{n}} X_i \Rightarrow E \left[ W_t^{(n)^2} \right] = \sum_{i=1}^m \frac{1}{n} E[X_i^2] = \frac{1}{n} m \sigma^2 = \sigma^2 t$$

# Random walk approx. of Wiener process

---

- As  $n \rightarrow \infty$ ,
  1. The power of the process is maintained.
  2. By the central limit theorem,  $W_t^{(n)}$  becomes Gaussian.
  3.  $W_t^{(n)}$  becomes a Wiener process.
  4. As the random walk is an independent increment process, so is the Wiener process.



# Markov process

---

- We discuss jointly discrete cases; jointly continuous cases are similar.

- Markov property:

For any  $t_1 < t_2 \cdots < t_n$  and  $x_1, \cdots, x_n$ ,

$$p(x_n | x_1, \cdots, x_{n-1}) = p(x_n | x_{n-1})$$

- **Markov process:** a process with the Markov property

$$\begin{aligned} p(x_1, \cdots, x_n) \\ &= p(x_1)p(x_2|x_1) \cdots p(x_n|x_1, \cdots, x_{n-1}) \\ &= p(x_1)p(x_2|x_1)p(x_3|x_2) \cdots p(x_n|x_{n-1}) \end{aligned}$$

- Examples: binomial counting process, random walk, Poisson process, Wiener process

# Markov process

---

- Chapman-Kolmogorov equation for a Markov process:

$$p(x_3|x_1) = \sum_{x_2} p(x_2|x_1)p(x_3|x_2)$$

proof:

$$\begin{aligned} p(x_3|x_1) &= \sum_{x_2} p(x_2, x_3|x_1) \\ &= \sum_{x_2} p(x_2|x_1)p(x_3|x_1, x_2) \text{ [ch]} \\ &= \sum_{x_2} p(x_2|x_1)p(x_3|x_2) \text{ [Mp]} \end{aligned}$$

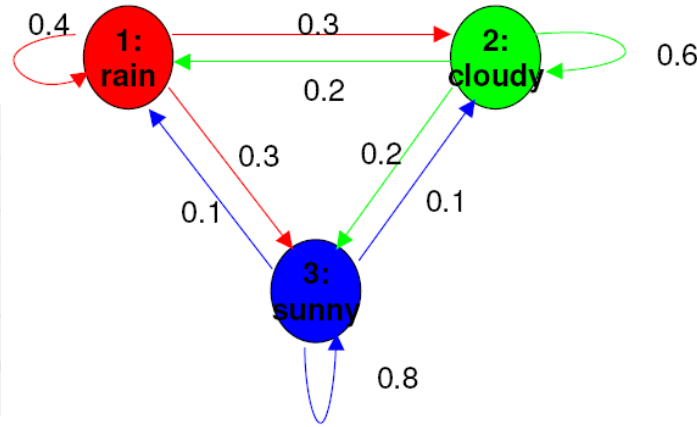
- Generalization

$$p(x_k|x_1) = \sum_{x_2} \cdots \sum_{x_{k-1}} p(x_2|x_1)p(x_3|x_2) \cdots p(x_k|x_{k-1})$$

# Markov process

- State transition matrix

$$P = \begin{bmatrix} p_{11} & p_{12} & \cdots & p_{1N} \\ p_{21} & p_{22} & \cdots & p_{2N} \\ \vdots & \vdots & \ddots & \vdots \\ p_{N1} & p_{NN} & \cdots & p_{NN} \end{bmatrix}$$



- Where

$$p_{ji} = P(X_n = j | X_{n-1} = i) \quad 1 \leq i, j \leq N$$

- With constraints

$$p_{ij} \geq 0, \quad \sum_{j=1}^N p_{ij} = 1$$

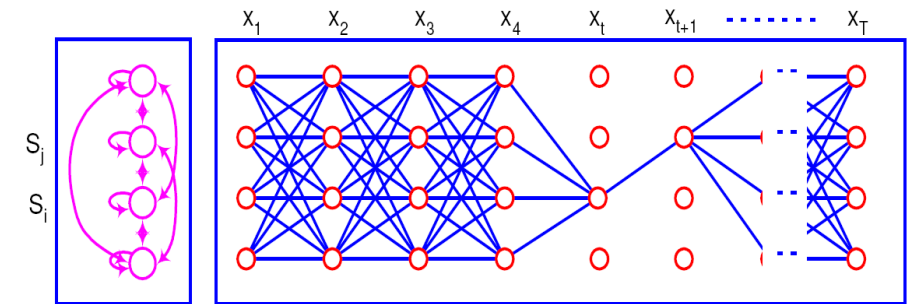
- Initial state probability

$$\pi_i = P(X_1 = i), \quad 1 \leq i \leq N \implies \pi^{(n+1)} = \pi^{(n)} P \quad \text{or} \quad \pi^{(n+1)} = P \pi^{(n)}$$



# Markov process

- transition matrix  $P$ : the matrix whose  $(i, j)$ -th element is  $p_{ij}$ 
  - $\sum_j p_{ij} = 1$
  - $p_{ij}^{(2)} := [P^2]_{ij} = \sum_k p_{ik} p_{kj}$ 
$$= \sum_k P(X_{n+1} = k | X_n = i) P(X_{n+2} = j | X_{n+1} = k)$$
$$= P(X_{n+2} = j | X_n = i): \text{Chapman-Kolmogorov equation}$$
  - $p_{ij}^{(m)} := [P^m]_{ij} = P(X_{n+m} = j | X_n = i)$
  - $p_{ij}^{(n+m)} = \sum_k p_{ik}^{(n)} p_{kj}^{(m)}$ : Chapman-Kolmogorov equation

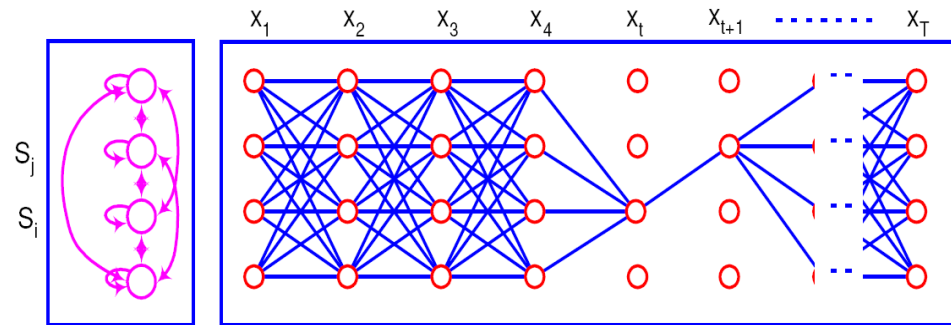


$$p(x_k | x_1) = \sum_{x_2} \cdots \sum_{x_{k-1}} p(x_2 | x_1) p(x_3 | x_2) \cdots p(x_k | x_{k-1})$$

# Markov process

---

5.  $P(X_{n+m} = j) = \sum_i p_{ij}^{(m)} P(X_n = i)$   
 $\Rightarrow p^{(n+m)} = p^{(n)} p^m$ , where  $p^{(n)}$  is the row vector  
whose  $j$ -th element is  $P(X_n = j)$ .  
 $\Rightarrow p^{(n)} = p^{(0)} p^n$



# Markov process

---

- stationary distribution for  $P: \pi^T = (\pi_1, \pi_2, \pi_3, \dots)$  that satisfies  $\pi = \pi P$  and  $\sum_i \pi_i = 1$ .

If  $\pi$  exists for  $P$  of a Markov chain,

$$\lim_{n \rightarrow \infty} P^n = \begin{pmatrix} \pi_1 & \pi_2 & \pi_3 & \cdots \\ \pi_1 & \pi_2 & \pi_3 & \cdots \\ \pi_1 & \pi_2 & \pi_3 & \cdots \\ \vdots & \vdots & \vdots & \ddots \end{pmatrix}$$

$\lim_{n \rightarrow \infty} p^{(n)} = \lim_{n \rightarrow \infty} p^{(0)} P^n = \pi$  regardless of  $p^{(0)}$ .

The Markov Chain is asymptotically stationary.

# Ergodicity

---

- Ergodicity means equality between time averages and statistical averages for wss processes.
- Assume  $X_t$  is wss; consider continuous-time cases.
- Statistical average:  $EX_t = m_X$
- Time average:

$$E_T X_t = \frac{1}{T} \sum_{t=1}^T X_t \text{ or } \frac{1}{T} \int_0^T X_t dt$$
$$E_\infty X_t = \lim_{T \rightarrow \infty} E_T X_t$$

$X_t$  is ergodic in the mean:  $E_\infty X_t = EX_t$

- We can compute the mean by time averaging a sample path.

# Ergodicity

---

- $X_t$  is ergodic in the 2nd moment:  $E_{\infty} X_t^2 = EX_t^2$ 
  - We can compute the 2nd moment by time averaging the square of a sample path.
- $X_t$  is ergodic in the acf:  $E_{\infty} X_{t+\tau} X_t = EX_{t+\tau} X_t \forall \tau$ .
  - We can compute the acf by computing the time-acf of a sample path.
- $X_t$  is ergodic :  $X_t$  is ergodic in all moments.
  - We can compute any moment by time averaging the appropriate function of a sample path.