```
# Make your creature input work
                                                        12 button = Button()
                                                        63 def sense(self):
                                                             if button.sense() == True:
                                                             return True
                                                                         # Effect the output changes
# Connect to the Great Interactive Reef
                                                                         130 motor.update(position1)
20: ecosystem = EcoSystem(ecosystem="reef",
                                                                         131 servo.update(position2)
  creature=creature, connect_to_ecosystem=False)
                                                                 lib/timer.py
   code.py
                      ecosystem.py
                                            creature.py
                                                                                      settings.py
                                                                          # Update your creature name in the reef
                    lib/components/
                                                                          3: "password" : "#########",
                                           behaviours.py
                      wifi_setup.py
                                                                          6: "mqtt_broker_password" : "#########",
                                                                           7: "mqtt_clientid": "team aadjan",
                                           lib/varspeed.py
                    lib/components/
                     mqtt_setup.py
                                                                 # Change the envelope to define behaviour
                                          lib/components/
                                                                 21 if state == self.state_day_somebody:
                                          analog_input.py
                                                                      sequence1 = [(65000, 0.1, 1, "QuadEaseIn")]
                                                                 22
                                                 11111
                                                                 23
                                                                      loops1 = 0
                                          lib/components/
                                                                      sequence2 = [(70, 0.1, 1, "QuadEaseIn"),
                                                                 24
                                             button.py
                                                                 25
                                                                        (110, 0.1, 1, "QuadEaseOut")]
                                                 11111111
                                                                 26
                                                                      loops2 = 0
                                                                 27
                                                                      return (sequence1, loops1, sequence2, loops2)
                                          lib/components/
                                             buzzer.py
                                                lib/components/
                                          electro_magnet.py
                                          lib/components/
                                            neo_pixel.py
                                          lib/components/
                                           servo_motor.py
                                          lib/components/
                                              slider.py
                                          lib/components/
                                               tof.py
                                           lib/components/
                                          vibration_motor.py
```