```
3: "password" : "#########",
                                                                            6: "mqtt_broker_password": "##########,
                                                                            7: "mqtt_clientid": "team aadjan",
20: ecosystem = EcoSystem(ecosystem="reef",
                                                        130 motor.update(position1)
  creature=creature, connect_to_ecosystem=False)
                                                        131 servo.update(position2)
         code.py
                                                  creature.py
                                                                        lib/timer.py
                                                                                             settings.py
                            ecosystem.py
                                                                        21 if state == self.state_day_somebody:
                           lib/components/
                                                                              sequence1 = [(65000, 0.1, 1, "QuadEaseIn")]
                                                  behaviours.py
                            wifi_setup.py
                                                                        23
                                                                              loops1 = 0
                                                                             sequence2 = [(70, 0.1, 1, "QuadEaseIn"),
                                                                        24
                                                                               (110, 0.1, 1, "QuadEaseOut")]
                                                                        25
                                                                        26
                                                                              loops2 = 0
                                                                        27
                                                                              return (sequence1, loops1, sequence2, loops2)
                                                 lib/varspeed.py
                           lib/components/
                            mqtt_setup.py
                                                 lib/components/
                                                 analog_input.py
                                                        111111
                                                 lib/components/
                                                    button.py
                                                        111111111
                                                 lib/components/
                                                    buzzer.py
                                                       lib/components/
                                                electro_magnet.py
                                                 lib/components/
                                                  neo_pixel.py
                                                 lib/components/
                                                 servo_motor.py
                                                 lib/components/
                                                     slider.py
                                                 lib/components/
                                                      tof.py
                                                 lib/components/
                                                 vibration_motor.py
```