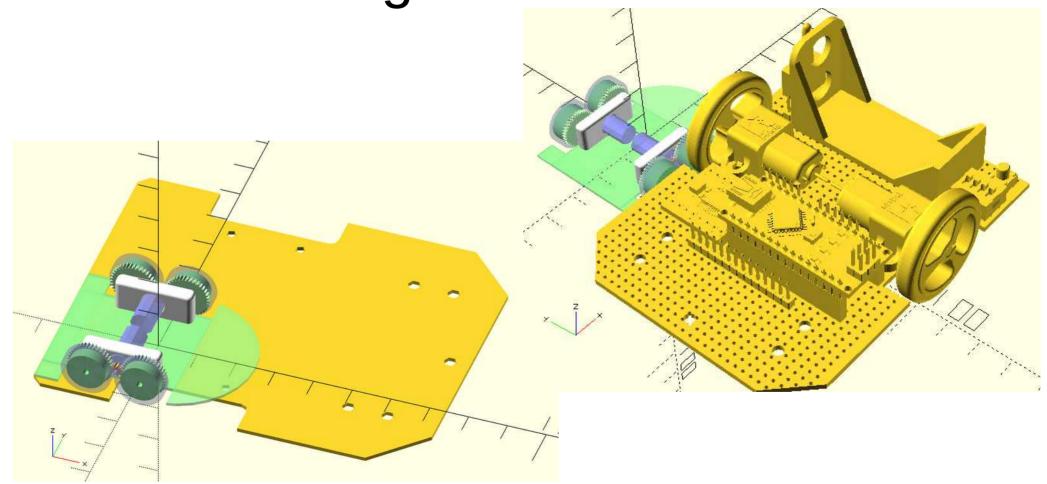
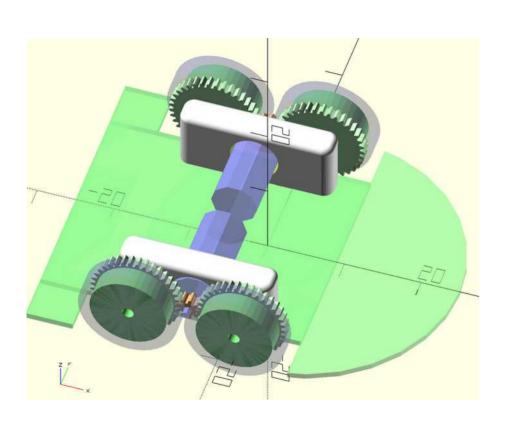


Size against ukmarsbot

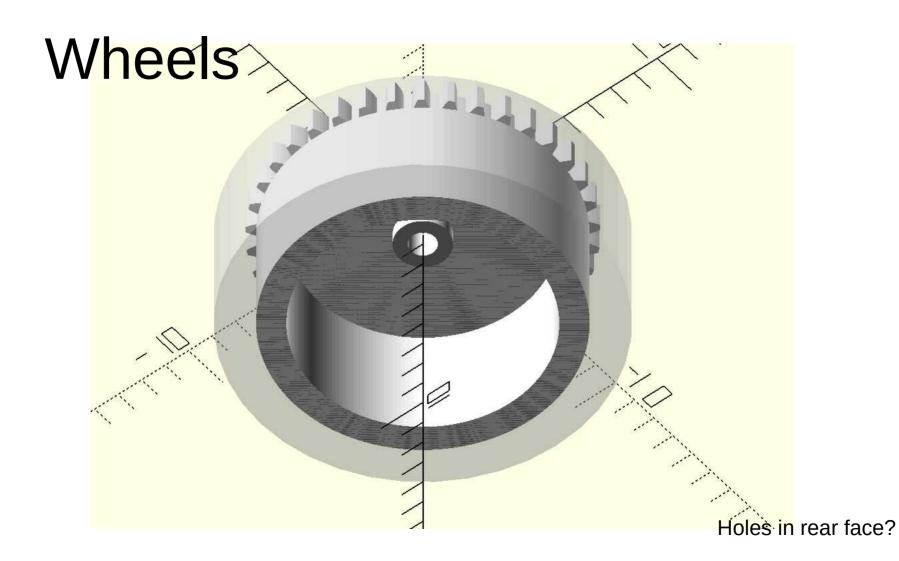


4 wheel concept

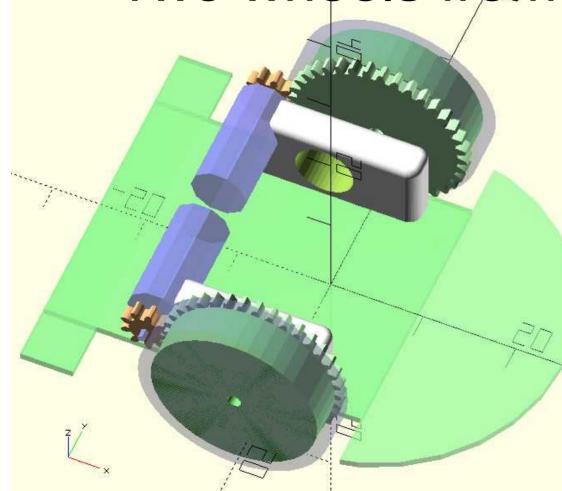


Potential Problems

Wheels need to be 0.3 module – basically custom gears/wheels (supply) ... and tyre availability.



Two wheels from same PCB?



Maybe wheels could be standard 0.5 mod gear attached to wheel?

Potential Problems

Encoder position not the same

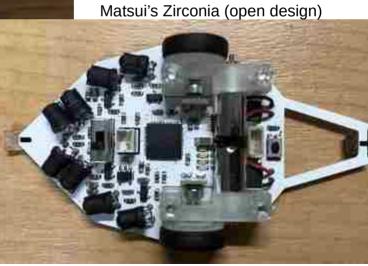
Extra motor keep outs PCB



tennisyi mouse







Matsui's Sapphire