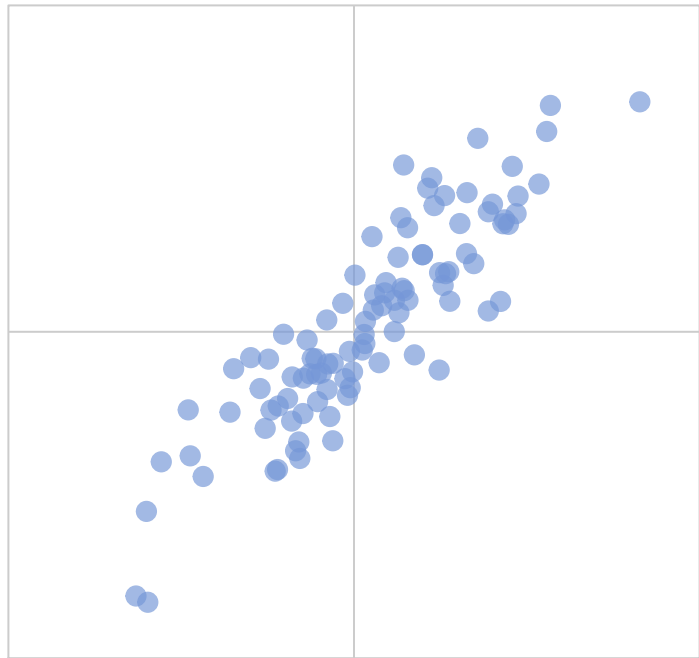


Inertia = 2.02



Inertia = 2