Recorded at time: 13.087 map Broadcaster: /rtabmap/rtabmap Average rate: 20.800 Hz Most recent transform: 13.147 (-0.060 sec old) Buffer length: 1.250 sec odom Broadcaster: /gazebo Average rate: 20.392 Hz Most recent transform: 13.055 (0.032 sec old) Buffer length: 1.275 sec chassis Broadcaster: /chassis_panda Average rate: 10000.000 Hz Most recent transform: 0.000 (13.087 sec old) Buffer length: 0.000 sec panda_link0 Broadcaster: /robot_state_publisher Average rate: 10.833 Hz Most recent transform: 12.989 (0.098 sec old) Buffer length: 1.200 sec panda_link1 Broadcaster: /robot_state_publisher Average rate: 10.833 Hz Most recent transform: 12.989 (0.098 sec old) Buffer length: 1.200 sec panda_link2 Broadcaster: /robot_state_publisher Average rate: 10.833 Hz Most recent transform: 12.989 (0.098 sec old) Buffer length: 1.200 sec panda_link3 Broadcaster: /robot_state_publisher Average rate: 10.833 Hz Most recent transform: 12.989 (0.098 sec old) Buffer length: 1.200 sec panda_link4 Broadcaster: /robot_state_publisher Average rate: 10.833 Hz Most recent transform: 12.989 (0.098 sec old) Buffer length: 1.200 sec panda_link5 Broadcaster: /robot_state_publisher Average rate: 10.833 Hz Most recent transform: 12.989 (0.098 sec old) Buffer length: 1.200 sec panda_link6 Broadcaster: /robot_state_publisher Average rate: 10.833 Hz Most recent transform: 12.989 (0.098 sec old) Buffer length: 1.200 sec panda_link7 Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (13.087 sec old) Buffer length: 0.000 sec panda_link8 Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (13.087 sec old) Buffer length: 0.000 sec panda_hand Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10.833 Hz Average rate: 10.833 Hz Most recent transform: 12.989 (0.098 sec old) Most recent transform: 12.989 (0.098 sec old) Buffer length: 1.200 sec Buffer length: 1.200 sec panda_leftfinger panda_rightfinger

view_frames Result