

# Differential neural ensemble search with diversity control

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# Goals of research

- ▶ Propose a novel method of sampling deep learning models with diversity control
- ▶ Investigate sampled models in terms of diversity and performance
- ▶ Test different ensembles of the sampled models
- ▶ Compare performance with other state-of-the-art methods

## Problem statement

Classic problem of searching for NN ensembles

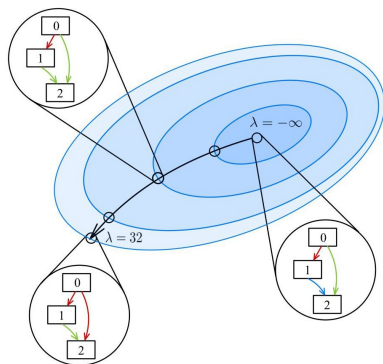
$$\begin{aligned} \min_S \mathcal{L}_{val} \left( \frac{1}{|S|} \sum_{\alpha \in S} f(\mathbf{w}_\alpha^*, \alpha) \right) \\ \text{s.t. } \forall \alpha \in S \quad \mathbf{w}_\alpha^* = \arg \min_{\mathbf{w}} \mathcal{L}_{train}(f(\mathbf{w}_\alpha^*, \alpha)) \end{aligned}$$

Rearranged problem of searching for NN ensembles

$$\begin{aligned} \min_{\alpha} \mathbb{E}_{\lambda \sim U(0, \Lambda)} [\mathcal{L}_{val}(\mathbf{w}^*, \alpha) - C(\lambda - \langle \alpha^*, GS(\alpha) \rangle)^2] \\ \text{s.t. } \mathbf{w}^* = \arg \min_{\mathbf{w}} \mathbb{E}_{\lambda \sim U(0, \Lambda)} [\mathcal{L}_{train}(\mathbf{w}, \alpha)] \end{aligned}$$

where  $\lambda$  is an amount of common edges

# Hypotheses and model



Architectural space

- ▶ Architectural space is continuous
- ▶ Architectures differ in terms of edges
- ▶ The further architecture locates the worse accuracy it performs
- ▶ Diversity and performance are both important for ensembling

# Solution

We sample architectures using hypernetwork, a parametric mapping

$$h : [0, \Lambda] \times \mathbb{R}^u \rightarrow \mathbb{R}^s,$$

where  $\mathbb{R}^u$  is hypernetwork parametric space and  $\mathbb{R}^s$  is architectural space

## Algorithm

**Initialize:**  $N \in \mathbb{N}$ ,  $\mathcal{S} = \emptyset$ , hypernetwork

$\mathcal{S} \leftarrow \{ \alpha^* \}$

▷ Result of NAS

**for**  $i = 1, \dots, N$  **do**

    Sample  $\lambda \sim U(0, \Lambda)$

$\mathcal{S} \leftarrow \mathcal{S} \cup \{ \alpha(\lambda, \alpha^*) \}$

▷  $\alpha$  gained from hypernetwork

**end for**

**Return:**  $\mathcal{S}$  as a resulting ensemble

# Goals of computational experiment

To conduct experiments on CIFAR100 dataset following two main problems

## Comparison of architectures

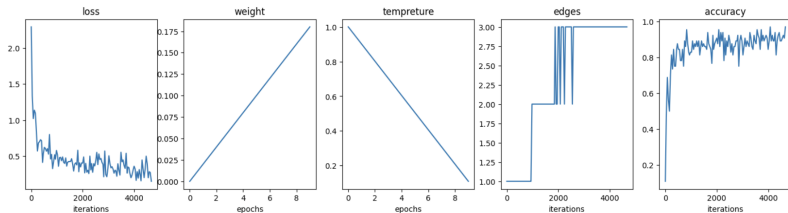
- ▶ Investigate performance of architectures
- ▶ Investigate diversity of architectures

## Ensembling effectiveness investigation

- ▶ Try different ensembles
- ▶ Compare results with DARTS ensembling

# Learning and warming

Weight increases while temperature decreases with iterations, regularizer become strict



Learning process

Experiments show that this trick significantly increases performance

Performance in terms of accuracy			
$\lambda$	Constant weight	Weight warming	Temperature warming
1	0.306	0.400	0.403
2	0.283	0.387	0.310
3	0.265	0.354	0.314



# Conclusion

## Achieved results

- ▶ A novel method of sampling deep learning models architectures with diversity control
- ▶ Base experiments directed to beat baseline
- ▶ Diversity of sampled models was controlled, ensemble shows compatible performance

## Further investigations

- ▶ Hypernetwork implementation, comparison with SOTA results
- ▶ MIPT conference
- ▶ International conference

- ▶ Yao Shu<sup>1</sup>, Yizhou Chen, Zhongxiang Dai, Bryan Kian, Hsiang Low: [Neural Ensemble Search via Bayesian Sampling](#)
- ▶ Hanxiao Liu, Karen Simonyan, Yiming Yang: [DARTS: Differentiable Architecture Search](#)
- ▶ Konstantin Yakovlev, Olga Grebenkova, Oleg Bakhteev, Vadim Strijov: [Neural Architecture Search with Structure Complexity Control](#)
- ▶ Ashwin Raaghav Narayanan, Arber Zela, Tonmoy Saikia, Thomas Brox, Frank Hutter: [Multi-headed Neural Ensemble Search](#)