Undersampled Magnetic Resonance Image Reconstruction

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Undersampled MRI Reconstruction Task

Problem

MRI reconstruction with incomplete information.

Goal

Develop a method which preserves the quality of the Undersampled MRI.

Formal problem statement

- lacktriangledown (M, Y) $\in \mathcal{D}$ Dataset
- ② $\mathbf{M}, \mathbf{Y} \in \mathbb{R}^{k \times k}$, $\mathbf{Y} = \mathcal{F}(\mathbf{M})$ MRI image and its Fourier transformation
- **3** $I: \mathbb{R}^{k \times k} \longrightarrow \mathbb{R}^{k \times k}$ Filter function, which preserves other elements and zeroes other

The goal is to find function $B^*: \mathbb{R}^{k \times k} \longrightarrow \mathbb{R}^{k \times k}$ which minimizes the risk over the image distribution:

$$B^* = argmin_B R(B)$$

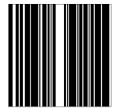
where

$$R(B) = \mathbb{E}_{\mathbf{Y},\mathbf{M}}[L(B(I(\mathbf{Y})),\mathbf{M})]$$

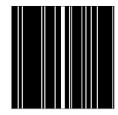
Evaluation functions

- Normalized Mean Square Error: $NMSE(\hat{v}, v) = \frac{||v \hat{v}||_2^2}{||v||_2^2}$
- 2 Peak Signal-to-Noise Ratio: $PSNR(\hat{v}, v) = 10log_{10} \frac{max(v)^2}{MSE(\hat{v}, v)}$
- Structural Similarity Index Metric: $SSIM(\hat{M}, M) = I(\hat{M}, M)^{\alpha} \cdot c(\hat{M}, M)^{\beta} \cdot s(\hat{M}, M)^{\gamma}$

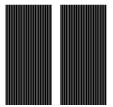
Examples of filters



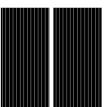
(a) Random mask with 4-fold acceleration



(b) Random mask with 8-fold acceleration



(c) Equispaced mask with 4-fold acceleration



(d) Equispaced mask with 8-fold acceleration

Figure 5: Examples of undersampled k-space trajectories

Taken from Zbonta[1].

Methods

Iterative shrinkage threshold algorithm

$$\mathsf{R}_{i+1} = \mathsf{M}_i - \rho \mathcal{F}^{-1}[I(\mathcal{F}(\mathsf{M}_i)) - I(\mathsf{Y})]$$

$$\mathsf{M}_{i+1} = \mathit{argmin}_{\hat{\mathsf{M}}} \frac{1}{2} ||\hat{\mathsf{M}} - \mathsf{R}_{i+1}||_2^2 + \lambda \mathit{Reg}(\hat{\mathsf{M}})$$

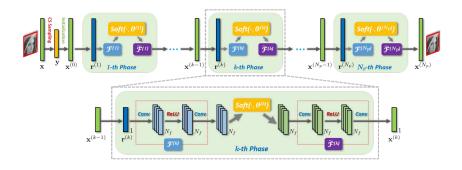
Stops when: $||\mathbf{R}_i|| \leq \epsilon$

- **1** $Reg_{L1}(M) = ||M||_1$

$$\mathsf{M}_{i+1} = \mathsf{W}^{-1} Soft(\mathsf{WR}_{i+1}, \lambda), \ Soft(\mathsf{U}, \lambda) = max(|\mathsf{U}| - \lambda, 0) \frac{\mathsf{U}}{|\mathsf{U}|}$$

3 $Reg_{TV}(M) = \sum_{i,j} \sqrt{|m_{i+1,j} - m_{i,j}|^2 + |m_{i,j+1} - m_{i,j}|^2}$

Methods



Future work

- Development a new method without multisteps
- Proof of its quality
- Tryout different filters I

Bibliography



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