### Minimum Spawning Tree

**DPHPC** 

Th. Cambier R. Dang-Nhu Th. Dardinier C. Trassoudaine

ETH Zürich

October 2018



- Problem definition
  - Concepts
  - Use cases
- 2 Algorithms
  - Prim
  - Kruskal
  - Borůvka (Sollin)
  - Others
- 3 Environment
- 4 Benchmarking
  - Reference, baseline, tools



### Problem definition



### The MST problem



### Concepts



(Somewhat) realistic use-cases and input sets?

- *G*(*n*, *p*)
- Preferential attachment
  - Social networks



rim ruskal orůvka (Sollin) Ithers

# Algorithms



Problem definition Algorithms Environment Benchmarking Prim Kruskal Borůvka (Sollin) Others

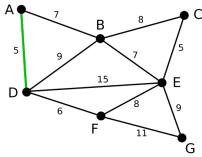
### Prim



- Sort all edges by growing weight.
- For each edge: Add it to the MST if it doesn't create a cycle.

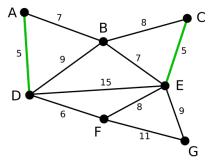


- Sort all edges by growing weight.
- For each edge: Add it to the MST if it doesn't create a cycle.

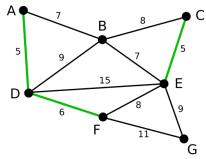




- Sort all edges by growing weight.
- For each edge: Add it to the MST if it doesn't create a cycle.

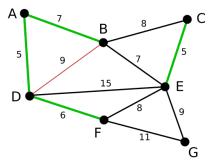


- Sort all edges by growing weight.
- For each edge: Add it to the MST if it doesn't create a cycle.



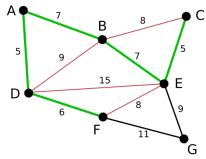


- Sort all edges by growing weight.
- For each edge: Add it to the MST if it doesn't create a cycle.

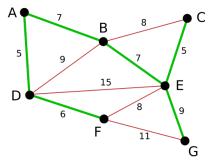




- Sort all edges by growing weight.
- For each edge: Add it to the MST if it doesn't create a cycle.



- Sort all edges by growing weight.
- For each edge: Add it to the MST if it doesn't create a cycle.





#### Data structure: Union-find

Represents the connected components of the graph given our MST. Implementation with an array *parent* and 3 operations:

- Create: Every vertex is in its own component



### Data structure: Union-find

Represents the connected components of the graph given our MST. Implementation with an array *parent* and 3 operations:

- Create: Every vertex is in its own component
- Find(x): Find the component of this vertex.
  - ① If  $parent[x] \neq x$ , then parent[x] = find(parent[x])
  - ② Return parent[x].



### Data structure: Union-find

Represents the connected components of the graph given our MST. Implementation with an array *parent* and 3 operations:

- Create: Every vertex is in its own component
  - parent[x] = x.
- Find(x): Find the component of this vertex.
  - ① If  $parent[x] \neq x$ , then parent[x] = find(parent[x])
  - 2 Return parent[x].
- Union(x, y): Unite two components.
  - parent[find(x)] = find(y).



### Sequential and parallel Kruskal

#### Sequential complexity:

- $O(E \log E)$ : Sort all edges by growing weight.
- O(E) (in practice): For each edge: Add it to the MST if it doesn't create a cycle.

We can parallelize the sort on  $O(\log E)$  processors: O(E) (in practice).



# A better parallel approach: Filter-Kruskal



# Borůvka (Sollin)



### A few ideas



#### Correctness

How to verify correctness of the parallelization?



Problem definition Algorithms Environment Benchmarking

### **Environment**



### Architecture



#### **EULER Cluster**

Xeon  $Ex, x \in \{3, 5, 7\}$ x86\_64 architecture

Source: https://scicomp.ethz.ch/wiki/Euler



#### Tools



- CMake v3.3+
- C++11 GCC v4.9.2+
- OpenMPI (shared memory) v1.6.5+



# Benchmarking



#### **Tools**

- Measures : LibSciBench library
- Interpretation :
  - LibSciBench's R scripts
  - (Custom python scripts)

Ref: https://spcl.inf.ethz.ch/Research/Performance/LibLSB/

#### **Baseline**



Borůvka's serial algorithm  $O(E \cdot log(V))$ 

https://en.wikipedia.org/wiki/Otakar\_Bor%C5%AFvka

