

Test Bench Measurement

Motor type: **HP 875-50-A8 S P30**

Date: 17.02.2021

Bearing type: RS

Controller: MST 400-133

Measuring Parameter

Voltage: **290.0 [V]**

Throttle setting: 100%

Calculated Motor Constants

nl: 9,060.4 [RPM] lo: 3.5 [A] kV: 31.7 [RPM/V] kn: -39.69 [RPM/A] kT: 36.60 [Ncm/A]

Voltage [V]	Current [A]	Speed [RPM]	Input Power [W]	Output Power [W]	Torque [Ncm]	Efficiency ¹ [%]
290.2	5.0	9,132.7	1,451.0	941.1	98.4	64.86
290.2	6.0	9,075.0	1,741.2	1,226.9	129.1	70.46
290.2	7.0	9,018.3	2,031.4	1,512.0	160.1	74.43
290.2	8.0	8,962.4	2,321.6	1,797.3	191.5	77.42
290.2	9.0	8,907.4	2,611.8	2,081.0	223.1	79.68
290.2	10.0	8,853.3	2,902.0	2,365.1	255.1	81.50
290.2	11.0	8,800.0	3,192.2	2,648.5	287.4	82.97
290.2	12.0	8,747.5	3,482.4	2,931.3	320.0	84.18
290.2	13.0	8,696.0	3,772.6	3,213.7	352.9	85.18
290.2	14.0	8,645.2	4,062.8	3,495.5	386.1	86.04
290.1	15.0	8,595.2	4,351.5	3,775.9	419.5	86.77
290.1	16.0	8,546.1	4,641.6	4,056.8	453.3	87.40
290.1	17.0	8,497.8	4,931.7	4,336.4	487.3	87.93
290.1	18.0	8,450.2	5,221.8	4,615.7	521.6	88.39
290.1	19.0	8,403.5	5,511.9	4,893.7	556.1	88.79
290.1	20.0	8,357.5	5,802.0	5,171.5	590.9	89.13
290.1	21.0	8,312.3	6,092.1	5,448.2	625.9	89.43
290.1	22.0	8,267.8	6,382.2	5,724.7	661.2	89.70
290.1	23.0	8,224.1	6,672.3	6,001.0	696.8	89.94
290.1	24.0	8,181.1	6,962.4	6,275.5	732.5	90.13
290.1	25.0	8,138.8	7,252.5	6,549.9	768.5	90.31
290.1	26.0	8,097.3	7,542.6	6,824.3	804.8	90.48
290.1	27.0	8,056.5	7,832.7	7,097.0	841.2	90.61
290.1	28.0	8,016.3	8,122.8	7,368.8	877.8	90.72
290.1	29.0	7,976.9	8,412.9	7,640.8	914.7	90.82
290.1	30.0	7,938.2	8,703.0	7,911.4	951.7	90.90

Voltage [V]	Current [A]	Speed [RPM]	Input Power [W]	Output Power [W]	Torque [Ncm]	Efficiency ¹ [%]
290.0	32.0	7,862.7	9,280.0	8,451.2	1,026.4	91.07
290.0	33.0	7,825.9	9,570.0	8,719.8	1,064.0	91.12
290.0	34.0	7,789.8	9,860.0	8,987.9	1,101.8	91.16
290.0	35.0	7,754.3	10,150.0	9,255.5	1,139.8	91.19
290.0	36.0	7,719.4	10,440.0	9,521.8	1,177.9	91.21
290.0	37.0	7,685.2	10,730.0	9,787.9	1,216.2	91.22
290.0	38.0	7,651.6	11,020.0	10,053.6	1,254.7	91.23
290.0	39.0	7,618.5	11,310.0	10,318.0	1,293.3	91.23
290.0	40.0	7,586.1	11,600.0	10,581.6	1,332.0	91.22
290.0	41.0	7,554.3	11,890.0	10,845.0	1,370.9	91.21
290.0	42.0	7,523.0	12,180.0	11,107.3	1,409.9	91.19
290.0	43.0	7,492.2	12,470.0	11,369.4	1,449.1	91.17
290.0	44.0	7,462.1	12,760.0	11,630.0	1,488.3	91.14
290.0	45.0	7,432.5	13,050.0	11,890.5	1,527.7	91.12
290.0	46.0	7,403.4	13,340.0	12,150.2	1,567.2	91.08
290.0	47.0	7,374.8	13,630.0	12,409.1	1,606.8	91.04
289.9	48.0	7,346.8	13,915.2	12,667.4	1,646.5	91.03
289.9	49.0	7,319.2	14,205.1	12,924.9	1,686.3	90.99
289.9	50.0	7,292.2	14,495.0	13,181.9	1,726.2	90.94
289.9	51.0	7,265.7	14,784.9	13,437.6	1,766.1	90.89
289.9	52.0	7,239.6	15,074.8	13,693.3	1,806.2	90.84
289.9	53.0	7,214.0	15,364.7	13,947.8	1,846.3	90.78
289.9	54.0	7,188.9	15,654.6	14,201.9	1,886.5	90.72
289.9	55.0	7,164.2	15,944.5	14,454.7	1,926.7	90.66
289.9	56.0	7,140.0	16,234.4	14,707.2	1,967.0	90.59
289.9	57.0	7,116.2	16,524.3	14,958.5	2,007.3	90.52
289.9	58.0	7,092.8	16,814.2	15,209.4	2,047.7	90.46
289.9	59.0	7,069.8	17,104.1	15,459.2	2,088.1	90.38
289.9	60.0	7,047.3	17,394.0	15,708.9	2,128.6	90.31
289.9	61.0	7,025.1	17,683.9	15,957.3	2,169.1	90.24
289.9	62.0	7,003.4	17,973.8	16,205.1	2,209.6	90.16
289.9	63.0	6,982.0	18,263.7	16,451.7	2,250.1	90.08
289.8	64.0	6,961.0	18,547.2	16,697.4	2,290.6	90.03
289.8	65.0	6,940.3	18,837.0	16,942.1	2,331.1	89.94
289.8	66.0	6,920.0	19,126.8	17,186.8	2,371.7	89.86
289.8	67.0	6,900.1	19,416.6	17,430.0	2,412.2	89.77
289.8	68.0	6,880.5	19,706.4	17,672.3	2,452.7	89.68
289.8	69.0	6,861.2	19,996.2	17,913.7	2,493.2	89.59
289.8	70.0	6,842.2	20,286.0	18,154.3	2,533.7	89.49

Voltage	Current	Speed	Input Power	Output Power	Torque	Efficiency ¹
[V]	[A]	[RPM]	[W]	[W]	[Ncm]	[%]
289.8	72.0	6,805.1	20,865.6	18,631.7	2,614.5	89.29
289.8	73.0	6,787.1	21,155.4	18,869.5	2,654.9	89.19
289.8	74.0	6,769.2	21,445.2	19,105.4	2,695.2	89.09
289.8	75.0	6,751.7	21,735.0	19,341.0	2,735.5	88.99

nl = rpm with no load

lo = current with no load

kV = specific rpm

kn = rpm drop per Amp

kT = torque constant

¹ incl. Controller