# Inversion of the spherical Radon transform by means of Gabor and Wavelet frames with applications in diffraction tomography

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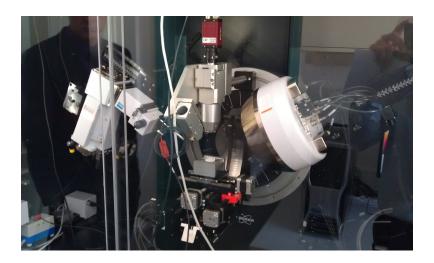
- Preliminaries
- Motivation: Problem of texture analysis
- 3 Spherical frame expansion
- Inversion of X-ray transform

Preliminaries

Motivation: Problem of texture analysis

Spherical frame expansion

## Diffraction tomography



- Polycrystalline specimen carries crystal grains with orientation within a given range G\* of all feasible orientations G ⊂ SO(3);
- Density of orientation function f: for given  $g \in SO(3)$ , we have  $\frac{\Delta V_g}{V} \to f(g)dg$ ;
- Pole figure  $P_x(y)$ : a correspondence of a fixed crystal direction x with a test direction y, that is,  $\frac{\Delta V_g}{V} \to P_x(y) dy$  for g(x) = y;

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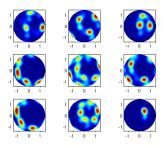
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## Pole figures example



These pole figures correspond to nine fixed crystal directions  $x \in S^2$  and all test directions  $y \in S^2_+$ ;

Polar density function  $\mathcal{P}f: \mathbb{S}^2 \times \mathbb{S}^2 \to \mathbb{R}^+$ , where  $\mathcal{P}f(x,y)$  denotes the probability that a given crystal direction x or its symmetric -x coincide with a specific direction y.

Therefore,

$$\mathcal{P}f(x,y) = \frac{1}{2} \left( \mathcal{R}f(-x,y) + \mathcal{R}f(x,y) \right),$$

where Rf denotes the spherical X-ray transform

$$\mathcal{R}f(x,y)=\frac{1}{2\pi}\int_{\mathcal{G}_{xy}}f(g)dg, \ \ \text{and} \ \mathcal{G}_{xy}=\{g\in SO(3):g(x)=y\}.$$

Polar density function  $\mathcal{P}f: \mathbb{S}^2 \times \mathbb{S}^2 \to \mathbb{R}^+$ , where  $\mathcal{P}f(x,y)$  denotes the probability that a given crystal direction x or its symmetric -x coincide with a specific direction y.

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## Motivation: Spherical X-Ray transform

An integral transform  $\mathcal{R}: L_2(\textit{Spin}(3)) \mapsto L_2(\textit{S}^2 \times \textit{S}^2)$  such that

$$\mathcal{R}f(x,y) = \frac{1}{2\pi} \int_{g \in Spin(3): y = g(x)} f(g) dg$$
$$= 4\pi \int_{Spin(3)} f(g) \delta_y(g(x)) dg$$
$$= 4\pi \int_{C(x,y)} f(q) dq,$$

where  $C(x,y)=\{q\in S^3\sim \mathbb{H}: qx\overline{q}=y\}$  is a great circle in  $S^3\sim \mathbb{H}$ .

## **Properties**

- $\mathcal{R}f$  satisfies the ultra-hyperbolic equation  $(\Delta_x \Delta_y)\mathcal{R}f = 0$
- Regularity:  $\mathcal{R}: L_2(Spin(3)) \mapsto H^{1/2}(S^2 \times S^2) \cap \ker(\Delta_x \Delta_y)$  and  $||f||_{H^{1/2}(S^2 \times S^2)} := ||(-2\Delta_{S^2 \times S^2} + 1)^{1/4}f||_{L_2(S^2 \times S^2)}$
- $\mathcal{R}$  is an isometry:  $||\mathcal{R}f||_{H^{1/2}(S^2 \times S^2)} = 16\pi^2 ||f||_{L_2(Spin(3))}$
- Inversion formula:  $f(g) = \frac{1}{4\pi} \int_{S^2} (-2\Delta_{S^2 \times S^2} + 1)^{1/2} \mathcal{R} f(x, gx) dx$
- For more details see also works of V. Palamodov, S. Helgason, and others

- Given the map  $R: L_2(Spin(3)) \mapsto L_2(S^2 \times S^2)$  and data y = Rf how retrieve f?
- Questions:
  - how to expand f? Spherical frame expansion
  - how to compute/approximate  $R^{-1}$ ? Iterative Approach
  - how to treat noisy data  $y_{\delta}, |y-y_{\delta}| \leq \delta$ ? Regularization

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#### What is a frame?

#### Frame definition

We call a system  $\{\psi_i\}_{i\in I}$  a frame for X if for all  $f\in X$  there exists constants A,B>0 such that

$$\frac{1}{A}||f||^2 \le \sum_{i \in I}|< f, \psi_i > |^2 \le \frac{1}{B}||f||^2$$

#### **Dual frame**

Given a frame  $\{\psi_i\}_{i\in I}$  there exists a dual frame  $\{\psi_i^*\}_{i\in I}$  such that for all  $f\in X$  one has

$$f = \sum_{i \in I} \langle f, \psi_i^* \rangle \psi_i.$$

### How we can work with frames?

•  $\{\psi_i : x_i \in X_i\}$  has a dual frame, i.e.

$$f = \sum < f, \tilde{\psi}_i > \psi_i$$

- In practical terms: Given  $(< f, \psi_i >)$  how to calculate  $(< f, \tilde{\psi}_i >)$ ?
- Frame operator  $F : f \mapsto (\langle f, \psi_i \rangle) = (c_i)$
- Adjoint operator  $F^*: (c_i) \mapsto \sum \psi_i c_i$
- Given system  $F^*c = f$



## Gabor frames - Concept in $\mathbb{R}^n$

- signal  $f \in L_2(\mathbb{R}^n)$
- windowed Fourier transform:

$$V_{\psi}f(\omega,b) = \int_{\mathbb{R}^n} f(x)\psi(x-b)e^{i<\omega,x>}dx$$

group-based interpretation:

$$\pi: G = \mathbb{R}^n \times \mathbb{R}^n \mapsto \mathcal{U}(L_2(\mathbb{R}^{\ltimes})) \text{ via } \pi(\omega, b) \psi(x) = e^{i < \omega, x >} \psi(x - b)$$
$$V_{\psi} f(\omega, b) = \int_{\mathbb{R}^n} f(x) \pi(\omega, b) \psi(x) dx$$

## Gabor frames - Concept in S<sup>3</sup>

- signal  $f \in L_2(S^3)$
- proper windowed Fourier transform:

translations and modulations on the sphere  $G := E(4) = Spin(4) \ltimes \mathbb{R}^4$ 

• Representation of G in  $L_2(S^3)$ :

$$\pi(s,p)f(q) = f(\overline{s}qs)e^{i\langle p,q\rangle}$$

windowed Fourier transform:

$$V_{\psi}f(s,
ho)=\int_{S^3}f(q)\psi(\overline{s}qs)e^{i\langle
ho,q
angle}dS_q$$



## Gabor frames - Concept in S<sup>3</sup>

Problem: representation is not square-integrable, i.e.

$$\|V_{\psi}f\|_{L_2(G)}$$
 is not finite

- group is too "large"
- therefore choose some closed subgroup H and consider X = G/H with G-invariant measure  $d\mu(x)$
- example:  $H = \{(0,0,0,p_4) \in G, p_4 \in \mathbb{R}\}$
- consider instead for  $(s, p) \in X$ ,

$$V_{\psi}f(s,p)=< f,\pi(\sigma(s,p)^{-1})\psi>$$

Admissibility condition:

$$\int_{X} |\langle f, \pi(\sigma(s, p)^{-1})\psi \rangle|^{2} d\mu(x) = \langle A_{\sigma}^{\psi} f, f \rangle \quad \forall f \in L_{2}(S^{3})$$



## Spherical Gabor transform

#### Lemma (admissibility and isometry)

Assume that the window  $\psi \in L_1(S^3) \cap L_2(S^3)$  is such that  $supp(\psi) \subseteq S^3_+$ 

$$0 \neq C_{\psi} = 64\pi^{5} \int_{0}^{2\pi} \int_{0}^{\pi} \int_{0}^{\pi/2} \frac{|\psi(q(\theta, \alpha, \phi))|^{2}}{\cos \phi} d\phi \, d\alpha \, d\theta < \infty.$$
 (1)

Then the map

$$f \in L^2(S^3) \mapsto rac{1}{\sqrt{C_\psi}} V_\psi f \in L^2(Spin(4) imes \mathbb{R}^3)$$

is an isometry, i.e.

$$\int_{Spin(4) imes\mathbb{R}^3} |V_\psi f(s,p)|^2\,d\mu(s)\,dp = C_\psi \int_{S^3} |f(q)|^2 dS_q.$$

15/42 U. Kähler Soherical frames

## Spherical Gabor transform

#### Corollary (reconstruction)

Any  $f \in L^2(S^3)$  can be reconstructed by

$$f(q) = \frac{1}{C_{\psi}} \int_{\mathrm{Spin}(4)} \int_{\mathbb{R}^3} V_{\psi} f(s,p) e^{-i\langle \overline{s} \rho s, q \rangle} \psi(sq\overline{s}) \, dp \, d\mu(s).$$

#### No discrete expansion formula

Possible choice of window function:

$$\psi(q) = \cos^{\eta}(\alpha \arccos(q_0))\chi_{\left[\frac{\pi}{6}, \frac{\pi}{2}\right]}(q_0)$$

Dual window is given approximately by finite linear combination of "shifted" windows



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## Continuous Wavelet transform - Concept in ${\mathbb R}$

Wavelet:

$$\psi_{a,b}(x) = \pi(a,b)\psi(x) = \frac{1}{\sqrt{a}}\psi\left(\frac{x-b}{a}\right),$$

with  $(a, b) \in \mathbb{R} \setminus \{0\} \times \mathbb{R}$ 

$$\pi(\mathbf{a}_1,\mathbf{b}_1)\pi(\mathbf{a}_2,\mathbf{b}_2)\psi=\pi(\mathbf{a},\mathbf{b})\psi$$

with 
$$(a, b) = (a_1 a_2, a_1 b_2 + b_1)$$

Wavelet transform

$$V_{\psi}f(a,b) = \int_{\mathbb{R}} \pi(a,b)\psi(x)f(x)dx$$



## Extensions to the sphere

- Many constructions based on approximate identities
- Diffusive wavelets using the heat kernel by S. Ebert (PhD thesis 2011)
- Using the Iwasawa decomposition of SO(n+1,1) by Antoine, Vandergheynst 1998
- Using the Cartan decomposition of Spin(n+1,1) by M. Ferreira 2005

## Conformal group of the ball

- Lorentz group Spin(1, n) conformal group of the ball.
- Cartan decomposition  $Spin(1, n) = Spin(n) \times Spin(1, 1) \times Spin(n)$ .
- For n ≥ 3 representations are not square-integrable ⇒ need to factorize
- $Spin(n) \times Spin(1,1) \Rightarrow Wavelet analysis$
- $Spin(1,1) \times Spin(n) \Rightarrow$  function theory in the unit ball
- Spin(1,1)×Spin(n) "group of Möbius transformations" does NOT form a group ⇒ representation theory for gyrogroups - M. Ferreira 2007

## Gyrogroup

#### Definition

A groupoid  $(G, \oplus)$  is a gyrogroup if its binary operation satisfies the following axioms:

- There is at least one element 0 satisfying  $0 \oplus a = a$ , for all  $a \in G$ ;
- ② For each  $a \in G$  there is an element  $\ominus a \in G$  such that  $\ominus a \oplus a = 0$ ;
- **③** For any  $a, b, c \in G$  there exists a unique element  $gyr[a, b]c \in G$  such that the binary operation satisfies the left gyroassociative law  $a \oplus (b \oplus c) = (a \oplus b) \oplus gyr[a, b]c$ ;
- **③** The map  $gyr[a, b] : G \to G$  given by  $c \to gyrc$  is an automorphism of the groupoid  $(G, \oplus)$ , that is  $gyr[a, b] \in Aut(G, \oplus)$ ;
- The gyroautomorphism gyr[a, b] possesses the left loop property

$$gyr[a, b] = gyr[a \oplus b, b]$$

## Spherical Wavelet Transform

Consider the Möbius transformations:

$$\varphi_a(x) = (a-x)(1-\bar{a}x)^{-1}, |a| < 1$$

•

Representation:

$$\pi_1(s, a_\phi)\psi(x) = \left(\frac{1 - |a_\phi|^2}{|1 - a_\phi \overline{s} x s|^2}\right)^{\frac{n-1}{2}} \psi(\varphi_{-a_\phi}(\overline{s} x s))$$

$$V_{\psi}: L_2(S^{n-1}) \rightarrow L_2(G)$$

$$v_{\psi}I(s, a_{\phi}) = \langle \pi_{1}(\underline{s}, \underline{a_{\phi}})\psi, I \rangle$$

$$= \int_{S^{n-1}} \frac{1 - |a_{\phi}|^{2}}{|1 - a_{\phi}\overline{s}xs|^{2}} \psi(\varphi_{-a_{\phi}}(\overline{s}xs)) f(x) dS(x)$$



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## Spherical Wavelet transform

#### Lemma (admissibility)

Assume that the Fourier coefficients of  $\psi \in L_2(S^3)$  satisfy

$$\frac{1}{N(n,l)} \sum_{M=1}^{N(n,l)} \int_{-1}^{1} |\hat{\psi}_{\sigma(te_n)}|^2 d\mu(te_n) < \infty$$
 (2)

uniformly in I then the map

$$f \in L^2(S^3) \mapsto W_{\psi}f \in L^2(Spin(4) \times Spin(1,1))$$

is an invertible operator, i.e.

$$\int_{\mathit{Spin}(4)\times\mathit{Spin}(1,1)} |W_{\psi}f(s,p)|^2\,d\mu(s)\,dp = \int_{S^3} \overline{(A_{\sigma}^{\psi}f)(q)}f(q)dS_q.$$



## Spherical Wavelet transform

#### Corollary (reconstruction)

Any  $f \in L^2(S^3)$  can be reconstructed by

$$f(q) = \int_{-1}^{1} \int_{\mathrm{Spin}(4)} W_{\psi} f(s, \sigma(te_n)) \left[ R_s(A_{\sigma}^{\psi})^{-1} D_{\sigma(te_n)} \psi \right] (q) d\mu(s) d\mu(te_n).$$

#### No discrete expansion formula

Admissible wavelets using Cayley transform:

$$g: H_4 \to S^3, g(x) = (x + e_4)(1 + e_4 x)^{-1}$$



## Spherical Wavelet transform

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## Frames via coorbit space theory

#### Correspondence principle

Let  $\pi$  be a square integrable representation of the Euclidean group  $Spin(4) \ltimes \mathbb{R}^4 \mod (H, \sigma)$  with an admissible pair  $(\psi, \sigma)$ . Then  $V_{\psi}$  is a bijection of  $L_2(S^3)$  onto the RKHS  $\mathcal{M}_2$ 

$$\mathcal{M}_2 = \{F \in L_2(X) : \langle R(g,\cdot), F \rangle = F(g) \}$$
 where

$$R(g,I) := \langle \psi, \pi(\sigma(h)\sigma(I)^{-1})\psi \rangle = V_{\psi}(\pi(\sigma(I)^{-1})\psi)(h)$$

#### Two classic assumptions:

- Representation is irreducible
- **3** Coorbit space  $Co(Y) = \{T \in S' | V_{\psi}T \in Y\}$

# Gabor Frames via coorbit space theory

- Choose  $\mathcal{U}$ -dense and relatively separated family  $\{x_i\}_{i\in I}\subset X$
- Define the oscillation kernel

$$\operatorname{osc}_{\mathcal{U}}(\mathit{I},\mathit{h}) := \sup_{\mathit{u} \in \mathcal{U}} |\langle \psi, \pi(\sigma(\mathit{I})\sigma(\mathit{h})^{-1})\psi - \pi(\mathit{u}^{-1}\sigma(\mathit{I})\sigma(\mathit{h})^{-1})\psi \rangle_{\mathit{L}_{2}(S^{3})}|$$

Estimate

$$\leq \sup_{u \in \mathcal{U}} \left| \int_{S_{+}^{3}} e^{i\langle q, p - s_{1}\overline{s_{2}}rs_{2}\overline{s_{1}}\rangle} \left( \psi(s_{2}\overline{s_{1}}qs_{1}\overline{s_{2}}) - \psi(s_{2}\overline{s_{1}}s_{u}q\overline{s_{u}}s_{1}\overline{s_{2}}) \right) \overline{\psi}(q) dS_{q} \right|$$

$$+ \sup_{u \in \mathcal{U}} \left| \int_{S_{+}^{3}} e^{i\langle q, p - s_{1}\overline{s_{2}}rs_{2}\overline{s_{1}}\rangle} \left( 1 - e^{i\langle q, s_{1}\overline{s_{2}}p_{u}s_{2}\overline{s_{1}}\rangle} \right) \psi(s_{2}\overline{s_{1}}s_{u}q\overline{s_{u}}s_{1}\overline{s_{2}}) \overline{\psi}(q) dS_{q} \right|$$

#### Gabor Frames

#### Theorem (frames)

Assume

$$\int_X \operatorname{osc}_{\mathcal{U}}(I,h) d\mu(I) < \frac{\eta}{C_\psi} \quad \text{and} \quad \int_X \operatorname{osc}_{\mathcal{U}}(I,h) d\mu(h) < \frac{\eta}{C_\psi} \qquad (3)$$

with  $\eta <$  1. Then the set  $\{\psi_i := \pi(\sigma(x_i))\psi : i \in I\}$  is a frame for  $L_2(S^3)$ . This means that

- 2 there exists constants  $0 < A < B < \infty$  such that

$$A \| f \|_{L_2(S^3)} \le \| \{ \langle f, \psi_i \rangle \}_{i \in I} \|_{\ell_2} \le B \| f \|_{L_2(S^3)},$$

• there exists a bounded, linear synthesis operator  $S: \ell_2 \to L_2(S^3)$  such that  $S(\{\langle f, \psi_i \rangle\}_{i \in I}) = f$ .

# Difference with case of spherical wavelets

$$R(t, s, t', s') = \int_{\mathbb{S}^3} \left[ \left( \frac{1 - \alpha^2}{|1 - \alpha e_n \bar{s'} s x \bar{s} s'|^2} \right)^{\frac{n-1}{2}} \psi(\varphi_{-\alpha e_n}(\bar{s'} s x \bar{s} s')) \overline{\psi(x)}) \right] dS_x$$

- L<sub>1</sub>-integrability is difficult to achieve
- Way out: Use  $T = \bigcap_{p>1} L_p$  as target space (S. Dahlke, et al., JFAA, 2016)
- $T = \bigcap_{p>1} L_p$  is still closed under convolution!



# Frames via coorbit space theory

- Choose *U*-dense and relatively separated family {x<sub>i</sub>}<sub>i∈I</sub> ⊂ X
- Define the oscillation kernel

$$\operatorname{osc}_{\mathcal{U}}(I,h) := \sup_{u \in \mathcal{U}} |\langle \psi, \pi(\sigma(I)\sigma(h)^{-1})\psi - \pi(u^{-1}\sigma(I)\sigma(h)^{-1})\psi \rangle_{L_2(S^3)}|^p$$

 Estimate the decay of the Fourier coefficients of the oscillation kernel

#### **Wavelet Frames**

#### Theorem (frames)

Assume

$$\int_X \operatorname{osc}_{\mathcal{U}}(I,h) d\mu(I) < \frac{\eta}{C_\psi} \quad \text{and} \quad \int_X \operatorname{osc}_{\mathcal{U}}(I,h) d\mu(h) < \frac{\eta}{C_\psi} \qquad \text{(4)}$$

with  $\eta <$  1. Then the set  $\{\psi_i := \pi(\sigma(x_i))\psi : i \in I\}$  is a frame for  $L_2(S^3)$ . This means that

- 2 there exists constants  $0 < A < B < \infty$  such that

$$A\|f\|_{L_2(S^3)} \le \|\{\langle f, \psi_i \rangle\}_{i \in I}\|_{\ell_2} \le B\|f\|_{L_2(S^3)}$$
,

**1** there exists a bounded, linear synthesis operator  $S: \ell_2 \to L_2(S^3)$  such that  $S(\{\langle f, \psi_i \rangle\}_{i \in I}) = f$ .

### Construction of wavelet frame

- Dilation discretization via a hyperbolic lattice for  $te_3, t \in [-1, 1]$
- Lattice for Spin(4) via a subdivision scheme (G. Nawratil, H. Pottmann, 2007) → quasi-uniform distribution
- Consider the function

$$h(x) = \begin{cases} \cos(2\pi f(2x)) & \frac{1}{8} \le |x| \le \frac{1}{4} \\ \sin(2\pi f(x)) & \frac{1}{4} \le |x| \le \frac{1}{2} \\ 0 & \end{cases}$$

with 
$$f_{\epsilon}(x) = \frac{\lambda(\epsilon(\frac{1}{2}-x))}{4(\lambda(\epsilon(x-\frac{1}{4})+\lambda(\epsilon(\frac{1}{2}-x))))}$$
,  $\lambda(x) = e^{-|x|^2}$ .



# Inversion of X-ray transform

- R is an integral transfrom → Rf belongs to smoothness space
- only noisy data  $y^{\delta}$  available:  $Rf + \epsilon = y^{\delta} \in L_2(S^3 \times S^3)$  with  $|y y^{\delta}| \le \delta$
- Assume f has a sparse expansion within  $\{\psi_i\}_{i\in I}$

$$f(p) = Fc(p) = \sum_{i \in J \subset I, |J| \text{ small}} c_i \psi_i(p)$$

# Inversion of X-ray transform

Optimization problem:

$$\min_{c \in B_R} ||y^\delta - R(Fc)||^2$$

with 
$$B_K = \{c \in I_2(I) : ||c||_{I_1(I) \le K}\}$$

Minimization through projected steepest descent with step length control

$$c_i^{n+1} = P_K \left( c_i^n + \frac{\beta_n}{r} (F^* R^* (y - R(F c_i^n))) \right)$$

Given	operator $R$ , some initial guess $c^0$ , and $K$ (sparsity constraint $\ell_1$ -ball $B_K$ )
Initialization	$\ RF^*\ ^2 \leq r,$ set $q=0.9$ (as an example)
Iteration	for $n = 0, 1, 2,$ 1. $\beta^n = C \cdot \sqrt{\frac{D(x^0)}{D(x^n)}}, C \ge 1$ (greedy guess)  2. $c^{n+1} = P_K \left( c^n + \frac{\beta^n}{r} F R^* (y - R(F^*(c^n))) \right);$ 3. verify (B2): $\beta^n \  R(F^* c^{n+1}) - R(F^* c^n) \ ^2 \le r \  c^{n+1} - c^n \ ^2$ if (B2) is satisfied increase $n$ and go to 1.  otherwise set $\beta^n = q \cdot \beta^n$ and go to 2. end

### Numerical Simulation with Gabor frames

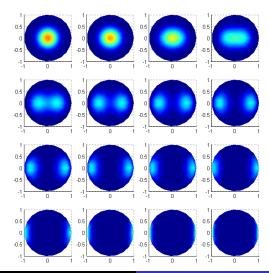
Simple analyzing atom

$$\psi(q) = \cos^6(2.6\arccos(q_0)), \quad \frac{\sqrt{3}}{2} \le q_0 \le 1,$$

- Frame grid: frequency  $\mathbb{Z}_3$ , rotation 120 vertices of the 600-cell
- 17 of the 32 space groups are subgroups of the 600-cell
- (synthetic) example of an ODF with orthorhombic crystal symmetry and triclinic symmetry for the specimen
- 3 cases: no noise, 5% noise, 10% noise

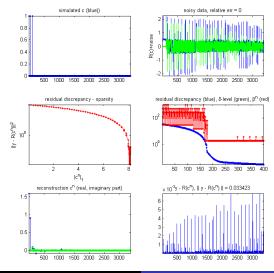


# Original configuration



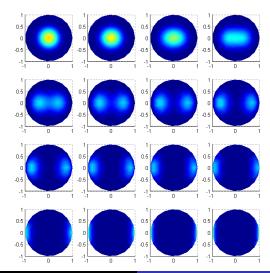


### Reconstruction without noise



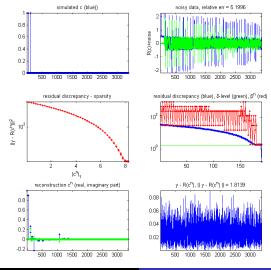


### Reconstruction without noise



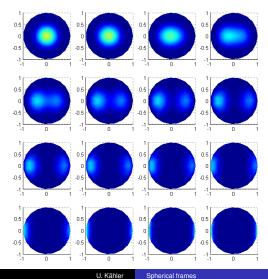


### Reconstruction with 5% error



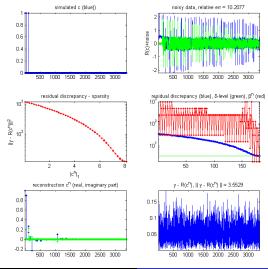


### Reconstruction with 5% error



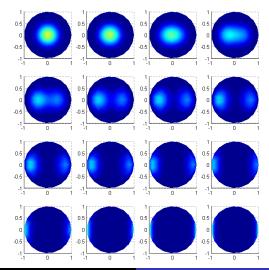


### Reconstruction with 10% error





### Reconstruction with 10% error





#### The end!

#### Thank you for your attention.

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