

## DATASET STATISTICS

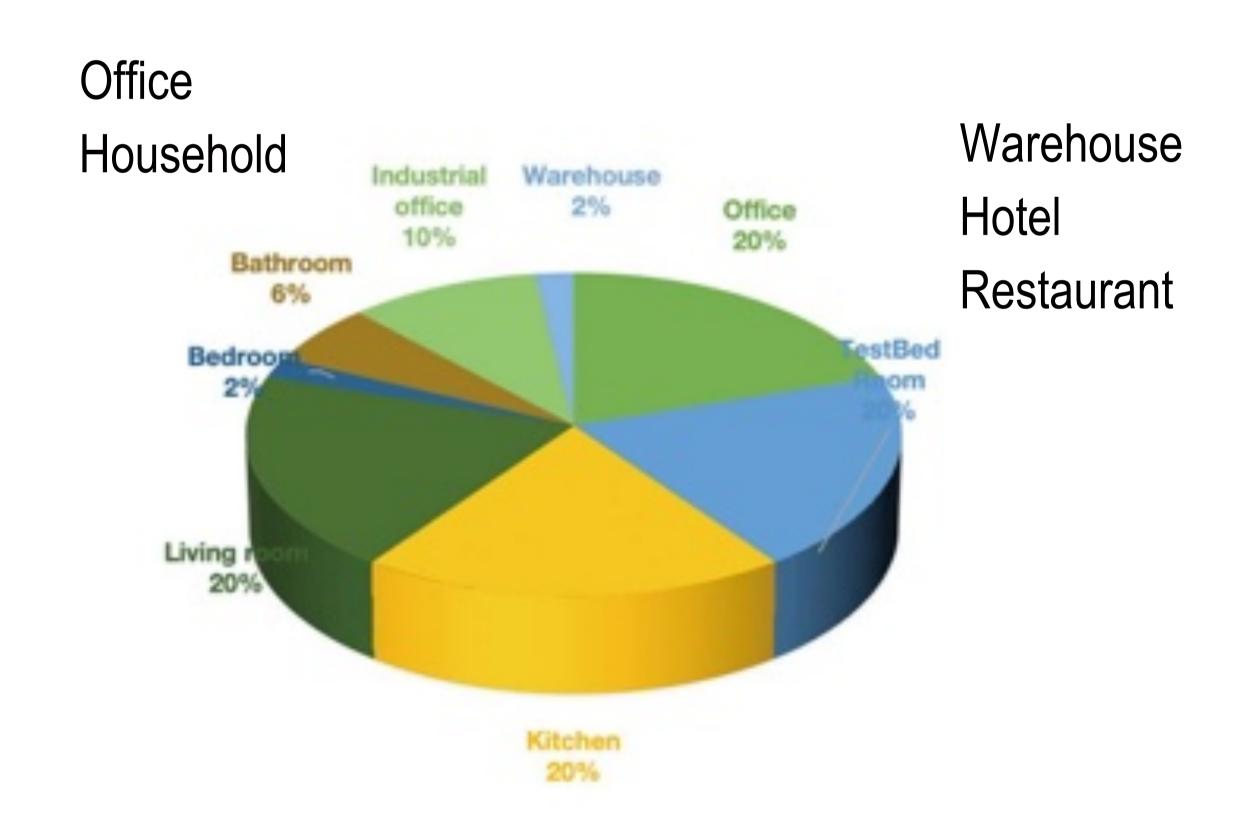
## **MASSIVE-SCALE**

Scripted: 500k trajectories

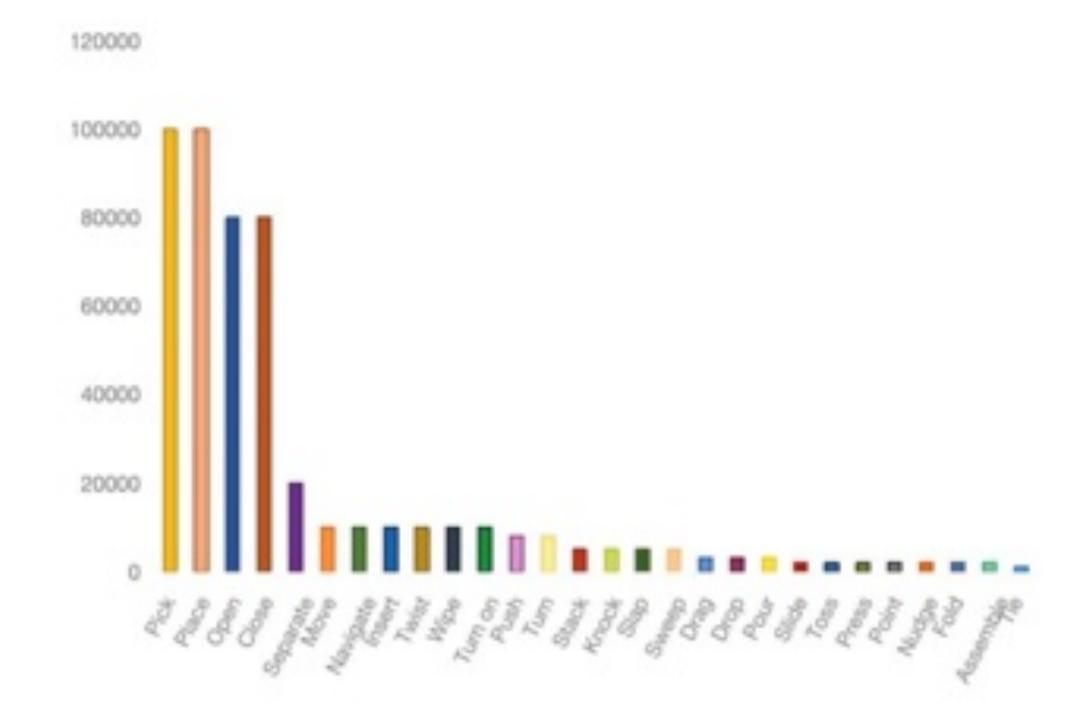
Real-Scenario: Hundreds of hours

### **MULTI-SCENE**

NO TOY SCENES ANYMORE!



#### **MULTI-TASK**



## **MULTI-MODAL**

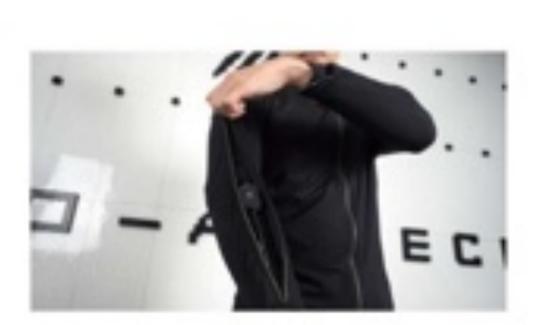
Vision: 3 RGB + 1 Depth + 1 Fisheye Action: whole body movement

Tactile: hands + feet

Audio: via a circular 4-mic array

Label: natural language task description

# DATA COLLECTION DEVICES



## Mocap Suit

Self-developed Low-cost

**17 IMUs** 



5 channel images

Circular mic array



## Gloves

Tactile Collection OR Haptic feedback

10 contact points each hand



#### Shoes

Waterproof

Pressure sensor array

99 contact point each foot

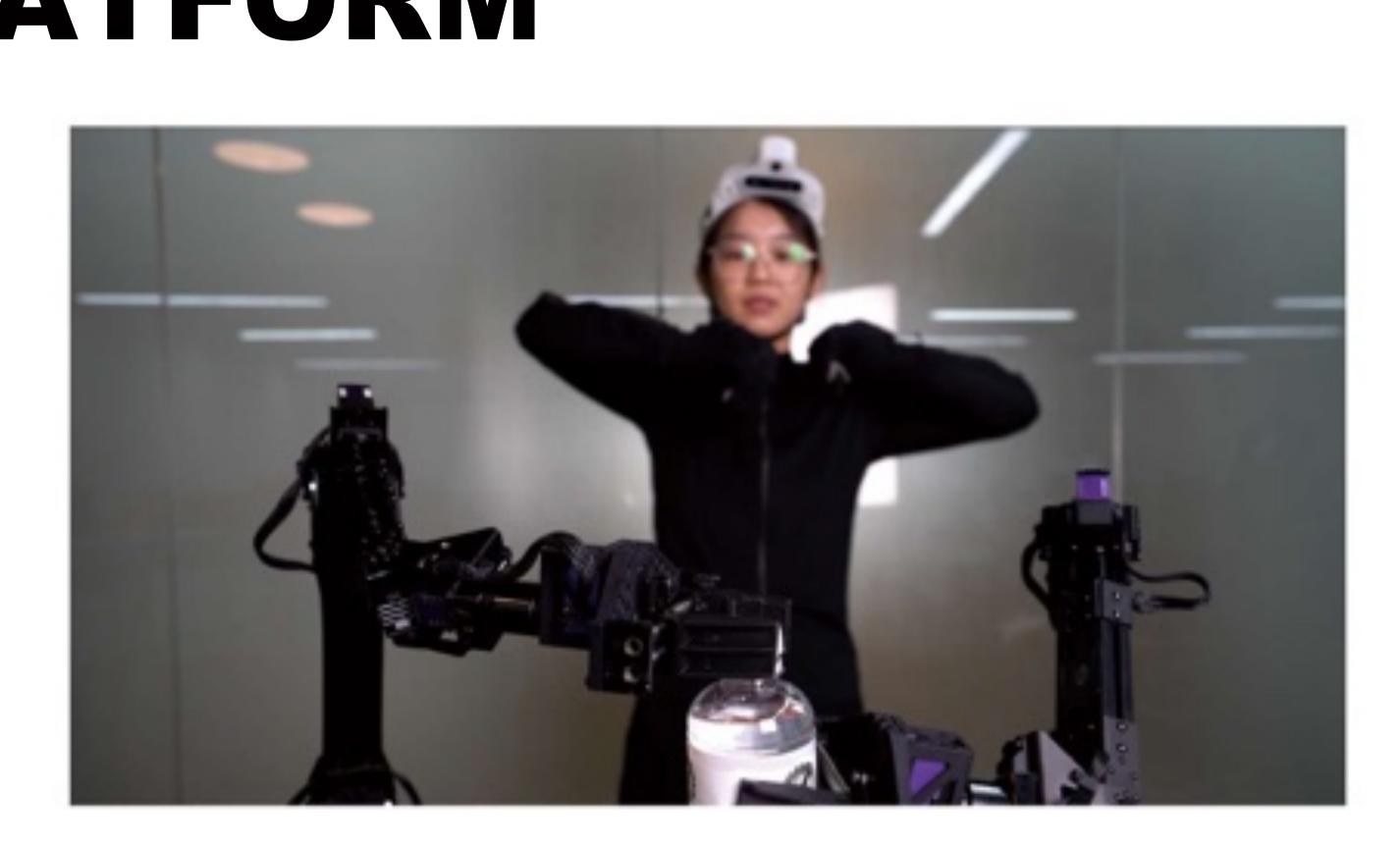
# TELEOPERATION PLATFORM

Same devices for a general robot teleoperation platform

More Affordable: no additional master robots

required

More Accurate: fused visual and motion results













Join Waiting List IO-AI.Tech **Github Example**