

Learning dynamics in a cellular automata model of classroom peer-to-peer interactions

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Abstract

This study aims to model the transfer of knowledge through peer-to-peer interactions in the classroom by using a binary probabilistic cellular automata (PCA) model. This study mainly focuses on the effects of the initial seating arrangement of learned or high aptitude students to the classes' overall learning rate. We also compared the efficiency of learning between the traditional learning model and peer-to-peer learning model. We found that in square classrooms with different lengths $L \in \{32, 48, 64, 96, 128\}$, the inner corner seating arrangement performed the best among the peer-to-peer learning setups in terms of both the time it takes to saturate the classroom with learned students (t_{max}) and the classroom's learning rate (m). This result is different from a previous studies. The difference stems from the simplifications made in this model that may not reflect real world factors. Our model uses binary values instead of continuous values as a measure of students' aptitude, does not consider memory or unlearning and directionality or orientation bias (non-isotropy). It also does not consider the similarity effect mentioned in related literature where peer discussion can enhance understanding even if none of the students knows the correct answer. However, despite these simplifications, we found that in smaller classrooms with slow learners, peer-to-peer learning is more efficient compared to the traditional learning model, just as the previous study has suggested.

Keywords: classroom dynamics, probabilistic cellular automata

1 Introduction

Peer instruction (PI) or peer-to-peer (P2P) learning is a type of teaching style where students are given the chance to interact with their classmates to discuss ideas and share answers to questions in the classroom in addition to interactions with the teacher and traditional lectures. Although there are many ways to implement PI in the classroom [1], one of the more common ways is for the teacher to pose a question the the class then give the class a chance to discuss their answers before re-answering the question [2]. PI has shown to improve students' understanding for both conceptual and problem solving skills across different subjects including calculus, physics, and life sciences [2] [3]. Students who learned through PI also showed better conceptual understanding and similar problem solving skills compared to students who were taught traditionally [4]. Furthermore, there are related literature that show that students' understanding of the lesson can improve after PI even if no one in the group initially knew the answer [3]. In line with this, other research has shown that students with less background knowledge that had PI opportunities in class learned as much as students with more background knowledge in the traditional set up [4].

A cellular automaton (CA) is a model in which agents or cells are placed in a grid and can take on different states. These CA evolve over time either synchronously or asynchronously. How they evolve are dictated by rules which can either be deterministic or probabilistic in nature. In a CA, neighborhoods are defined to be a locality of cells that can affect one another. The neighborhood can be defined arbitrarily, but two common types in a 2D CA on a square grid are the Moore neighborhood (square) and the von Neumann neighborhood (diamond) [5]. Since their introduction, CA have become computational tools that are used to model complex and dynamic systems effectively despite the relative simplicity of their rules. Probabilistic CA (PCA) are extensions of the CA model in which the rules to update the cells' states involve some randomness. Its probabilistic nature gives the model more flexibility to model physical phenomena that are also probabilistic in nature like in epidemiology and wildfire models [6]. Due to the discrete nature of students' positions in the classroom and the probabilistic nature of learning, we decided that it would be apt to use a PCA to model the information propagation or learning in the classroom and to learn the dynamics of this system.

2 Methodology

2.1 Peer-to-peer (P2P) learning model

We used a two-dimensional binary probabilistic cellular automata (PCA) model to simulate the learning of students from peer-to-peer interactions in a square classroom. The PCA model runs until the classroom is fully saturated with learned students and includes three parameters. Firstly, (1) the dimensions of the classroom ($L_1 \times L_2$) such that the size is $N = L_1 \times L_2$. In the simulations ran for this experiment, the classrooms were set to be squares with lengths $L \in \{32, 48, 64, 96, 128\}$. This is not representative of reality and is different from the previous study [7]. This was done because a classroom length of $L = 8$ (and corresponding size of $N = 64$) will not give much insight as the simulations would end too quickly and would not yield enough data points for analysis. Secondly, (2) the initial position or seating arrangement (SA) of the learned students. The SA's chosen for the simulations are based on a previous study [7], namely inner corner, outer corner, center, and random with the number of initial learned students being constantly $n_0 = 4$. The inner corner SA places learned students halfway between the corners of the classroom and the middle. The outer corner SA places the learned students at the classroom's corners, while the center SA places the learned students in the center of the classroom, and the random SA places the learned students randomly within the classroom. Lastly, (3) the spread coefficient matrix Λ within a neighborhood given by

$$\Lambda = \begin{bmatrix} \lambda_1 & \lambda_4 & \lambda_7 \\ \lambda_2 & \lambda_5 & \lambda_8 \\ \lambda_3 & \lambda_6 & \lambda_9 \end{bmatrix} \quad (1)$$

The spread coefficient matrix Λ can be both isotropic (no orientation bias, all λ_i are equal) and anisotropic (has orientation bias, not all λ_i are equal). However, in the simulations ran for this experiment, we only considered isotropic spreading with spread coefficients (λ) between 0.1 to 1.0 with increments of 0.1. The matrix Λ dictates the probability of the student of interest, placed at the center of the matrix, to learn from its neighbors based on the latter's relative position. In the case of students who are at the edge of the classroom, the part of the neighborhood where there are no more students are treated as seats with unlearned students. For example, an unlearned student whose only learned neighbor is in front of them will have a λ_4 chance of learning in the next generation. In the case where an unlearned student has more than one learned student in their neighborhood, probability of learning is dictated by:

$$P = 1 - \prod_{n=1}^9 (1 - S_n \lambda_n), \text{ where } S_n = \begin{cases} 0 & \text{when neighbor is learned} \\ 1 & \text{when neighbor is not learned} \end{cases} \quad (2)$$

2.2 Traditional learning model

To simulate traditional learning models where the teacher simply gives a lecture to the class, a different set of rules were applied to the 2D binary PCA model using the same parameters as in the P2P model. Instead of having a chance to learn based on a probability matrix Λ and learned neighbors, each student has a chance λ to learn from the teacher. That is, for every generation, a student has a λ probability of transitioning from unlearned to learned. Similar to the P2P model, this model runs until the classroom is saturated with learned students.

2.3 Time to learn (t_{max}) and learning rate (m)

From the simulations, we compared both the average number of generations it takes to saturate the classroom with learned students (t_{max}) and the average learning rate (m) across different configurations over 5 independent runs. The learning rate for each trial was obtained by fitting a power law ($y = ax^m$) to the first half of the data for the P2P model or the first quarter of the data for the traditional model. This truncation was done so that we only fit the part of the data before the finite size effect starts to affect the simulation.

2.4 Class size dependence

We also analyzed the dependence of the time to learn (t_{max}) on the class size (N). We took representative learning coefficients $\lambda \in \{0.1, 0.5, 0.9\}$ from the traditional model and the inner corner SA from the P2P model to see how the class size and the learning coefficient affects the time to learn.

3 Results and Discussion

The data shown in Figure 1 suggests that the time to learn (t_{max}) does not vary significantly within the same SA's when we vary the class size and spread coefficient. Among the P2P models, the inner corner seating arrangement consistently performs the best with the shortest time to learn (t_{max}) and the highest learning rate (m), while the random arrangement generally performs the worst. These findings can be attributed to the simplicity of the model which lends itself to being heavily influenced by geometric factors. Analytically, the configurations' performance is heavily dependent on the maximum distance of any point to an initially learned student. The outer corner and center seating arrangements perform very similarly because they are geometrically one circle expanding at a constant rate. In these two configurations, the maximum distance of any unlearned student to an initially learned student is the same at $d_{\max, \text{center}} = d_{\max, \text{outer corner}} = \frac{L\sqrt{2}}{2}$. The inner corner seating arrangement performs the best because it minimizes this distance to $d_{\max, \text{inner corner}} = \frac{L\sqrt{2}}{4}$. The data in Figure 1 also shows that the traditional learning model is generally more efficient for bigger classrooms and higher spread coefficients λ . However, this result may change if we vary the number of initially learned students with respect to the classroom size.

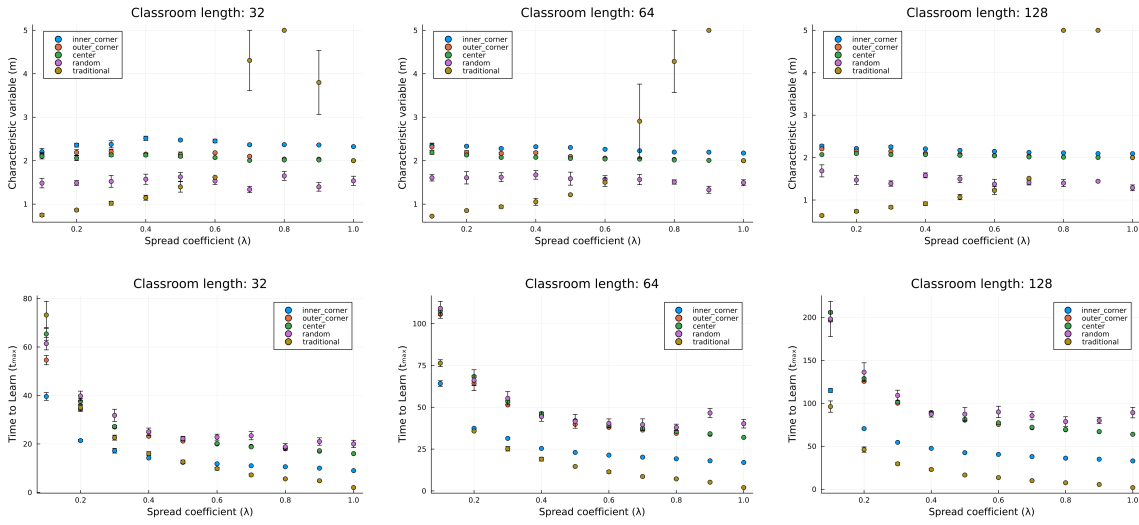


Figure 1: Characteristic variable (m) (higher is better) and time to learn (T) (lower is better) vs. Spread coefficient (λ).

Our findings regarding the optimal seating arrangement for peer-to-peer learning, however, do not agree with existing studies. In a similar study [7], they found that the outer corner configuration performed the best in reality. The difference is expected due to the simplifications made in this study. They mentioned that there is a similarity effect that goes on in peer-to-peer learning wherein students of similar aptitude levels, regardless of their actual aptitude, learn better when seated together. The similarity effect has not yet been implemented in our system because it is not applicable to a binary system. The system being binary also introduces more granularity when compared to reality where aptitude is measured more continuously. This study also does not consider the non-isotropy or the presence of an orientation bias when it comes to the learning within each neighborhood. This study also assumes that everyone is equally receptive to learning from their peers which may not be the case, so future models should take into account the non-uniformity of individuals' learning rates.

When we analyze the dependence of t_{max} on N , we see that resulting trend for both P2P and traditional models also follow the power law ($t_{max} = aN^b$). Figure 2 shows that there is a point where in one model can perform better than the other. P2P learning models perform better than traditional in small classrooms with slower learners (low spread coefficient λ). This agrees with the results shown in Figure 1. It also similar to the results from previous study [7] wherein they show that low aptitude students are the ones who benefitted the most from the P2P learning model.

We see from both Table 1 and Figure 2 that there are two major groups of power law fits based on their exponent or b-values: (1) those from the P2P model (inner corner SA) with $\bar{b} = 0.432 \pm 0.019$, (2) those from the traditional model with $\bar{b} = 0.087 \pm 0.021$. From this, we can say that the traditional learning model is more scalable or that it is less size dependent compared to the P2P model. Numerically, this is explained by the lower b-values of the traditional models vs the P2P models. We also found that

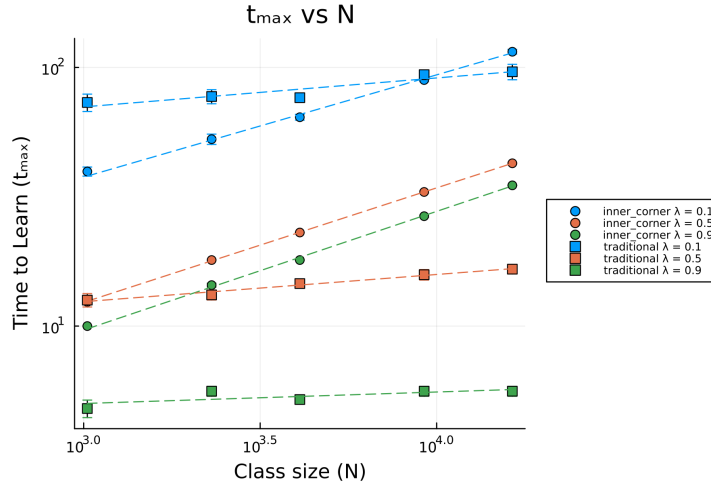


Figure 2: Maximum time t_{max} vs class size N for P2P and traditional models (lower is better). Symbols denote the data points and the dash lines are the power law fit in the form of $t_{max} = a \cdot N^b$ using three λ values, $\lambda \in \{0.1, 0.5, 0.9\}$ for two cases: (1) peer-to-peer learning (inner corner configuration), and (2) traditional learning. The two major groups of power law fits are obtained based on the exponent b : (a) inner corner, $b = 0.432 \pm 0.019$, (b) traditional, $b = 0.087 \pm 0.021$

	Inner corner		Traditional	
	a	b	a	b
$\lambda = 0.1$	2.4515	0.3955	32.4884	0.1119
$\lambda = 0.5$	0.5795	0.4428	6.0079	0.1052
$\lambda = 0.9$	0.4055	0.4589	3.6914	0.0445

Table 1: Power law fit parameters a and b for t_{max} vs N , where $t_{max} = a \cdot N^b$

b-values generally increase as the spread coefficient λ increases as shown in Table 1. This suggests that in classrooms with higher aptitude students are more affected by the class size than classrooms with lower aptitude students.

4 Conclusions

Due to the simplifications made in our model, our results in comparing between different SA's in the peer-to-peer learning model were heavily influence by geometric biases, and may not represent reality as well as other models. However, even with a simplified model, we were able to show when one method of teaching is more advantageous than the other. Classrooms with slow learners benefit the most from peer-to-peer learning methods and classrooms with fast learners are likely better off with traditional learning methods.

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