

The Voronoi Diagram of Rotating Rays with applications to Floodlight Illumination

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EuroCG 2021
Saint Petersburg, Russia

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Introduction

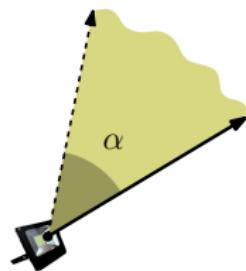
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RVD in the Plane

RVD of a Convex Polygon

Brocard Illumination

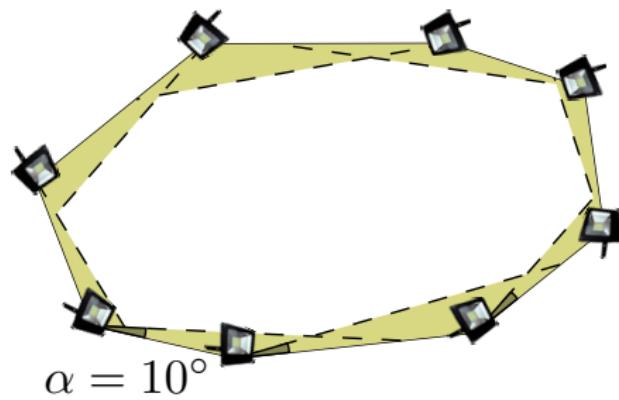
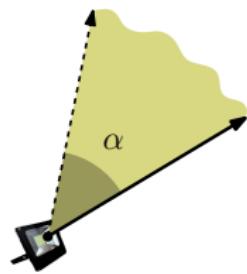
α -floodlight



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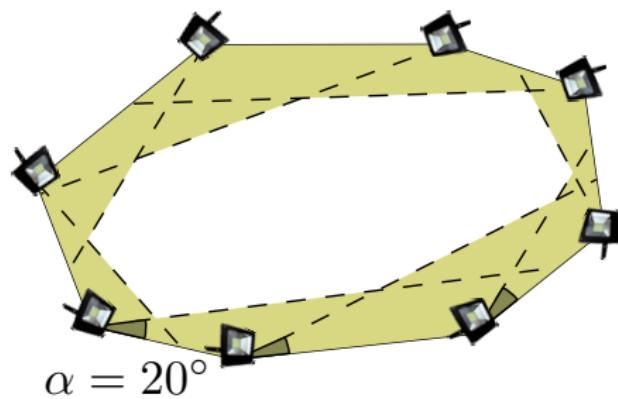
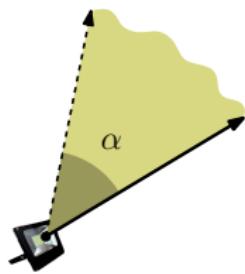
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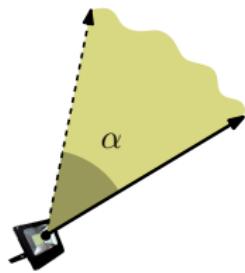
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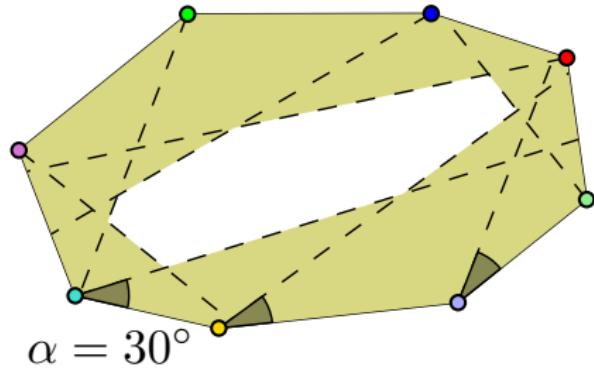


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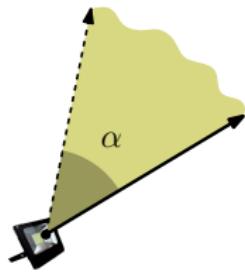


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Goal: Minimum angle α^* to illuminate P

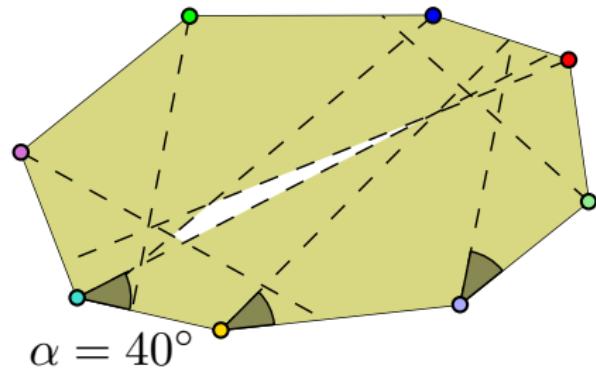


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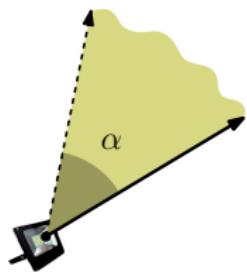


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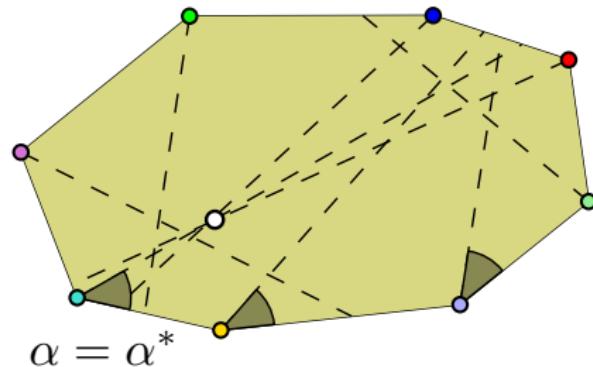
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Brocard illumination problem

Input: Polygon P with edge-aligned α -floodlights

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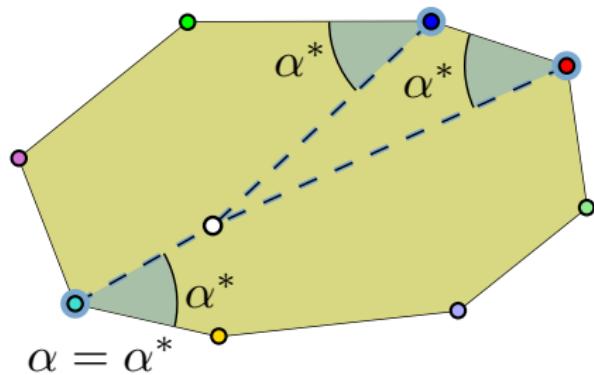
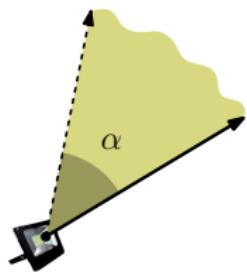
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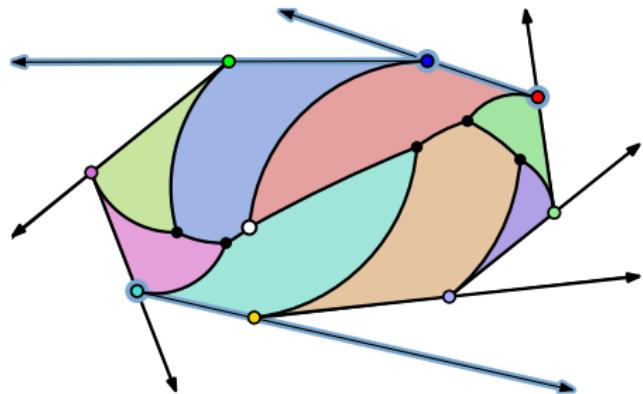
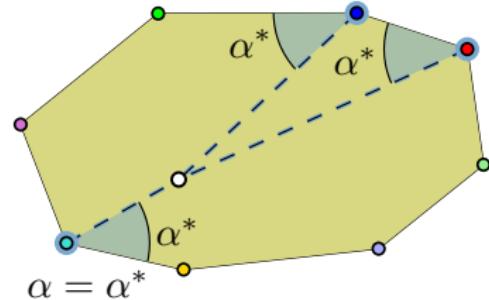


Brocard Illumination

Input: Polygon P with edge-aligned α -floodlights.

Goal: Minimum angle α^* to illuminate P .

Approach: Define the **Voronoi Diagram of Rotating Rays**.



Related Work

Brocard Polygons - Illumination

- ▶ Brocard Polygons (only harmonic polygons)
e.g. [Casey 1888, Dmitriev & Dynkin 1946, Bernhart 1959]

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- ▶ Several variants/results, e.g. [Bose et al. 1993, Urutia 2000]
- ▶ Uniform angle, e.g. [O'Rourke 1995, Toth 2002]

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Application - Domain coverage

- ▶ Directional Antennas or Surveillance Cameras [Berman et al. 2007, Kranakis et al. 2011, Neishaboori et al. 2014, Czyzowicz et al. 2015]

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RVD Definitions & Properties

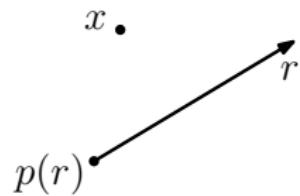
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RVD of a Convex Polygon

Angular distance - bisectors

Definition

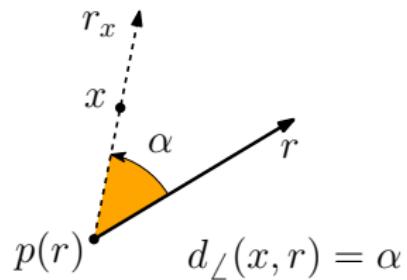
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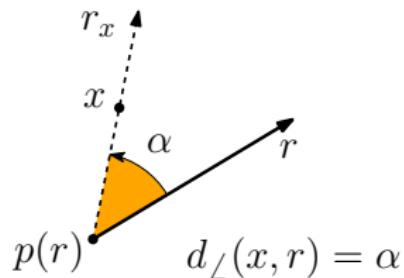
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Angular distance - bisectors

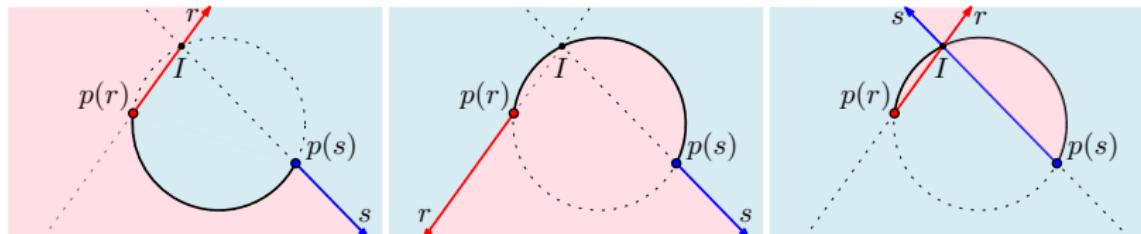
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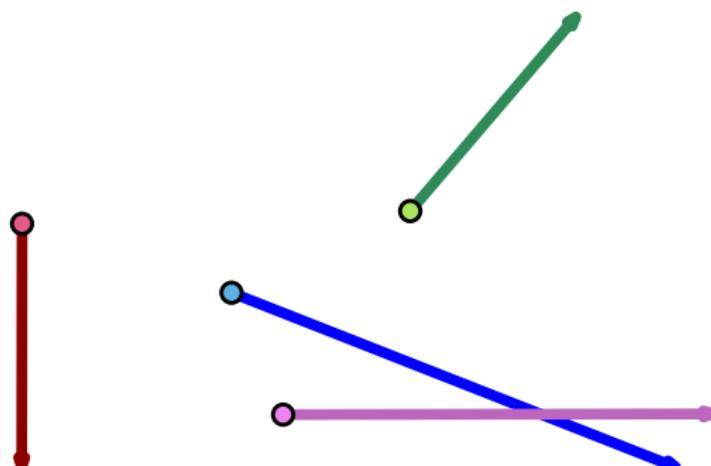
Given two rays r and s , their **angular bisector**, $b_{\angle}(r, s)$, is the curve delimiting the points closer to r and the points closer to s .



Rotating Rays Voronoi Diagram (RVD)

Definition

Given a set of rays \mathcal{S} .

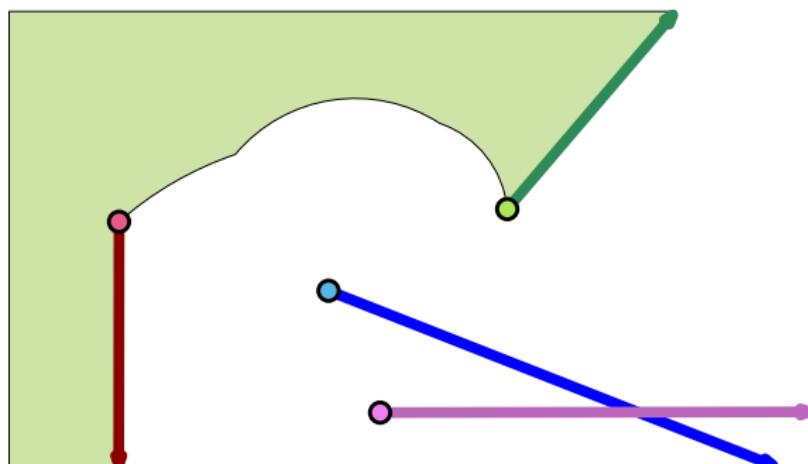


Rotating Rays Voronoi Diagram (RVD)

Definition

Given a set of rays \mathcal{S} . The **Voronoi region** of a ray $r \in \mathcal{S}$ is:

$$vreg(r) := \{ x \in \mathbb{R}^2 \mid \forall s \in \mathcal{S} \setminus \{r\} : d_{\angle}(x, r) < d_{\angle}(x, s) \}.$$

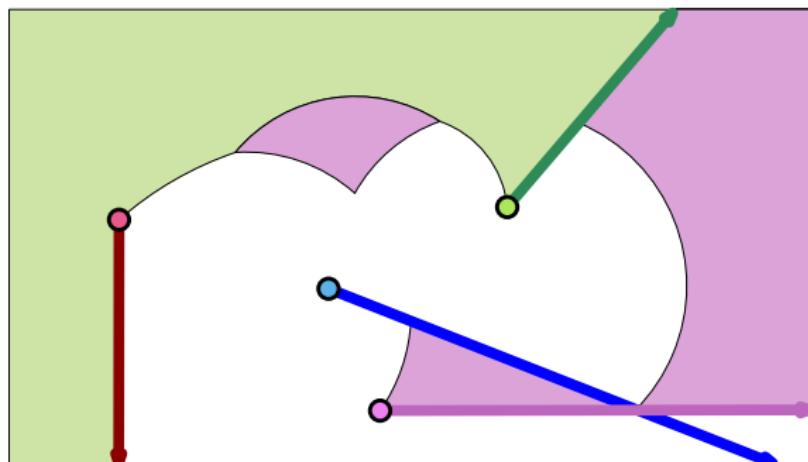


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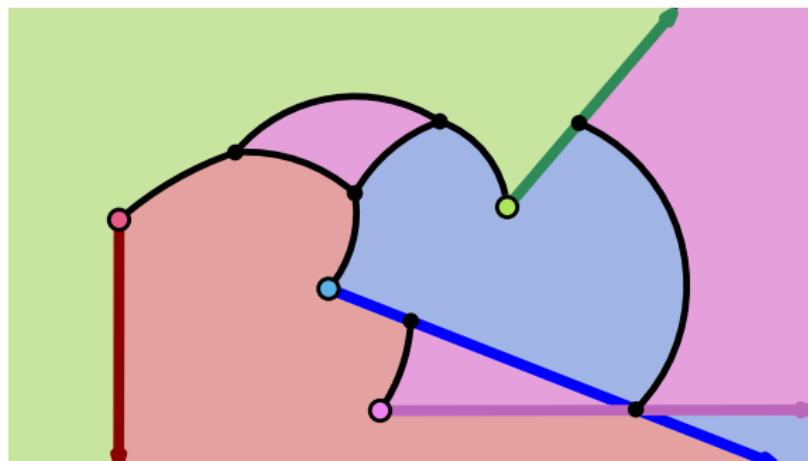
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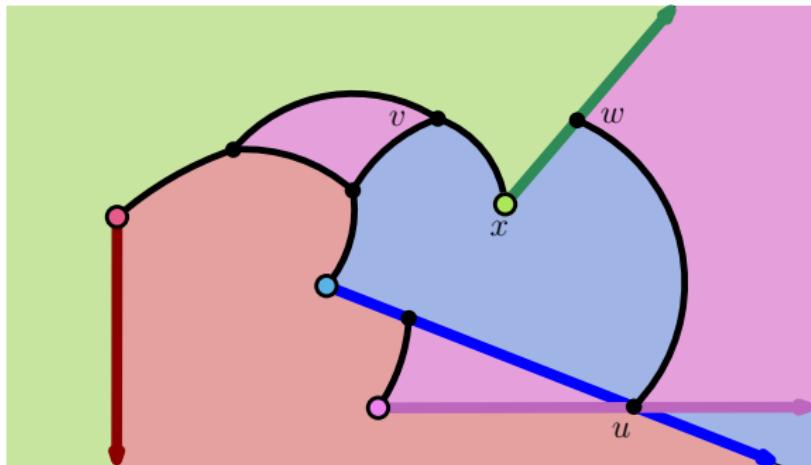
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The **Rotating Rays Voronoi Diagram** of \mathcal{S} is the subdivision of \mathbb{R}^2 in Voronoi regions. $RVD(\mathcal{S})$ is the graph structure of the diagram.

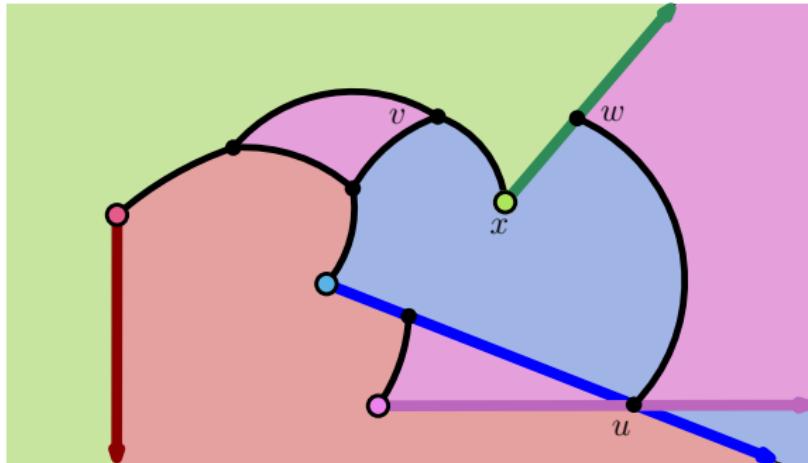


Properties



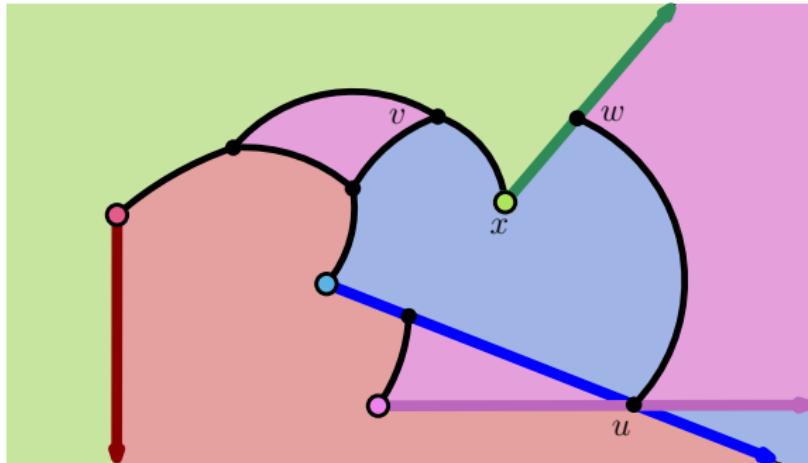
- ▶ $\text{RVD}(\mathcal{S})$ has different types of vertices and edges.

Properties



- ▶ $\text{RVD}(\mathcal{S})$ has different types of vertices and edges.
- ▶ A region can have many faces; exactly one is unbounded.

Properties



- ▶ RVD(S) has different types of vertices and edges.
- ▶ A region can have many faces; exactly one is unbounded.
- ▶ RVD(S) is connected.

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Theorem

Given a set \mathcal{S} of n rays RVD(\mathcal{S}) has $\Omega(n^2)$ worst case complexity.

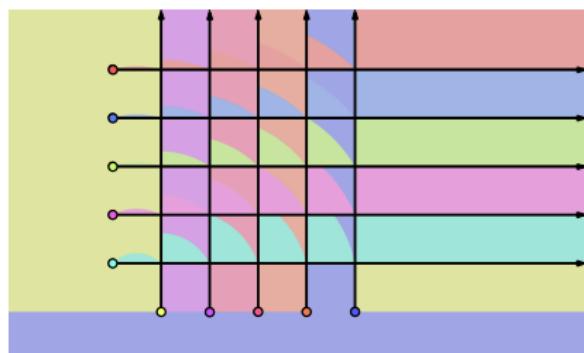


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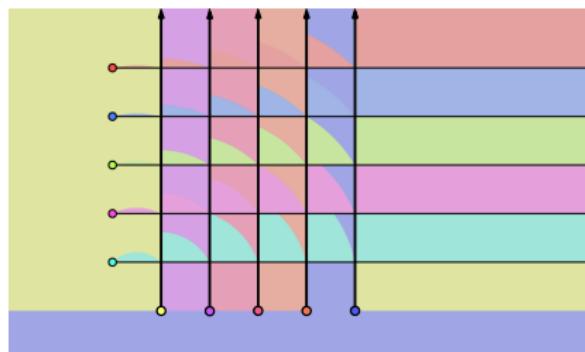


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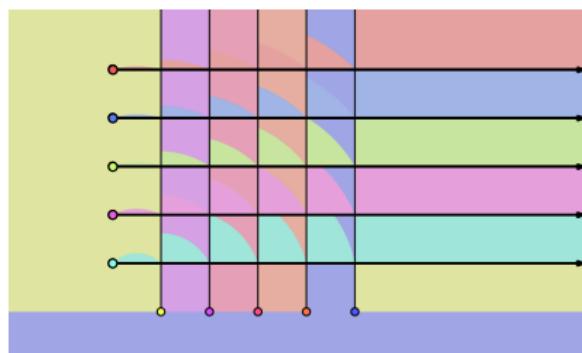


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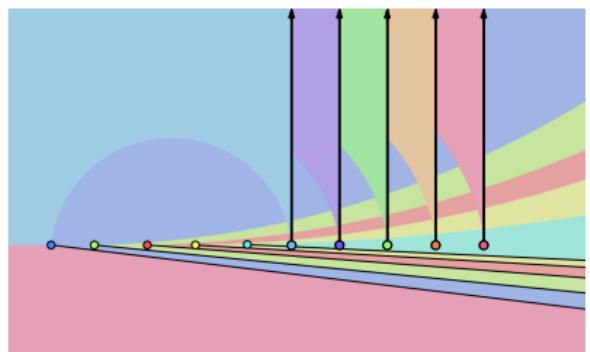
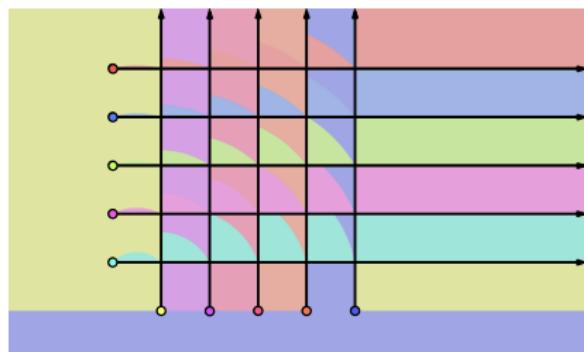


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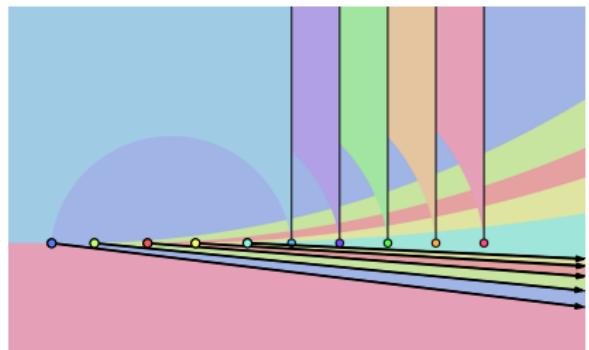
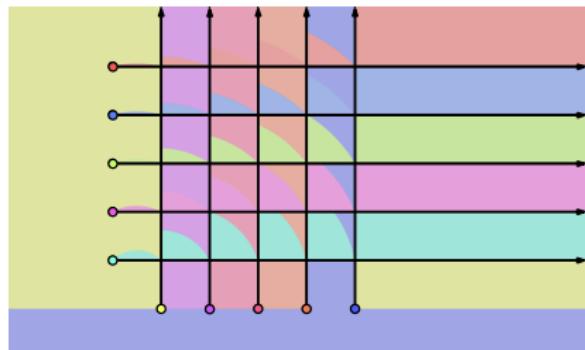


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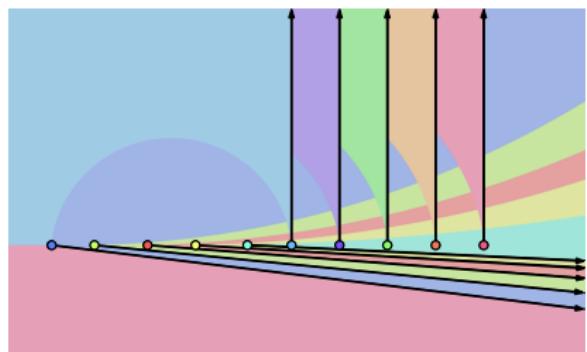
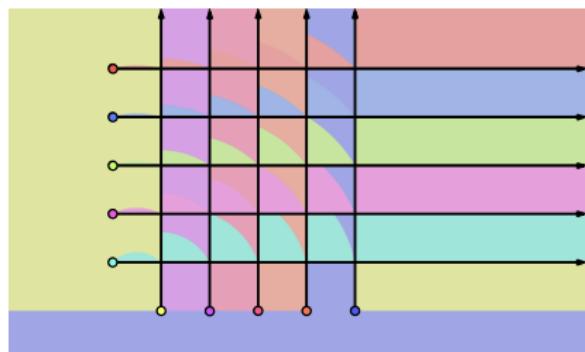
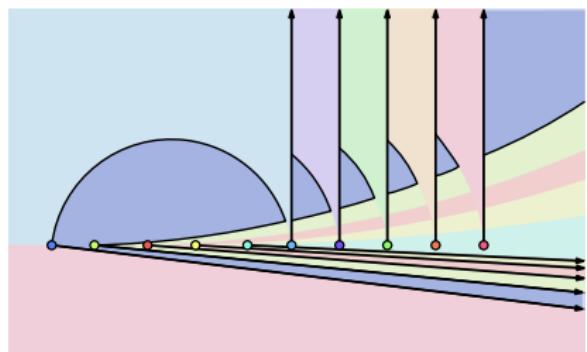
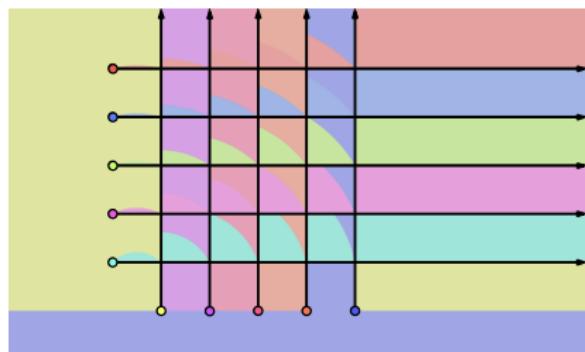


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Region Complexity

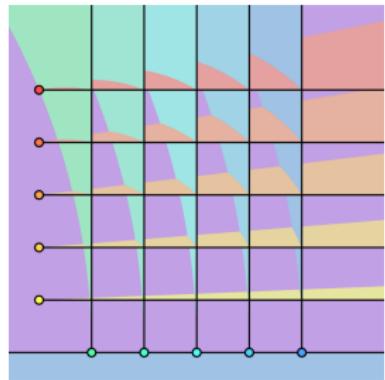
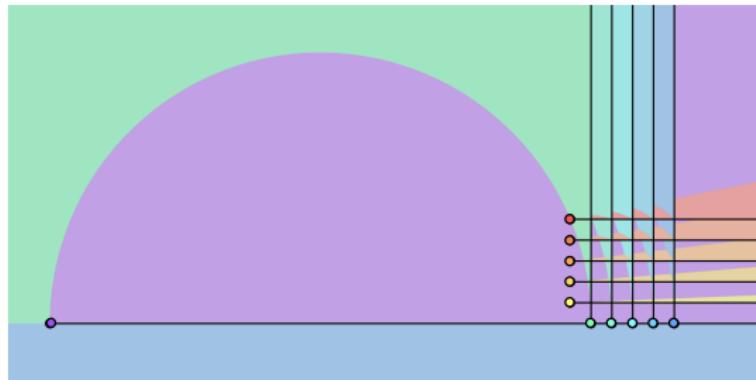
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A region of $\text{RVD}(\mathcal{S})$ has $\Theta(n^2)$ worst case complexity.

Region Complexity

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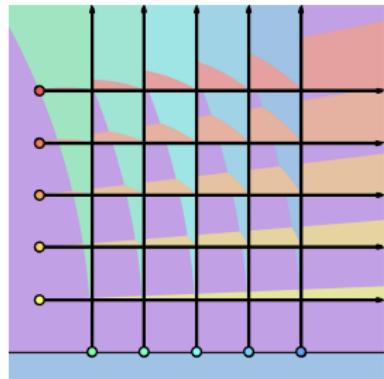
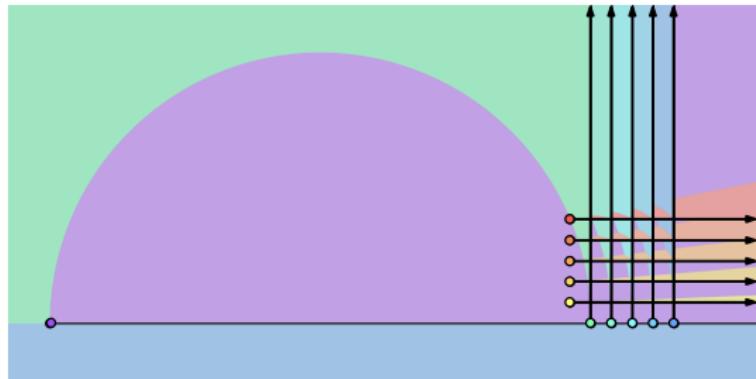
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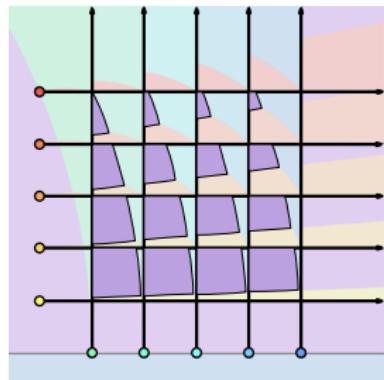
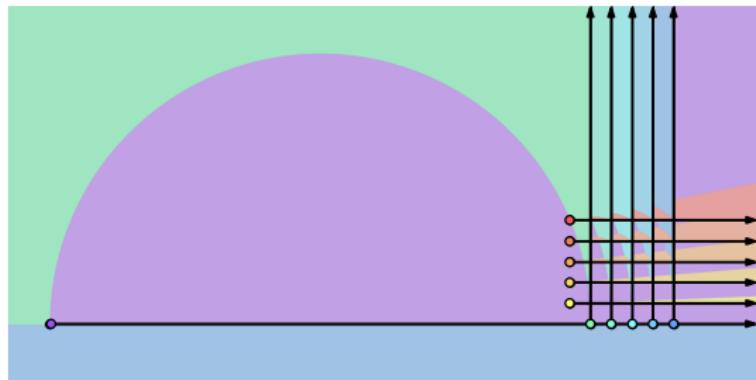
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Complexity upper bound & Algorithm

Theorem

Given a set \mathcal{S} of n rays $\text{RVD}(\mathcal{S})$ has $O(n^{2+\epsilon})$ complexity $\forall \epsilon > 0$.

- ▶ Lower envelopes of distance functions in 3-space [Sharir 1994].

Complexity upper bound & Algorithm

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*Given a set \mathcal{S} of n rays $\text{RVD}(\mathcal{S})$ has $O(n^{2+\epsilon})$ complexity $\forall \epsilon > 0$.
Further, $\text{RVD}(\mathcal{S})$ can be constructed in $O(n^{2+\epsilon})$ time.*

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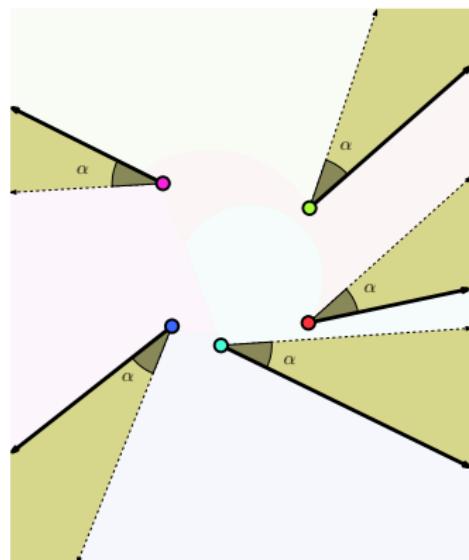
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Given a set S of n rays $\text{RVD}(S)$ has $O(n^{2+\epsilon})$ complexity $\forall \epsilon > 0$.

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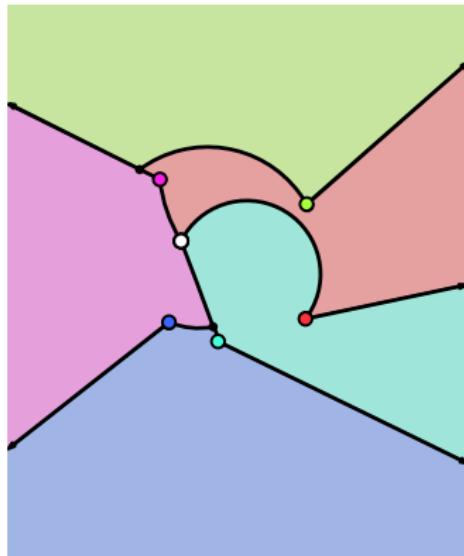
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Minimum angle α^* to illuminate \mathbb{R}^2

1. Construct $\text{RVD}(S)$. $O(n^{2+\epsilon})$ time.
2. Traverse $\text{RVD}(S)$. Linear time.

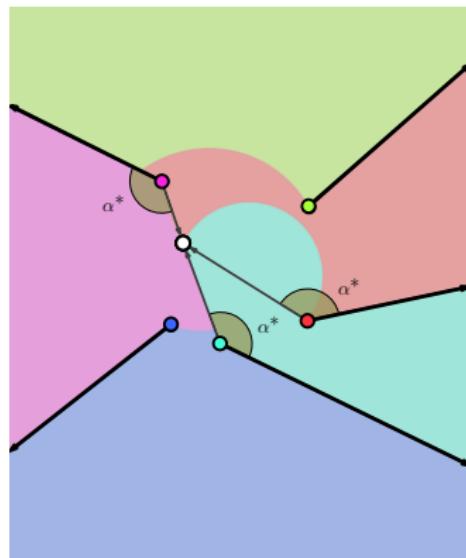
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Minimum angle α^* to illuminate \mathbb{R}^2

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- ▶ $\alpha^* \in (2\pi/n, 2\pi)$

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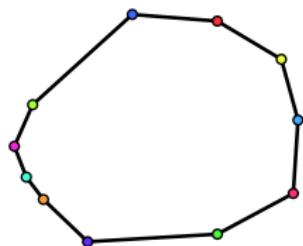
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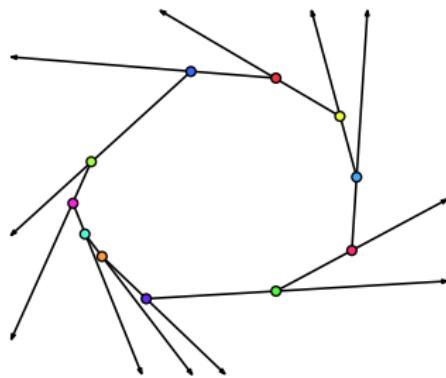
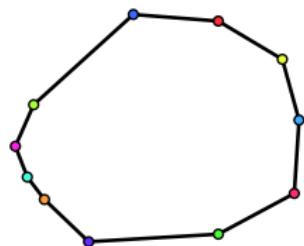
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- ▶ Input: A convex polygon P with n vertices.



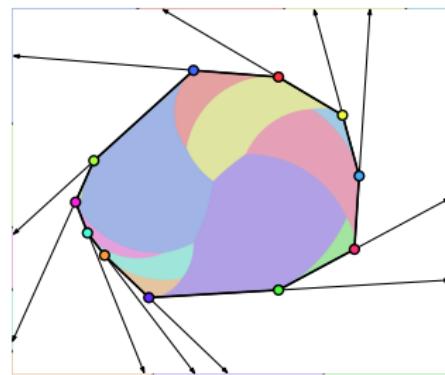
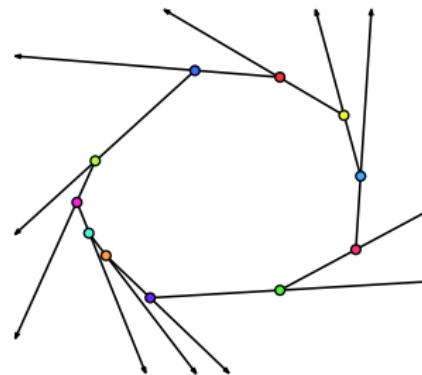
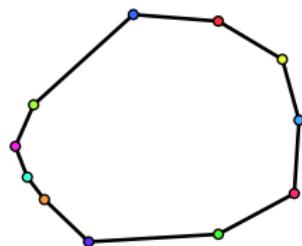
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- ▶ Input: A convex polygon P with n vertices.
- ▶ Obtain a set of n edge-aligned rays \mathcal{S}_P



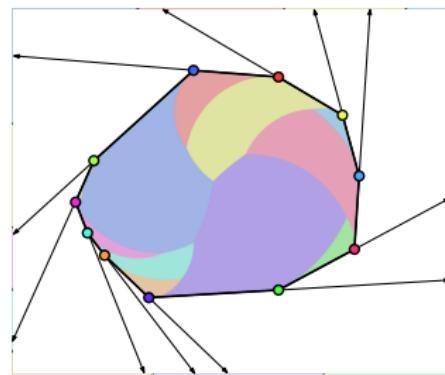
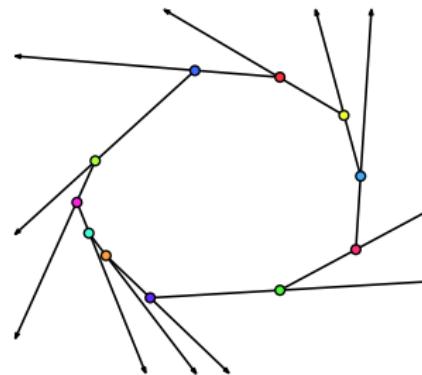
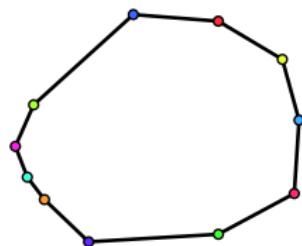
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- ▶ Output: Brocard angle of P .



Algorithm outline

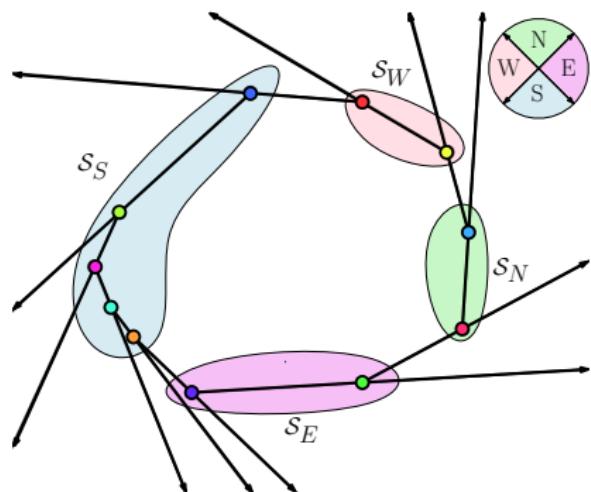
1. Divide \mathcal{S}_P into 4 sets of rays.
2. Construct the diagrams of the 4 sets.
3. Merge the 4 diagrams to obtain PRVD(\mathcal{S}_P).

Algorithm outline

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3. Merge the 4 diagrams to obtain $\text{PRVD}(\mathcal{S}_P)$.

Step 1.

Partition \mathcal{S}_P into 4 sets $\mathcal{S}_N, \mathcal{S}_W, \mathcal{S}_S$ and \mathcal{S}_E depending on the direction of the rays.



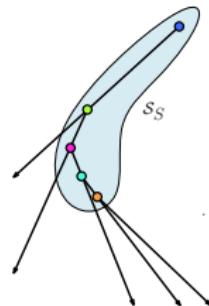
Constructing the 4 diagrams

Step. 2

For each S_d , $d \in \{N,W,S,E\}$:

Use Hamiltonian Abstract Voronoi Diagrams.
[Klein 1989, Klein & Lingas 1994]

- ▶ For each $S' \subseteq S_d^r$ satisfy a set of axioms.



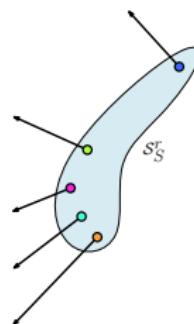
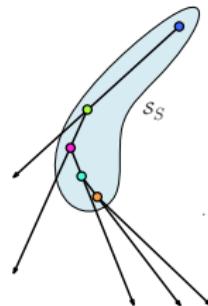
Constructing the 4 diagrams

Step. 2

For each S_d , $d \in \{N,W,S,E\}$: obtain a set S_d^r in which every ray of S_d is rotated by $-\pi/2$.

Use Hamiltonian Abstract Voronoi Diagrams.
[Klein 1989, Klein & Lingas 1994]

- ▶ For each $S' \subseteq S_d^r$ satisfy a set of axioms.



Constructing the 4 diagrams

Step. 2

For each \mathcal{S}_d , $d \in \{N,W,S,E\}$: obtain a set \mathcal{S}_d^r in which every ray of \mathcal{S}_d is rotated by $-\pi/2$.

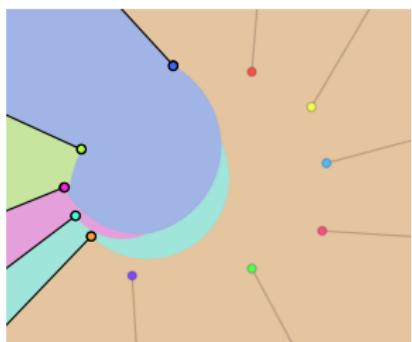
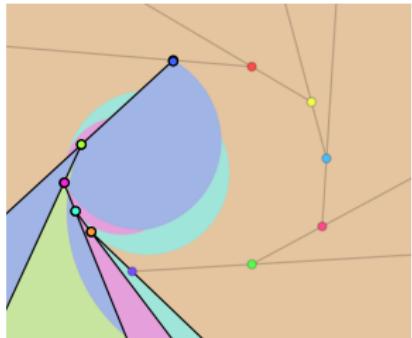
Use Hamiltonian Abstract Voronoi Diagrams.
[Klein 1989, Klein & Lingas 1994]

- ▶ For each $\mathcal{S}' \subseteq \mathcal{S}_d^r$ satisfy a set of axioms.

Lemma

$RVD(\mathcal{S}_d^r)$ is a tree of $\Theta(|\mathcal{S}_d^r|)$ complexity.

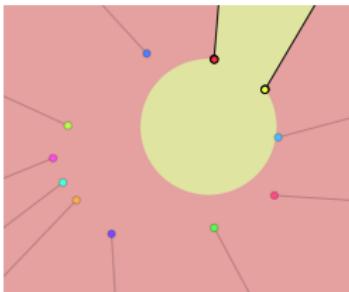
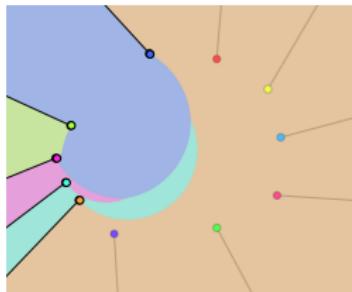
$RVD(\mathcal{S}_d^r)$ can be constructed in $\Theta(|\mathcal{S}_d^r|)$ time.



Step 3. Merging the 4 diagrams

Step 3.a.

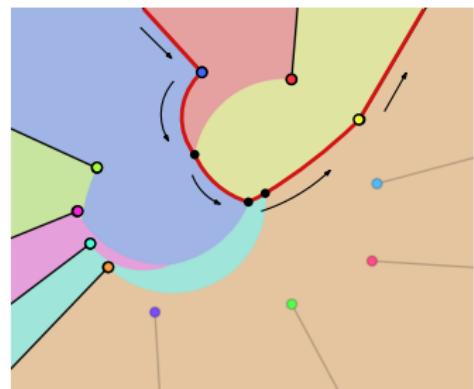
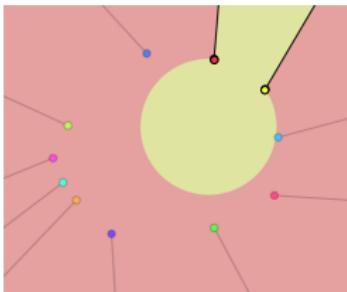
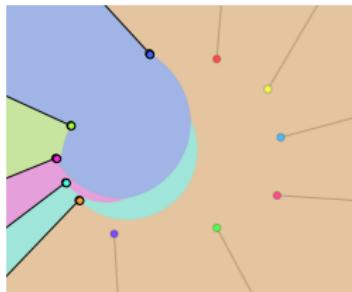
Merge RVD(S_W^r) with RVD(S_S^r)



Step 3. Merging the 4 diagrams

Step 3.a.

Merge $\text{RVD}(\mathcal{S}_W^r)$ with $\text{RVD}(\mathcal{S}_S^r)$ into $\text{RVD}(\mathcal{S}_W^r \cup \mathcal{S}_S^r)$.

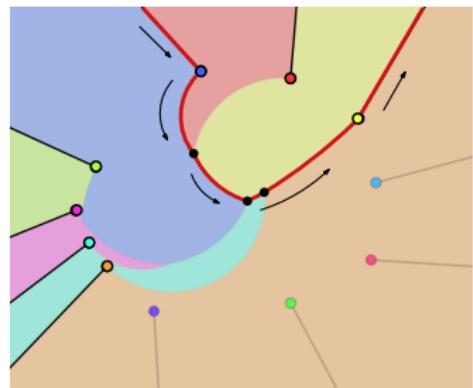
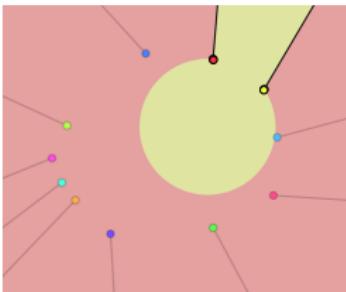
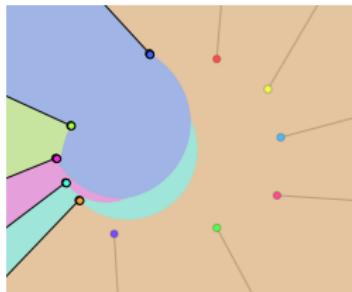


Step 3. Merging the 4 diagrams

Step 3.a.

Merge $\text{RVD}(\mathcal{S}_W^r)$ with $\text{RVD}(\mathcal{S}_S^r)$ into $\text{RVD}(\mathcal{S}_W^r \cup \mathcal{S}_S^r)$.

Respectively $\text{RVD}(\mathcal{S}_E^r \cup \mathcal{S}_N^r)$.



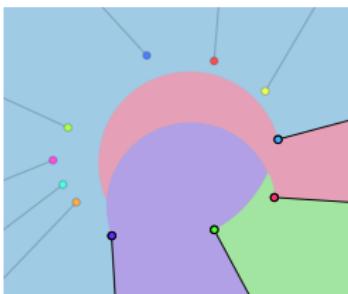
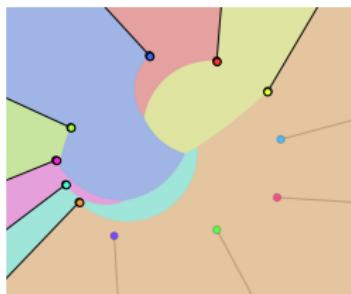
Step 3. Merging the 4 diagrams

Step 3.a.

Merge $\text{RVD}(\mathcal{S}_W^r)$ with $\text{RVD}(\mathcal{S}_S^r)$ into $\text{RVD}(\mathcal{S}_W^r \cup \mathcal{S}_S^r)$.
Respectively $\text{RVD}(\mathcal{S}_E^r \cup \mathcal{S}_N^r)$.

Step 3.b.

Merge $\text{RVD}(\mathcal{S}_W^r \cup \mathcal{S}_S^r)$ with $\text{RVD}(\mathcal{S}_E^r \cup \mathcal{S}_N^r)$ confined into P .
Obtain $\text{PRVD}(\mathcal{S}_P)$.



Step 3. Merging the 4 diagrams

Step 3.a.

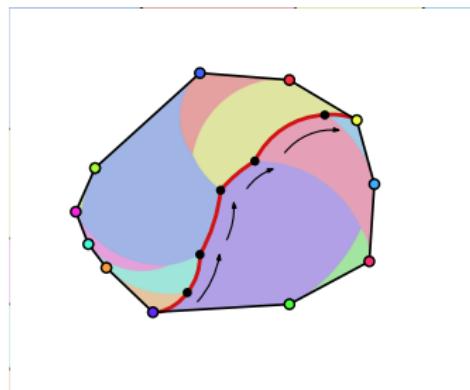
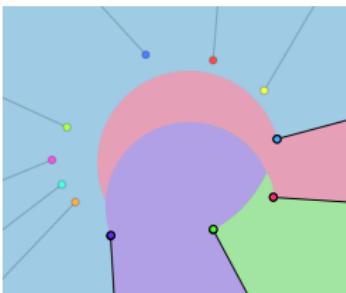
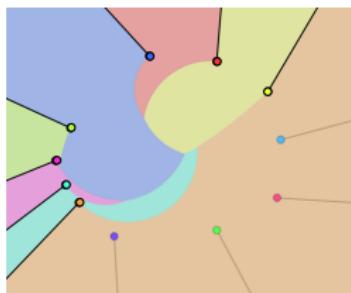
Merge $\text{RVD}(\mathcal{S}_W^r)$ with $\text{RVD}(\mathcal{S}_S^r)$ into $\text{RVD}(\mathcal{S}_W^r \cup \mathcal{S}_S^r)$.

Respectively $\text{RVD}(\mathcal{S}_E^r \cup \mathcal{S}_N^r)$.

Step 3.b.

Merge $\text{RVD}(\mathcal{S}_W^r \cup \mathcal{S}_S^r)$ with $\text{RVD}(\mathcal{S}_E^r \cup \mathcal{S}_N^r)$ confined into P .

Obtain $\text{PRVD}(\mathcal{S}_P)$.



Step 3. Merging the 4 diagrams

Step 3.a.

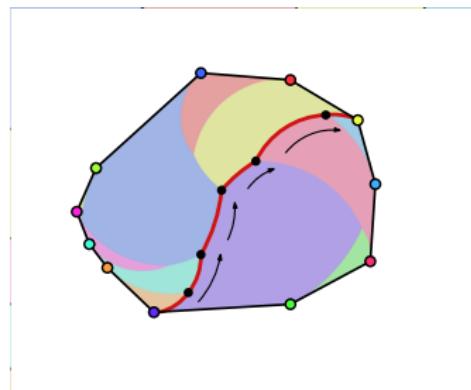
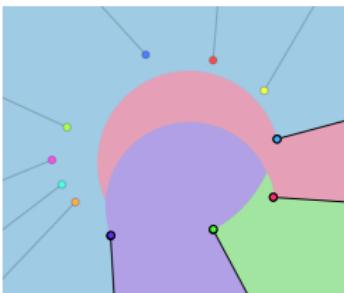
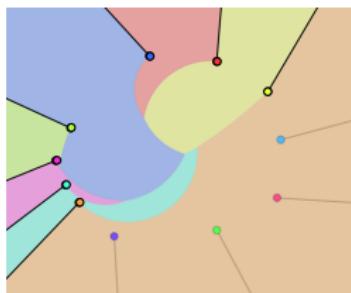
Merge $\text{RVD}(\mathcal{S}_W^r)$ with $\text{RVD}(\mathcal{S}_S^r)$ into $\text{RVD}(\mathcal{S}_W^r \cup \mathcal{S}_S^r)$.

Respectively $\text{RVD}(\mathcal{S}_E^r \cup \mathcal{S}_N^r)$. $O(n)$ time

Step 3.b.

Merge $\text{RVD}(\mathcal{S}_W^r \cup \mathcal{S}_S^r)$ with $\text{RVD}(\mathcal{S}_E^r \cup \mathcal{S}_N^r)$ confined into P .

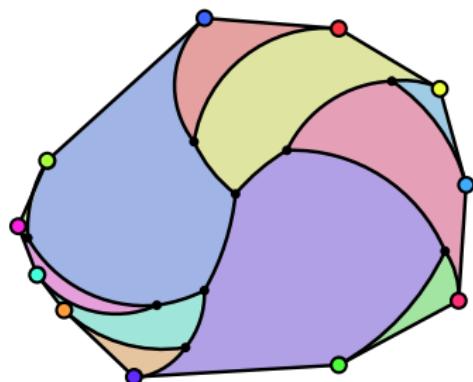
Obtain $\text{PRVD}(\mathcal{S}_P)$. $O(n)$ time



Finding the Brocard angle

Theorem

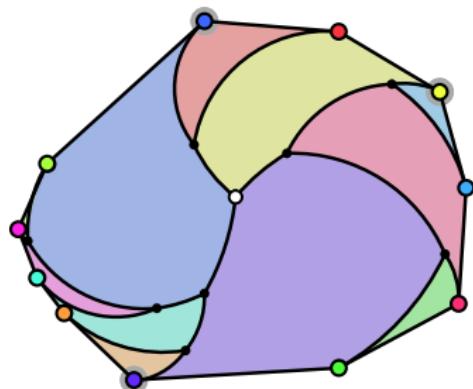
$\text{PRVD}(S_P)$ can be constructed $\Theta(n)$ time.



Finding the Brocard angle

Theorem

$\text{PRVD}(\mathcal{S}_P)$ can be constructed $\Theta(n)$ time.



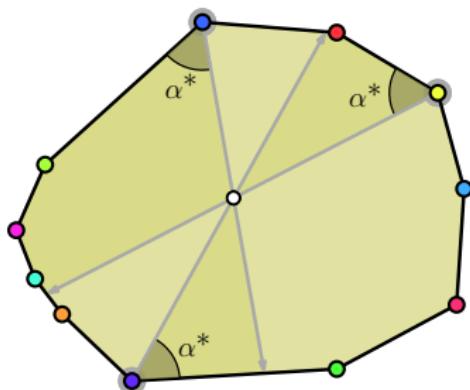
Brocard Illumination of P

1. Construct $\text{PRVD}(\mathcal{S}_P)$. $\Theta(n)$ time.
2. Traverse $\text{PRVD}(\mathcal{S}_P)$. $\Theta(n)$ time.

Finding the Brocard angle

Theorem

$\text{PRVD}(\mathcal{S}_P)$ can be constructed $\Theta(n)$ time.



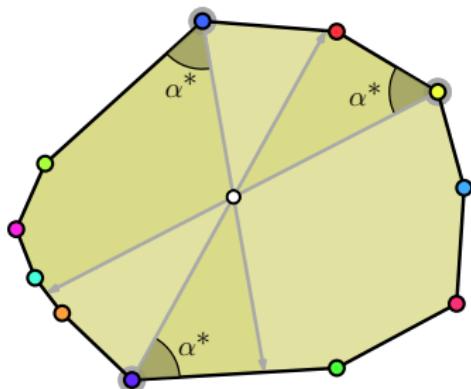
Brocard Illumination of P

1. Construct $\text{PRVD}(\mathcal{S}_P)$. $\Theta(n)$ time.
 2. Traverse $\text{PRVD}(\mathcal{S}_P)$. $\Theta(n)$ time.
- Three α^* -floodlights suffice.

Finding the Brocard angle

Theorem

$\text{PRVD}(\mathcal{S}_P)$ can be constructed $\Theta(n)$ time.



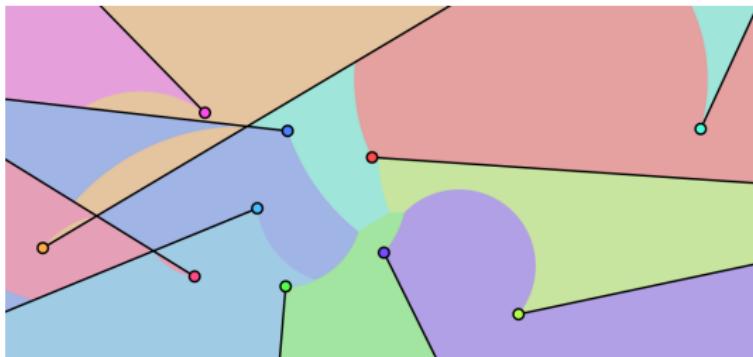
Brocard Illumination of P

1. Construct $\text{PRVD}(\mathcal{S}_P)$. $\Theta(n)$ time.
2. Traverse $\text{PRVD}(\mathcal{S}_P)$. $\Theta(n)$ time.
 - ▶ Three α^* -floodlights suffice.
 - ▶ $\alpha^* \in (0, \pi/2 - \pi/n]$.

Summary and open questions

Summary

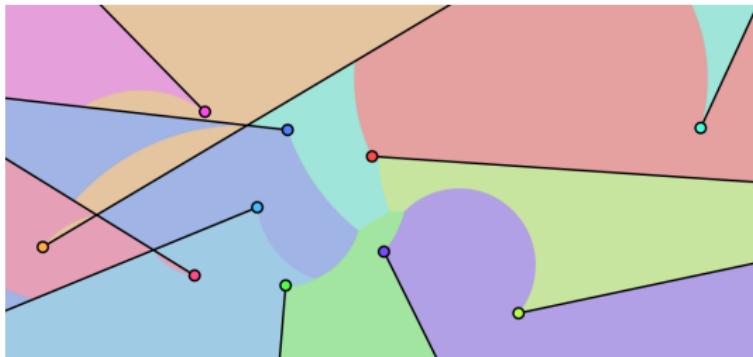
- ▶ RVD: definition, useful in Floodlight Illumination.
- ▶ RVD in \mathbb{R}^2 : properties, complexity & algorithm.
- ▶ Brocard Illumination of convex polygons: optimal $\Theta(n)$ time.



Summary and open questions

Summary

- ▶ RVD: definition, useful in Floodlight Illumination.
- ▶ RVD in \mathbb{R}^2 : properties, complexity & algorithm.
- ▶ Brocard Illumination of convex polygons: optimal $\Theta(n)$ time.



Open Questions

- ▶ Gap in the complexity of $\text{RVD}(\mathcal{S})$ in \mathbb{R}^2 : $\Omega(n^2) - O(n^{2+\epsilon})$
- ▶ Extend our approach to other classes of polygons.