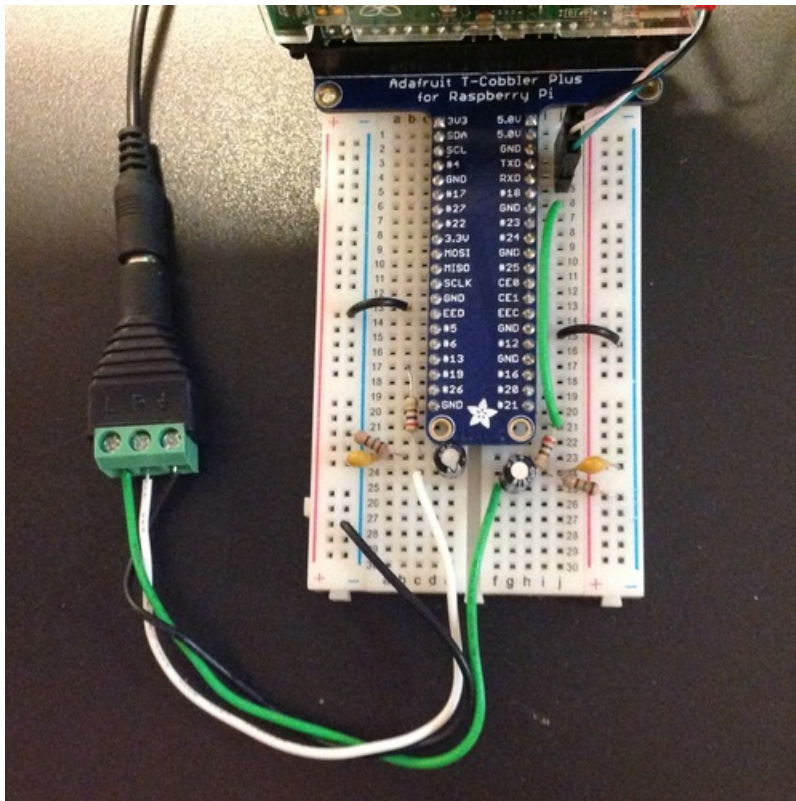


## Adding Basic Audio Output to Raspberry Pi Zero

Created by lady ada

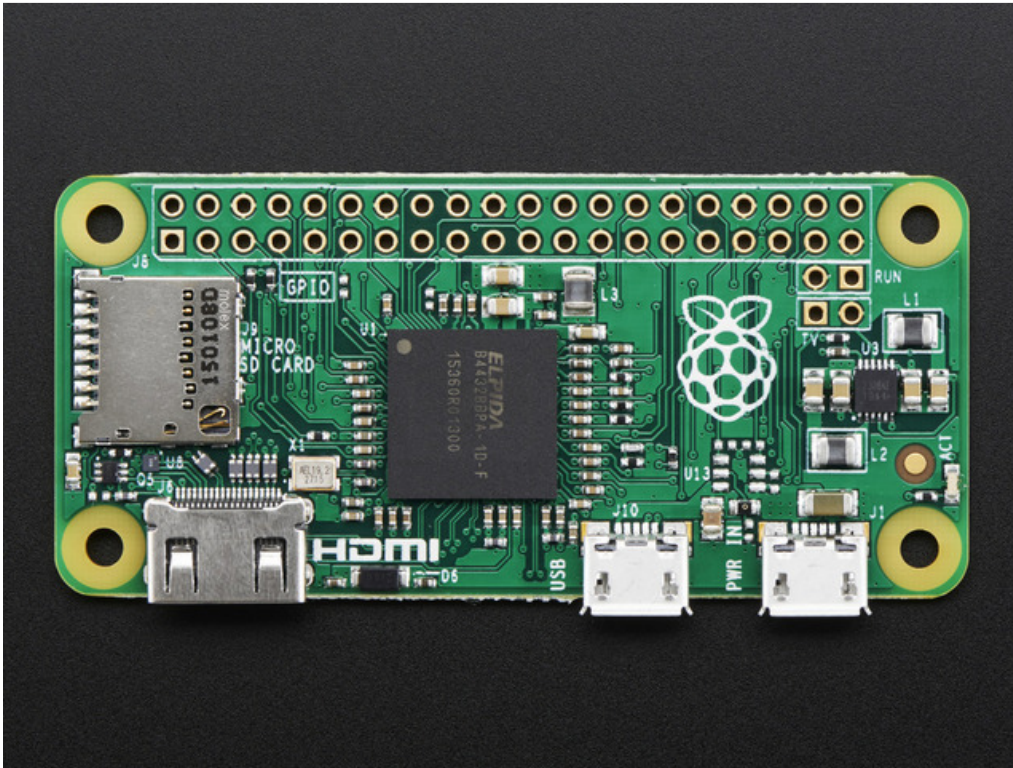


Last updated on 2018-08-22 03:51:12 PM UTC

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## Overview



To keep the Raspberry Pi Zero as low cost and small as possible, the Pi foundation didn't include a 3.5mm audio jack. There's also no breakout pads for the audio output. This made us a little :( at first but then we thought "hey you know, we can probably figure out how to get audio out with a little hacking!"

## How Audio Works on Other Pi Computers

The Broadcom chipset used for the Pi does not have a true analog output. Instead, two pins are PWM (pulse-width-modulated) at very high speeds, and filtered. The PWM frequency has to be at least 10x as high as the highest frequency we want to replicate in audio. Then, by adjusting the duty cycle of the PWM, we can 'fake' an audio signal.

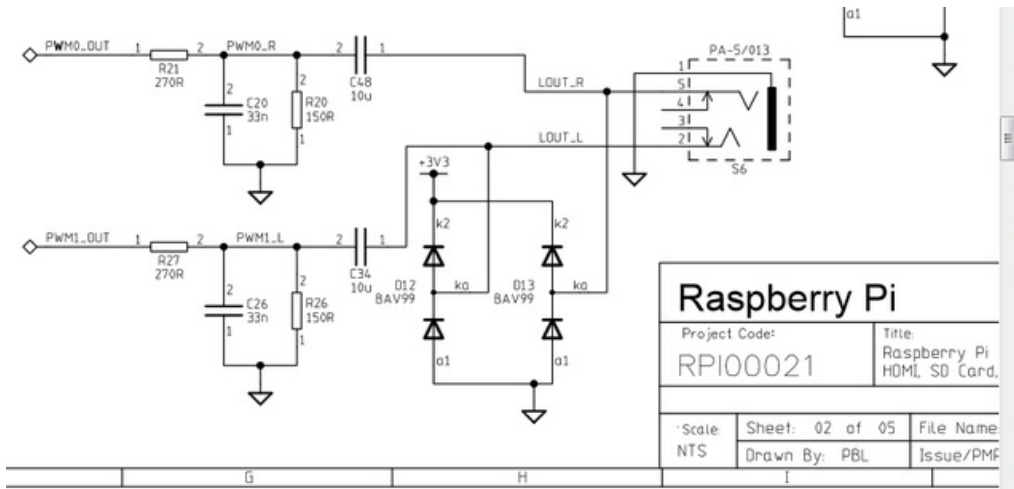
Audio is 20Hz to 20KHz, and the PWM output from the Pi is 50MHz so we can easily filter the high 50MHz out (and anyways it cant be heard).

Looking at the Pi B schematic, we can see **PWM0\_OUT** and **PWM1\_OUT** are the left and right channels. **R21** and **R20** are voltage dividers to get the 3.3V signal down to about 1.1V max (that's the max peak-to-peak voltage you want for audio line level).

**C20/C26** works with **R21/R27** to create an "RC low-pass filter". You can calculate the cut-off frequency with  $1/(2*\pi*RC) = 1/(2*\pi*270*33*10^{-9}) = 17865 \text{ Hz}$  which is pretty close to 20KHz!

**C48/C34** acts as a DC-filter capacitor, it only allows AC through - speakers and headphones don't like DC voltage!

Finally **BAV99** are ESD protection diodes. That's to protect the Pi from static coming in and zapping the PWM pins..



## Pi Zero PWM Audio

---

On the Pi Zero, we don't have pins **PWM0** (pin #40) and **PWM1** (pin #45)- those are not available on the PCB. That would normally be super :( but it turns out that while those pads are not exposed, we *can* re-route those signals to *other* pins that we can get to!

You can get to **PWM0** on GPIO #18 (ALT5) and **PWM1** on GPIO #13 (ALT0) or GPIO #19 (ALT5) - [see the full list of pins and alternate functions here \(https://adafru.it/jEa\)](https://adafru.it/jEa)

## Let's go!

---

Get started by burning and booting a Raspbian OS card in your Zero, we'll be using Raspbian Jessie. You don't need network connectivity to get this going but it's handy so if you can configure WiFi or Ethernet thru a USB adapter, do that too.

Then log into a command line console.

## Option 1. Use Device Tree Overlay

---

There's two options, the easy way is using a DTO which will set up all your pins and PWMs. However, we have not tested it.

The other way is to manually set the pin GPIO alt functions. We've tested it but it's more difficult!

Here's two DTO options that people have written in to suggest. The first uses a DTO that was recently added it seems:

1. *There is a much simpler way to configure the Pi GPIO pins for PWM audio. Simply adding the following line to your **/boot/config.txt** will reconfigure the pins at boot without any external software or services: `dtoverlay=pwm-2chan,pin=18,func=2,pin2=13,func2=4`*

Or, you can craft your own DTO

1. *Hi, I got the pwm audio working on my pi-zero, with an dtoverlay: <https://hackaday.io/project/9467-pigrrl-zero/log/35090-pi-zero-pwm-audio-device-tree-overlay> (<https://adafru.it/rIA>)*

Either way, if you use a DTO [you can skip down to the low pass wiring section \(https://adafru.it/rIB\)](https://adafru.it/rIB)

## Option 2. Manually Assigning PWM pins

---

This is how to manually set the pin functionality - you can do this if you want to set up the individual pins and usages

Before we start it's handy to [use wiringpi's gpio utility \(https://adafru.it/jWD\)](https://adafru.it/jWD) to list all the GPIO pins and their current set functions/alternates.

If you have network access, run **sudo apt-get update**

Then install it (in the off chance it isn't installed/updated) with **sudo apt-get install raspi-gpio**

On our Pi Zero, it didn't have a Zero-compatible version, and said "unable to determine board type". If you have network access, and can run **sudo apt-get update** and then the install line, this will likely fix it by grabbing a new version.

```
COM62 - PuTTY
pi@raspberrypi:~$ sudo apt-get install raspi-gpio
Reading package lists... Done
Building dependency tree
Reading state information... Done
raspi-gpio is already the newest version.
0 upgraded, 0 newly installed, 0 to remove and 0 not upgraded.
pi@raspberrypi:~$ gpio readall
Oops - unable to determine board type... model: 0
pi@raspberrypi:~$
```

However...I didn't have network access for my Pi and figured its worth documenting how to get around this. **sudo shutdown -h now** your Pi Zero, eject the SD card. Then on your desktop computer, [download the latest snapshot from the wiringPi Git repo \(https://adafru.it/jWF\)](https://adafru.it/jWF)

## Gordons Projects

--> [Projects Top-Level GIT](#)

### / [wiringPi](#) / summary

summary | [shortlog](#) | [log](#) | [commit](#) | [commitdiff](#) | [tree](#)

description wiringPi - A 'wiring' like library for the Raspberry Pi  
owner GIT  
last change Wed, 2 Dec 2015 10:13:50 -0500 (15:13 +0000)

#### shortlog

30 hours ago	Gordon Henderson	Bumped Version to 2.31 <a href="#">master</a> <a href="#">2.31</a>	<a href="#">commit</a>   <a href="#">commitdiff</a>   <a href="#">tree</a>   <a href="#">snapshot</a>
30 hours ago	Gordon Henderson	gpio readall didn't work on the Zero. This fixed that...	<a href="#">commit</a>   <a href="#">commitdiff</a>   <a href="#">tree</a>   <a href="#">snapshot</a>
4 days ago	Gordon Henderson	Updated wiringPi for the new Pi Zero. <a href="#">2.30</a>	<a href="#">commit</a>   <a href="#">commitdiff</a>   <a href="#">tree</a>   <a href="#">snapshot</a>
2015-09-30	Gordon Henderson	Fixing a few issues - makefile goofs. <a href="#">2.29</a>	<a href="#">commit</a>   <a href="#">commitdiff</a>   <a href="#">tree</a>   <a href="#">snapshot</a>
2015-09-24	Gordon Henderson	Fixed the requirement for -lm	<a href="#">commit</a>   <a href="#">commitdiff</a>   <a href="#">tree</a>   <a href="#">snapshot</a>
2015-09-20	Gordon Henderson	Updated the Debian build system thanks to Ian Jackson...	<a href="#">commit</a>   <a href="#">commitdiff</a>   <a href="#">tree</a>   <a href="#">snapshot</a>
2015-09-12	Ian Jackson	Introduce a proper Debian source package build system	<a href="#">commit</a>   <a href="#">commitdiff</a>   <a href="#">tree</a>   <a href="#">snapshot</a>

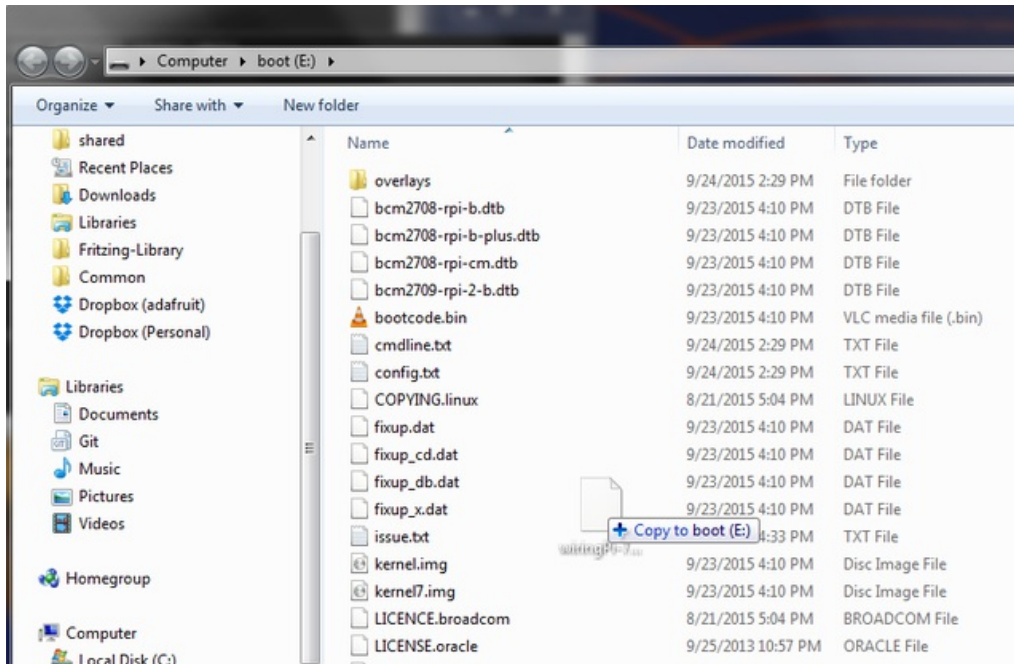
In case its not available, you can download it by clicking this button:

<https://adafru.it/jWF>

<https://adafru.it/jWF>

Transfer the file to the root directory of the Jessie SD card

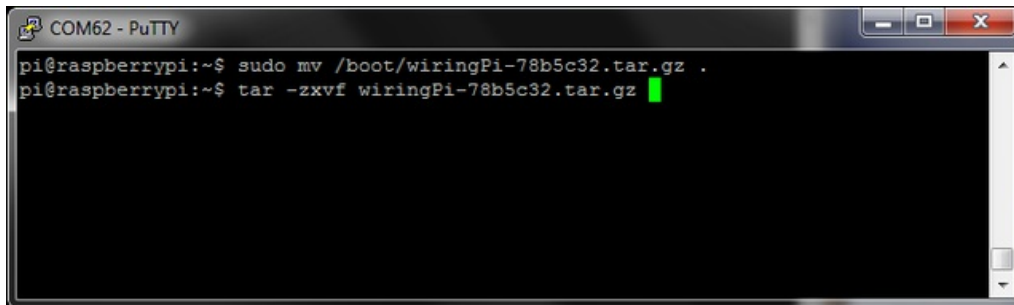




Re-boot your Pi Zero up, and get back to the command line. Then **mv** the file over and **un-tar** it

```
sudo mv /boot/wiringPi-78b5c32.tar.gz .
```

```
tar -zxvf wiringPi-78b5c32.tar.gz
```



then go into the uncompressed directory and run the compile/install script with

```
cd wiringPi-78b5c32.tar.gz
```

```
./build
```

```
COM62 - PuTTY
wiringPi-78b5c32/wiringPi/wpiExtensions.c
tar: wiringPi-78b5c32/wiringPi/wpiExtensions.c: time stamp 2015-12-02 15:13:50 is 5892151.193691 s in the future
wiringPi-78b5c32/wiringPi/wpiExtensions.h
tar: wiringPi-78b5c32/wiringPi/wpiExtensions.h: time stamp 2015-12-02 15:13:50 is 5892151.192715 s in the future
tar: wiringPi-78b5c32/wiringPi: time stamp 2015-12-02 15:13:50 is 5892151.192095 s in the future
tar: wiringPi-78b5c32: time stamp 2015-12-02 15:13:50 is 5892151.191786 s in the future
pi@raspberrypi:~$ cd wiringPi-78b5c32/
pi@raspberrypi:~/wiringPi-78b5c32$ ./build
wiringPi Build script
=====

WiringPi Library
make: Warning: File 'Makefile' has modification time 5892138 s in the future
[UnInstall]
make: warning: Clock skew detected. Your build may be incomplete.
make: Warning: File 'Makefile' has modification time 5892132 s in the future
[Compile] wiringPi.c
[Compile] wiringSerial.c
[Compile] wiringShift.c
[Compile] piHiPri.c
[Compile] piThread.c
[^[[2~[Compile] wiringPiI2C.c
[Compile] wiringPiSPI.c
```

```
COM62 - PuTTY
[Install Headers]
[Install Dynamic Lib]
make: warning: Clock skew detected. Your build may be incomplete.

GPIO Utility
make: Warning: File 'Makefile' has modification time 5892036 s in the future
[Compile] readall.c
[Compile] gpio.c
[Compile] pins.c
[Link]
make: warning: Clock skew detected. Your build may be incomplete.
make: Warning: File 'Makefile' has modification time 5892024 s in the future
[Compile] gpio.c
[Compile] readall.c
[Compile] pins.c
[Link]
[Install]
make: warning: Clock skew detected. Your build may be incomplete.

All Done.

NOTE: To compile programs with wiringPi, you need to add:
    -lwiringPi
to your compile line(s) To use the Gertboard, MaxDetect, etc.
code (the devLib), you need to also add:
    -lwiringPiDev
to your compile line(s).

pi@raspberrypi:~/wiringPi-78b5c32$
```

OK now you can run the updated version of **gpio** to read the states of all the pins:

```
gpio -v
```

(to make sure it works with the Pi Zero now, it should properly detect the board type)



```
COM62 - PuTTY
pi@raspberrypi:~/wiringPi-78b5c32$ gpio -v
gpio version: 2.31
Copyright (c) 2012-2015 Gordon Henderson
This is free software with ABSOLUTELY NO WARRANTY.
For details type: gpio -warranty

Raspberry Pi Details:
  Type: Pi Zero, Revision: 02, Memory: 512MB, Maker: Sony
  Device tree is enabled.
  This Raspberry Pi supports user-level GPIO access.
  -> See the man-page for more details
pi@raspberrypi:~/wiringPi-78b5c32$
```

gpio readall

```
COM62 - PuTTY
Device tree is enabled.
This Raspberry Pi supports user-level GPIO access.
-> See the man-page for more details
pi@raspberrypi:~/wiringPi-78b5c32$ gpio readall
+-----+-----+-----+-----+-----+-----+-----+-----+
| BCM | wPi |   Name   | Mode | V | Physical | V | Mode |   Name   | wPi | BCM |
+-----+-----+-----+-----+-----+-----+-----+-----+
| 2   | 8   | SDA.1    | IN    | 1 | 3   | 4   |      | 5V        |     |     |
| 3   | 9   | SCL.1    | IN    | 1 | 5   | 6   |      | 0V        |     |     |
| 4   | 7   | GPIO. 7  | IN    | 1 | 7   | 8   | 1    | ALT0 TxD  | 15  | 14  |
|     |     | 0V       |       |   | 9   | 10  | 1    | ALT0 RxD  | 16  | 15  |
| 17  | 0   | GPIO. 0  | IN    | 0 | 11  | 12  | 0    | IN GPIO. 1 | 1   | 18  |
| 27  | 2   | GPIO. 2  | IN    | 0 | 13  | 14  |      | 0V        |     |     |
| 22  | 3   | GPIO. 3  | IN    | 0 | 15  | 16  | 0    | IN GPIO. 4 | 4   | 23  |
|     |     | 3.3v     |       |   | 17  | 18  | 0    | IN GPIO. 5 | 5   | 24  |
| 10  | 12  | MOSI     | IN    | 0 | 19  | 20  |      | 0V        |     |     |
| 9   | 13  | MISO     | IN    | 0 | 21  | 22  | 0    | IN GPIO. 6 | 6   | 25  |
| 11  | 14  | SCLK     | IN    | 0 | 23  | 24  | 1    | IN CE0     | 10  | 8   |
|     |     | 0V       |       |   | 25  | 26  | 1    | IN CE1     | 11  | 7   |
| 0   | 30  | SDA.0    | IN    | 1 | 27  | 28  | 1    | IN SCL.0   | 31  | 1   |
| 5   | 21  | GPIO.21  | IN    | 1 | 29  | 30  |      | 0V        |     |     |
| 6   | 22  | GPIO.22  | IN    | 1 | 31  | 32  | 0    | IN GPIO.26 | 26  | 12  |
| 13  | 23  | GPIO.23  | IN    | 0 | 33  | 34  |      | 0V        |     |     |
| 19  | 24  | GPIO.24  | IN    | 0 | 35  | 36  | 0    | IN GPIO.27 | 27  | 16  |
| 26  | 25  | GPIO.25  | IN    | 0 | 37  | 38  | 0    | IN GPIO.28 | 28  | 20  |
|     |     | 0V       |       |   | 39  | 40  | 0    | IN GPIO.29 | 29  | 21  |
+-----+-----+-----+-----+-----+-----+-----+-----+
| BCM | wPi |   Name   | Mode | V | Physical | V | Mode |   Name   | wPi | BCM |
+-----+-----+-----+-----+-----+-----+-----+-----+
+-----+-----+-----+-----+-----+-----+-----+-----+
pi@raspberrypi:~/wiringPi-78b5c32$
```

The table has a *ton* of information going on. What you want to look for is BCM pins #18 and #13

```

COM62 - PuTTY
Device tree is enabled.
This Raspberry Pi supports user-level GPIO access.
-> See the man-page for more details
pi@raspberrypi:~/wiringPi-78b5c32$ gpio readall
+-----+-----+-----+-----+Pi Zero-----+-----+-----+
| BCM | wPi |   Name   | Mode | V | Physical | V | Mode |   Name   | wPi | BCM |
+-----+-----+-----+-----+-----+-----+-----+
| 2 | 8 | SDA.1 | IN | 1 | 3 | 4 | | 5v | 15 | 14 | |
| 3 | 9 | SCL.1 | IN | 1 | 5 | 6 | | 5V | 16 | 15 |
| 4 | 7 | GPIO. 7 | IN | 1 | 7 | 8 | 1 | ALT0 | TxD | 15 | 14 |
| | | 0v | | 9 | 10 | 1 | ALT0 | RxD | 16 | 15 |
| 17 | 0 | GPIO. 0 | IN | 0 | 11 | 12 | 0 | IN | GPIO. 1 | 1 | 18 |
| 27 | 2 | GPIO. 2 | IN | 0 | 13 | 14 | | 0v | | |
| 22 | 3 | GPIO. 3 | IN | 0 | 15 | 16 | 0 | IN | GPIO. 4 | 4 | 23 |
| | | 3.3v | | 17 | 18 | 0 | IN | GPIO. 5 | 5 | 24 |
| 10 | 12 | MOSI | IN | 0 | 19 | 20 | | 0v | | |
| 9 | 13 | MISO | IN | 0 | 21 | 22 | 0 | IN | GPIO. 6 | 6 | 25 |
| 11 | 14 | SCLK | IN | 0 | 23 | 24 | 1 | IN | CE0 | 10 | 8 |
| | | 0v | | 25 | 26 | 1 | IN | CE1 | 11 | 7 |
| 0 | 30 | SDA.0 | IN | 1 | 27 | 28 | 1 | IN | SCL.0 | 31 | 1 |
| 5 | 21 | GPIO.21 | IN | 1 | 29 | 30 | | 0v | | |
| 6 | 22 | GPIO.22 | IN | 1 | 31 | 32 | 0 | IN | GPIO.26 | 26 | 12 |
| 13 | 23 | GPIO.23 | IN | 0 | 33 | 34 | | 0v | | |
| 19 | 24 | GPIO.24 | IN | 0 | 35 | 36 | 0 | IN | GPIO.27 | 27 | 16 |
| 26 | 25 | GPIO.25 | IN | 0 | 37 | 38 | 0 | IN | GPIO.28 | 28 | 20 |
| | | 0v | | 39 | 40 | 0 | IN | GPIO.29 | 29 | 21 |
+-----+-----+-----+-----+Pi Zero-----+-----+-----+
| BCM | wPi |   Name   | Mode | V | Physical | V | Mode |   Name   | wPi | BCM |
+-----+-----+-----+-----+-----+-----+-----+
pi@raspberrypi:~/wiringPi-78b5c32$

```

As you can see, these two pins have **MODE** type **IN** - that means they are just plain inputs. You can see that pins like **TxD** and **RxD** are 'ALT0', that's the built in serial console.

Anyways, time to change these pins!

## Changing the GPIO ALTs

We can manually tweak the GPIO ALTs using a very handy tool by TimG in the Pi forums (<https://adafru.it/jEc>)

Here's the code in entirety:

```

/*
Utility to switch Raspberry-Pi GPIO pin functions
Tim Giles 01/04/2013

Usage:
$ gpio_alt -p PIN_NUMBER -f ALT_NUMBER

Based on RPi code from Dom and Gert, 15-Feb-2013, <http://elinux.org/RPi_Low-level_peripherals#C_2>
and Gnu getopt() example <http://www.gnu.org/software/libc/manual/html_node/Example-of-Getopt.html#Ex
*/

#include <ctype.h>
#include <stdio.h>
#include <stdlib.h>
#include <unistd.h>
#include <fcntl.h>
#include <sys/mman.h>

```

```

#define BCM2708_PERI_BASE      0x20000000
#define GPIO_BASE              (BCM2708_PERI_BASE + 0x200000) /* GPIO controller */
#define PAGE_SIZE (4*1024)
#define BLOCK_SIZE (4*1024)

int mem_fd;
void *gpio_map;
volatile unsigned *gpio;
void setup_io();

// GPIO setup macros. Always use INP_GPIO(x) before using OUT_GPIO(x) or SET_GPIO_ALT(x,y)
#define INP_GPIO(g) *(gpio+((g)/10)) &= ~(7<<(((g)%10)*3))
#define OUT_GPIO(g) *(gpio+((g)/10)) |= (1<<(((g)%10)*3))
#define SET_GPIO_ALT(g,a) *(gpio+(((g)/10))) |= (((a)<=3?(a)+4:(a)==4?3:2)<<(((g)%10)*3))

#define GPIO_SET *(gpio+7)  // sets   bits which are 1 ignores bits which are 0
#define GPIO_CLR *(gpio+10) // clears bits which are 1 ignores bits which are 0

int main (int argc, char **argv) {
    int opt, flag, n_pin, n_alt;
    flag=0;

    while ((opt = getopt (argc, argv, "hp:f:")) != -1) {
        switch (opt) {
            case 'h':
                break;
            case 'p':
                n_pin = atoi(optarg); flag |= 0b0001; break;
            case 'f':
                n_alt = atoi(optarg); flag |= 0b0010; break;
            case '?':
                // getopt() prints error messages, so don't need to repeat them here
                return 1;
            default:
                abort ();
        }
    }

    if (flag != 0b0011) {
        fprintf (stderr, "Usage:\n$ gpio_alt -p PIN_NUM -f FUNC_NUM\n");
        return 1;
    }

    setup_io(); // Set up gpi pointer for direct register access
    INP_GPIO(n_pin); // Always use INP_GPIO(x) before using SET_GPIO_ALT(x,y)
    SET_GPIO_ALT(n_pin, n_alt);

    printf("Set pin %i to alternative-function %i\n", n_pin, n_alt);

    return 0;
}

void setup_io() {
    /* open /dev/mem */
    if ((mem_fd = open("/dev/mem", O_RDWR|O_SYNC) ) < 0) {

```

```

        printf("can't open /dev/mem \n");
        exit(-1);
    }

    /* mmap GPIO */
    gpio_map = mmap(
        NULL,                //Any address in our space will do
        BLOCK_SIZE,          //Map length
        PROT_READ|PROT_WRITE, // Enable reading & writing to mapped memory
        MAP_SHARED,           //Shared with other processes
        mem_fd,               //File to map
        GPIO_BASE             //Offset to GPIO peripheral
    );

    close(mem_fd); //No need to keep mem_fd open after mmap

    if (gpio_map == MAP_FAILED) {
        printf("mmap error %d\n", (int)gpio_map); //errno also set!
        exit(-1);
    }

    // Always use volatile pointer!
    gpio = (volatile unsigned *)gpio_map;
}

```

On your Pi Zero, create a new file and edit it with

**nano gpio\_alt.c**

(it doesnt matter what directory you are in)

Then paste in the entire code above

```

COM62 - PuTTY
GNU nano 2.2.6 File: gpio_alt.c Modified

    close(mem_fd); //No need to keep mem_fd open after mmap

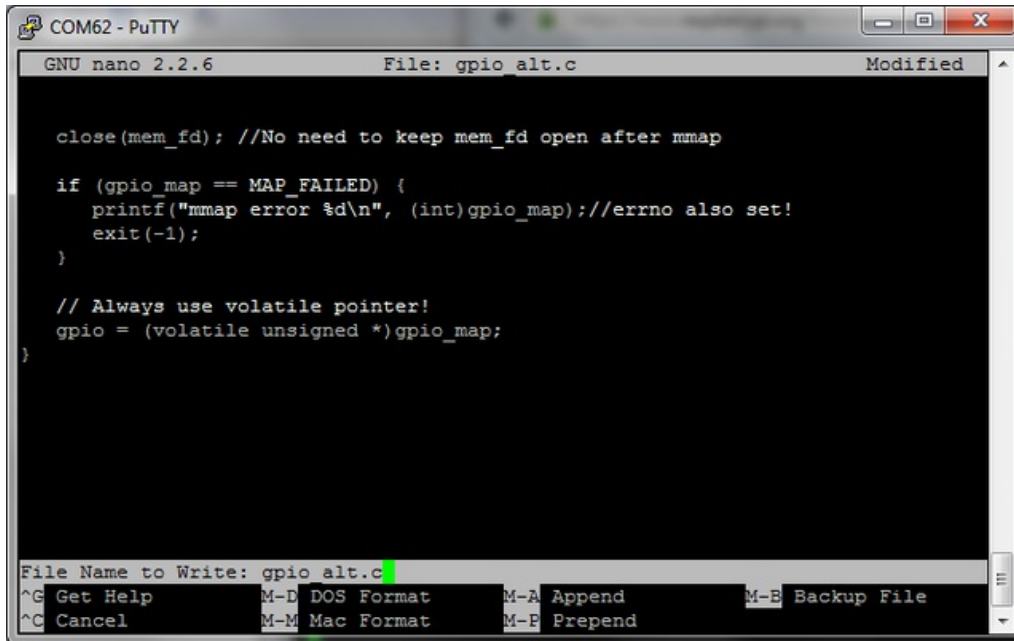
    if (gpio_map == MAP_FAILED) {
        printf("mmap error %d\n", (int)gpio_map); //errno also set!
        exit(-1);
    }

    // Always use volatile pointer!
    gpio = (volatile unsigned *)gpio_map;
}

```

^G Get Help   ^O WriteOut   ^R Read File   ^Y Prev Page   ^K Cut Text   ^C Cur Pos  
 ^X Exit   ^J Justify   ^W Where Is   ^V Next Page   ^U UnCut Text   ^T To Spell

Save it...



```
COM62 - PuTTY
GNU nano 2.2.6      File: gpio_alt.c      Modified

close(mem_fd); //No need to keep mem_fd open after mmap

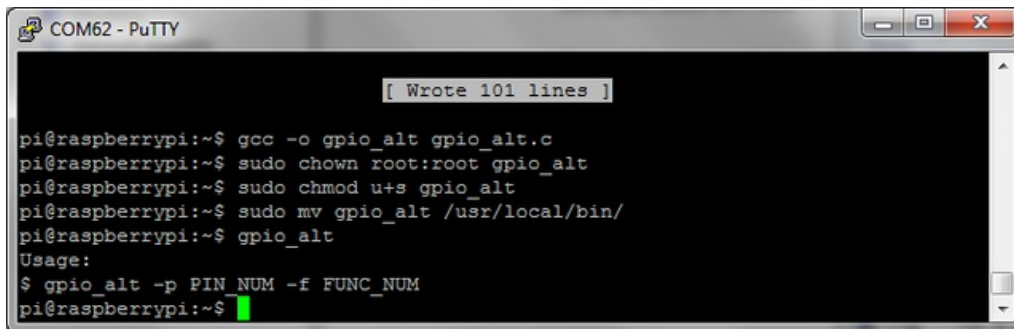
if (gpio_map == MAP_FAILED) {
    printf("mmap error %d\n", (int)gpio_map);//errno also set!
    exit(-1);
}

// Always use volatile pointer!
gpio = (volatile unsigned *)gpio_map;
}

File Name to Write: gpio_alt.c
^G Get Help      M-D DOS Format    M-A Append      M-B Backup File
^C Cancel        M-M Mac Format    M-P Prepend
```

Compile it & install with

```
gcc -o gpio_alt gpio_alt.c
sudo chown root:root gpio_alt
sudo chmod u+s gpio_alt
sudo mv gpio_alt /usr/local/bin/
```



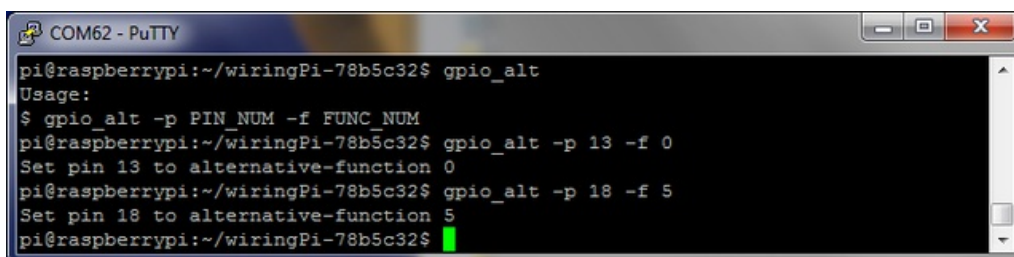
```
COM62 - PuTTY
[ Wrote 101 lines ]

pi@raspberrypi:~$ gcc -o gpio_alt gpio_alt.c
pi@raspberrypi:~$ sudo chown root:root gpio_alt
pi@raspberrypi:~$ sudo chmod u+s gpio_alt
pi@raspberrypi:~$ sudo mv gpio_alt /usr/local/bin/
pi@raspberrypi:~$ gpio_alt
Usage:
$ gpio_alt -p PIN_NUM -f FUNC_NUM
pi@raspberrypi:~$
```

Now you can set the **ALT** functions of the two GPIO!

```
gpio_alt -p 13 -f 0
```

```
gpio_alt -p 18 -f 5
```



```
COM62 - PuTTY

pi@raspberrypi:~/wiringPi-78b5c32$ gpio_alt
Usage:
$ gpio_alt -p PIN_NUM -f FUNC_NUM
pi@raspberrypi:~/wiringPi-78b5c32$ gpio_alt -p 13 -f 0
Set pin 13 to alternative-function 0
pi@raspberrypi:~/wiringPi-78b5c32$ gpio_alt -p 18 -f 5
Set pin 18 to alternative-function 5
pi@raspberrypi:~/wiringPi-78b5c32$
```

Sweet. Now go back to wiringPi to check that we did it!



```

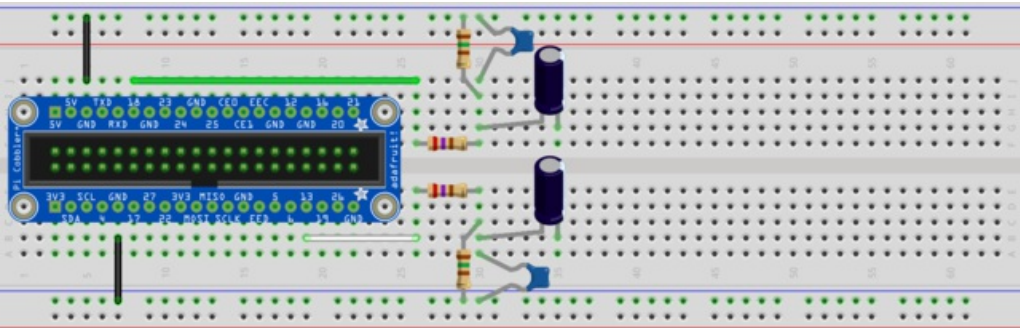
COM62 - PuTTY
Set pin 13 to alternative-function 0
pi@raspberrypi:~/wiringPi-78b5c32$ gpio_alt -p 18 -f 5
Set pin 18 to alternative-function 5
pi@raspberrypi:~/wiringPi-78b5c32$ gpio readall
+-----+-----+-----+-----+-----+-----+-----+-----+-----+-----+
| BCM | wPi |   Name   | Mode | V | Physical | V | Mode | Name   | wPi | BCM |
+-----+-----+-----+-----+-----+-----+-----+-----+-----+-----+
| 2   | 8   | SDA.1    | IN    | 1 | 3   | 4   |      | 5V     |     |     | |
| 3   | 9   | SCL.1    | IN    | 1 | 5   | 6   |      | 0v     |     |     |
| 4   | 7   | GPIO. 7   | IN    | 1 | 7   | 8   | 0    | ALT0   | TxD  | 15  | 14  |
|     |     | 0v       |       |   | 9   | 10  | 1    | ALT0   | RxD  | 16  | 15  |
| 17  | 0   | GPIO. 0   | IN    | 0 | 11  | 12  | 0    | ALT5   | GPIO. 1 | 1  | 18  |
| 27  | 2   | GPIO. 2   | IN    | 0 | 13  | 14  |      | 0v     |     |     |
| 22  | 3   | GPIO. 3   | IN    | 0 | 15  | 16  | 0    | IN     | GPIO. 4 | 4  | 23  |
|     |     | 3.3v     |       |   | 17  | 18  | 0    | IN     | GPIO. 5 | 5  | 24  |
| 10  | 12  | MOSI     | IN    | 0 | 19  | 20  |      | 0v     |     |     |
| 9   | 13  | MISO     | IN    | 0 | 21  | 22  | 0    | IN     | GPIO. 6 | 6  | 25  |
| 11  | 14  | SCLK     | IN    | 0 | 23  | 24  | 1    | IN     | CE0    | 10  | 8   |
|     |     | 0v       |       |   | 25  | 26  | 1    | IN     | CE1    | 11  | 7   |
| 0   | 30  | SDA.0    | IN    | 1 | 27  | 28  | 1    | IN     | SCL.0  | 31  | 1   |
| 5   | 21  | GPIO.21  | IN    | 1 | 29  | 30  |      | 0v     |     |     |
| 6   | 22  | GPIO.22  | IN    | 1 | 31  | 32  | 0    | IN     | GPIO.26 | 26  | 12  |
| 13  | 23  | GPIO.23  | ALT0  | 0 | 33  | 34  |      | 0v     |     |     |
| 19  | 24  | GPIO.24  | IN    | 0 | 35  | 36  | 0    | IN     | GPIO.27 | 27  | 16  |
| 26  | 25  | GPIO.25  | IN    | 0 | 37  | 38  | 0    | IN     | GPIO.28 | 28  | 20  |
|     |     | 0v       |       |   | 39  | 40  | 0    | IN     | GPIO.29 | 29  | 21  |
+-----+-----+-----+-----+-----+-----+-----+-----+-----+-----+
| BCM | wPi |   Name   | Mode | V | Physical | V | Mode | Name   | wPi | BCM |
+-----+-----+-----+-----+-----+-----+-----+-----+-----+-----+
pi@raspberrypi:~/wiringPi-78b5c32$

```

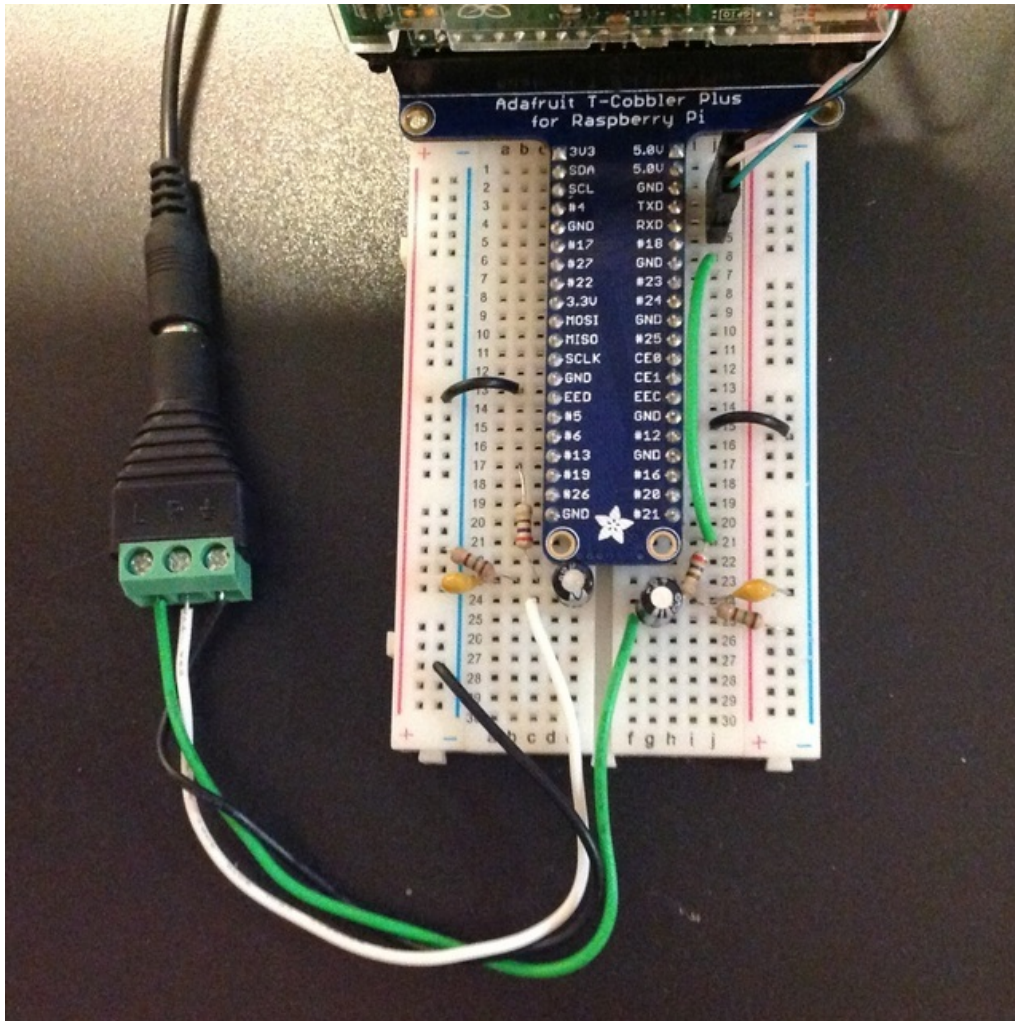
Yep! You can see the new ALT settings.

### Low Pass Filter Wiring

Now wire up the schematic to GPIO #13 as **PWM1** and #18 **PWM0** on a breadboard. You can skip the diodes. If you don't have the exact values it's ok. I built it with a 10nF capacitor (0.01uF) rather than 33nF and it worked just fine (the cutoff frequency is higher but the speakers dont hear those high frequencies anyways)



fritzing



<https://adafru.it/qlF>

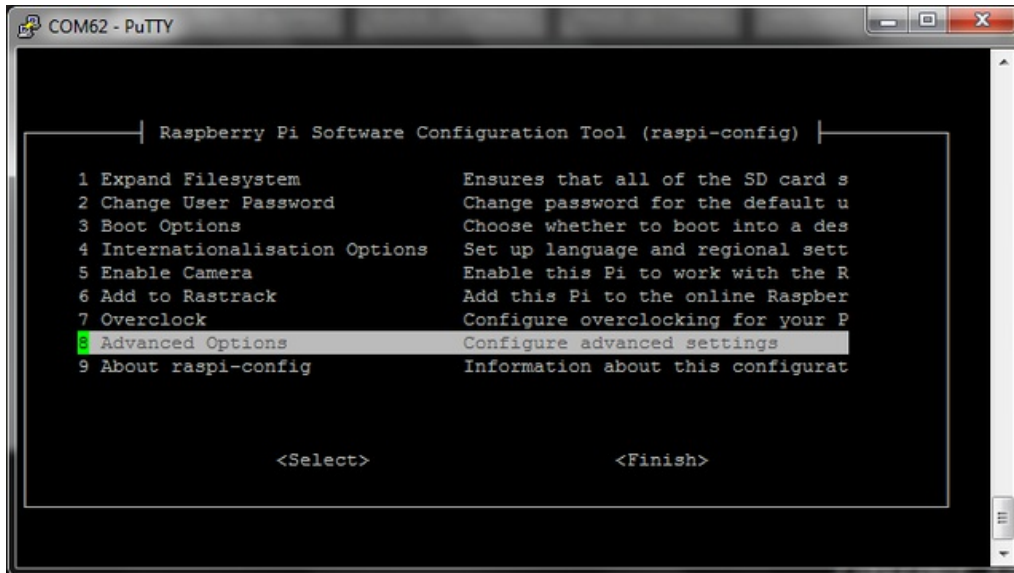
<https://adafru.it/qlF>

I'm using a 3.5mm audio jack terminal block (<http://adafru.it/2791>) to wire up the left & right channels + ground.

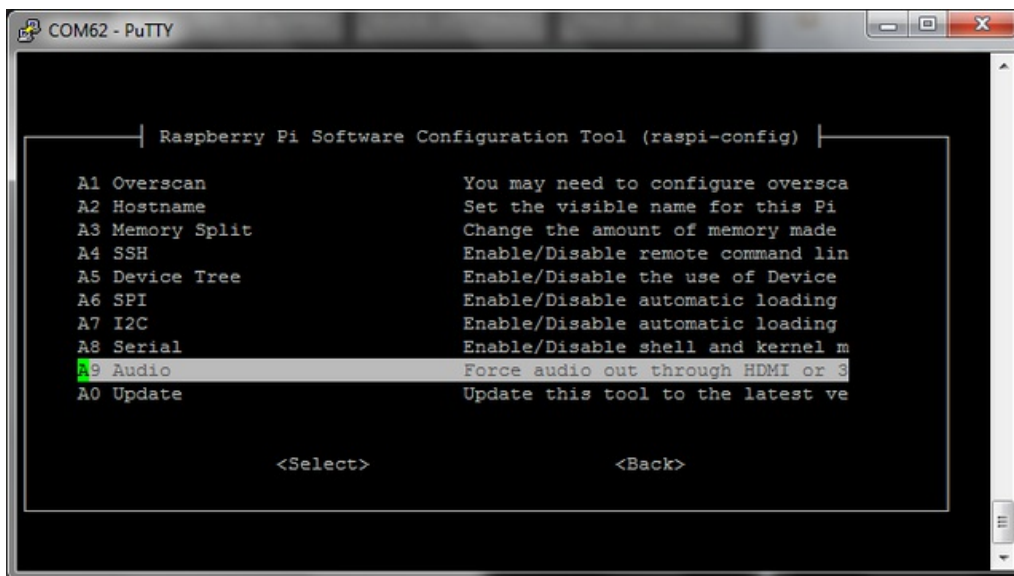
## Set Audio Output

You'll also want to 'fix' the Pi so the audio is definitely getting piped out the 'headphone jack' (PWM output) rather than HDMI. From the console run **sudo raspi-config**

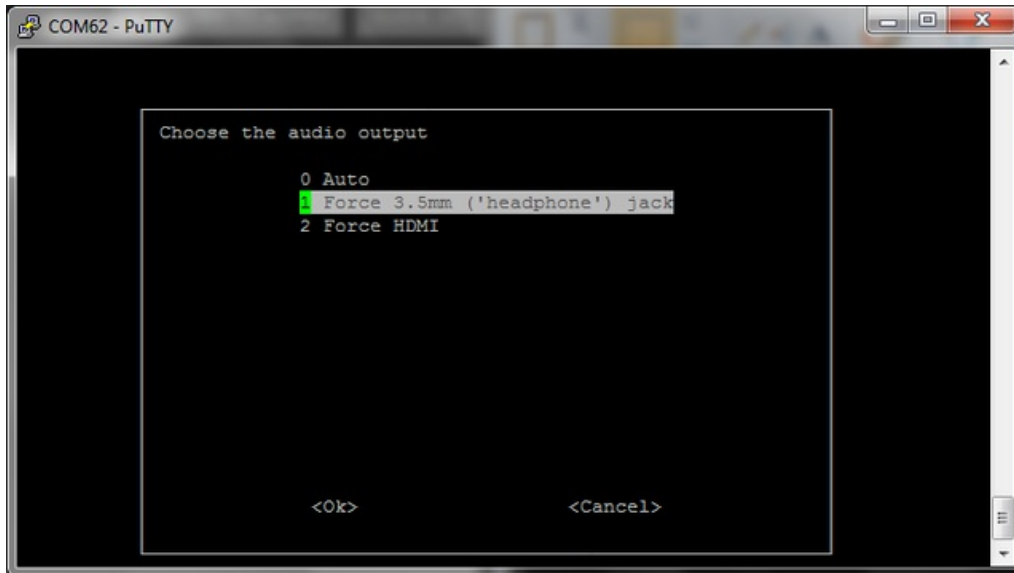
Go to **Advanced**



Then Audio



Finally Force 3.5mm (Headphone)

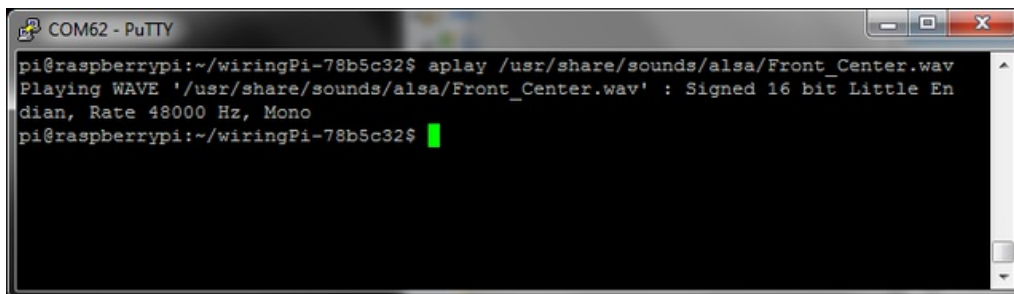


You only have to do this once, you can hit return and then **Finish** to exit

## First Test

You can now play audio! Plug in powered speakers or headphones. We will use the built in **aplay** audio player. Run

```
aplay /usr/share/sounds/alsa/Front_Center.wav
```



You should hear audio!

## Adjusting Volume

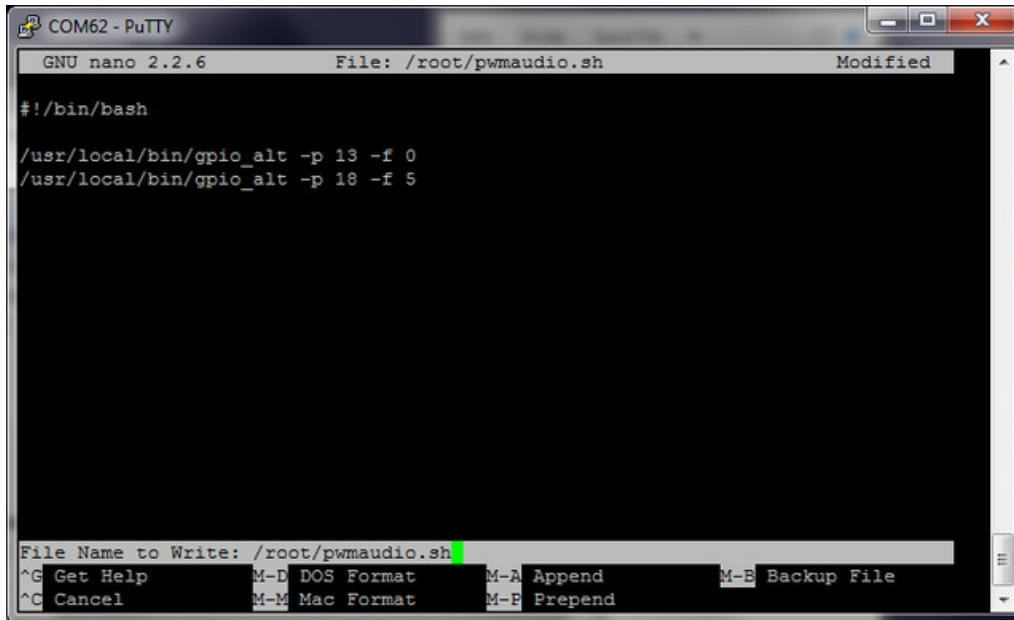
You may notice a bit of hum, or maybe its just not very loud. To get the best quality audio, you'll want to have the audio level out of the Pi be as high as possible. You can do this with **alsamixer** which is easier in my opinion than **amixer** although both work.

On my terminal the ascii art is a bit tough to read, just press the **up arrow** until the volume is at 100% Then you can hit **Esc** to save & quit









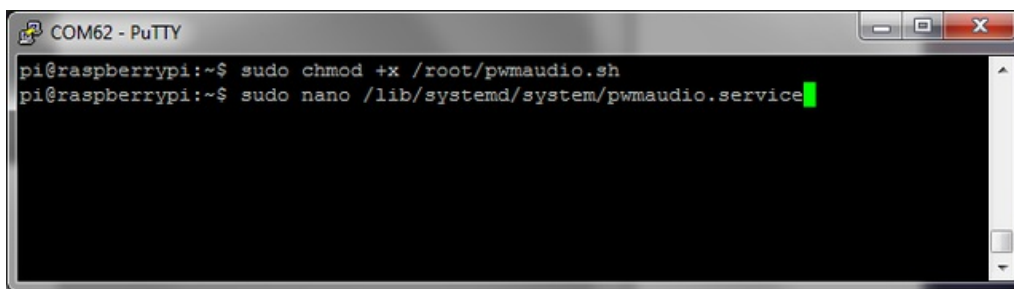
```
COM62 - PuTTY
GNU nano 2.2.6      File: /root/pwmaudio.sh      Modified

#!/bin/bash

/usr/local/bin/gpio_alt -p 13 -f 0
/usr/local/bin/gpio_alt -p 18 -f 5

File Name to Write: /root/pwmaudio.sh
^G Get Help      M-D DOS Format    M-A Append      M-B Backup File
^C Cancel        M-M Mac Format    M-E Prepend
```

run `sudo chmod +x /root/pwmaudio.sh` and then create *another* script with `sudo nano /lib/systemd/system/pwmaudio.service`



```
COM62 - PuTTY

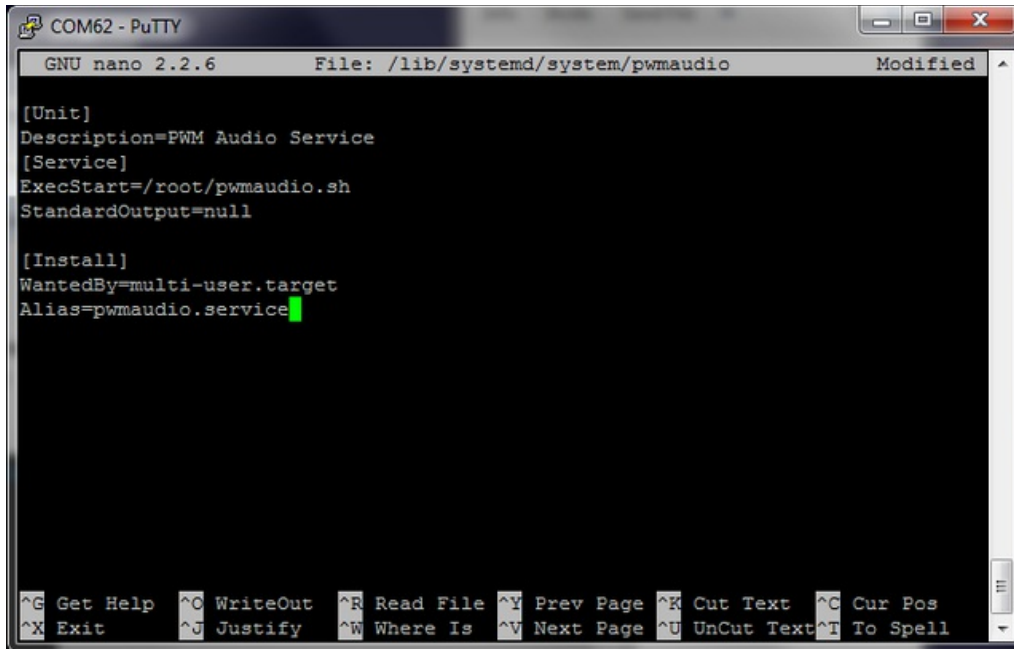
pi@raspberrypi:~$ sudo chmod +x /root/pwmaudio.sh
pi@raspberrypi:~$ sudo nano /lib/systemd/system/pwmaudio.service
```

and in there stick:

```
[Unit]
Description=PWM Audio Service

[Service]
ExecStart=/root/pwmaudio.sh
StandardOutput=null

[Install]
WantedBy=multi-user.target
Alias=pwmaudio.service
```



A screenshot of a terminal window titled "COM62 - PuTTY". Inside, the GNU nano 2.2.6 text editor is open, editing the file `/lib/systemd/system/pwmaudio`. The file content is as follows:

```
[Unit]
Description=PWM Audio Service
[Service]
ExecStart=/root/pwmaudio.sh
StandardOutput=null

[Install]
WantedBy=multi-user.target
Alias=pwmaudio.service
```

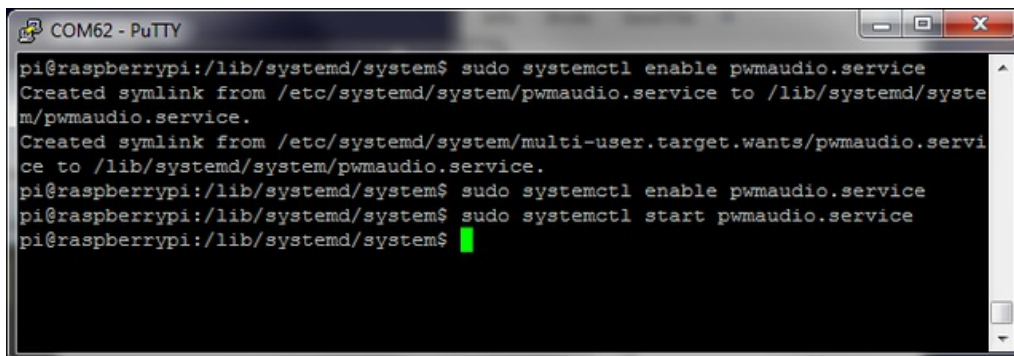
The cursor is at the end of the `Alias=pwmaudio.service` line. The bottom status bar shows various keyboard shortcuts like `^G Get Help`, `^O WriteOut`, etc.

save the file. Now enable the service with

```
sudo systemctl enable pwmaudio.service
```

and test-start the service with

```
sudo systemctl start pwmaudio.service
```



A screenshot of a terminal window titled "COM62 - PuTTY" showing the execution of systemctl commands on a Raspberry Pi. The prompt is `pi@raspberrypi:/lib/systemd/system$`. The commands and their outputs are:

```
pi@raspberrypi:/lib/systemd/system$ sudo systemctl enable pwmaudio.service
Created symlink from /etc/systemd/system/pwmaudio.service to /lib/systemd/system/pwmaudio.service.
Created symlink from /etc/systemd/system/multi-user.target.wants/pwmaudio.service to /lib/systemd/system/pwmaudio.service.
pi@raspberrypi:/lib/systemd/system$ sudo systemctl enable pwmaudio.service
pi@raspberrypi:/lib/systemd/system$ sudo systemctl start pwmaudio.service
pi@raspberrypi:/lib/systemd/system$
```

Reboot the pi (`sudo reboot`) and re-log in. You can run the `gpio readall` commands to verify that the alts are set

```
COM62 - PuTTY
pi@raspberrypi:/lib/systemd/system$ gpio readall
+-----+-----+-----+-----+-----+-----+-----+-----+-----+-----+
| BCM | wPi |   Name   | Mode | V | Physical | V | Mode |   Name   | wPi | BCM |
+-----+-----+-----+-----+-----+-----+-----+-----+-----+-----+
|     |     |   3.3v   |      |   | 1 || 2 |      |   5v     |     |     | |
|  2  |  8  |  SDA.1   |  IN  | 1 | 3 || 4 |      |  5V      |     |     |
|  3  |  9  |  SCL.1   |  IN  | 1 | 5 || 6 |      |  0v      |     |     |
|  4  |  7  | GPIO. 7   |  IN  | 1 | 7 || 8 |  0  |  ALT0    | TxD   | 15  | 14  |
|     |     |   0v     |      |   | 9 ||10 |  1  |  ALT0    | RxD   | 16  | 15  |
| 17  |  0  | GPIO. 0   |  IN  | 0 |11 ||12 |  0  |  ALT5    | GPIO. 1 | 1  | 18  |
| 27  |  2  | GPIO. 2   |  IN  | 0 |13 ||14 |      |  0v      |     |     |
| 22  |  3  | GPIO. 3   |  IN  | 0 |15 ||16 |  0  |  IN      | GPIO. 4 | 4  | 23  |
|     |     |   3.3v   |      |   |17 ||18 |  0  |  IN      | GPIO. 5 | 5  | 24  |
| 10  | 12  |  MOSI    |  IN  | 0 |19 ||20 |      |  0v      |     |     |
|  9  | 13  |  MISO    |  IN  | 0 |21 ||22 |  0  |  IN      | GPIO. 6 | 6  | 25  |
| 11  | 14  |  SCLK    |  IN  | 0 |23 ||24 |  1  |  IN      | CE0    |10  |  8  |
|     |     |   0v     |      |   |25 ||26 |  1  |  IN      | CE1    |11  |  7  |
|  0  | 30  |  SDA.0   |  IN  | 1 |27 ||28 |  1  |  IN      | SCL.0   |31  |  1  |
|  5  | 21  | GPIO.21   |  IN  | 1 |29 ||30 |      |  0v      |     |     |
|  6  | 22  | GPIO.22   |  IN  | 1 |31 ||32 |  0  |  IN      | GPIO.26 |26  | 12  |
| 13  | 23  | GPIO.23   |  ALT0 | 0 |33 ||34 |      |  0v      |     |     |
| 19  | 24  | GPIO.24   |  IN  | 0 |35 ||36 |  0  |  IN      | GPIO.27 |27  | 16  |
| 26  | 25  | GPIO.25   |  IN  | 0 |37 ||38 |  0  |  IN      | GPIO.28 |28  | 20  |
|     |     |   0v     |      |   |39 ||40 |  0  |  IN      | GPIO.29 |29  | 21  |
+-----+-----+-----+-----+-----+-----+-----+-----+-----+-----+
| BCM | wPi |   Name   | Mode | V | Physical | V | Mode |   Name   | wPi | BCM |
+-----+-----+-----+-----+-----+-----+-----+-----+-----+-----+
pi@raspberrypi:/lib/systemd/system$
```

That's it! You're done, enjoy :)