

# IMPROVING A MODEL OF HUMAN PLANNING VIA LARGE-SCALE DATA AND DEEP NEURAL NETWORKS

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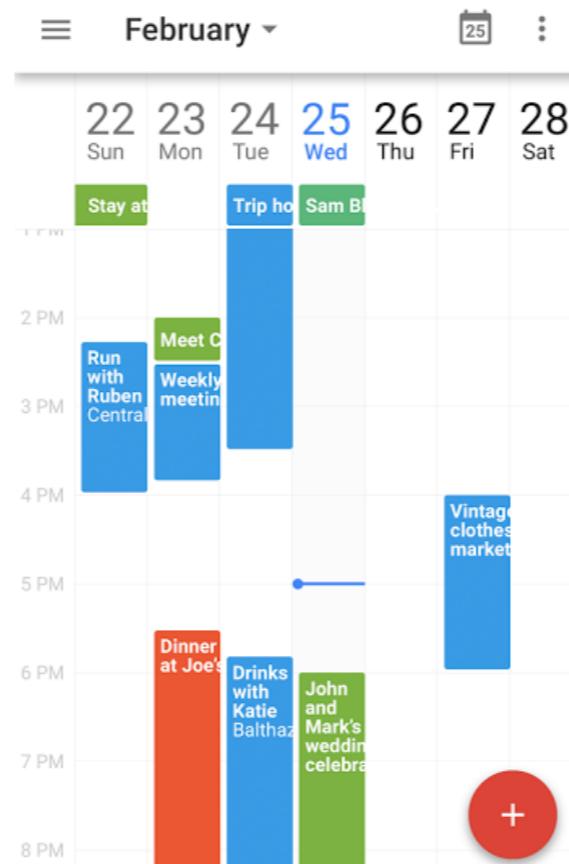


# How do people think ahead?

# Planning: mental simulation of possible futures



Foraging

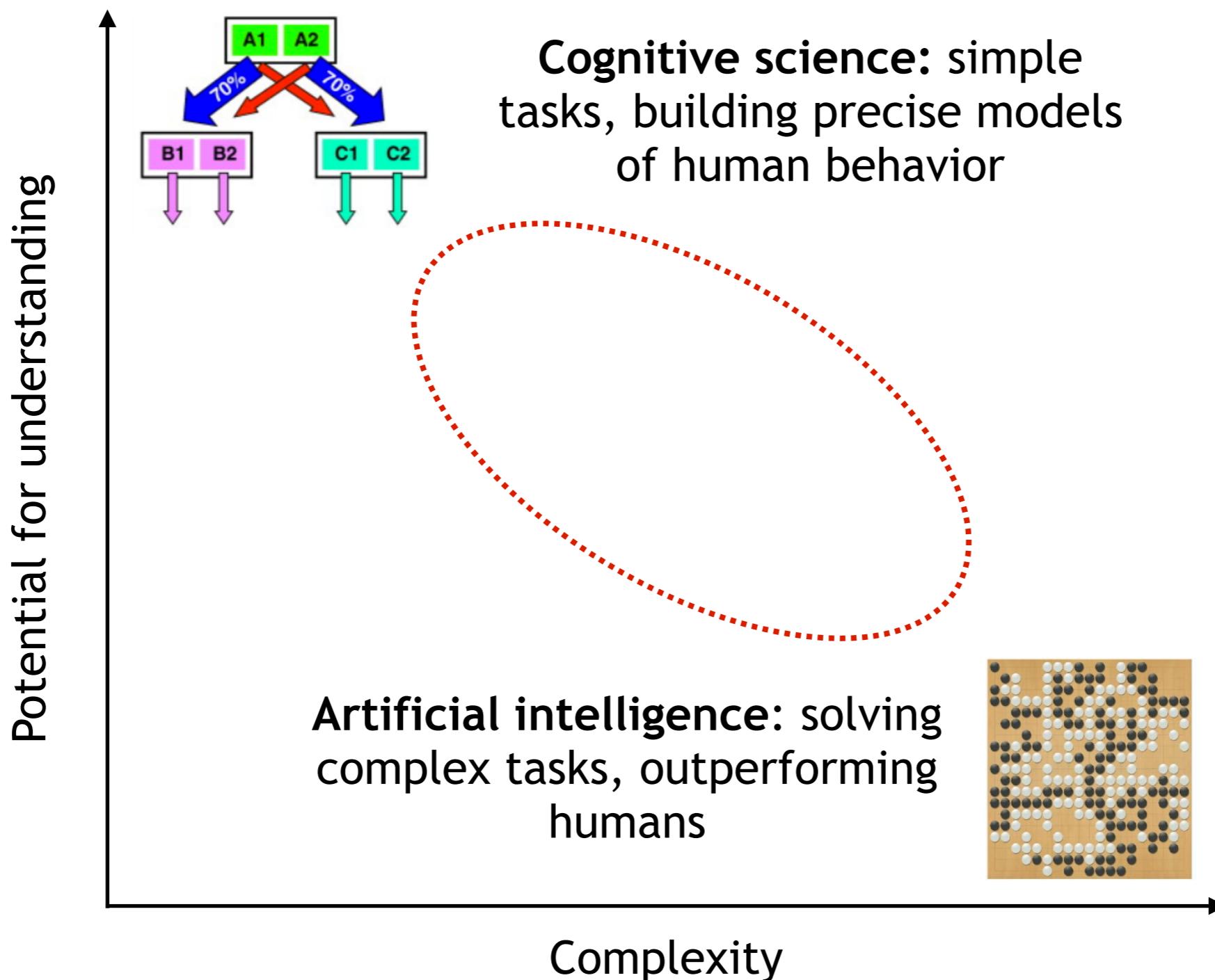


Organizational  
strategy



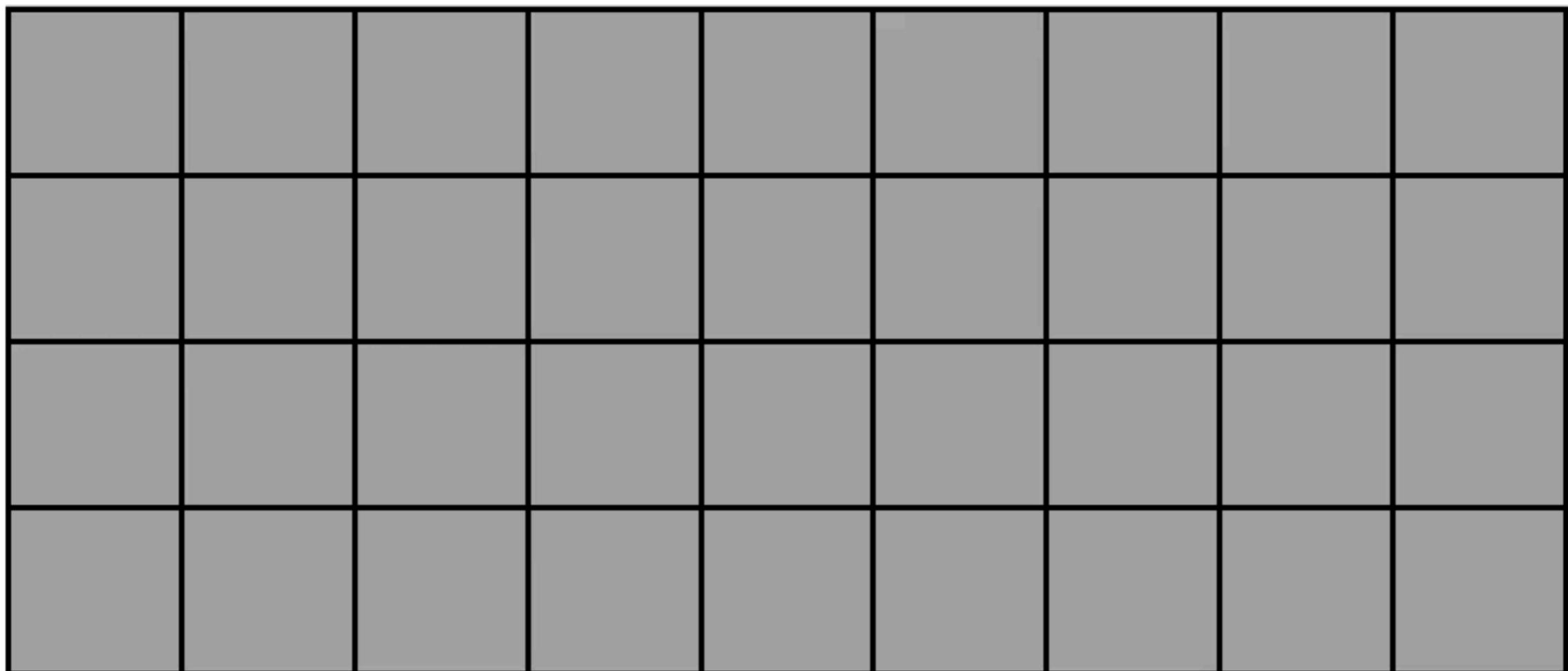
Spatial navigation

# SPACE OF PLANNING TASKS



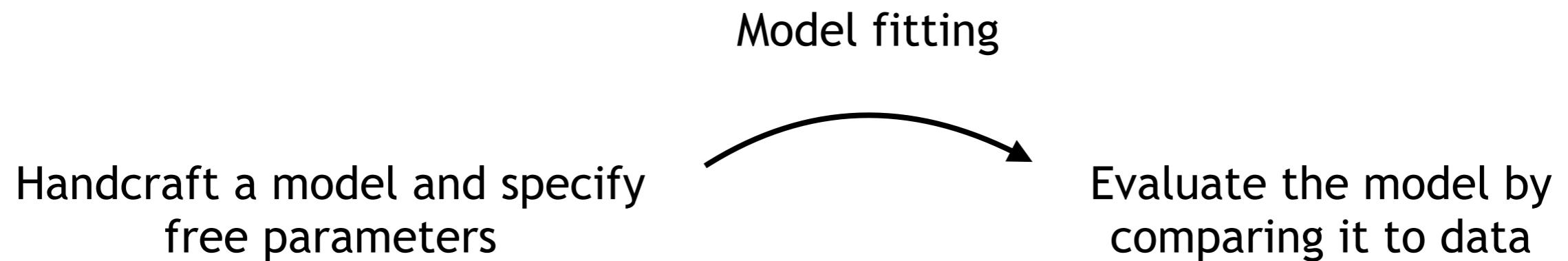
# 4-IN-A-ROW

In the lab, we developed a combinatorial planning task of **intermediate complexity** with high potential for modeling human behavior



van Opheusden, Galbiati, Kuperwajs, Bnaya, Li, Ma, *PsyArxiv*, 2021

# THE STANDARD APPROACH TO COMPUTATIONAL MODELING

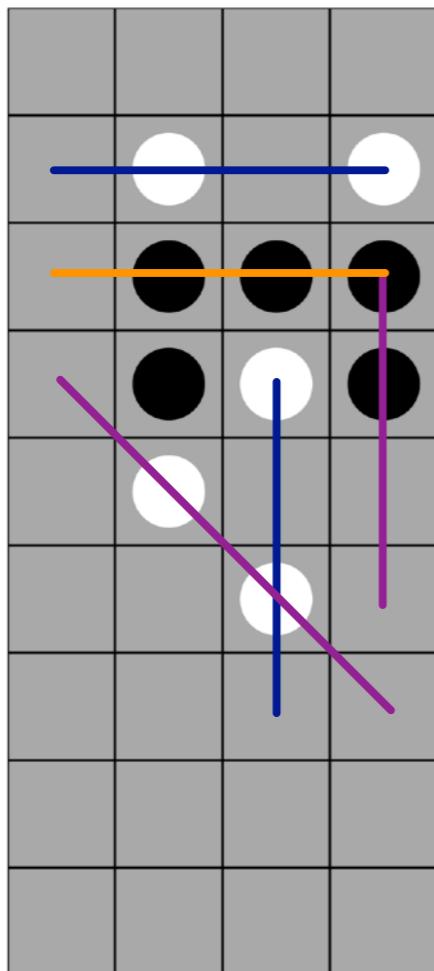


# A MODEL OF HUMAN PLANNING

Heuristic value function + decision tree search

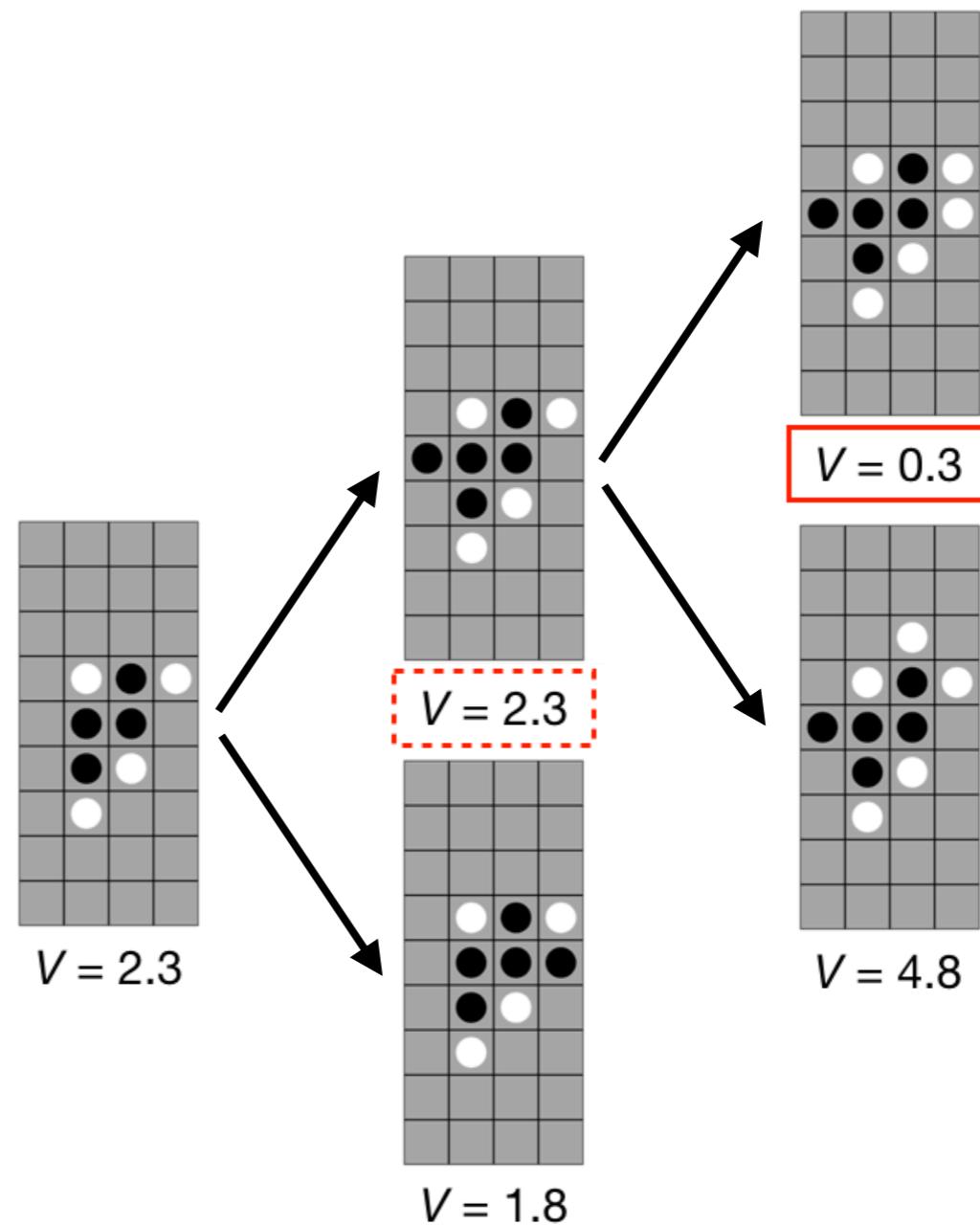
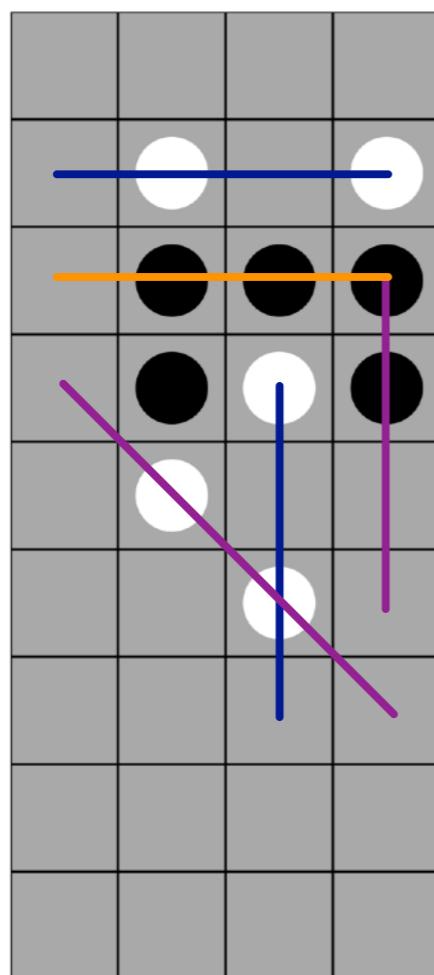
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Heuristic value function + decision tree search

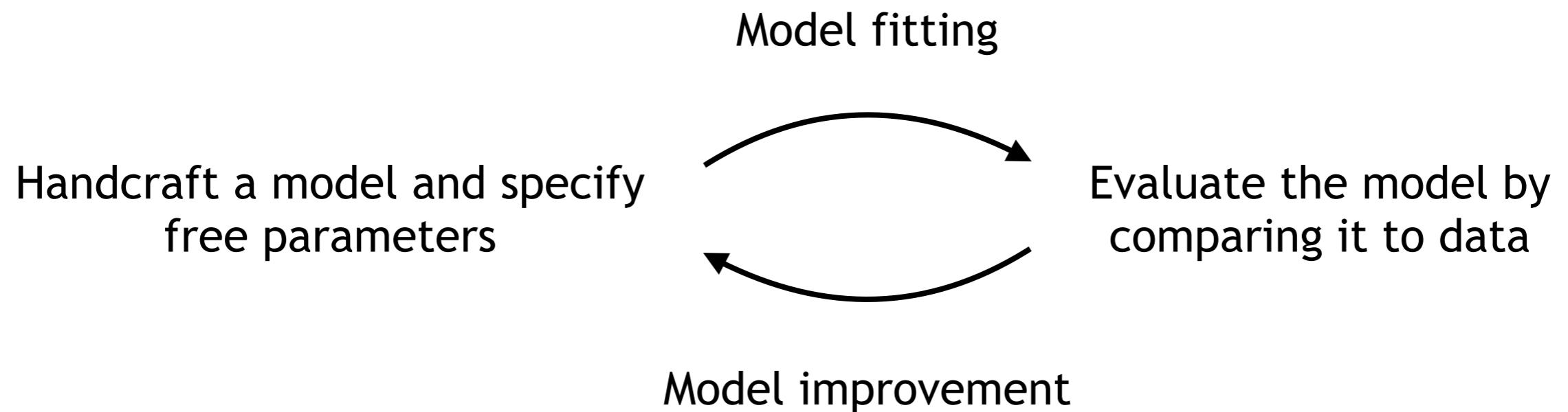


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Heuristic value function + decision tree search

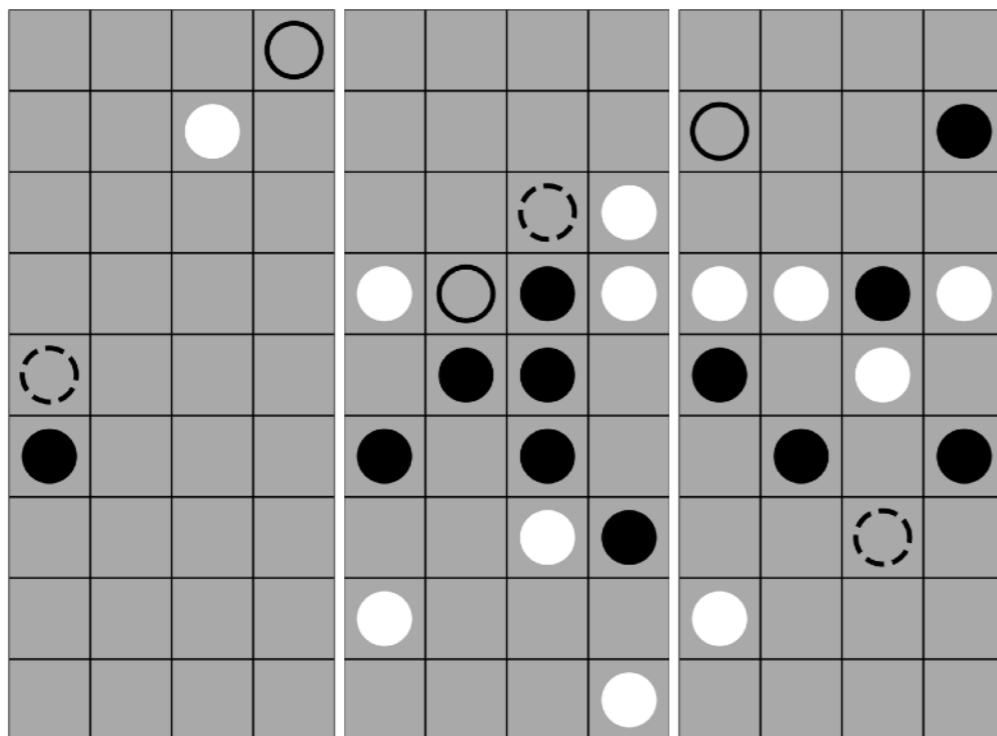


# THE STANDARD APPROACH TO COMPUTATIONAL MODELING



# MODEL IMPROVEMENT WITH DATA

One sensible approach is to iteratively amend the model to reduce fitting errors by looking at the largest errors the model makes



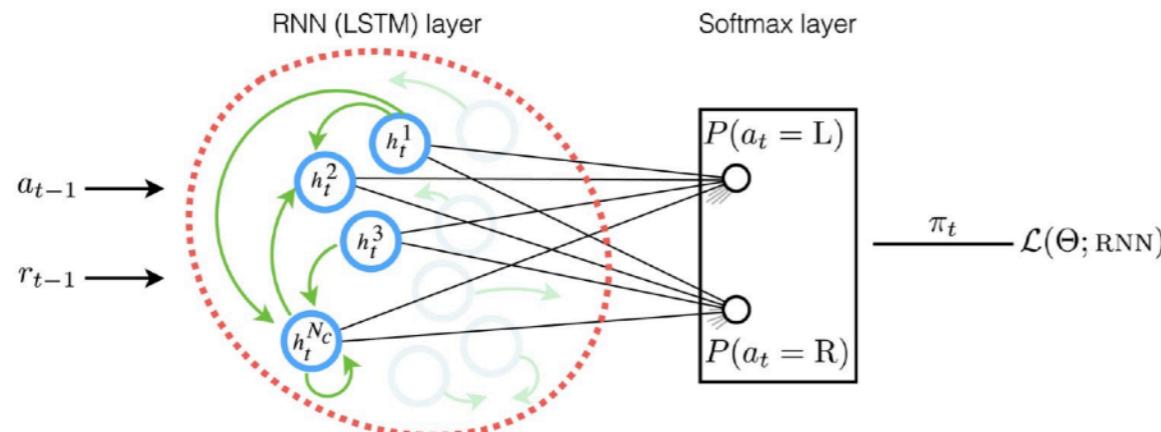
- human move
- planning model's prediction

When directly comparing between a model and data, we don't know how much of the *unexplained variance* is *unexplainable*

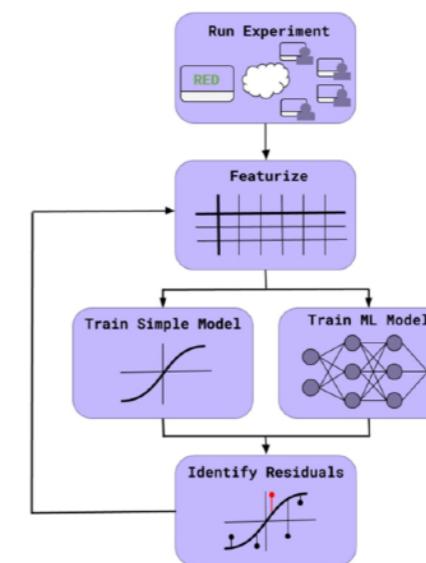
# NEURAL NETWORKS AS A BENCHMARK FOR MODELING

A powerfully predictive model trained to predict human behavior can be used to establish the absolute goodness of fit of a model

- Deep neural networks make minimal assumptions and have the capacity to represent virtually any computational process
- The network can detect patterns in the data without human understanding
- After training, a model can be compared to the network to judge whether there is still room for model improvement and in which situations to do so
- By pooling information across trials, the network is a less noisy representation of the data



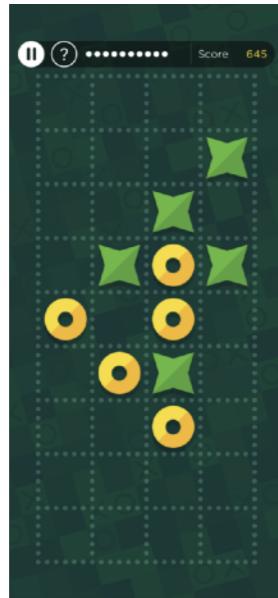
Dezfouli et al., 2019



Agrawal et al., 2020

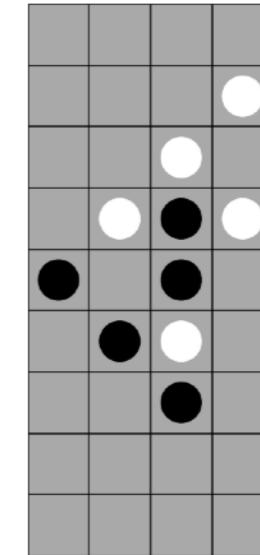
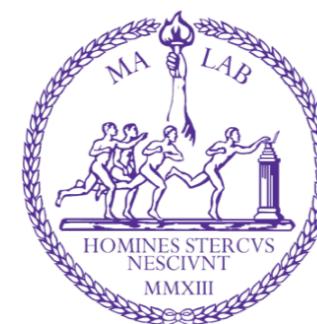
Training deep neural networks requires large-scale data

# SCALING UP 4-IN-A-ROW



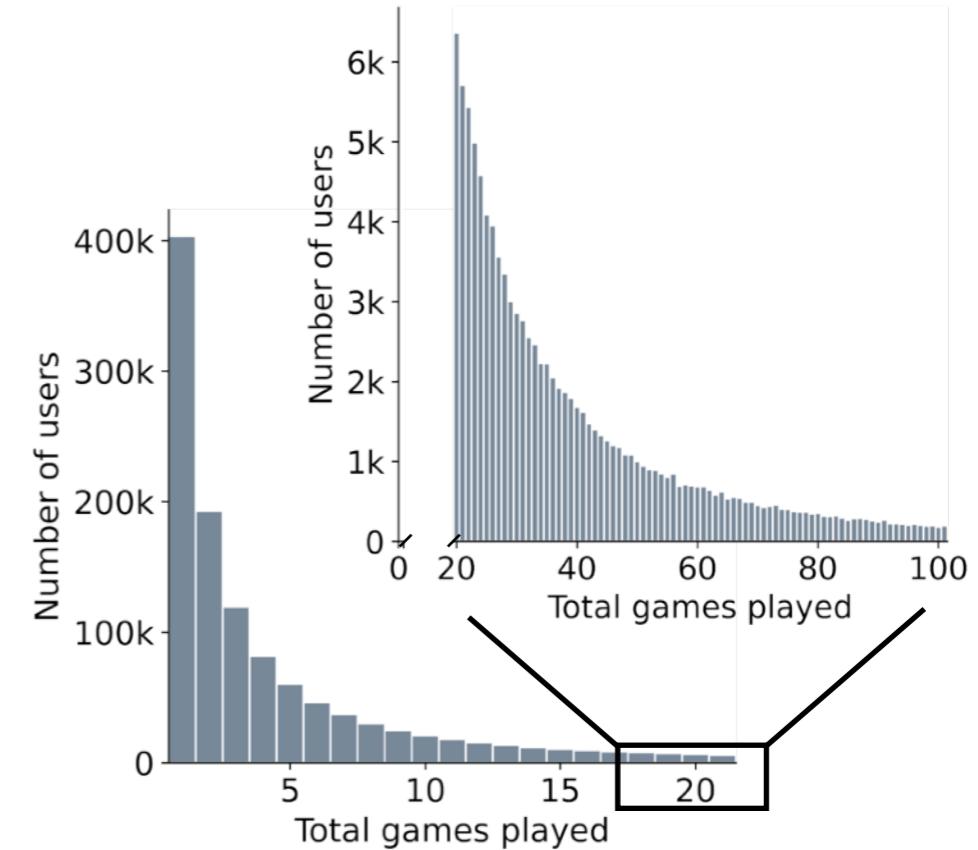
Game development  
Anonymized data

Task specification  
AI opponents



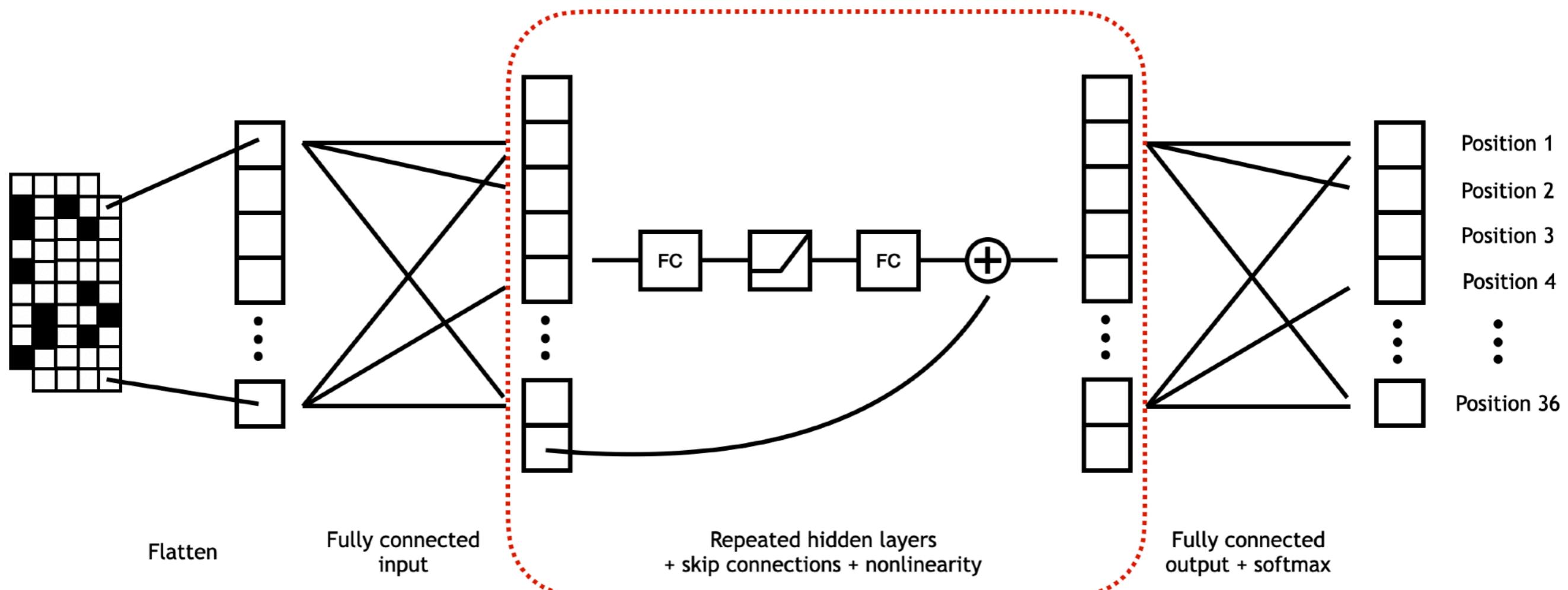
## Features of the data set:

- Human vs. AI games
- User always plays first
- ~10.8 million games
- ~1.2 million unique users
- ~1.5 million new games/month



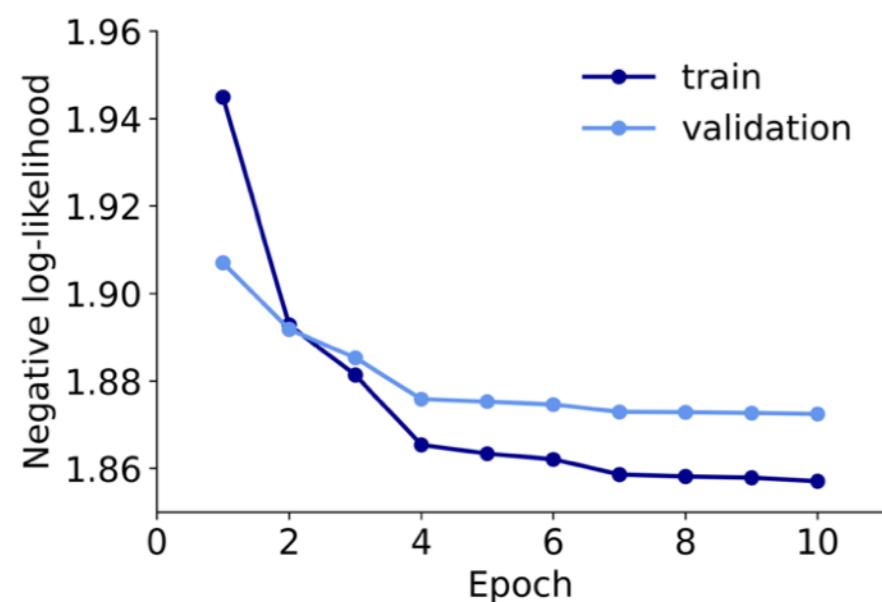
# PREDICTING HUMAN PLAY IN 4-IN-A-ROW

What architecture should we use to **estimate a noise ceiling** in 4-in-a-row and **find patterns** in the data that previous models have missed?

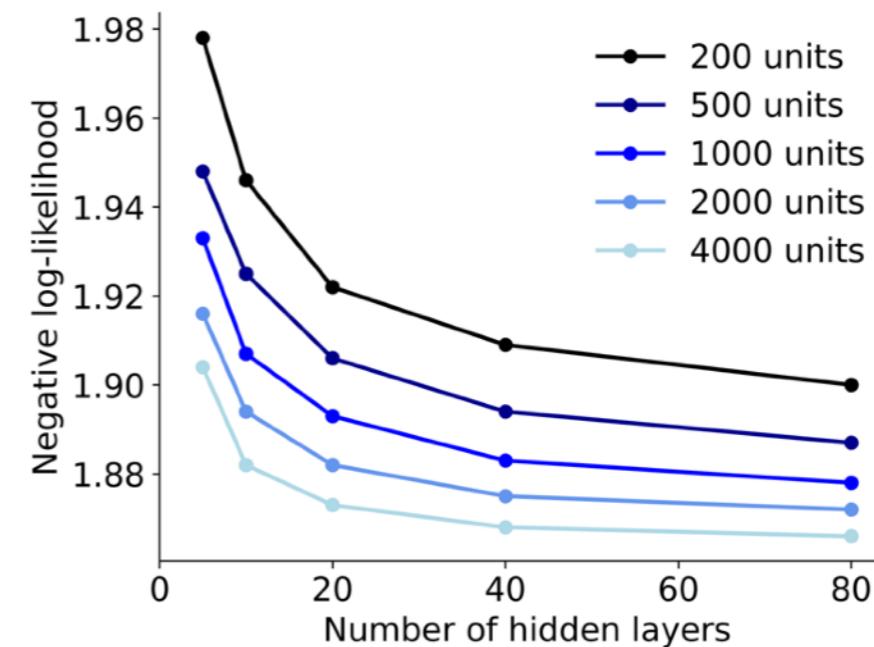


# NETWORK TRAINING

- Split into train (90%), validation (5%), and test (5%) sets
- Stochastic gradient descent
- Learning rate annealing and early stopping
- No concerns about overfitting with large-scale data



Learning curve for the best network

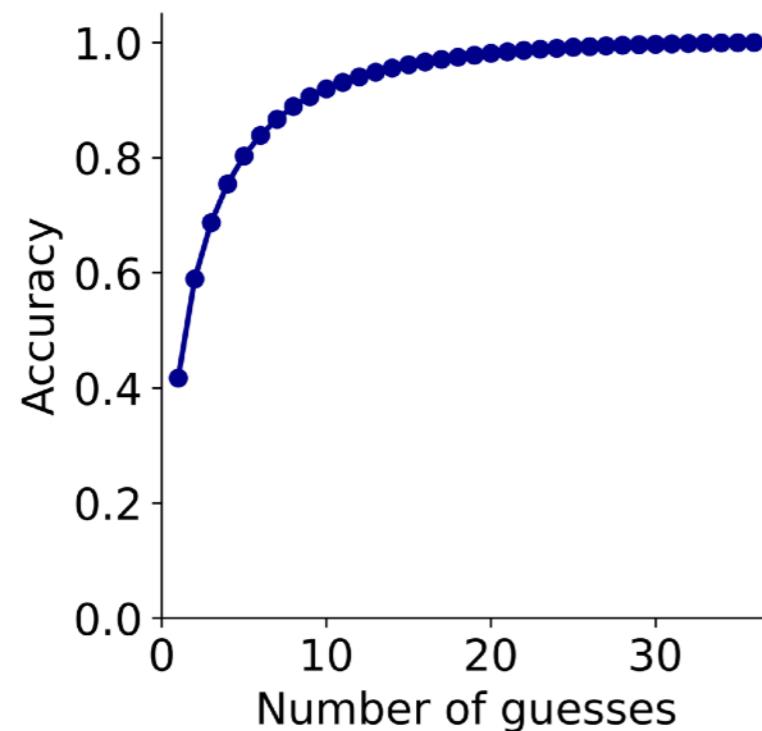


Scaling up the network

# NETWORK EVALUATION

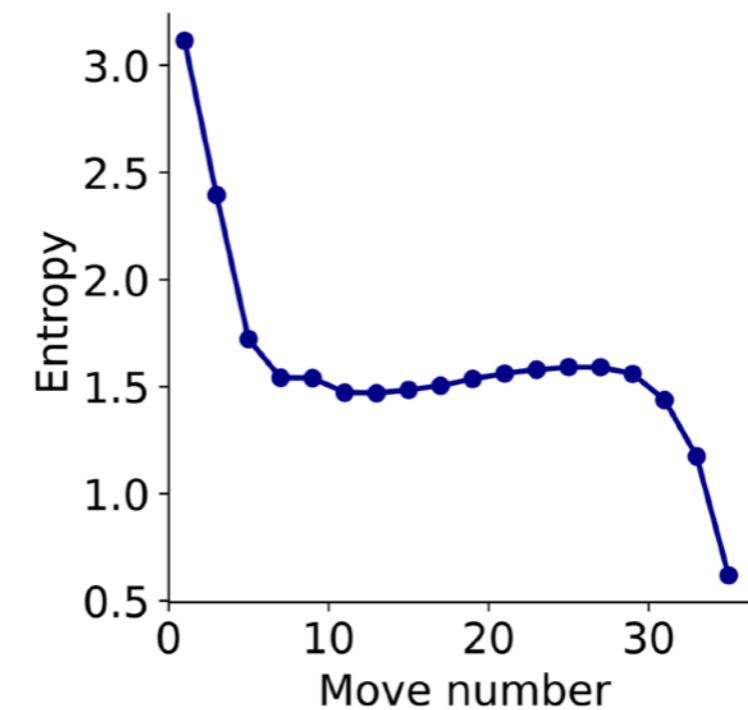
## Method #1: accuracy

Is the network able to correctly predict human choices?



## Method #2: entropy

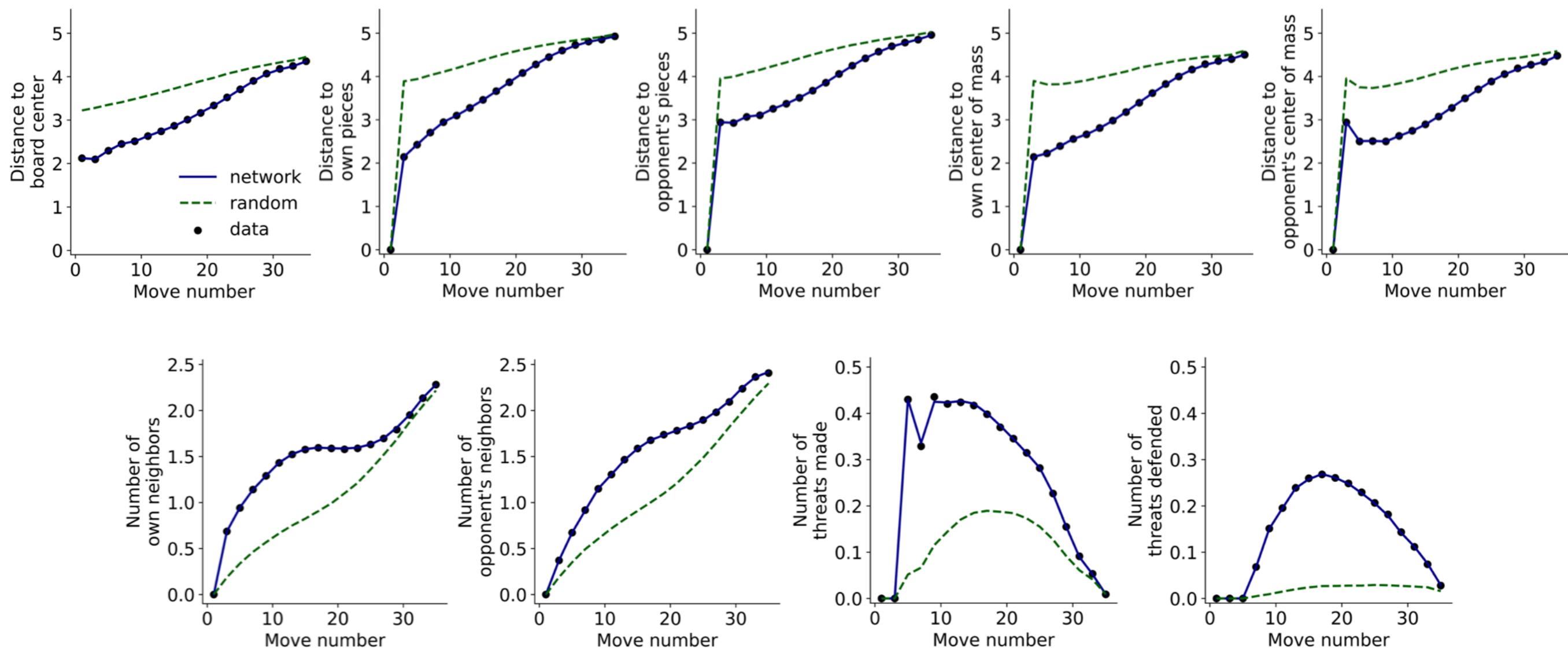
Is the network's confidence in its predictions sensible?



# NETWORK EVALUATION

## Method #3: summary statistics

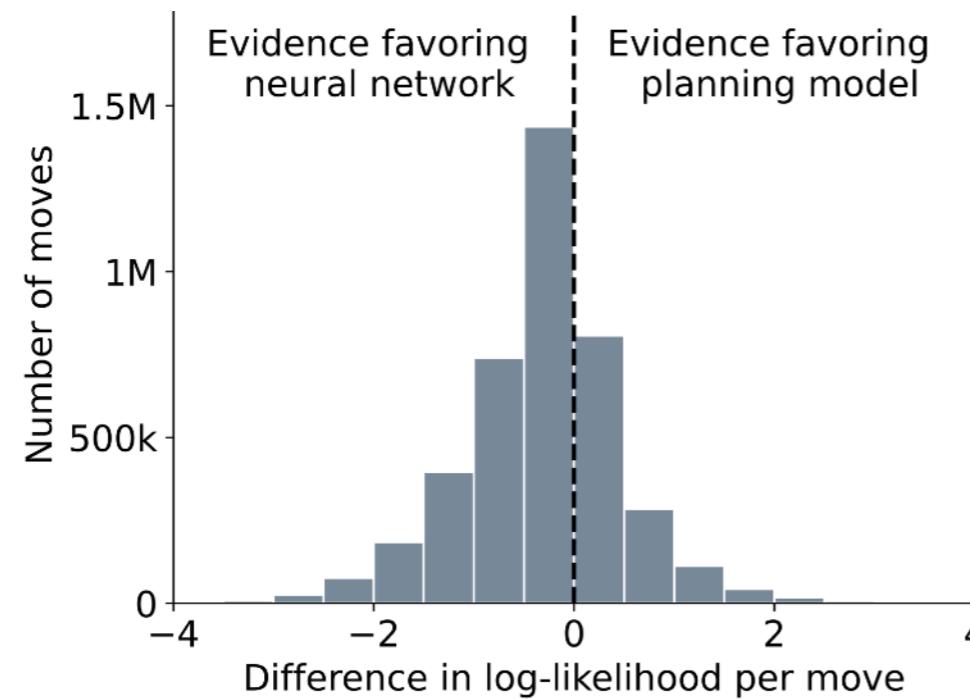
Does the network capture trends in human gameplay?



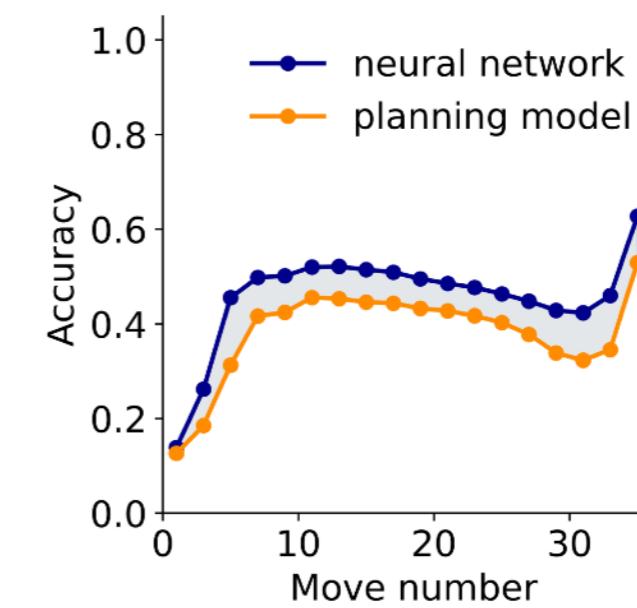
# PLANNING MODEL COMPARISON AND IMPROVEMENTS

The network outperforms the planning model in predicting human choices

Individual move prediction



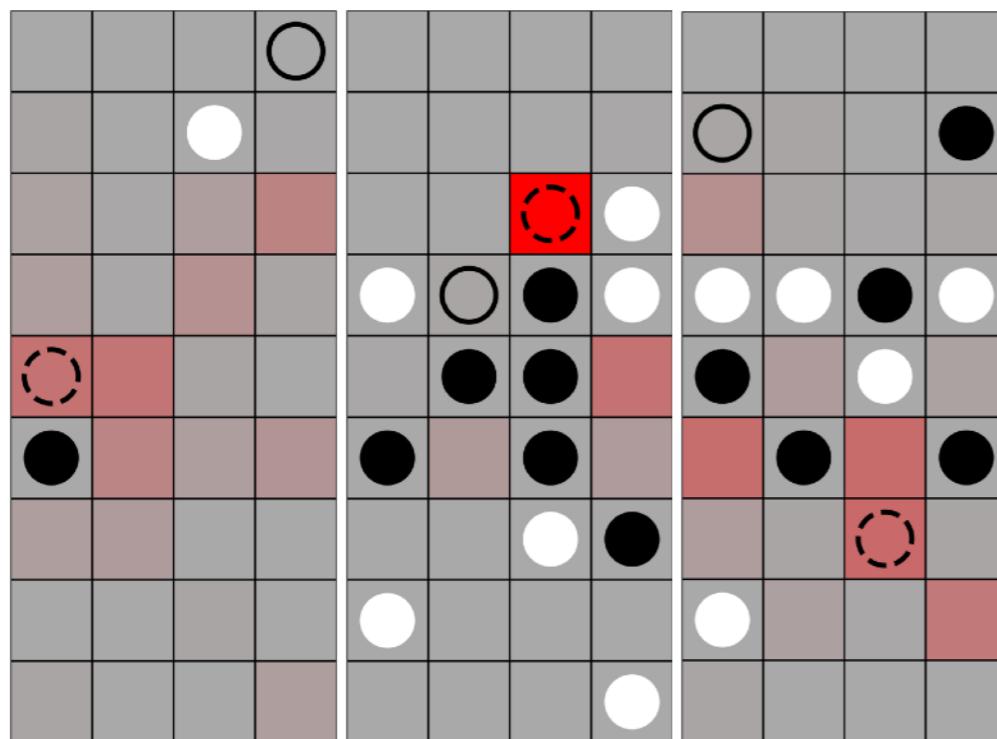
Accuracy across gameplay



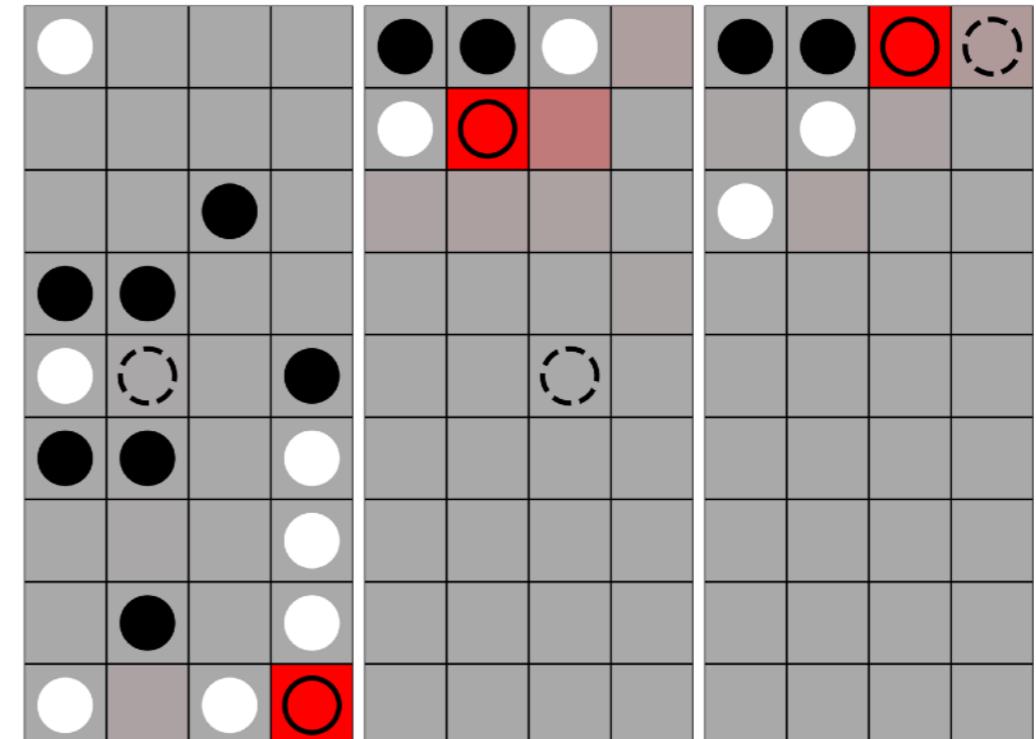
We now have a defined subset of board positions to explore where the network correctly predicts human choices and the planning model does not

# PLANNING MODEL COMPARISON AND IMPROVEMENTS

Largest differences between the planning model and the data



Largest differences between the planning model and the network

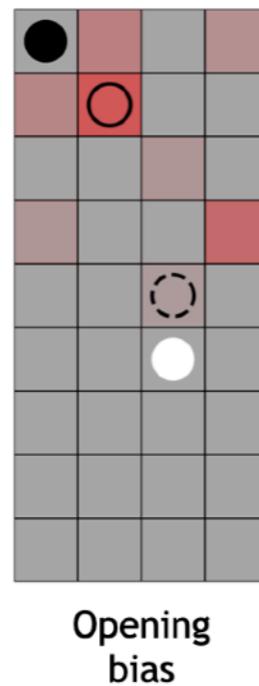


○ human move

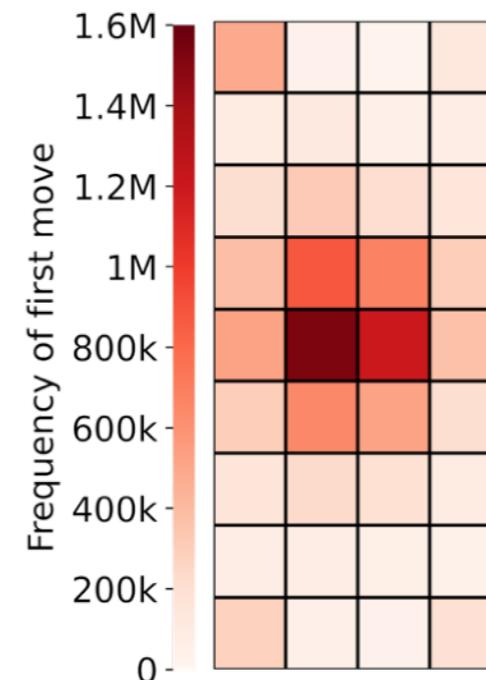
○ planning model's prediction

■ neural network's prediction

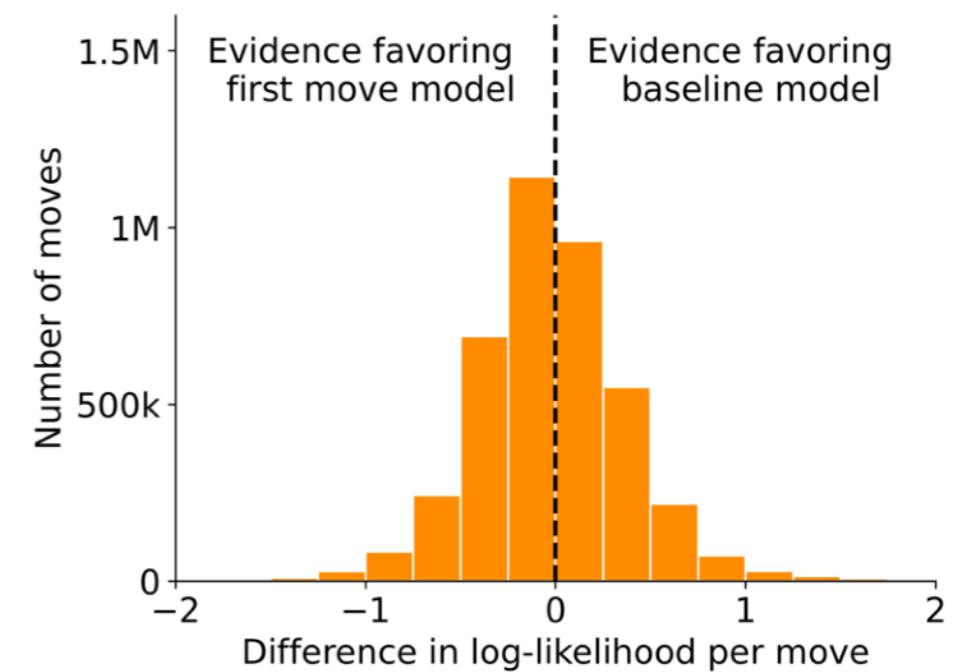
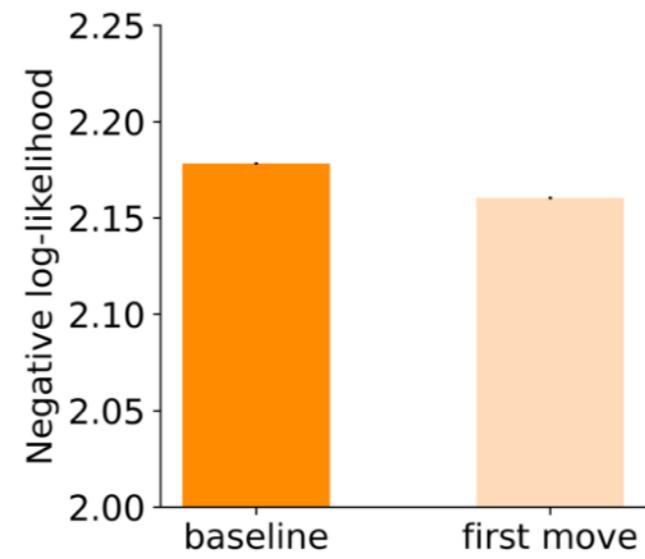
# A PROOF OF CONCEPT MODEL IMPROVEMENT



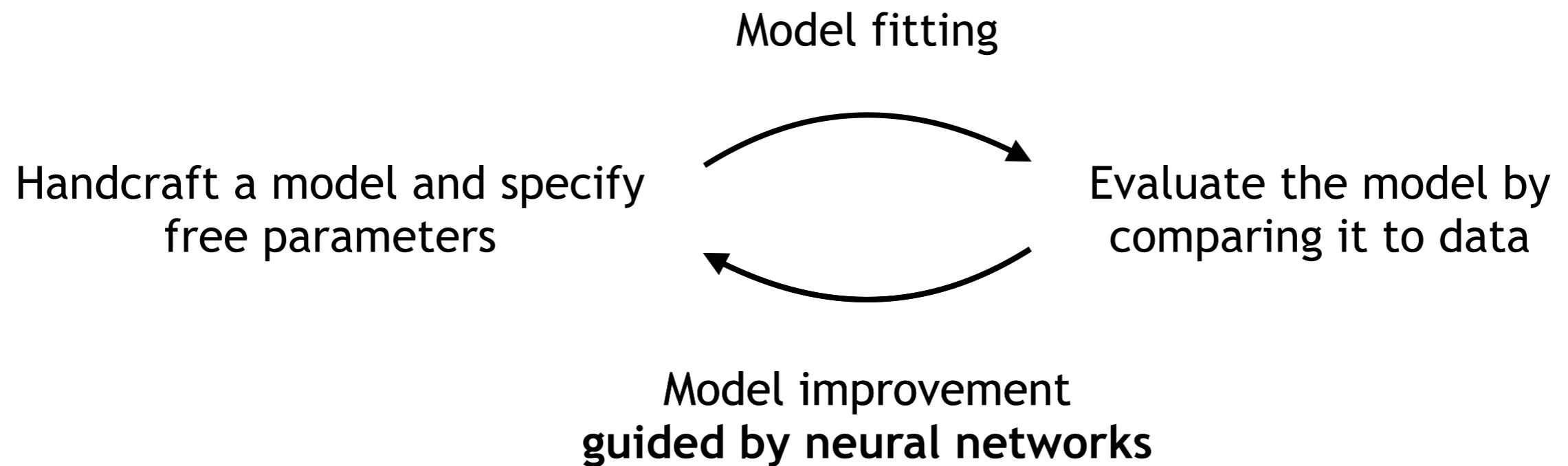
Histogram of first moves



New model parameter: weight of first move histogram



# AN IMPROVED APPROACH TO COMPUTATIONAL MODELING



# SUMMARY

**Provided a framework for model improvement that utilizes large-scale data and deep neural networks**

- Trained neural networks to predict human moves in a planning task of intermediate complexity
- Ensured that the best network represents a reasonable upper bound on how well any model can explain the data
- Explored positions in which the network is more accurate than a simpler model of human planning, leading to several candidate mechanisms for model improvement

## Ma Lab

Wei Ji Ma  
Heiko Schütt  
Hsin-Hung Li  
Dongjae Kim  
Peiyuan Zhang  
Xiang Li  
Daisy Lin  
Nastaran Arfaei  
Jordan Lei  
Jeroen Olieslagers

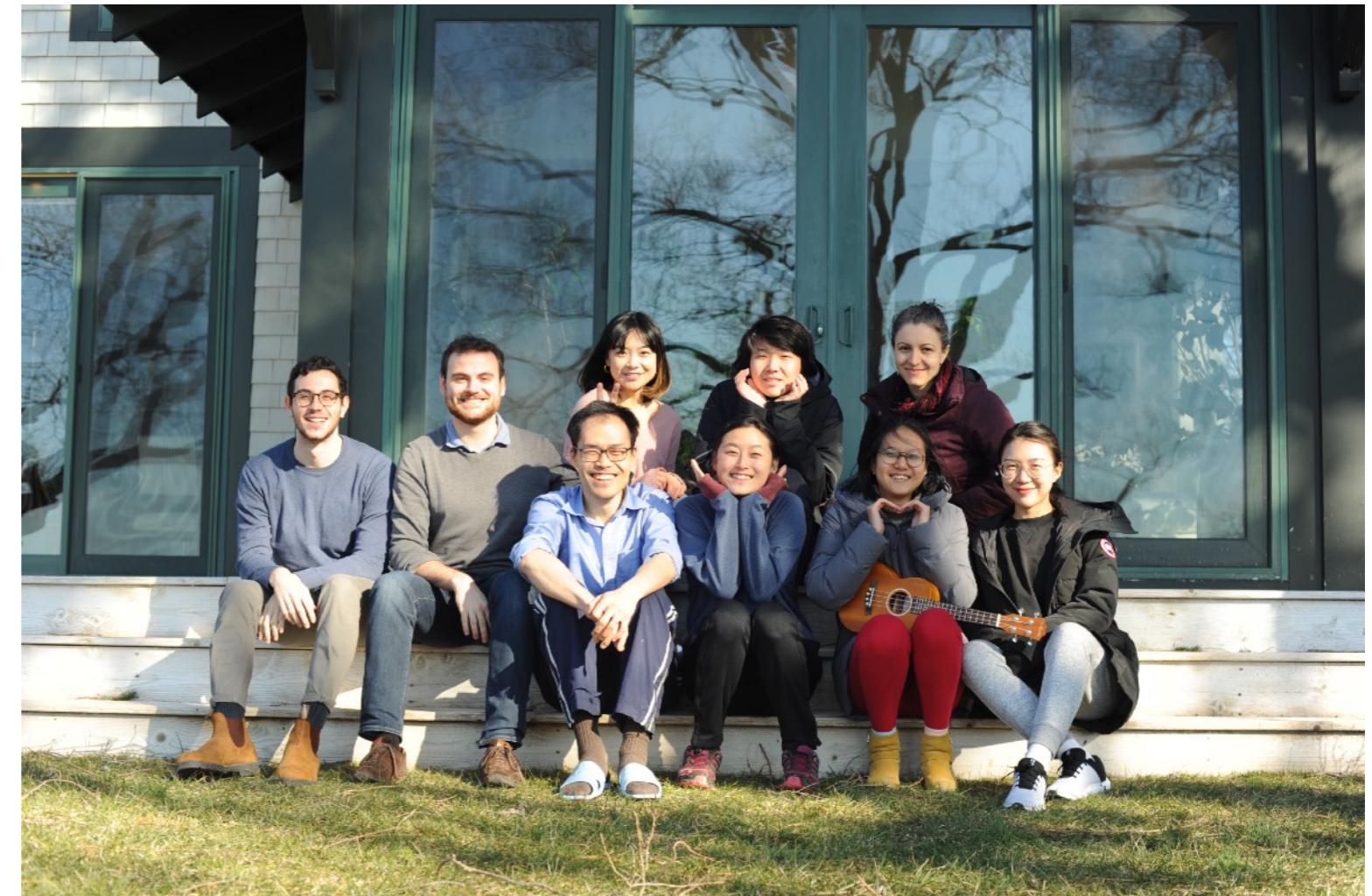
## Collaborators

Bas van Opheusden

## Funding

NSF GRFP

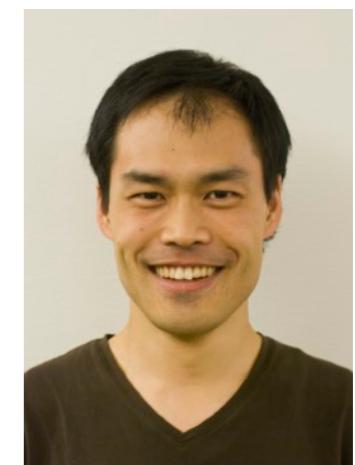
-  [ionatankuperwajs.github.io](https://ionatankuperwajs.github.io)
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Heiko Schütt



Bas van Opheusden



Wei Ji Ma

# Extra slides

# A MODEL OF HUMAN PLANNING

Heuristic value function + decision tree search

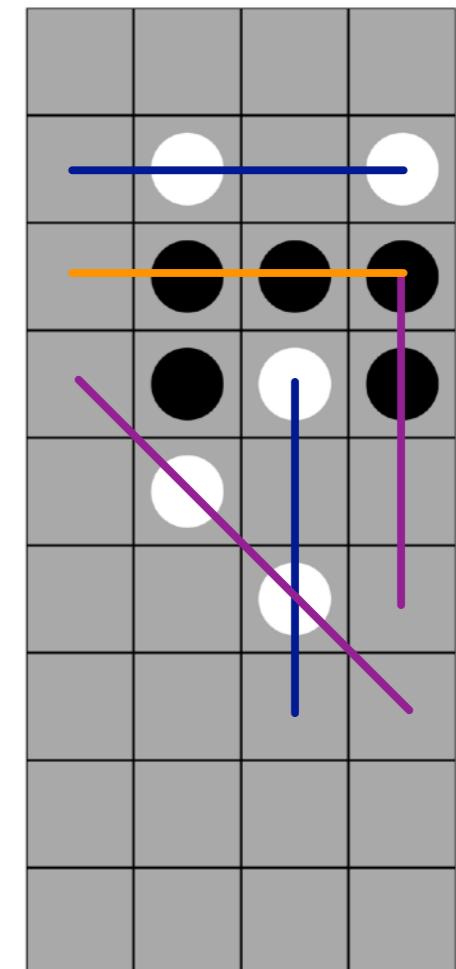
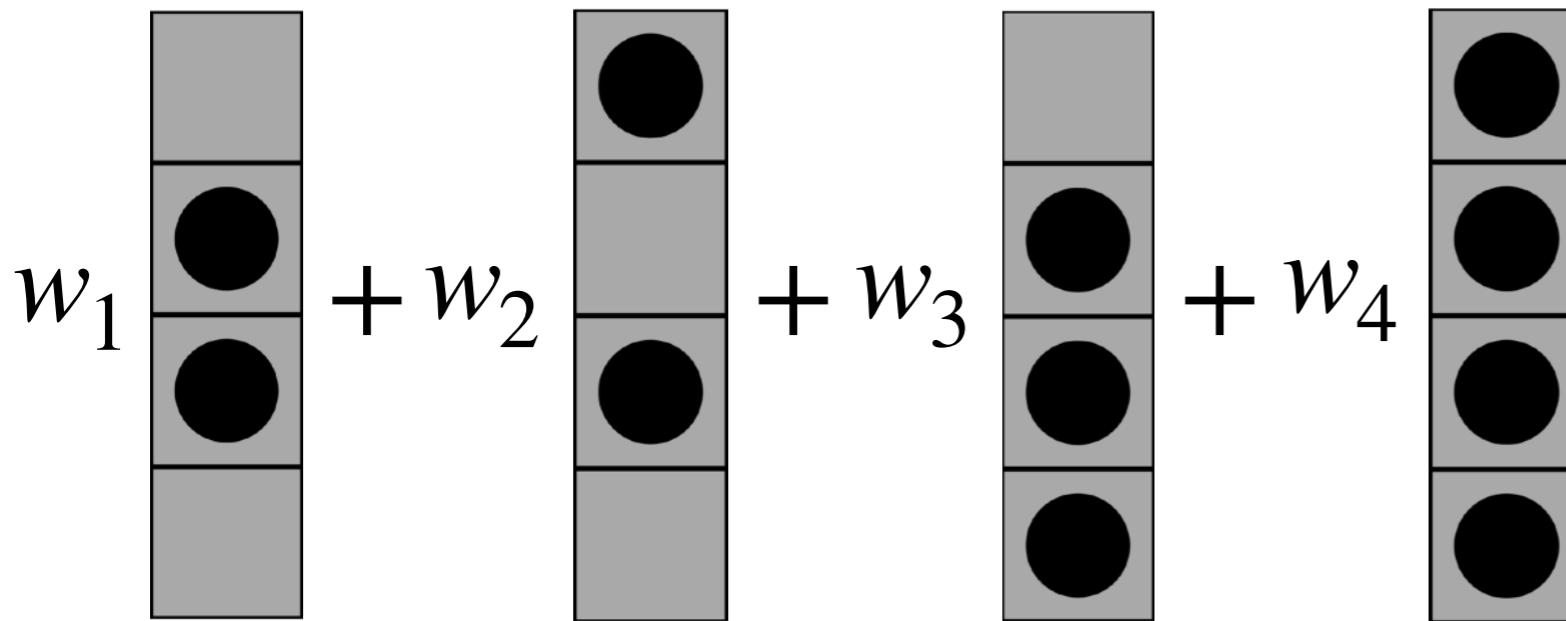
Positional  
features

Learned  
weights

Scaling  
constant

Opponent

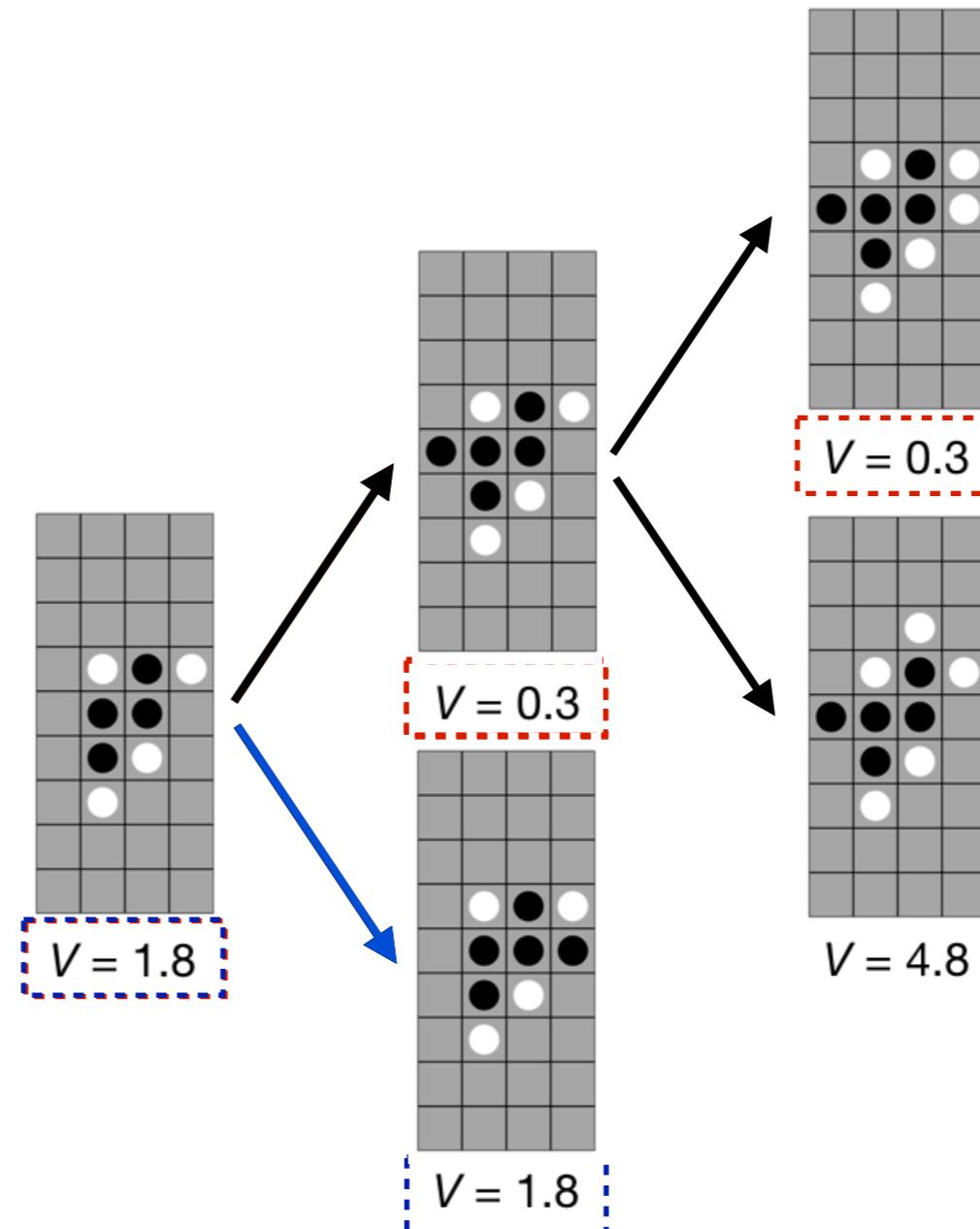
$$V(s) = c_{\text{self}} \sum_{i=0}^4 w_i f_i(s, \text{self}) - c_{\text{opp}} \sum_{i=0}^4 w_i f_i(s, \text{opp})$$



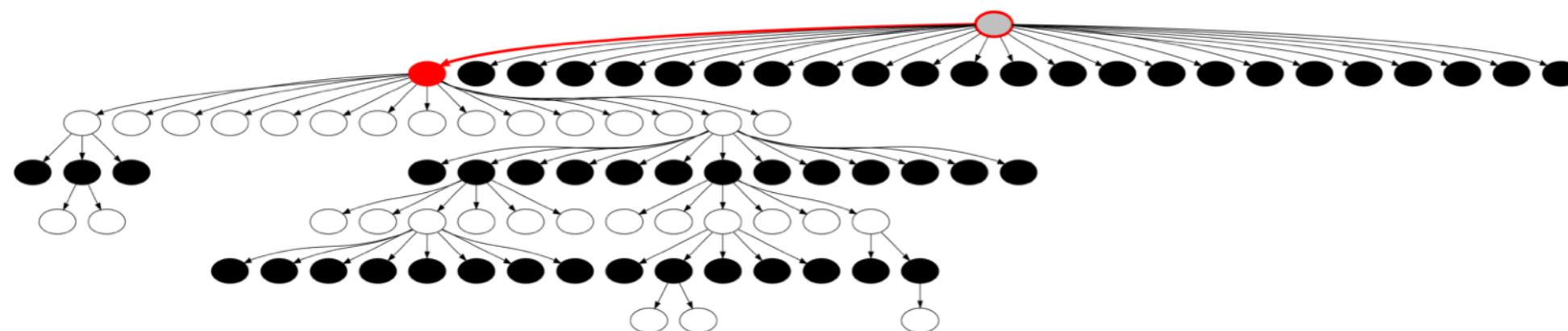
# A MODEL OF HUMAN PLANNING

Heuristic value function + decision tree search

- Expand
- Evaluate
- Backpropagate
- Select



# A SINGLE MODEL SIMULATION



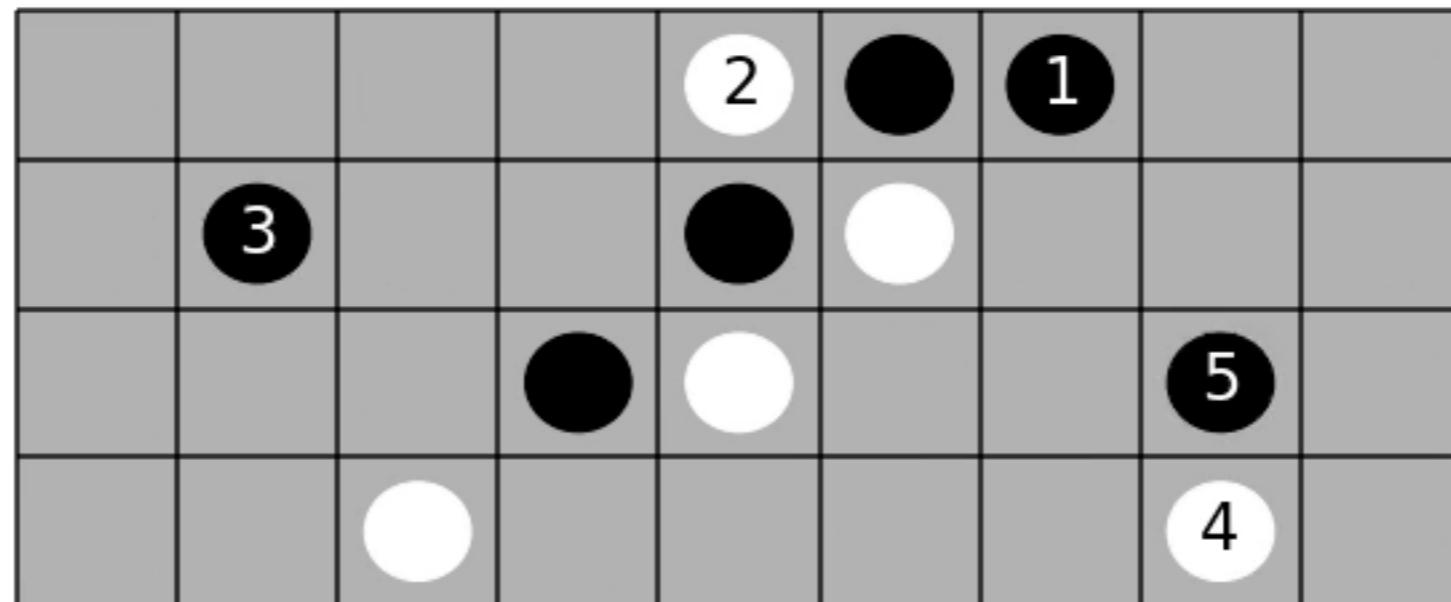
Principal variation 1

Principal variation 2

Principal variation 3

Principal variation 4

Decision



# A MODEL OF HUMAN PLANNING

## Additional model components

### Pruning

- Nodes with a value below that of the best move minus a threshold are removed from the tree

### "Human-like" modes of failure

- Gaussian noise
- Feature dropping: overlook features
- Lapse rate: make a random move

### Stopping criterion to terminate search

- Randomly with a small probability
- When the preferred move hasn't changed for a number of iterations

# CATEGORIES FOR CANDIDATE MODEL IMPROVEMENTS

