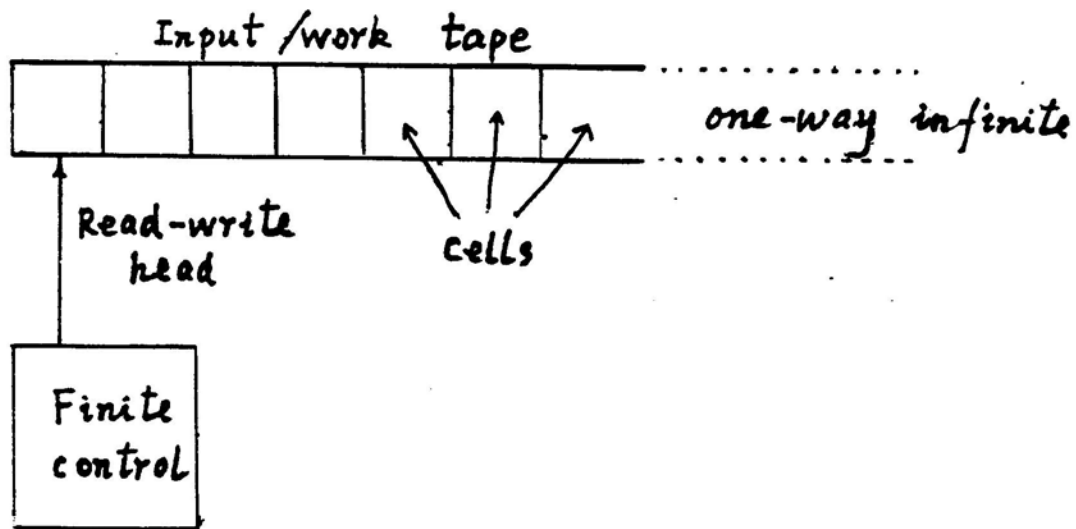


## V. TURING MACHINES



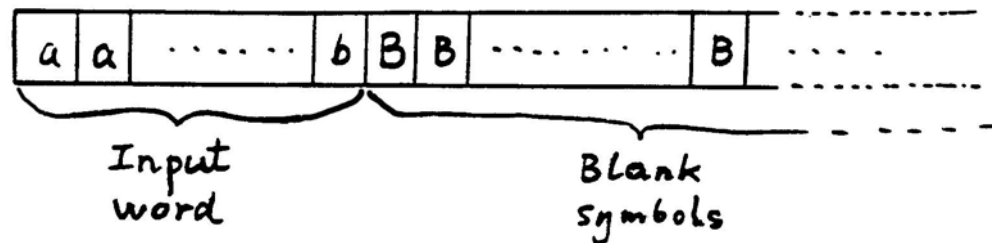
Turing machines have more features than FA and PDA.

- (1) The read-write head can move in either direction.
- (2) It can write on the tape.

Turing machines are studied as a theoretical model of computers.

Some assumptions for TM's:

- (1) At beginning, the input string (symbols) is placed at the left end of the input tape and followed by infinitely many blank symbols denoted by  $B$ 's.



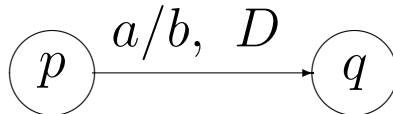
- (2) There is only one final state denoted by " $f$ ".
- (3) A TM stops when it enters the final state " $f$ ".

**Definition** A deterministic Turing Machine (DTM) is specified by a sextuple  $(Q, \Sigma, \Gamma, \delta, s, f)$  where

- $Q$ : is a finite set of states;
- $\Sigma$ : is an alphabet of input symbols;
- $\Gamma$ : is an alphabet of tape symbols,  
 $\Sigma \cup \{B\} \subseteq \Gamma$
- $\delta : Q \times \Gamma \rightarrow Q \times \Gamma \times \{L, R, \varepsilon\}$  is a transition function;
- $s \in Q$  is a start state;
- $f \in Q$  is a final state;

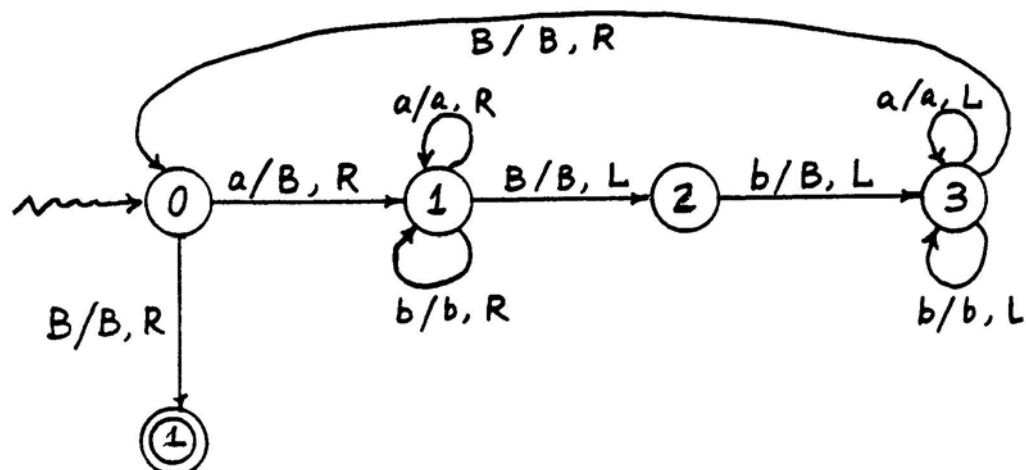
### State diagram

$\delta(p, a) = (q, b, D)$  is depicted graphically:



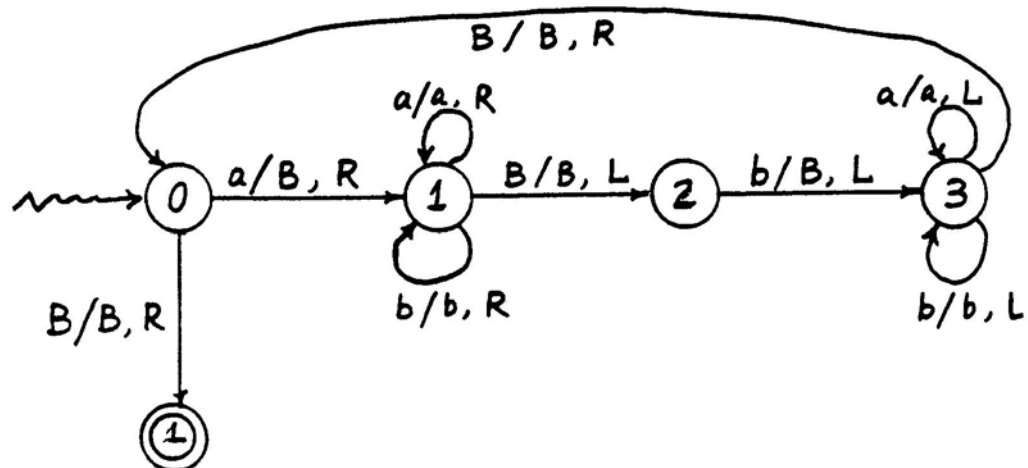
Example A DTM that accepts

$$L = \{a^i b^i \mid i \geq 0\}$$



Example A DTM that accepts

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## Configuration

A configuration is a word in

$$\Gamma^*Q\Gamma^*.$$

Strictly speaking, a configuration is a word in  $\Gamma^*Q\Gamma^*(\Gamma - \{B\}) \cup \Gamma^*Q$

(Note:  $Q \cap \Gamma = \emptyset$ )

## One move of a DTM

$$g_1ph_1 \vdash g_2qh_2 \quad \text{if}$$

- (i) either  $h_1 = Ah'_1$ , for some  $A$  in  $\Gamma$ ,  $h'_1$  in  $\Gamma^*$  or  $h_1 = \varepsilon$ , then  $A = B$  and  $h'_1 = \varepsilon$ ;
- (ii)  $\delta(p, A)$  is defined and  $p \neq f$ ;
- (iii)  $\delta(p, A) = (q, A', D)$ 
  - (a)  $D = L$ ,  $g_1 = g'_1C$  for some  $C \in \Gamma$ , and then  $h_2 = CA'h'_1$  (if  $g_1 = \varepsilon$ , then  $M$  halts)
  - (b)  $D = R$ ,  $g_1A' = g_2$  and  $h_2 = h'_1$
  - (c)  $D = \varepsilon$ ,  $g_2 = g_1$  and  $h_2 = A'h'_1$  (if  $A' = B$ ,  $h'_1 = \varepsilon$ , then  $h_2 = \varepsilon$ )

$\vdash^i, \vdash^+, \vdash^*$  are defined as before.

### Language acceptance

$$L(M) = \{x \mid sx \vdash^* yfz, \text{ for some } y, z \in \Gamma^*\}$$
$$\mathcal{L}_{DTM} = \{L \mid L = L(M) \text{ for some DTM } M\}.$$

A DTM can be used

- (i) as a language acceptor;
- (ii) to compute a function:

$$f_M : \Sigma^* \rightarrow (\Gamma - \{B\})^*$$

$$f_M(x) = y \text{ in } (\Gamma - \{B\})^* \text{ iff}$$

$$sx \vdash^* y_1fy_2, \text{ where } y = y_1y_2$$

- (iii) as a decision maker.

## Example A right shift machine

Initial state:

$B$ : write  $B$ , move  $-$ , goto  $f$ ;  
 $a$ : write  $B$ , move right, goto  $A$ ;  
 $b$ : write  $B$ , move right, goto  $B$ ;

$A$ -state:

$a$ : write  $a$ , move right, goto  $A$ ;  
 $b$ : write  $a$ , move right, goto  $B$ ;  
 $B$ : write  $a$ , move right, goto  $f$ ;

$B$ -state:

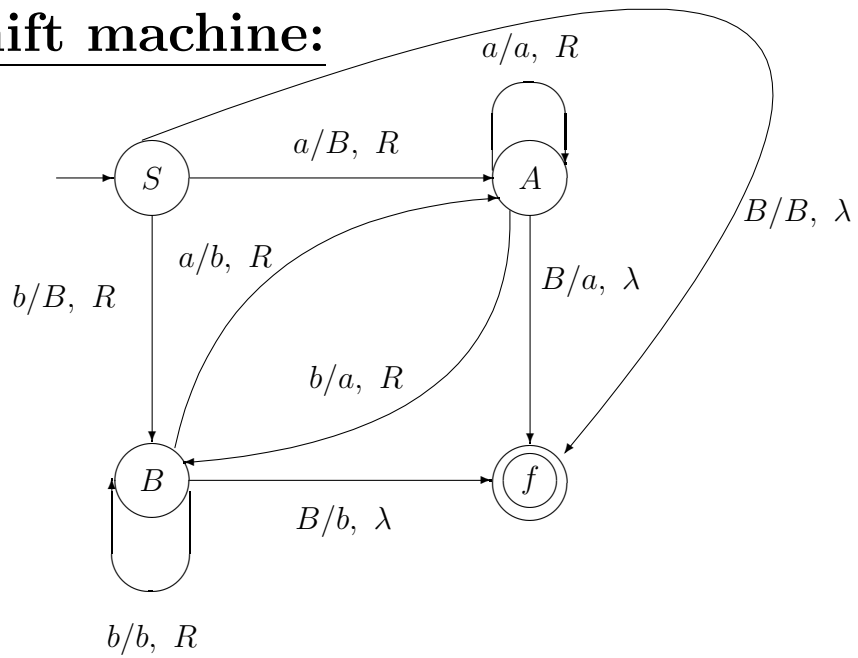
$a$ : write  $b$ , move right, goto  $A$ ;  
 $b$ : write  $b$ , move right, goto  $B$ ;  
 $B$ : write  $b$ , move right, goto  $f$ ;

$a$	$a$	$b$	$b$	$b$	$a$	$a$	$a$	$B$	$B$	
-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	--

$B$	$a$	$a$	$b$	$b$	$b$	$a$	$a$	$a$	$B$	
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## Right-shift machine:

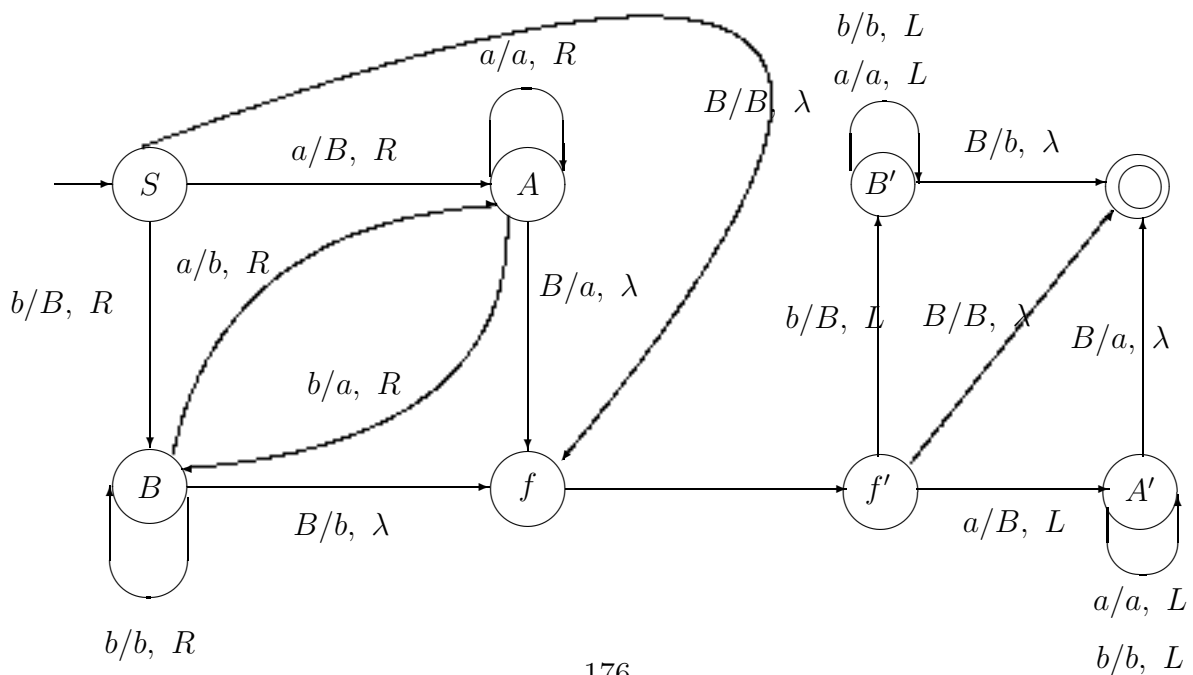


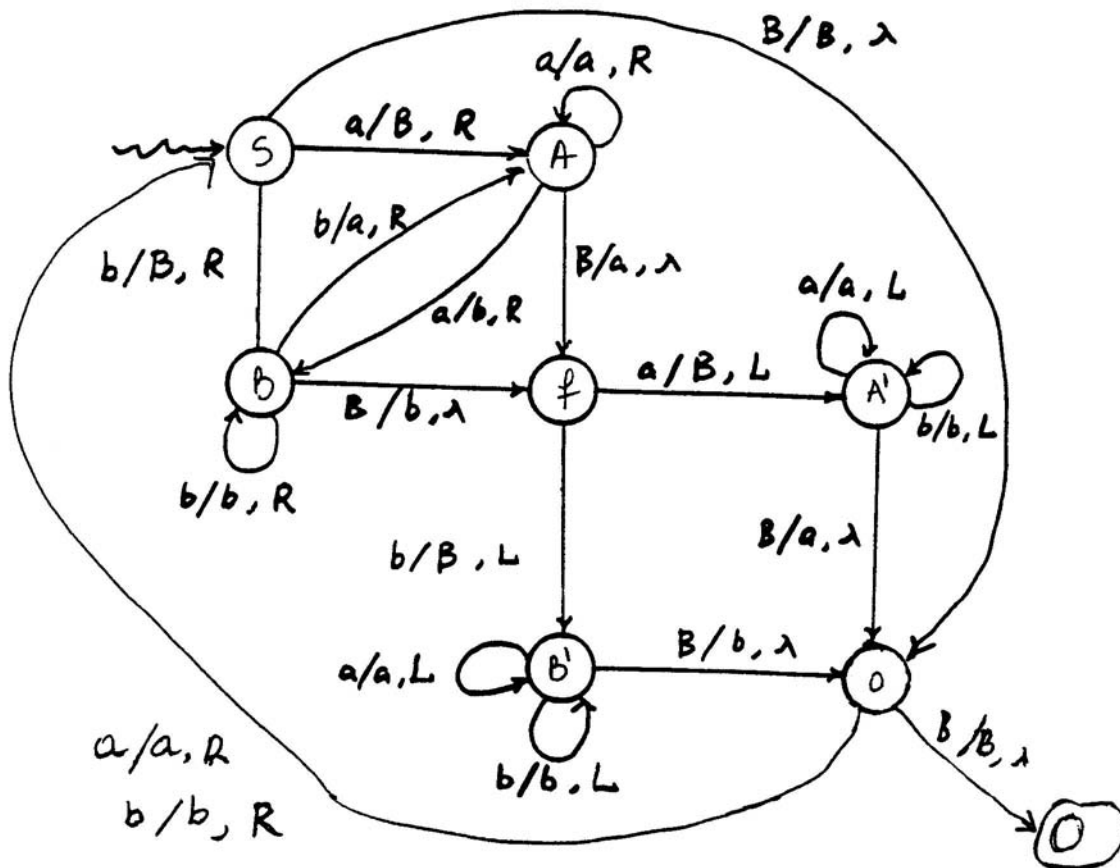
## Example A cyclic right shift machine:

$\overline{b|a|a|b|b|b|a|B|B|.....}$

is transformed in:

$\overline{a|b|a|a|b|b|b|B|B|.....}$





### Example A reversal machine

input: *aabba*

## The Busy Beaver Problem

Consider a DTM with

- two-way infinite tape;
- a tape alphabet  $\Gamma = \{1, B\}$ ;
- $n$  states apart from  $f$ .

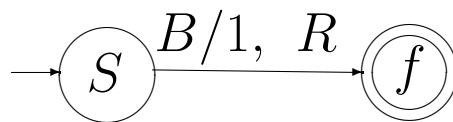
Question (by Tibor Rado)

How many 1's can there be on entering  $f$ ,  
when given the empty word as input?

(1's are like twigs. Beavers build busily with twigs.)

Define  $\Sigma(n)$  to be the maximum number of 1's that can be obtained by a DTM with  $n$  states.

1-state DTM:



$$\Sigma(1) = 1$$

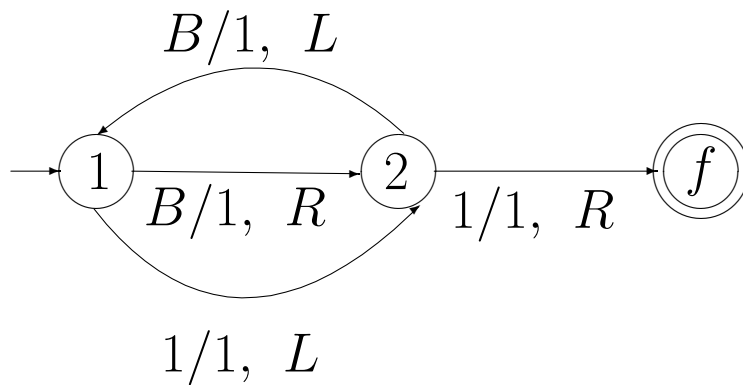
$$\Sigma(2) = 4$$

$$\Sigma(3) = 6$$

$$\Sigma(4) = 13$$

$$\Sigma(5) = ?, \quad \geq 1915$$

## 2-state Machine:



$$\dots\dots|B|B|\underbrace{B}_1|B|\dots\dots$$

$$\dots\dots|B|B|1|\underbrace{B}_2|\dots\dots$$

$$\dots\dots|B|B|\underbrace{1}_{1}|1|\dots\dots$$

$$\dots\dots|B|\underbrace{B}_2|1|1|\dots\dots$$

$$\dots\dots\dots \underbrace{|B|}_{1} |1| |1| |1| \dots\dots\dots$$

$$\dots\dots\dots|1|\underbrace{1}_2|1|1|\dots\dots\dots$$

$$\dots\dots\dots|1|1|\underbrace{1}_{f}|1|\dots\dots\dots$$

## Definitions

### Decision-making TM

A DTM  $M = (Q, \Sigma, \Gamma, \delta, s, f)$  is said to be a decision making TM if  $y$  and  $n$  are in  $\Gamma$  and not in  $\Sigma$ , and for all  $x \in \Sigma^*$ , either  $sx \vdash^* fy$  or  $sx \vdash^* fn$ .

### Yes language of $M$

$$Y(M) = \{x \mid x \in \Sigma^* \text{ and } sx \vdash^* fy\}$$

### No language of $M$

$$N(M) = \{x \mid x \in \Sigma^* \text{ and } sx \vdash^* fn\}$$

### Decidability

Let  $L \subseteq \Sigma^*$ , ( $B \notin \Sigma$ ).  $L$  is decidable iff there is a decision-making TM  $M$  with  $L = Y(M)$ .

## Recursive Languages

$L$  is recursive iff  $L$  is decidable.

## Notation

$\mathcal{L}_{REC}$  denotes the family of recursive languages.

## Computability

Let  $f : \Sigma^* \rightarrow \Delta^*$  be a function, where  $B \notin \Sigma \cup \Delta$ .  
 $f$  is said to be computable iff there is a DTM  
 $M = (Q, \Sigma, \Gamma, \delta, s, f)$  with  $\Delta \subseteq \Gamma$  and for all  $x \in \Sigma^*$

if  $f(x) = y$  then

$sx \vdash^* y_1 f y_2$  and  $y = y_1 y_2$

for some  $y_1, y_2 \in \Delta^*$ .