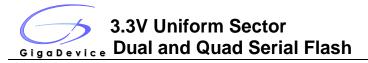
GD25Q127C

DATASHEET



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1. FEATURES

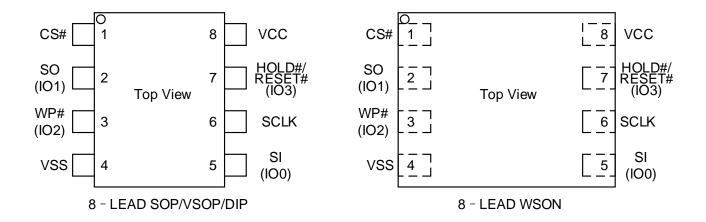
- ◆ 128M-bit Serial Flash
 - -16384K-byte
 - -256 bytes per programmable page
- Standard, Dual, Quad SPI
 - -Standard SPI: SCLK, CS#, SI, SO, WP#, HOLD#/ RESET#
 - -Dual SPI: SCLK, CS#, IO0, IO1, WP#, HOLD#/ RESET#
 - -Quad SPI: SCLK, CS#, IO0, IO1, IO2, IO3
- High Speed Clock Frequency
 - -104MHz for Standard and Dual SPI fast read with 30PF load ◆ Low Power Consumption
 - -Dual I/O Data transfer up to 208Mbits/s
 - -Quad I/O Data transfer up to 416Mbits/s
- ♦ Software/Hardware Write Protection
 - -Write protect all/portion of memory via software
 - -Enable/Disable protection with WP# Pin
 - -Top/Bottom Block protection
- ◆ Allows XIP (execute in place) Operation
 - -Continuous Read With 8/16/32/64-byte Wrap
- ◆ Minimum 100,000 Program/Erase Cycles
- ◆ Data Retention
 - -20-year data retention typical

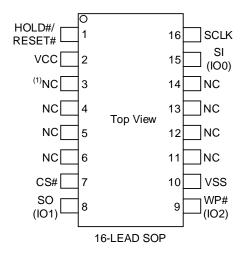
- Fast Program/Erase Speed
 - -Page Program time: 0.5ms typical
 - -Sector Erase time: 50ms typical
 - -Block Erase time: 0.16/0.3s typical
 - -Chip Erase time: 50s typical
- ◆ Flexible Architecture
 - -Uniform Sector of 4K-byte
 - -Uniform Block of 32/64K-byte
- - -20µA typical standby current
 - -1µA typical power down current
- Advanced Security Features
 - -128-bit Unique ID for each device
 - -3x1024-Byte Security Registers With OTP Locks
 - -Discoverable parameters (SFDP) register
- ◆ Single Power Supply Voltage
 - -Full voltage range: 2.7~3.6V
- Package Information
 - -SOP8 (208mil)
 - -VSOP8 (208mil)
 - -SOP16 (300mil)
 - -DIP8 (300mil)
 - -WSON8 (8*6mm)
 - -WSON8 (6*5mm)
 - -TFBGA-24 (6*4 ball array)

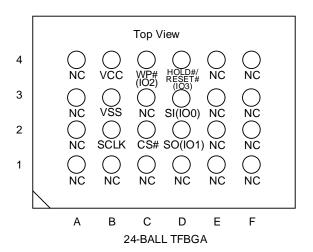
2. GENERAL DESCRIPTION

The GD25Q127C (128M-bit) Serial flash supports the standard Serial Peripheral Interface (SPI), and supports the Dual/Quad SPI: Serial Clock, Chip Select, Serial Data I/O0 (SI), I/O1 (SO), I/O2 (WP#), and I/O3 (HOLD#/ RESET#). The Dual I/O data is transferred with speed of 208Mbits/s and the Quad I/O & Quad output data is transferred with speed of 416Mbits/s.

CONNECTION DIAGRAM

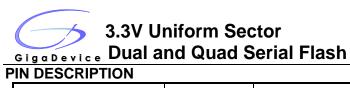






Note:

(1) Only for special order, Pin 3 of 16-LEAD SOP package is RESET# pin. Please contact GigaDevice for detail.

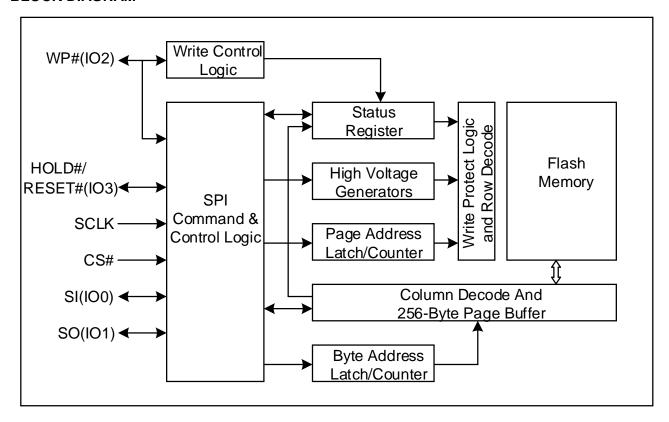


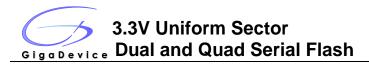
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Pin Name	1/0	Description		
CS# I		Chip Select Input		
SO (IO1)	I/O	Data Output (Data Input Output 1)		
WP# (IO2) I/O		Write Protect Input (Data Input Output 2)		
VSS		Ground		
SI (IO0)	I/O	Data Input (Data Input Output 0)		
SCLK	ı	Serial Clock Input		
HOLD#/RESET# (IO3) I/O		Hold or Reset Input (Data Input Output 3)		
vcc		Power Supply		

Note: CS# must be driven high if chip is not selected. Please don't leave CS# floating any time after power is on.

BLOCK DIAGRAM





3. MEMORY ORGANIZATION

GD25Q127C

Each device has	Each block has	Each sector has	Each page has	
16M	64/32K	4K	256	bytes
64K	256/128	16	-	pages
4096	16/8	-	-	sectors
256/512	-	-	-	blocks

UNIFORM BLOCK SECTOR ARCHITECTURE GD25Q127C 64K Bytes Block Sector Architecture

Block	Sector	Address range		
	4095	FFF000H	FFFFFH	
255				
	4080	FF0000H	FF0FFFH	
	4079	FEF000H	FEFFFFH	
254				
	4064	FE0000H	FE0FFFH	
	47	02F000H	02FFFFH	
2				
	32	020000H	020FFFH	
	31	01F000H	01FFFFH	
1				
	16	010000H	010FFFH	
	15	00F000H	00FFFFH	
0				
	0	000000H	000FFFH	

4. DEVICE OPERATION

SPI Mode

Standard SPI

The GD25Q127C features a serial peripheral interface on 4 signals bus: Serial Clock (SCLK), Chip Select (CS#), Serial Data Input (SI) and Serial Data Output (SO). Both SPI bus mode 0 and 3 are supported. Input data is latched on the rising edge of SCLK and data shifts out on the falling edge of SCLK.

Dual SPI

The GD25Q127C supports Dual SPI operation when using the "Dual Output Fast Read" and "Dual I/O Fast Read" (3BH and BBH) commands. These commands allow data to be transferred to or from the device at twice the rate of the standard SPI. When using the Dual SPI command the SI and SO pins become bidirectional I/O pins: IOO and IO1.

Quad SPI

The GD25Q127C supports Quad SPI operation when using the "Quad Output Fast Read"," Quad I/O Fast Read", "Quad I/O Word Fast Read" (6BH,EBH,E7H) commands. These commands allow data to be transferred to or from the device at four times the rate of the standard SPI. When using the Quad SPI command the SI and SO pins become bidirectional I/O pins: IOO and IO1, and WP# and HOLD#/RESET# pins become IO2 and IO3. Quad SPI commands require the non-volatile Quad Enable bit(QE) in Status Register to be set.

Hold

The HOLD/RST bit is used to determine whether HOLD# or RESET# function should be implemented on the hardware pin for 8-pin packages. When HOLD/RST=0, the pin7 acts as HOLD#, the HOLD# function is only available when QE=0, If QE=1, The HOLD# functions is disabled, the pin acts as dedicated data I/O pin.

The HOLD# signal goes low to stop any serial communications with the device, but doesn't stop the operation of write status register, programming, or erasing in progress.

The operation of HOLD, need CS# keep low, and starts on falling edge of the HOLD# signal, with SCLK signal being low (if SCLK is not being low, HOLD operation will not start until SCLK being low). The HOLD condition ends on rising edge of HOLD# signal with SCLK being low (If SCLK is not being low, HOLD operation will not end until SCLK being low).

The SO is high impedance, both SI and SCLK don't care during the HOLD operation, if CS# drives high during HOLD operation, it will reset the internal logic of the device. To re-start communication with chip, the HOLD# must be at high and then CS# must be at low.

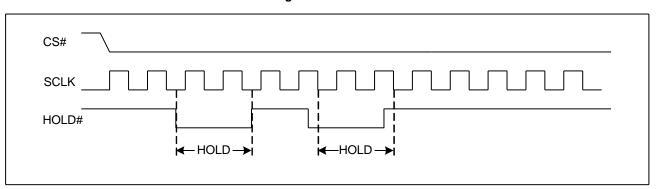


Figure 1. Hold Condition



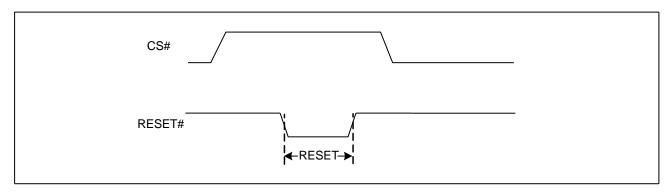
RESET

The RESET# pin allows the device to be reset by the control. For the WSON8 package, the pin7 can be configured as a RESET# pin depending on the status register setting, which need QE=0 and HOLD/RST=1. On the SOP16 package, a dedicated RESET# pin is provided and it is independent of QE bit setting.

The RESET# pin goes low for a period of tRLRH or longer will reset the flash. After reset cycle, the flash is at the following states:

- -Standby mode
- -All the volatile bits will return to the default status as power on.

Figure 2. RESET Condition



5. DATA PROTECTION

The GD25Q127Cprovide the following data protection methods:

- Write Enable (WREN) command: The WREN command is set the Write Enable Latch bit (WEL). The WEL bit will return to reset by the following situation:
 - -Power-Up
 - -Write Disable (WRDI)
 - -Write Status Register (WRSR)
 - -Page Program (PP)
 - -Sector Erase (SE) / Block Erase (BE) / Chip Erase (CE)
- ◆ Software Protection Mode:
 - -The Block Protect (BP4, BP3, BP2, BP1, and BP0) bits define the section of the memory array that can be read but not change.
- ♦ Hardware Protection Mode: WP# goes low to protect the writable bit of Status Register.
- ◆ Deep Power-Down Mode: In Deep Power-Down Mode, all commands are ignored except the Release from Deep Power-Down Mode command and reset command (66H+99H).

Table 5.1. GD25Q127C Protected area size (CMP=0)

;	Status Register Content					Memory Content				
BP4	ВР3	BP2	BP1	BP0	Blocks	Addresses	Density	Portion		
Х	Х	0	0	0	NONE	NONE	NONE	NONE		
0	0	0	0	1	252 to 255	FC0000H-FFFFFFH	256KB	Upper 1/64		
0	0	0	1	0	248 to 255	F80000H-FFFFFFH	512KB	Upper 1/32		
0	0	0	1	1	240 to 255	F00000H-FFFFFFH	1MB	Upper 1/16		
0	0	1	0	0	224 to 255	E00000H-FFFFFFH	2MB	Upper 1/8		
0	0	1	0	1	192 to 255	C00000H-FFFFFFH	4MB	Upper 1/4		
0	0	1	1	0	128 to 255	800000H-FFFFFH	8MB	Upper 1/2		
0	1	0	0	1	0 to 3	000000H-03FFFFH	256KB	Lower 1/64		
0	1	0	1	0	0 to 7	000000H-07FFFFH	512KB	Lower 1/32		
0	1	0	1	1	0 to 15	000000H-0FFFFH	1MB	Lower 1/16		
0	1	1	0	0	0 to 31	000000H-1FFFFFH	2MB	Lower 1/8		
0	1	1	0	1	0 to 63	000000H-3FFFFFH	4MB	Lower 1/4		
0	1	1	1	0	0 to 127	000000H-7FFFFH	8MB	Lower 1/2		
Х	Х	1	1	1	0 to 255	000000H-FFFFFH	16MB	ALL		
1	0	0	0	1	255	FFF000H-FFFFFFH	4KB	Top Block		
1	0	0	1	0	255	FFE000H-FFFFFFH	8KB	Top Block		
1	0	0	1	1	255	FFC000H-FFFFFFH	16KB	Top Block		
1	0	1	0	Х	255	FF8000H-FFFFFFH	32KB	Top Block		
1	0	1	1	0	255	FF8000H-FFFFFFH	32KB	Top Block		
1	1	0	0	1	0	000000H-000FFFH	4KB	Bottom Block		
1	1	0	1	0	0	000000H-001FFFH	8KB	Bottom Block		
1	1	0	1	1	0	000000H-003FFFH	16KB	Bottom Block		
1	1	1	0	Х	0	000000H-007FFFH	32KB	Bottom Block		



3.3V Uniform Sector Gigabevice Dual and Quad Serial Flash

GD25Q127C

Table 5.2. GD25Q127C Protected area size (CMP=1)

	Status F	Register			2. GD25Q127C Protected area size (CMP=1) Memory Content			
BP4	BP3	BP2	BP1	BP0	Blocks	Addresses	Density	Portion
Х	Х	0	0	0	0 to 255	000000H-FFFFFFH	ALL	ALL
0	0	0	0	1	0 to 251	000000H-FBFFFFH	16128KB	Lower 63/64
0	0	0	1	0	0 to 247	000000H-F7FFFFH	15872KB	Lower 31/32
0	0	0	1	1	0 to 239	000000H-EFFFFFH	15MB	Lower 15/16
0	0	1	0	0	0 to 223	000000H-DFFFFFH	14MB	Lower 7/8
0	0	1	0	1	0 to 191	000000H-BFFFFFH	12MB	Lower 3/4
0	0	1	1	0	0 to 127	000000H-7FFFFFH	8MB	Lower 1/2
0	1	0	0	1	4 to 255	040000H-FFFFFFH	16128KB	Upper 63/64
0	1	0	1	0	8 to 255	080000H-FFFFFFH	15872KB	Upper 31/32
0	1	0	1	1	16 to 255	100000H-FFFFFFH	15MB	Upper 15/16
0	1	1	0	0	32 to 255	200000H-FFFFFFH	14MB	Upper 7/8
0	1	1	0	1	64 to 255	400000H-FFFFFFH	12MB	Upper 3/4
0	1	1	1	0	128 to 255	800000H-FFFFFFH	8MB	Upper 1/2
Х	Х	1	1	1	NONE	NONE	NONE	NONE
1	0	0	0	1	0 to 255	000000H-FFEFFFH	16380KB	L-4095/4096
1	0	0	1	0	0 to 255	000000H-FFDFFFH	16376KB	L-2047/2048
1	0	0	1	1	0 to 255	000000H-FFBFFFH	16368KB	L-1023/1024
1	0	1	0	Х	0 to 255	000000H-FF7FFFH	16352KB	L-511/512
1	0	1	1	0	0 to 255	000000H-FF7FFFH	16352KB	L-511/512
1	1	0	0	1	0 to 255	001000H-FFFFFFH	16380KB	U-4095/4096
1	1	0	1	0	0 to 255	0 255 002000H-FFFFFH		U-2047/2048
1	1	0	1	1	0 to 255	0 to 255 004000H-FFFFFH		U-1023/1024
1	1	1	0	Х	0 to 255	o 255 008000H-FFFFFH		U-511/512
1	1	1	1	0	0 to 255	008000H-FFFFFH	16352KB	U-511/512



6. STATUS REGISTER

S23	S22	S21	S20	S19	S18	S17	S16
HOLD/RST	DRV1	DRV0	Reserved	Reserved	LPE	Reserved	Reserved
S15	S14	S13	S12	S11	S10	S9	S8
SUS1	CMP	LB3	LB2	LB1	SUS2	QE	SRP1
S 7	S6	S 5	S4	S3	S2	S1	S0
SRP0	BP4	BP3	BP2	BP1	BP0	WEL	WIP

The status and control bits of the Status Register are as follows:

WIP bit.

The Write in Progress (WIP) bit indicates whether the memory is busy in program/erase/write status register progress. When WIP bit sets to 1, means the device is busy in program/erase/write status register progress, when WIP bit sets 0, means the device is not in program/erase/write status register progress.

WEL bit.

The Write Enable Latch (WEL) bit indicates the status of the internal Write Enable Latch. When set to 1 the internal Write Enable Latch is set, when set to 0 the internal Write Enable Latch is reset and no Write Status Register, Program or Erase command is accepted.

BP4, BP3, BP2, BP1, BP0 bits.

The Block Protect (BP4, BP3, BP2, BP1 and BP0) bits are non-volatile. They define the size of the area to be software protected against Program and Erase commands. These bits are written with the Write Status Register (WRSR) command. When the Block Protect (BP4, BP3, BP2, BP1, BP0) bits are set to 1, the relevant memory area (as defined in Table1).becomes protected against Page Program (PP), Sector Erase (SE) and Block Erase (BE) commands. The Block Protect (BP4, BP3, BP2, BP1, and BP0) bits can be written provided that the Hardware Protected mode has not been set. The Chip Erase (CE) command is executed, only if the Block Protect (BP2, BP1, and BP0) bits are 0 and CMP=0 or the Block Protect (BP2, BP1, and BP0) bits are 1 and CMP=1.

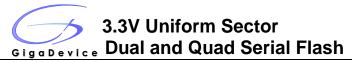
SRP1, SRP0 bits.

The Status Register Protect (SRP1 and SRP0) bits are non-volatile Read/Write bits in the status register. The SRP bits control the method of write protection: software protection, hardware protection, power supply lock-down or one time programmable protection.

SRP1	SRP0	#WP	Status Register	Description		
0	0	Х	Software Protected	The Status Register can be written to after a Write Enable		
U	U	^	Software Protected	command, WEL=1.(Default)		
0	1	0	0 Hardware Protected WP#=0, the Status Register locked and cannot be writt			
0	4	1	Hardwara Haarataatad	WP#=1, the Status Register is unlocked and can be written		
U	'	'	Hardware Unprotected	to after a Write Enable command, WEL=1.		
1	0	Х	Power Supply Lock-	Status Register is protected and cannot be written to again		
_ '		Down ⁽¹⁾⁽²⁾	Down ⁽¹⁾⁽²⁾	until the next Power-Down, Power-Up cycle.		
1	1	Х	One Time Program ⁽²⁾	Status Register is permanently protected and cannot be		
	ľ	٨	One fille Flogram	written to.		

NOTE:

1. When SRP1, SRP0= (1, 0), a Power-Down, Power-Up cycle will change SRP1, SRP0 to (0, 0) state.



2. This feature is available on special order. (GD25Q127CxxSx)Please contact GigaDevice for details.

QE bit.

The Quad Enable (QE) bit is a non-volatile Read/Write bit in the Status Register that allows Quad operation. When the QE bit is set to 0 (Default) the WP# pin and HOLD# / RESET# pin are enable. When the QE pin is set to 1, the Quad IO2 and IO3 pins are enabled. (It is best to set the QE bit to 0 to avoid short issue if the WP# or HOLD# pin is tied directly to the power supply or ground.)

LB3, LB2, LB1 bits.

The LB3, LB2, LB1 bits are non-volatile One Time Program (OTP) bits in Status Register (S13-S11) that provide the write protect control and status to the Security Registers. The default state of LB3-LB1 are 0, the security registers are unlocked. The LB3-LB1 bits can be set to 1 individually using the Write Register instruction. The LB3-LB1 bits are One Time Programmable, once they are set to 1, the Security Registers will become read-only permanently.

CMP bit

The CMP bit is a non-volatile Read/Write bit in the Status Register (S14). It is used in conjunction with the BP4-BP0 bits to provide more flexibility for the array protection. Please see the Status registers Memory Protection table for details. The default setting is CMP=0.

SUS1, SUS2 bits

The SUS1 and SUS2 bits are read only bits in the status register (S15 and S10) that are set to 1 after executing an Program/Erase Suspend (75H) command (The Erase Suspend will set the SUS1 to 1, and the Program Suspend will set the SUS2 to 1). The SUS1 and SUS2 bits are cleared to 0 by Program/Erase Resume (7AH) command, software reset (66H+99H) command as well as a power-down, power-up cycle.

DRV1, DRV0 bits

The DRV1&DRV0 bits are used to determine the output driver strength for the Read operations.

DRV1,DRV0	Driver Strength
00	100%
01	75%
10	50% (default)
11	25%

HOLD/RST bit

The HOLD/RST bit is used to determine whether HOLD# or RESET# function should be implemented on the hardware pin for 8-pin packages. When HOLD/RST=0, the pin acts as HOLD#, When the HOLD/RST=1, the pin acts as RESET#. However, the HOLD# or RESET# function are only available when QE=0, If QE=1, The HOLD# and RESET# functions are disabled, the pin acts as dedicated data I/O pin.

LPE bit

The Low Power Enable (LPE) bit is a non-volatile writable bit, indicating the status of Low Power Mode (LPM). When LPE bit sets to 1, it means the device is in Low Power Mode, when LPE bit sets 0 (default), it means the device is not in Low Power Mode.

7. COMMANDS DESCRIPTION

All commands, addresses and data are shifted in and out of the device, beginning with the most significant bit on the first rising edge of SCLK after CS# is driven low. Then, the one-byte command code must be shifted in to the device, with most significant bit first on SI, and each bit being latched on the rising edges of SCLK.

See Table 7.1., every command sequence starts with a one-byte command code. Depending on the command, this might be followed by address bytes, or by data bytes, or by both or none. CS# must be driven high after the last bit of the command sequence has been completed. For the command of Read, Fast Read, Read Status Register or Release from Deep Power-Down, and Read Device ID, the shifted-in command sequence is followed by a data-out sequence. All read instruction can be completed after any bit of the data-out sequence is being shifted out, and then CS# must be driven high to return to deselected status.

For the command of Page Program, Sector Erase, Block Erase, Chip Erase, Write Status Register, Write Enable, Write Disable or Deep Power-Down command, CS# must be driven high exactly at a byte boundary, otherwise the command is rejected, and is not executed. That is CS# must be driven high when the number of clock pulses after CS# being driven low is an exact multiple of eight. For Page Program, if at any time the input byte is not a full byte, nothing will happen and WEL will not be reset.

Table 7.1. Commands (Standard/Dual/Quad SPI)

Command Name	Byte 1	Byte 2	Byte 3	Byte 4	Byte 5	Byte 6	n-Bytes
Write Enable	06H						
Write Disable	04H						
Volatile SR	50H						
Write Enable							
Read Status Register-1	05H	(S7-S0)					(continuous)
Read Status Register-2	35H	(S15-S8)					(continuous)
Read Status Register-3	15H	(S23-S16)					
Write Status Register-1	01H	S7-S0					
Write Status Register-2	31H	S15-S8					
Write Status Register-3	11H	S23-S16					
Read Data	03H	A23-A16	A15-A8	A7-A0	(D7-D0)	(Next byte)	(continuous)
Fast Read	0BH	A23-A16	A15-A8	A7-A0	dummy	(D7-D0)	(continuous)
Dual Output	3BH	A23-A16	A15-A8	A7-A0	dummy	(D7-D0) ⁽¹⁾	(continuous)
Fast Read							
Dual I/O	BBH	A23-A8 ⁽²⁾	A7-A0	(D7-D0) ⁽¹⁾			(continuous)
Fast Read			M7-M0 ⁽²⁾				
Quad Output	6BH	A23-A16	A15-A8	A7-A0	dummy	(D7-D0) ⁽³⁾	(continuous)
Fast Read							
Quad I/O	EBH	A23-A0	dummy ⁽⁵⁾	(D7-D0) ⁽³⁾			(continuous)
Fast Read		M7-M0 ⁽⁴⁾					
Quad I/O Word	E7H	A23-A0	dummy ⁽⁶⁾	(D7-D0) ⁽³⁾			(continuous)
Fast Read ⁽⁷⁾		M7-M0 ⁽⁴⁾					
Page Program	02H	A23-A16	A15-A8	A7-A0	D7-D0	Next byte	
Quad Page Program	32H	A23-A16	A15-A8	A7-A0	D7-D0		
Sector Erase	20H	A23-A16	A15-A8	A7-A0			
Block Erase(32K)	52H	A23-A16	A15-A8	A7-A0			
Block Erase(64K)	D8H	A23-A16	A15-A8	A7-A0			
Chip Erase	C7/60						
	Н						
Enable Reset	66H						
Reset	99H						
Set Burst with Wrap	77H	dummy ⁽⁹⁾					



3.3V Uniform Sector Giga Device Dual and Quad Serial Flash

GD25Q127C

		W7-W0					
Program/Erase Suspend	75H						
Program/Erase Resume	7AH						
Release From Deep Power-Down, And Read Device ID	ABH	dummy	dummy	dummy	(DID7- DID0)		(continuous)
Release From Deep Power-Down	ABH						
Deep Power-Down	В9Н						
Manufacturer/ Device ID	90H	dummy	dummy	00H	(MID7- MID0)	(DID7- DID0)	(continuous)
Manufacturer/ Device ID by Dual I/O	92H	A23-A8	A7-A0, M7-M0	(MID7- MID0) (DID7- DID0)			(continuous)
Manufacturer/ Device ID by Quad I/O	94H	A23-A0, M7-M0	dummy (10)(MID7- MID0) (DID7- DID0)				(continuous)
Read Identification	9FH	(MID7- MID0)	(JDID15- JDID8)	(JDID7- JDID0)			(continuous)
Read Serial Flash Discoverable Parameter	5AH	A23-A16	A15-A8	A7-A0	dummy	(D7-D0)	(continuous)
Read Unique ID	4BH	dummy	dummy	dummy	dummy	(UID7- UID0)	(continuous)
Erase Security Registers ⁽⁸⁾	44H	A23-A16	A15-A8	A7-A0			
Program Security Registers ⁽⁸⁾	42H	A23-A16	A15-A8	A7-A0	D7-D0	D7-D0	
Read Security Registers ⁽⁸⁾	48H	A23-A16	A15-A8	A7-A0	dummy	(D7-D0)	

NOTE:

1. Dual Output data

IO0=(D6,D4,D2,D0)

IO1=(D7,D5,D3,D1)

2. Dual Input Address

IO0=A22,A20,A18,A16,A14,A12,A10,A8 A6,A4,A2,A0,M6,M4,M2,M0

IO1=A23,A21,A19,A17,A15,A13,A11,A9 A7,A5,A3,A1,M7,M5,M3,M1

3. Quad Output Data

IO0=(D4,D0,....)

IO1=(D5,D1,....)

IO2=(D6,D2,....)

IO3=(D7,D3,....)

4. Quad Input Address

IO0=A20,A16,A12,A8, A4,A0,M4,M0

IO1=A21,A17,A13,A9, A5,A1,M5,M1

IO2=A22,A18,A14,A10,A6,A2,M6,M2

IO3=A23,A19,A15,A11,A7,A3,M7,M3

5. Fast Read Quad I/O Data

IO0=(x,x,x,x, D4, D0,...)

IO1=(x,x,x,x, D5, D1,...)

IO2=(x,x,x,x, D6, D2,...)

IO3=(x,x,x,x, D7, D3,...)

6. Fast Word Read Quad I/O Data

IO0=(x,x, D4, D0,...)

IO1=(x,x, D5, D1,...)

IO2=(x,x, D6, D2,...)

IO3=(x,x, D7, D3,...)

- 7. Fast Word Read Quad I/O Data: the lowest address bit must be 0.
- 8. Security Registers Address:

Security Register1: A23-A16=00H, A15-A10=000100b, A9-A0=Byte Address;

Security Register2: A23-A16=00H, A15-A10=001000b, A9-A0=Byte Address;

Security Register3: A23-A16=00H, A15-A10=001100b, A9-A0=Byte Address.

9. Dummy bits and Wrap Bits

100=(x,x, x,x, x,x, W4,x)

IO1=(x,x, x,x, x,x, W5, x)

102=(x,x, x,x, x,x, W6, x)

103=(x,x, x,x, x,x, x, x)

10. Address, Continuous Read Mode bits, Dummy bits, Manufacture ID and Device ID

IO0=(A20, A16, A12, A8, A4, A0, M4, M0, x,x, x,x, MID4, MID0, DID4, DID0, ...)

IO1=(A21, A17, A13, A9, A5, A1, M5, M1, x,x, x,x, MID5, MID1, DID5, DID1, ...)

IO2=(A22, A18, A14, A10, A6, A2, M6, M2,x,x, x,x, MID6, MID2, DID6, DID2, ...)

IO3=(A23, A19, A15, A11, A7, A3, M7, M3, x,x, x,x, MID7, MID3, DID7, DID3, ...)

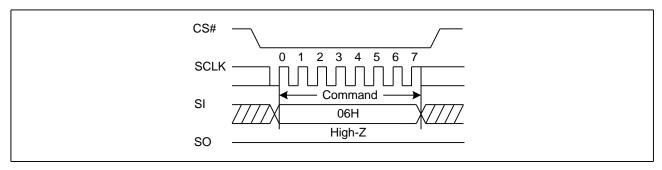
Table 7.2. Table of ID Definitions for GD25Q127C

Operation Code	MID7-MID0	ID15-ID8	ID7-ID0
9FH	C8	40	18
90H/92H/94H	C8		17
ABH			17

7.1. Write Enable (WREN) (06H)

The Write Enable (WREN) command is for setting the Write Enable Latch (WEL) bit. The Write Enable Latch (WEL) bit must be set prior to every Page Program (PP), Sector Erase (SE), Block Erase (BE), Chip Erase (CE), Write Status Register (WRSR) and Erase/Program Security Registers command. The Write Enable (WREN) command sequence: CS# goes low → sending the Write Enable command → CS# goes high.

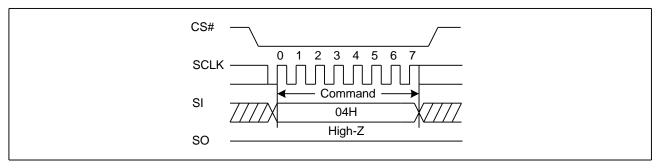
Figure 3. Write Enable Sequence Diagram



7.2. Write Disable (WRDI) (04H)

The Write Disable command is for resetting the Write Enable Latch (WEL) bit. The Write Disable command sequence: CS# goes low→Sending the Write Disable command →CS# goes high. The WEL bit is reset by following condition: Power-up and upon completion of the Write Status Register, Page Program, Sector Erase, Block Erase, Chip Erase, Erase/Program Security Registers and Reset commands.

Figure 4. Write Disable Sequence Diagram



7.3. Write Enable for Volatile Status Register (50H)

The non-volatile Status Register bits can also be written to as volatile bits. This gives more flexibility to change the system configuration and memory protection schemes quickly without waiting for the typical non-volatile bit write cycles or affecting the endurance of the Status Register non-volatile bits. The Write Enable for Volatile Status Register command must be issued prior to a Write Status Register command, and any other commands cannot be inserted between them. Otherwise, Write Enable for Volatile Status Register will be cleared. The Write Enable for Volatile Status Register command will not set the Write Enable Latch bit, it is only valid for the Write Status Register command to change the volatile Status Register bit values.

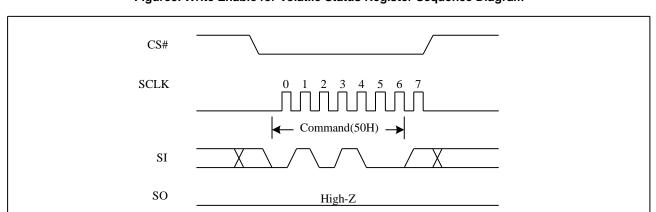


Figure 5. Write Enable for Volatile Status Register Sequence Diagram

7.4. Read Status Register (RDSR) (05H or 35H or 15H)

The Read Status Register (RDSR) command is for reading the Status Register. The Status Register may be read at any time, even while a Program, Erase or Write Status Register cycle is in progress. When one of these cycles is in progress, it is recommended to check the Write in Progress (WIP) bit before sending a new command to the device. It is also possible to read the Status Register continuously. For command code "05H"/ "35H" / "15H", the SO will output Status Register bits S7~S0/S15-S8 / S23-S16.

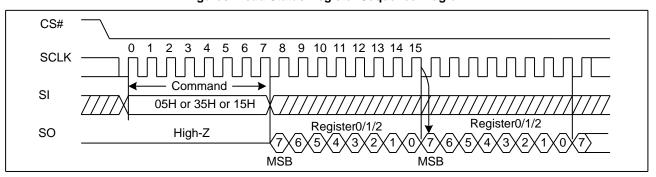


Figure 6. Read Status Register Sequence Diagram

7.5. Write Status Register (WRSR) (01H or 31H or 11H)

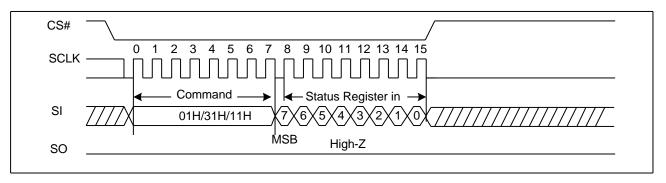
The Write Status Register (WRSR) command allows new values to be written to the Status Register. Before it can be accepted, a Write Enable (WREN) command must previously have been executed. After the Write Enable (WREN) command has been decoded and executed, the device sets the Write Enable Latch (WEL).

The Write Status Register (WRSR) command has no effect on S20, S19, S17, S16, S15, S10, S1 and S0 of the Status Register. CS# must be driven high after the eighth of the data byte has been latched in. If not, the Write Status Register (WRSR) command is not executed. As soon as CS# is driven high, the self-timed Write Status Register cycle (whose duration is tw) is initiated. While the Write Status Register cycle is in progress, the Status Register may still be read to check the value of the Write In Progress (WIP) bit. The Write In Progress (WIP) bit is 1 during the self-timed Write Status Register cycle, and is 0 when it is completed. When the cycle is completed, the Write Enable Latch (WEL) is reset.

The Write Status Register (WRSR) command allows the user to change the values of the Block Protect (BP4, BP3, BP2, BP1, and BP0) bits, to define the size of the area that is to be treated as read-only. The Write Status Register (WRSR) command also allows the user to set or reset the Status Register Protect (SRP1 and SRP0) bits in accordance with the Write Protect (WP#) signal. The Status Register Protect (SRP1 and SRP0) bits and Write Protect (WP#) signal allow the device to be put in the Hardware Protected Mode. The Write Status Register (WRSR) command is not executed once the

Hardware Protected Mode is entered.

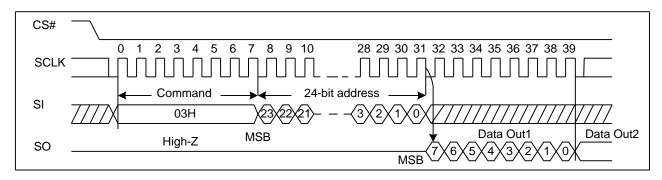
Figure 7. Write Status Register Sequence Diagram



7.6. Read Data Bytes (READ) (03H)

The Read Data Bytes (READ) command is followed by a 3-byte address (A23-A0), and each bit is latched-in on the rising edge of SCLK. Then the memory content, at that address, is shifted out on SO, each bit being shifted out, at a Max frequency f_R, during the falling edge of SCLK. Then the memory content at that address is shifted out on SO. The first byte addressed can be at any location. The address is automatically incremented to the next higher address after each byte of data is shifted out. The whole memory can, therefore, be read with a single Read Data Bytes (READ) command. Any Read Data Bytes (READ) command, while an Erase, Program or Write cycle is in progress, is rejected without having any effects on the cycle that is in progress.

Figure8. Read Data Bytes Sequence Diagram



Read Data Bytes at Higher Speed (Fast Read) (0BH)

The Read Data Bytes at Higher Speed (Fast Read) command is for quickly reading data out. It is followed by a 3-byte address (A23-A0) and a dummy byte, each bit being latched-in during the rising edge of SCLK. Then the memory content, at that address, is shifted out on SO, each bit being shifted out, at a Max frequency fc, during the falling edge of SCLK. The first byte addressed can be at any location. The address is automatically incremented to the next higher address after each byte of data is shifted out.

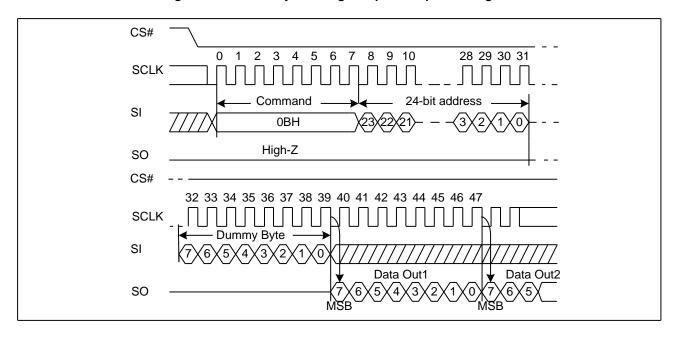


Figure 9. Read Data Bytes at Higher Speed Sequence Diagram

7.8. Dual Output Fast Read (3BH)

The Dual Output Fast Read command is followed by 3-byte address (A23-A0) and a dummy byte, each bit being latched in during the rising edge of SCLK, then the memory contents are shifted out 2-bit per clock cycle from SI and SO. The command sequence is shown in followed Figure 10. The first byte addressed can be at any location. The address is automatically incremented to the next higher address after each byte of data is shifted out.

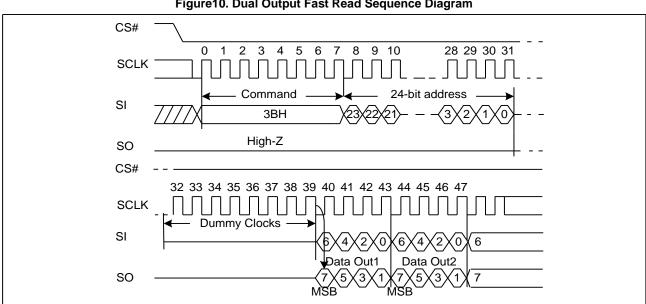


Figure 10. Dual Output Fast Read Sequence Diagram

7.9. Quad Output Fast Read (6BH)

The Quad Output Fast Read command is followed by 3-byte address (A23-A0) and a dummy byte, each bit being latched in during the rising edge of SCLK, then the memory contents are shifted out 4-bit per clock cycle from IO3, IO2, IO1 and IO0. The command sequence is shown in followed Figure11. The first byte addressed can be at any location. The address is automatically incremented to the next higher address after each byte of data is shifted out.

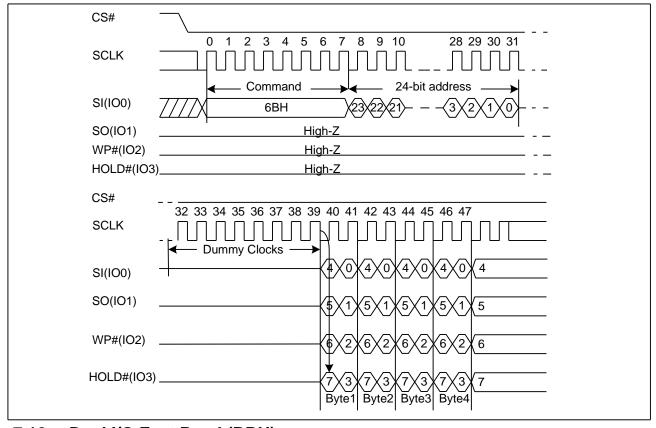


Figure 11. Quad Output Fast Read Sequence Diagram

7.10. Dual I/O Fast Read (BBH)

The Dual I/O Fast Read command is similar to the Dual Output Fast Read command but with the capability to input the 3-byte address (A23-0) and a "Continuous Read Mode" byte 2-bit per clock by SI and SO, each bit being latched in during the rising edge of SCLK, then the memory contents are shifted out 2-bit per clock cycle from SI and SO. The command sequence is shown in followed Figure 12. The first byte addressed can be at any location. The address is automatically incremented to the next higher address after each byte of data is shifted out.

Dual I/O Fast Read with "Continuous Read Mode"

The Dual I/O Fast Read command can further reduce command overhead through setting the "Continuous Read Mode" bits (M7-4) after the input 3-byte address (A23-A0). If the "Continuous Read Mode" bits (M5-4)= (1, 0), then the next Dual I/O Fast Read command (after CS# is raised and then lowered) does not require the BBH command code. The command sequence is shown in followed Figure12a. If the "Continuous Read Mode" bits (M5-4) do not equal (1, 0), the next command requires the first BBH command code, thus returning to normal operation. A "Continuous Read Mode" Reset command can be used to reset (M5-4) before issuing normal command.



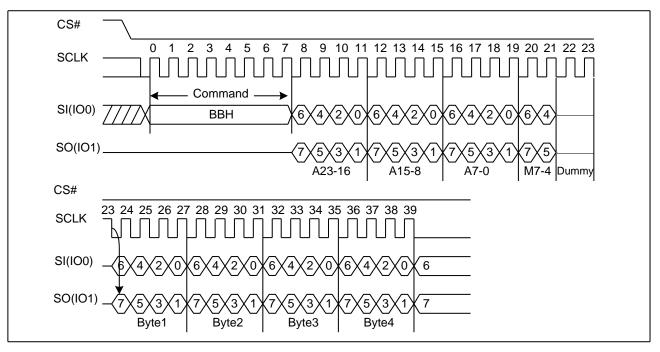
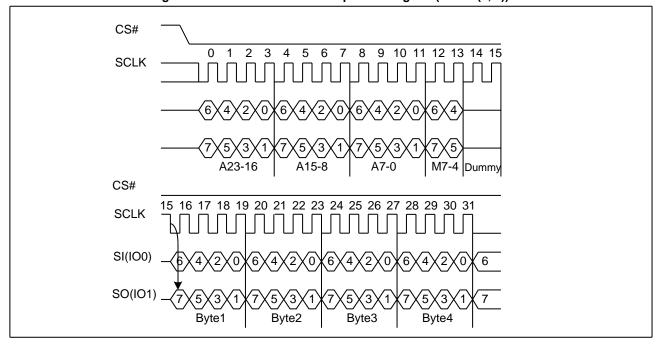


Figure12a. Dual I/O Fast Read Sequence Diagram (M5-4= (1, 0))



7.11. Quad I/O Fast Read (EBH)

The Quad I/O Fast Read command is similar to the Dual I/O Fast Read command but with the capability to input the 3-byte address (A23-0) and a "Continuous Read Mode" byte and 4-dummy clock4-bit per clock by IO0, IO1, IO2, IO3, each bit being latched in during the rising edge of SCLK, then the memory contents are shifted out 4-bit per clock cycle from IO0, IO1, IO2, IO3. The command sequence is shown in followed Figure 13. The first byte addressed can be at any location. The address is automatically incremented to the next higher address after each byte of data is shifted out. The Quad Enable bit (QE) of Status Register (S9) must be set to enable for the Quad I/O Fast read command.

Quad I/O Fast Read with "Continuous Read Mode"

The Quad I/O Fast Read command can further reduce command overhead through setting the "Continuous Read Mode" bits (M7-0) after the input 3-byte address (A23-A0). If the "Continuous Read Mode" bits (M5-4) = (1, 0), then the next Quad I/O Fast Read command (after CS# is raised and then lowered) does not require the EBH command code. The command sequence is shown in followed Figure13a. If the "Continuous Read Mode" bits (M5-4) do not equal to (1, 0), the next command requires the first EBH command code, thus returning to normal operation. A "Continuous Read Mode" Reset command can be used to reset (M5-4) before issuing normal command.

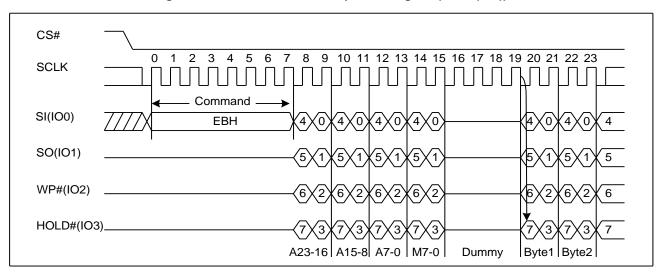
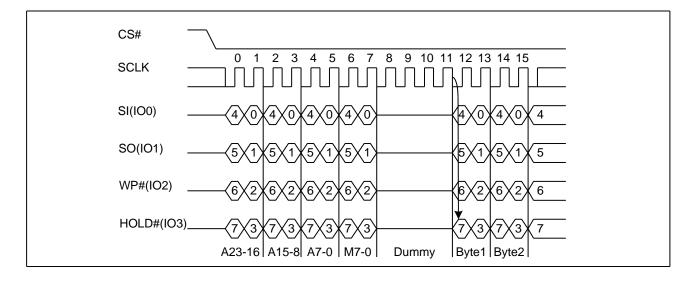


Figure 13. Quad I/O Fast Read Sequence Diagram (M5-4≠(1, 0))





Quad I/O Fast Read with "8/16/32/64-Byte Wrap Around" in Standard SPI Mode

The Quad I/O Fast Read command can be used to access a specific portion within a page by issuing "Set Burst with Wrap" (77H) commands prior to EBH. The "Set Burst with Wrap" (77H) command can either enable or disable the "Wrap Around" feature for the following EBH commands. When "Wrap Around" is enabled, the data being accessed can be limited to either an8/16/32/64-byte section of a 256-byte page. The output data starts at the initial address specified in the command, once it reaches the ending boundary of the 8/16/32/64-byte section, the output will wrap around the beginning boundary automatically until CS# is pulled high to terminate the command.

The Burst with Wrap feature allows applications that use cache to quickly fetch a critical address and then fill the cache

afterwards within a fixed length (8/16/32/64-byte) of data without issuing multiple read commands. The "Set Burst with Wrap" command allows three "Wrap Bits" W6-W4 to be set. The W4 bit is used to enable or disable the "Wrap Around" operation while W6-W5 is used to specify the length of the wrap around section within a page.

7.12. Quad I/O Word Fast Read (E7H)

The Quad I/O Word Fast Read command is similar to the Quad I/O Fast Read command except that the lowest address bit (A0) must equal 0 and only 2-dummy clock. The command sequence is shown in followed Figure 14. The first byte addressed can be at any location. The address is automatically incremented to the next higher address after each byte of data is shifted out. The Quad Enable bit (QE) of Status Register (S9) must be set to enable for the Quad I/O Word Fast read command.

Quad I/O Word Fast Read with "Continuous Read Mode"

The Quad I/O Word Fast Read command can further reduce command overhead through setting the "Continuous Read Mode" bits (M7-0) after the input 3-byte address (A23-A0). If the "Continuous Read Mode" bits (M5-4) =(1, 0), then the next Quad I/O Word Fast Read command (after CS# is raised and then lowered) does not require the E7H command code. The command sequence is shown in followed Figure 14a. If the "Continuous Read Mode" bits (M5-4) do not equal to (1, 0), the next command requires the first E7H command code, thus returning to normal operation. A "Continuous Read Mode" Reset command can be used to reset (M5-4) before issuing normal command.

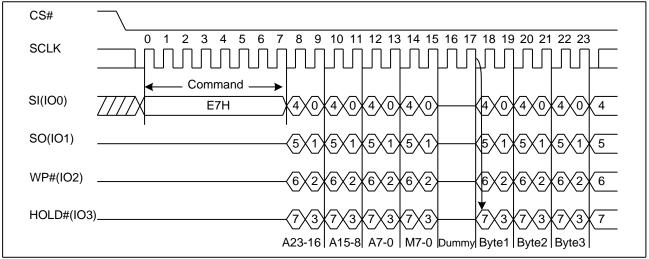
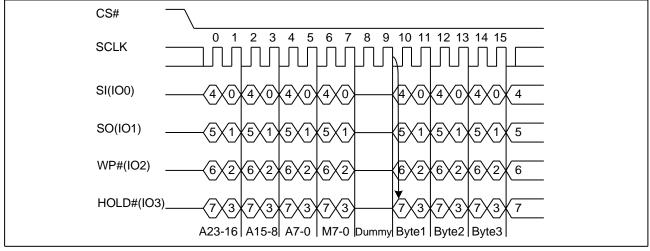


Figure 14. Quad I/O Word Fast Read Sequence Diagram (M5-4≠ (1, 0))

Figure14a. Quad I/O Word Fast Read Sequence Diagram (M5-4= (1, 0))



Quad I/O Word Fast Read with "8/16/32/64-Byte Wrap Around" in Standard SPI Mode

The Quad I/O Word Fast Read command can be used to access a specific portion within a page by issuing "Set Burst with Wrap" (77H) commands prior to E7H. The "Set Burst with Wrap" (77H) command can either enable or disable the "Wrap Around" feature for the following E7H commands. When "Wrap Around" is enabled, the data being accessed can be limited to either an 8/16/32/64-byte section of a 256-byte page. The output data starts at the initial address specified in the command, once it reaches the ending boundary of the 8/16/32/64-byte section, the output will wrap around the beginning boundary automatically until CS# is pulled high to terminate the command.

The Burst with Wrap feature allows applications that use cache to quickly fetch a critical address and then fill the cache afterwards within a fixed length (8/16/32/64-byte) of data without issuing multiple read commands. The "Set Burst with Wrap" command allows three "Wrap Bits" W6-W4 to be set. The W4 bit is used to enable or disable the "Wrap Around" operation while W6-W5 is used to specify the length of the wrap around section within a page.

7.13. Set Burst with Wrap (77H)

The Set Burst with Wrap command is used in conjunction with "Quad I/O Fast Read" and "Quad I/O Word Fast Read" command to access a fixed length of 8/16/32/64-byte section within a 256-byte page.

The Set Burst with Wrap command sequence: CS# goes low →Send Set Burst with Wrap command→ Send 24 dummy bits → Send 8 bits "Wrap bits" → CS# goes high.

W6,W5	W4	l=0	W4=1 (default)		
	Wrap Around	Wrap Length	Wrap Around	Wrap Length	
0, 0	Yes	8-byte	No	N/A	
0, 1	Yes	16-byte	No	N/A	
1, 0	Yes	32-byte	No	N/A	
1, 1	Yes	64-byte	No	N/A	

If the W6-W4 bits are set by the Set Burst with Wrap command, all the following "Quad I/O Fast Read" and "Quad I/O Word Fast Read" command will use the W6-W4 setting to access the 8/16/32/64-byte section within any page. To exit the "Wrap Around" function and return to normal read operation, another Set Burst with Wrap command should be issued to set W4=1.

CS#

SCLK

0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15

SI(IO0)

77H

XXXXXXXXXXXX

SO(IO1)

WP#(IO2)

WP#(IO2)

HOLD#(IO3)

XXXXXXXXXXXXXX

W6-W4

Figure 15. Set Burst with Wrap Sequence Diagram

7.14. Page Program (PP) (02H)

The Page Program (PP) command is for programming the memory. A Write Enable (WREN) command must previously have been executed to set the Write Enable Latch (WEL) bit before sending the Page Program command.

The Page Program (PP) command is entered by driving CS# Low, followed by the command code, three address bytes and at least one data byte on SI. If the 8 least significant address bits (A7-A0) are not all zero, all transmitted data that goes beyond the end of the current page are programmed from the start address of the same page (from the address whose 8 least significant bits (A7-A0) are all zero). CS# must be driven low for the entire duration of the sequence. The Page Program command sequence: CS# goes low → sending Page Program command → 3-byte address on SI → at least 1 byte data on SI →CS# goes high. The command sequence is shown in Figure 16. If more than 256 bytes are sent to the device, previously latched data are discarded and the last 256 data bytes are guaranteed to be programmed correctly within the same page. If less than 256 data bytes are sent to device, they are correctly programmed at the requested addresses without having any effects on the other bytes of the same page. CS# must be driven high after the eighth bit of the last data byte has been latched in; otherwise the Page Program (PP) command is not executed.

As soon as CS# is driven high, the self-timed Page Program cycle (whose duration is t_{PP}) is initiated. While the Page Program cycle is in progress, the Status Register may be read to check the value of the Write in Progress (WIP) bit. The Write in Progress (WIP) bit is 1 during the self-timed Page Program cycle, and is 0 when it is completed. At some unspecified time before the cycle is completed, the Write Enable Latch (WEL) bit is reset.

A Page Program (PP) command applied to a page which is protected by the Block Protect (BP4, BP3, BP2, BP1, and BP0) is not executed.

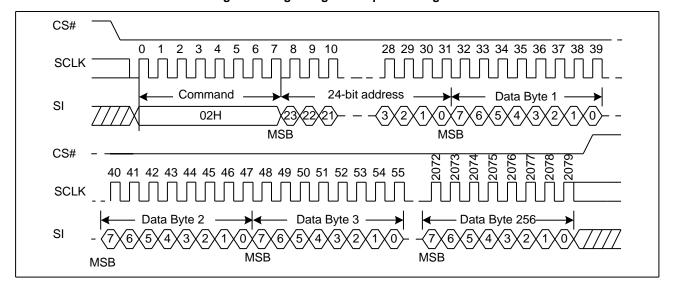


Figure 16. Page Program Sequence Diagram

7.15. Quad Page Program (32H)

The Quad Page Program command is for programming the memory using four pins: IO0, IO1, IO2, and IO3. To use Quad Page Program the Quad enable in status register Bit9 must be set (QE=1). A Write Enable (WREN) command must previously have been executed to set the Write Enable Latch (WEL) bit before sending the Page Program command. The quad Page Program command is entered by driving CS# Low, followed by the command code (32H), three address bytes and at least one data byte on IO pins.

The command sequence is shown in Figure 17. If more than 256 bytes are sent to the device, previously latched data are discarded and the last 256 data bytes are guaranteed to be programmed correctly within the same page. If less than 256 data bytes are sent to device, they are correctly programmed at the requested addresses without having any effects on

the other bytes of the same page. CS# must be driven high after the eighth bit of the last data byte has been latched in; otherwise the Quad Page Program (PP) command is not executed.

As soon as CS# is driven high, the self-timed Quad Page Program cycle (whose duration is tpp) is initiated. While the Quad Page Program cycle is in progress, the Status Register may be read to check the value of the Write In Progress (WIP) bit. The Write in Progress (WIP) bit is 1 during the self-timed Quad Page Program cycle, and is 0 when it is completed. At some unspecified time before the cycle is completed, the Write Enable Latch (WEL) bit is reset.

A Quad Page Program command applied to a page which is protected by the Block Protect (BP4, BP3, BP2, BP1, and BP0) is not executed.

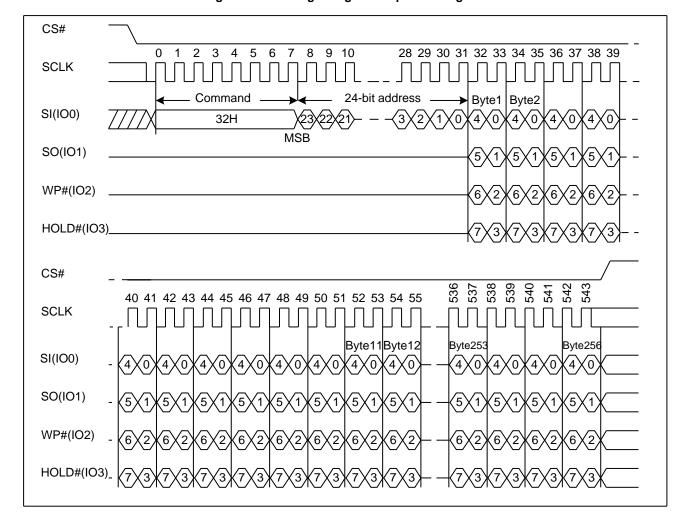


Figure 17. Quad Page Program Sequence Diagram

7.16. Sector Erase (SE) (20H)

The Sector Erase (SE) command is erased the all data of the chosen sector. A Write Enable (WREN) command must previously have been executed to set the Write Enable Latch (WEL) bit. The Sector Erase (SE) command is entered by driving CS# low, followed by the command code, and 3-address byte on SI. Any address inside the sector is a valid address for the Sector Erase (SE) command. CS# must be driven low for the entire duration of the sequence.

The Sector Erase command sequence: CS# goes low \rightarrow sending Sector Erase command \rightarrow 3-byte address on SI \rightarrow CS# goes high. The command sequence is shown in Figure 18. CS# must be driven high after the eighth bit of the last address byte has been latched in; otherwise the Sector Erase (SE) command is not executed. As soon as CS# is driven high, the self-timed Sector Erase cycle (whose duration is t_{SE}) is initiated. While the Sector Erase cycle is in progress, the

Status Register may be read to check the value of the Write in Progress (WIP) bit. The Write in Progress (WIP) bit is 1 during the self-timed Sector Erase cycle, and is 0 when it is completed. At some unspecified time before the cycle is completed, the Write Enable Latch (WEL) bit is reset. A Sector Erase (SE) command applied to a sector which is protected by the Block Protect (BP4, BP3, BP2, BP1, and BP0) bit is not executed.

Figure 18. Sector Erase Sequence Diagram

7.17. 32KB Block Erase (BE) (52H)

The 32KB Block Erase (BE) command is erased the all data of the chosen block. A Write Enable (WREN) command must previously have been executed to set the Write Enable Latch (WEL) bit. The 32KB Block Erase (BE) command is entered by driving CS# low, followed by the command code, and three address bytes on SI. Any address inside the block is a valid address for the 32KB Block Erase (BE) command. CS# must be driven low for the entire duration of the sequence.

The 32KB Block Erase command sequence: CS# goes low \rightarrow sending 32KB Block Erase command \rightarrow 3-byte address on SI \rightarrow CS# goes high. The command sequence is shown in Figure 19. CS# must be driven high after the eighth bit of the last address byte has been latched in; otherwise the 32KB Block Erase (BE) command is not executed. As soon as CS# is driven high, the self-timed Block Erase cycle (whose duration is t_{BE}) is initiated. While the Block Erase cycle is in progress, the Status Register may be read to check the value of the Write in Progress (WIP) bit. The Write in Progress (WIP) bit is 1 during the self-timed Block Erase cycle, and is 0 when it is completed. At some unspecified time before the cycle is completed, the Write Enable Latch (WEL) bit is reset. A 32KB Block Erase (BE) command applied to a block which is protected by the Block Protect (BP4, BP3, BP2, BP1, and BP0) bits is not executed.

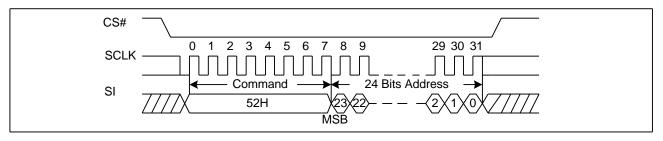


Figure 19. 32KB Block Erase Sequence Diagram

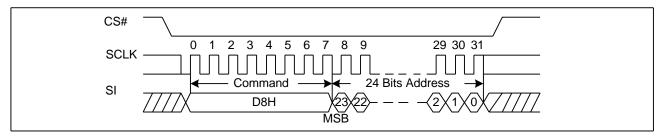
7.18. 64KB Block Erase (BE) (D8H)

The 64KB Block Erase (BE) command is erased the all data of the chosen block. A Write Enable (WREN) command must previously have been executed to set the Write Enable Latch (WEL) bit. The 64KB Block Erase (BE) command is entered by driving CS# low, followed by the command code, and three address bytes on SI. Any address inside the block is a valid address for the 64KB Block Erase (BE) command. CS# must be driven low for the entire duration of the sequence.

The 64KB Block Erase command sequence: CS# goes low → sending 64KB Block Erase command → 3-byte address on SI → CS# goes high. The command sequence is shown in Figure 20. CS# must be driven high after the eighth bit of the last address byte has been latched in; otherwise the 64KB Block Erase (BE) command is not executed. As soon as CS# is

driven high, the self-timed Block Erase cycle (whose duration is t_{BE}) is initiated. While the Block Erase cycle is in progress, the Status Register may be read to check the value of the Write in Progress (WIP) bit. The Write in Progress (WIP) bit is 1 during the self-timed Block Erase cycle, and is 0 when it is completed. At some unspecified time before the cycle is completed, the Write Enable Latch (WEL) bit is reset. A 64KB Block Erase (BE) command applied to a block which is protected by the Block Protect (BP4, BP3, BP2, BP1, and BP0) bits is not executed.

Figure 20. 64KB Block Erase Sequence Diagram

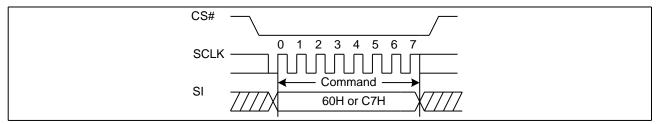


7.19. Chip Erase (CE) (60/C7H)

The Chip Erase (CE) command is erased the all data of the chip. A Write Enable (WREN) command must previously have been executed to set the Write Enable Latch (WEL) bit .The Chip Erase (CE) command is entered by driving CS# Low, followed by the command code on Serial Data Input (SI). CS# must be driven Low for the entire duration of the sequence.

The Chip Erase command sequence: CS# goes low \rightarrow sending Chip Erase command \rightarrow CS# goes high. The command sequence is shown in Figure21. CS# must be driven high after the eighth bit of the command code has been latched in; otherwise the Chip Erase command is not executed. As soon as CS# is driven high, the self-timed Chip Erase cycle (whose duration is t_{CE}) is initiated. While the Chip Erase cycle is in progress, the Status Register may be read to check the value of the Write in Progress (WIP) bit. The Write in Progress (WIP) bit is 1 during the self-timed Chip Erase cycle, and is 0 when it is completed. At some unspecified time before the cycle is completed, the Write Enable Latch (WEL) bit is reset. The Chip Erase (CE) command is executed if the Block Protect (BP2, BP1, and BP0) bits are 0 and CMP=0 or the Block Protect (BP2, BP1, and BP0) bits are 1 and CMP=1. The Chip Erase (CE) command is ignored if one or more sectors are protected

Figure 21. Chip Erase Sequence Diagram



7.20. Deep Power-Down (DP) (B9H)

Executing the Deep Power-Down (DP) command is the only way to put the device in the lowest consumption mode (the Deep Power-Down Mode). It can also be used as an extra software protection mechanism, while the device is not in active use, since in this mode, the device ignores all Write, Program and Erase commands. Driving CS# high deselects the device, and puts the device in the Standby Mode (if there is no internal cycle currently in progress). But this mode is not the Deep Power-Down Mode. The Deep Power-Down Mode can only be entered by executing the Deep Power-Down (DP) command. Once the device has entered the Deep Power-Down Mode, all commands are ignored except the Release from Deep Power-Down and Read Device ID (RDI) (ABH) or Enable Reset (66H) and Reset (99H) commands. These commands can release the device from this mode. The Release from Deep Power-Down and Read Device ID (RDI) command releases

the device from deep power down mode, also allows the Device ID of the device to be output on SO.

The Deep Power-Down Mode automatically stops at Power-Down, and the device is in the Standby Mode after Power-Up. The Deep Power-Down (DP) command is entered by driving CS# low, followed by the command code on SI. CS# must be driven low for the entire duration of the sequence.

The Deep Power-Down command sequence: CS# goes low \rightarrow sending Deep Power-Down command \rightarrow CS# goes high. The command sequence is shown in Figure 22. CS# must be driven high after the eighth bit of the command code has been latched in; otherwise the Deep Power-Down (DP) command is not executed. As soon as CS# is driven high, it requires a delay of t_{DP} before the supply current is reduced to t_{CC2} and the Deep Power-Down Mode is entered. Any Deep Power-Down (DP) command, while an Erase, Program or Write cycle is in progress, is rejected without having any effects on the cycle that is in progress.

SCLK 0 1 2 3 4 5 6 7

SCLK Command Stand-by mode Deep Power-down mode

B9H

Figure 22. Deep Power-Down Sequence Diagram

7.21. Release from Deep Power-Down and Read Device ID (RDI) (ABH)

The Release from Power-Down and Read Device ID command is a multi-purpose command. It can be used to release the device from the Power-Down state or obtain the devices electronic identification (ID) number.

To release the device from the Power-Down state, the command is issued by driving the CS# pin low, shifting the instruction code "ABH" and driving CS# high as shown below. Release from Power-Down will take the time duration of trees (See AC Characteristics) before the device will resume normal operation and other command are accepted. The CS# pin must remain high during the trees time duration.

When used only to obtain the Device ID while not in the Power-Down state, the command is initiated by driving the CS# pin low and shifting the instruction code "ABH" followed by 3-dummy byte. The Device ID bits are then shifted out on the falling edge of SCLK with most significant bit (MSB) first as shown below. The Device ID value is listed in Manufacturer and Device Identification table. The Device ID can be read continuously. The command is completed by driving CS# high.

When used to release the device from the Power-Down state and obtain the Device ID, the command is the same as previously described, except that after CS# is driven high it must remain high for a time duration of t_{RES2} (See AC Characteristics). After this time duration the device will resume normal operation and other command will be accepted. If the Release from Power-Down / Device ID command is issued while an Erase, Program or Write cycle is in process (when WIP equal 1) the command is ignored and will not have any effects on the current cycle.

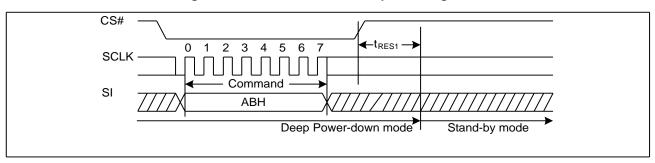


Figure 23. Release Power-Down Sequence Diagram

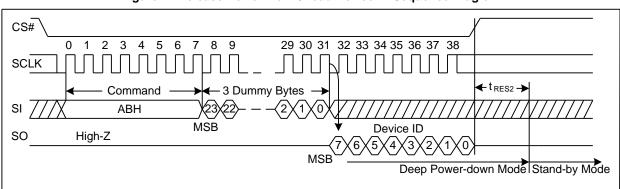


Figure 24. Release Power-Down/Read Device ID Sequence Diagram

7.22. Read Manufacture ID/ Device ID (REMS) (90H)

The Read Manufacturer/Device ID command is an alternative to the Release from Power-Down / Device ID command that provides both the JEDEC assigned Manufacturer ID and the specific Device ID.

The command is initiated by driving the CS# pin low and shifting the command code "90H" followed by a 24-bit address (A23-A0) of 000000H. After which, the Manufacturer ID and the Device ID are shifted out on the falling edge of SCLK with most significant bit (MSB) first as shown in Figure 25. If the 24-bit address is initially set to 000001H, the Device ID will be read first.

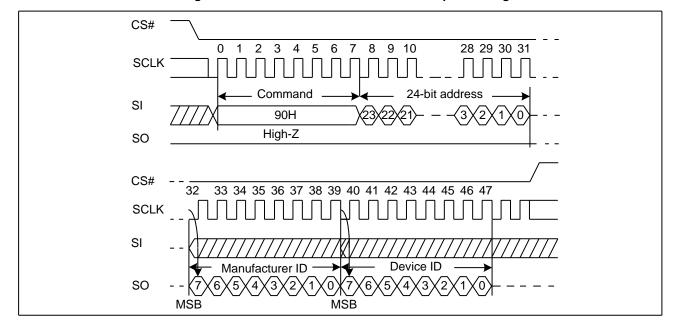


Figure 25. Read Manufacture ID/ Device ID Sequence Diagram

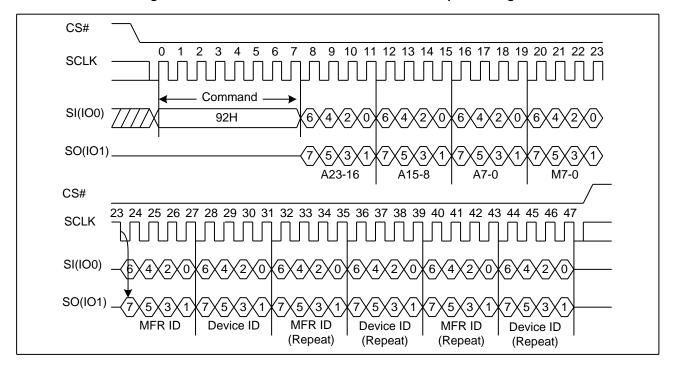
7.23. Read Manufacture ID/ Device ID Dual I/O (92H)

The Read Manufacturer/Device ID Dual I/O command is an alternative to the Release from Power-Down / Device ID command that provides both the JEDEC assigned Manufacturer ID and the specific Device ID by dual I/O.

The command is initiated by driving the CS# pin low and shifting the command code "92H" followed by a 24-bit address (A23-A0) of 000000H. After which, the Manufacturer ID and the Device ID are shifted out on the falling edge of SCLK with most significant bit (MSB) first as shown in Figure 26. If the 24-bit address is initially set to 000001H, the Device ID will be

read first.

Figure 26. Read Manufacture ID/ Device ID Dual I/O Sequence Diagram



7.24. Read Manufacture ID/ Device ID Quad I/O (94H)

The Read Manufacturer/Device ID Quad I/O command is an alternative to the Release from Power-Down / Device ID command that provides both the JEDEC assigned Manufacturer ID and the specific Device ID by quad I/O.

The command is initiated by driving the CS# pin low and shifting the command code "94H" followed by a 24-bit address (A23-A0) of 000000H. After which, the Manufacturer ID and the Device ID are shifted out on the falling edge of SCLK with most significant bit (MSB) first as shown in Figure 27. If the 24-bit address is initially set to 000001H, the Device ID will be read first.

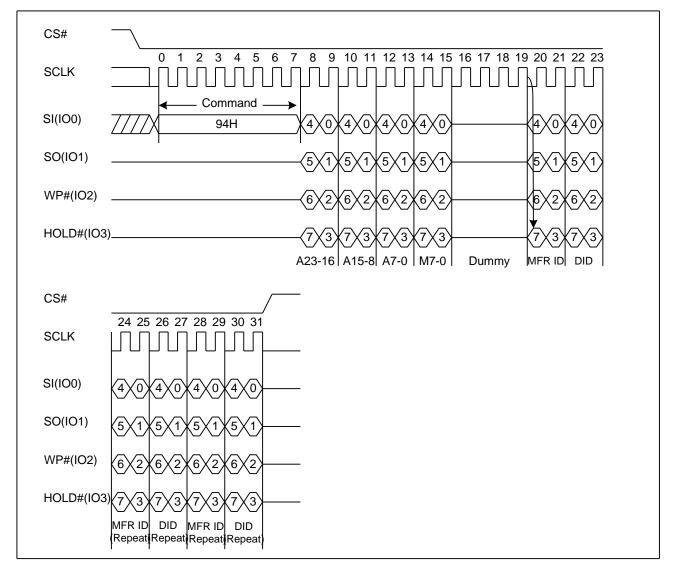


Figure 27. Read Manufacture ID/ Device ID Quad I/O Sequence Diagram

7.25. Read Identification (RDID) (9FH)

The Read Identification (RDID) command allows the 8-bit manufacturer identification to be read, followed by two bytes of device identification. The device identification indicates the memory type in the first byte, and the memory capacity of the device in the second byte. The Read Identification (RDID) command while an Erase or Program cycle is in progress is not decoded, and has no effect on the cycle that is in progress. The Read Identification (RDID) command should not be issued while the device is in Deep Power-Down Mode.

The device is first selected by driving CS# low. Then, the 8-bit command code for the command is shifted in. This is followed by the 24-bit device identification, stored in the memory. Each bit is shifted out on the falling edge of Serial Clock. The command sequence is shown in Figure 27. The Read Identification (RDID) command is terminated by driving CS# high at any time during data output. When CS# is driven high, the device is in the Standby Mode. Once in the Standby Mode, the device waits to be selected, so that it can receive, decode and execute commands.

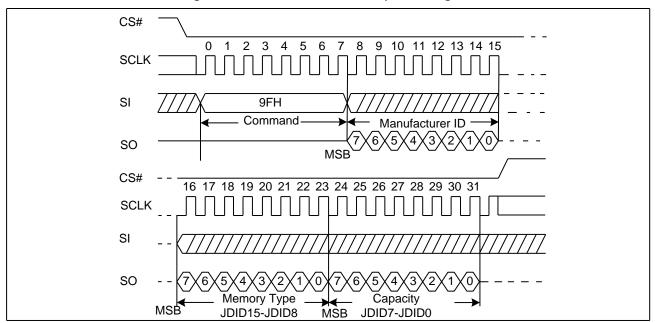


Figure 28. Read Identification ID Sequence Diagram

7.26. Program/Erase Suspend (PES) (75H)

The Program/Erase Suspend command "75H", allows the system to interrupt a page program or sector/block erase operation and then read data from any other sector or block. The Write Status Register command (01H/31H/11H) and Erase/Program Security Registers command (44H, 42H) and Erase commands (20H, 52H, D8H, C7H, 60H) and Page Program command (02H, 32H) are not allowed during Program suspend. The Write Status Register command (01H/31H/11H) and Erase Security Registers command (44H) and Erase commands (20H, 52H, D8H, C7H, 60H) are not allowed during Erase suspend. Program/Erase Suspend is valid only during the page program or sector/block erase operation. A maximum of time of "tsus" (See AC Characteristics) is required to suspend the program/erase operation.

The Program/Erase Suspend command will be accepted by the device only if the SUS2/SUS1 bit in the Status Register equal to 0 and WIP bit equal to 1 while a Page Program or a Sector or Block Erase operation is on-going. If the SUS2/SUS1 bit equal to 1 or WIP bit equal to 0, the Suspend command will be ignored by the device. The WIP bit will be cleared from 1 to 0 within "tsus" and the SUS2/SUS1 bit will be set from 0 to 1 immediately after Program/Erase Suspend. A power-off during the suspend period will reset the device and release the suspend state. The command sequence is show in Figure 29.

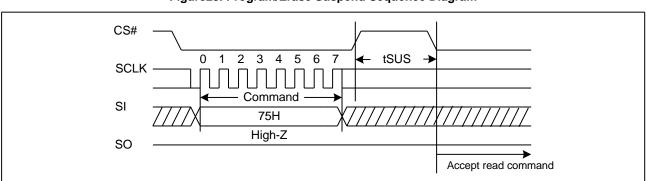


Figure 29. Program/Erase Suspend Sequence Diagram

7.27. Program/Erase Resume (PER) (7AH)

The Program/Erase Resume command must be written to resume the program or sector/block erase operation after a Program/Erase Suspend command. The Program/Erase command will be accepted by the device only if the SUS2/SUS1 bit equal to 1 and the WIP bit equal to 0. After issued the SUS2/SUS1 bit in the status register will be cleared from 1 to 0 immediately, the WIP bit will be set from 0 to 1 within 200ns and the Sector or Block will complete the erase operation or the page will complete the program operation. The Program/Erase Resume command will be ignored unless a Program/Erase Suspend is active. The command sequence is show in Figure 30.

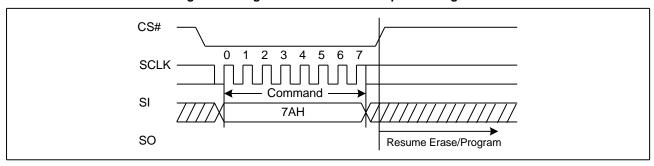


Figure 30. Program/Erase Resume Sequence Diagram

7.28. Erase Security Registers (44H)

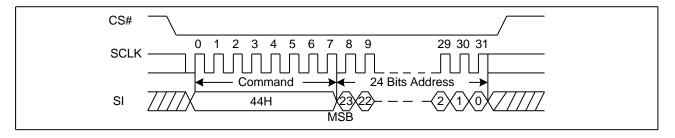
The GD25Q127C provides three 1024-byte Security Registers which can be erased and programmed individually. These registers may be used by the system manufacturers to store security and other important information separately from the main memory array.

The Erase Security Registers command is similar to Sector/Block Erase command. A Write Enable (WREN) command must previously have been executed to set the Write Enable Latch (WEL) bit.

The Erase Security Registers command sequence: CS# goes low → sending Erase Security Registers command → CS# goes high. The command sequence is shown in Figure31. CS# must be driven high after the eighth bit of the command code has been latched in; otherwise the Erase Security Registers command is not executed. As soon as CS# is driven high, the self-timed Erase Security Registers cycle (whose duration is tse) is initiated. While the Erase Security Registers cycle is in progress, the Status Register may be read to check the value of the Write in Progress (WIP) bit. The Write in Progress (WIP) bit is 1 during the self-timed Erase Security Registers cycle, and is 0 when it is completed. At some unspecified time before the cycle is completed, the Write Enable Latch (WEL) bit is reset. The Security Registers Lock Bit (LB3-1) in the Status Register can be used to OTP protect the security registers. Once the LB bit is set to 1, the Security Registers will be permanently locked; the Erase Security Registers command will be ignored.

Address	A23-16	A15-12	A11-10	A9-0
Security Register #1	00H	0001	0 0	Don't care
Security Register #2	00H	0010	0 0	Don't care
Security Register #3	00H	0011	0 0	Don't care

Figure 31. Erase Security Registers command Sequence Diagram



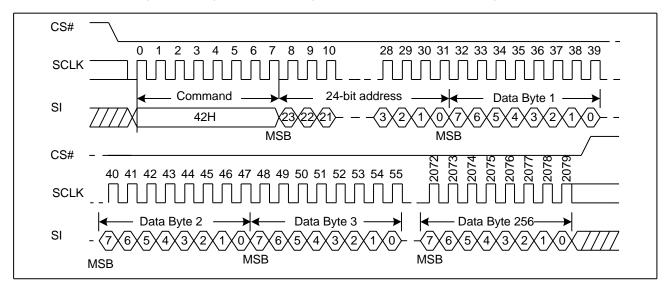
7.29. Program Security Registers (42H)

The Program Security Registers command is similar to the Page Program command. It allows from 1 to 1024 bytes Security Registers data to be programmed. A Write Enable (WREN) command must previously have been executed to set the Write Enable Latch (WEL) bit before sending the Program Security Registers command. The Program Security Registers command is entered by driving CS# Low, followed by the command code (42H), three address bytes and at least one data byte on SI. As soon as CS# is driven high, the self-timed Program Security Registers cycle (whose duration is t_{PP}) is initiated. While the Program Security Registers cycle is in progress, the Status Register may be read to check the value of the Write in Progress (WIP) bit. The Write in Progress (WIP) bit is 1 during the self-timed Program Security Registers cycle, and is 0 when it is completed. At some unspecified time before the cycle is completed, the Write Enable Latch (WEL) bit is reset.

If the Security Registers Lock Bit (LB3-1) is set to 1, the Security Registers will be permanently locked. Program Security Registers command will be ignored.

Address	A23-16	A15-12	A11-10	A9-0
Security Register #1	00H	0001	0 0	Byte Address
Security Register #2	00H	0010	0 0	Byte Address
Security Register #3	00H	0011	0 0	Byte Address

Figure 32. Program Security Registers command Sequence Diagram



7.30. Read Security Registers (48H)

The Read Security Registers command is similar to Fast Read command. The command is followed by a 3-byte address (A23-A0) and a dummy byte, each bit being latched-in during the rising edge of SCLK. Then the memory content, at that address, is shifted out on SO, each bit being shifted out, at a Max frequency fC, during the falling edge of SCLK. The first byte addressed can be at any location. The address is automatically incremented to the next higher address after each byte of data is shifted out. Once the A9-A0 address reaches the last byte of the register (Byte 3FFH), it will reset to 000H, the command is completed by driving CS# high.

Address	A23-16	A15-12	A11-10	A9-0
Security Register #1	00H	0001	0 0	Byte Address
Security Register #2	00H	0010	0 0	Byte Address
Security Register #3	00H	0011	0 0	Byte Address

Figure 33. Read Security Registers command Sequence Diagram

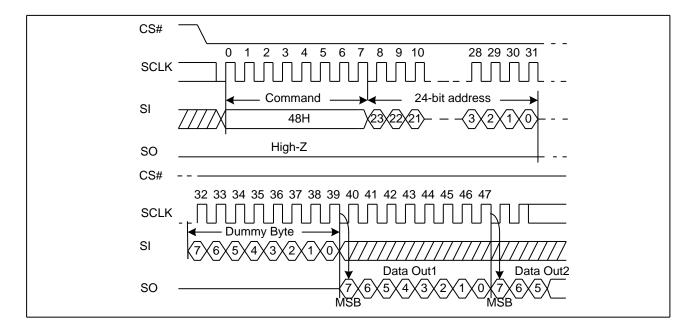
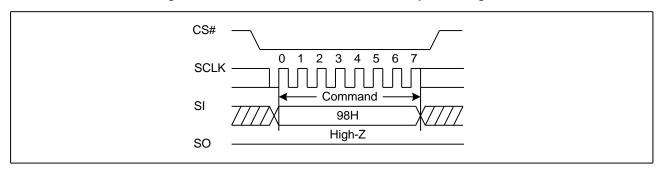


Figure 38. The Global Block/Sector Unlock Sequence Diagram



7.31. Enable Reset (66H) and Reset (99H)

If the Reset command is accepted, any on-going internal operation will be terminated and the device will return to its default power-on state and lose all the current volatile settings, such as Volatile Status Register bits, Write Enable Latch status (WEL), Program/Erase Suspend status, Read Parameter setting (P7-P0), Continuous Read Mode bit setting (M7-M0) and Wrap Bit Setting (W6-W4).

The "Enable Reset (66H)" and the "Reset (99H)" commands can be issued in either SPI mode. The "Reset (99H)"

command sequence as follow: CS# goes low \rightarrow Sending Enable Reset command \rightarrow CS# goes high \rightarrow CS# goes low \rightarrow Sending Reset command \rightarrow CS# goes high. Once the Reset command is accepted by the device, the device will take approximately t_{RST} / t_{RST_E} to reset. During this period, no command will be accepted. Data corruption may happen if there is an on-going or suspended internal Erase or Program operation when Reset command sequence is accepted by the device. It is recommended to check the BUSY bit and the SUS bit in Status Register before issuing the Reset command sequence.

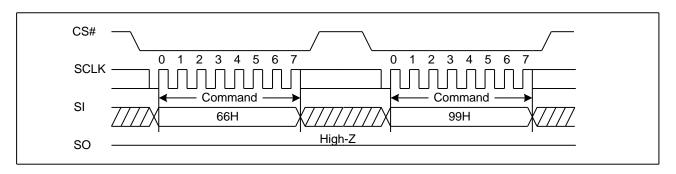


Figure 39. Enable Reset and Reset command Sequence Diagram

7.32. Read Unique ID (4BH)

The Read Unique ID command accesses a factory-set read-only 128bit number that is unique to each device. The Unique ID can be used in conjunction with user software methods to help prevent copying or cloning of a system.

The Read Unique ID command sequence: CS# goes low → sending Read Unique ID command →Dummy Byte1 →Dummy Byte2 →Dummy Byte3 →Dummy Byte4→128bit Unique ID Out →CS# goes high.

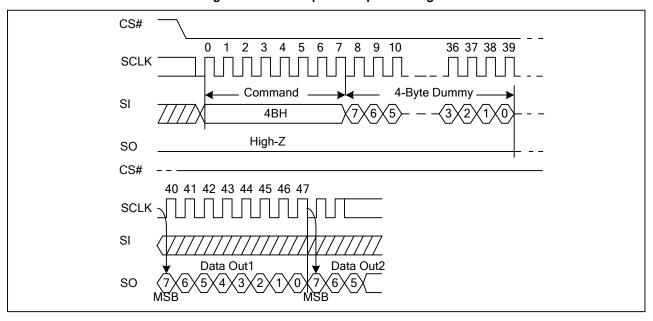


Figure 40 Read Unique ID Sequence Diagram

7.33. Read Serial Flash Discoverable Parameter (5AH)

The Serial Flash Discoverable Parameter (SFDP) standard provides a consistent method of describing the functional and feature capabilities of serial flash devices in a standard set of internal parameter tables. These parameter tables can be interrogated by host system software to enable adjustments needed to accommodate divergent features from multiple vendors. The concept is similar to the one found in the Introduction of JEDEC Standard, JESD68 on CFI. SFDP is a standard of JEDEC Standard No.216.

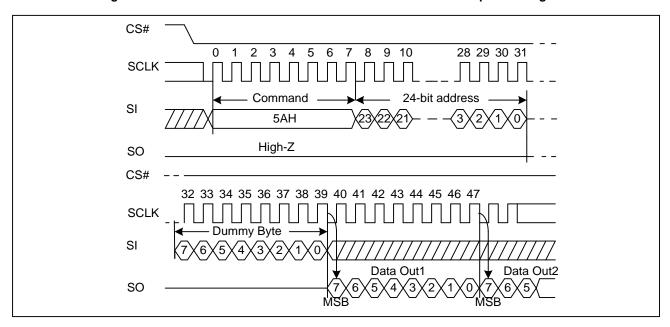


Figure 41. Read Serial Flash Discoverable Parameter command Sequence Diagram

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Table 7.3. Signature and Parameter Identification Data Values

Description	Comment	Add(H)	DW Add	Data	Data
		(Byte)	(Bit)		
SFDP Signature	Fixed:50444653H	00H	07:00	53H	53H
		01H	15:08	46H	46H
		02H	23:16	44H	44H
		03H	31:24	50H	50H
SFDP Minor Revision Number	Start from 00H	04H	07:00	00H	00H
SFDP Major Revision Number	Start from 01H	05H	15:08	01H	01H
Number of Parameters Headers	Start from 00H	06H	23:16	01H	01H
Unused	Contains 0xFFH and can never be changed	07H	31:24	FFH	FFH
ID number (JEDEC)	00H: It indicates a JEDEC specified header	08H	07:00	00H	00H
Parameter Table Minor Revision Number	Start from 0x00H	09H	15:08	00H	00H
Parameter Table Major Revision Number	Start from 0x01H	0AH	23:16	01H	01H
Parameter Table Length (in double word)	How many DWORDs in the Parameter table	0BH	31:24	09H	09H
Parameter Table Pointer (PTP)	First address of JEDEC Flash	0CH	07:00	30H	30H
	Parameter table	0DH	15:08	00H	00H
		0EH	23:16	00H	00H
Unused	Contains 0xFFH and can never be changed	0FH	31:24	FFH	FFH
ID Number (GigaDevice Manufacturer ID)	It is indicates GigaDevice manufacturer ID	10H	07:00	C8H	C8H
Parameter Table Minor Revision Number	Start from 0x00H	11H	15:08	00H	00H
Parameter Table Major Revision Number	Start from 0x01H	12H	23:16	01H	01H
Parameter Table Length	How many DWORDs in the	13H	31:24	03H	03H
(in double word)	Parameter table				
Parameter Table Pointer (PTP)	First address of GigaDevice Flash	14H	07:00	60H	60H
	Parameter table	15H	15:08	00H	00H
		16H	23:16	00H	00H
Unused	Contains 0xFFH and can never be	17H	31:24	FFH	FFH
	changed				

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Table 7.4. Parameter Table (0): JEDEC Flash Parameter Tables

Description	Comment	Add(H)	DW Add	Data	Data
		(Byte)	(Bit)		
	00: Reserved; 01: 4KB erase;				
Block/Sector Erase Size	10: Reserved;		01:00	01b	
	11: not support 4KB erase				
Write Granularity	0: 1Byte, 1: 64Byte or larger		02	1b	
Write Enable Instruction	0: Nonvolatile status bit				
Requested for Writing to Volatile	1: Volatile status bit		03	0b	
Status Registers	(BP status register bit)	30H			E5H
	0: Use 50H Opcode,	3011			Lon
Write Enable Opcode Select for	1: Use 06H Opcode,				
Writing to Volatile Status	Note: If target flash status register is		04	0b	
Registers	Nonvolatile, then bits 3 and 4 must				
	be set to 00b.				
Unused	Contains 111b and can never be		07:05	111b	
	changed		07.00		
4KB Erase Opcode		31H	15:08	20H	20H
(1-1-2) Fast Read	0=Not support, 1=Support	16 1b		1b	
Address Bytes Number used in	00: 3Byte only, 01: 3 or 4Byte,		18:17	00b	
addressing flash array	10: 4Byte only, 11: Reserved		10.17	000	
Double Transfer Rate (DTR)	0=Not support, 1=Support		19	0b	
clocking	о-поставроп, 1-сарроп	32H	10		F1H
(1-2-2) Fast Read	0=Not support, 1=Support		20	1b	
(1-4-4) Fast Read	0=Not support, 1=Support		21	1b	
(1-1-4) Fast Read	0=Not support, 1=Support		22	1b	
Unused			23	1b	
Unused		33H	31:24	FFH	FFH
Flash Memory Density		37H:34H	31:00	07FFFF	FFH
(1-4-4) Fast Read Number of Wait	0 0000b: Wait states (Dummy		0.4.00	221221	
states	Clocks) not support	0011	04:00	00100b	4411
(1-4-4) Fast Read Number of	000k Mada Bita a 1	38H	07.05	0401	44H
Mode Bits	000b:Mode Bits not support		07:05	010b	
(1-4-4) Fast Read Opcode		39H	15:08	EBH	EBH
(1-1-4) Fast Read Number of Wait	0 0000b: Wait states (Dummy		20:46	010006	
states	Clocks) not support	241	20:16	01000b	0011
(1-1-4) Fast Read Number of	000h:Mada Pita nat augnart	3AH	22:24	0006	08H
Mode Bits	000b:Mode Bits not support		23:21	000b	
(1-1-4) Fast Read Opcode		3BH	31:24	6BH	6BH



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Description	Comment	Add(H) (Byte)	DW Add (Bit)	Data	Data
(1-1-2) Fast Read Number of Wait states	0 0000b: Wait states (Dummy Clocks) not support		04:00	01000b	
(1-1-2) Fast Read Number of Mode Bits	000b: Mode Bits not support	3CH	07:05	000b	- 08H
(1-1-2) Fast Read Opcode		3DH	15:08	3BH	3BH
(1-2-2) Fast Read Number of Wait states	0 0000b: Wait states (Dummy Clocks) not support	- 3EH	20:16	00010b	- 42H
(1-2-2) Fast Read Number of Mode Bits	000b: Mode Bits not support	SETT	23:21	010b	7211
(1-2-2) Fast Read Opcode		3FH	31:24	BBH	BBH
(2-2-2) Fast Read	0=not support 1=support		00	0b	
Unused		40H	03:01	111b	EEH
(4-4-4) Fast Read	0=not support 1=support	400	04	0b] [[
Unused			07:05	111b	
Unused		43H:41H	31:08	0xFFH	0xFFH
Unused		45H:44H	15:00	0xFFH	0xFFH
(2-2-2) Fast Read Number of Wait states	0 0000b: Wait states (Dummy Clocks) not support		20:16	00000b	
(2-2-2) Fast Read Number of Mode Bits	000b: Mode Bits not support	- 46H	23:21	000b	00H
(2-2-2) Fast Read Opcode		47H	31:24	FFH	FFH
Unused		49H:48H	15:00	0xFFH	0xFFH
(4-4-4) Fast Read Number of Wait states	0 0000b: Wait states (Dummy Clocks) not support	- 4AH	20:16	00000b	- 00H
(4-4-4) Fast Read Number of Mode Bits	000b: Mode Bits not support	4AII	23:21	000b	0011
(4-4-4) Fast Read Opcode		4BH	31:24	EBH	EBH
Sector Type 1 Size	Sector/block size=2^N bytes 0x00b: this sector type don't exist	4CH	07:00	0CH	0CH
Sector Type 1 erase Opcode		4DH	15:08	20H	20H
Sector Type 2 Size	Sector/block size=2^N bytes 0x00b: this sector type don't exist	4EH	23:16	0FH	0FH
Sector Type 2 erase Opcode		4FH	31:24	52H	52H
Sector Type 3 Size	Sector/block size=2^N bytes 0x00b: this sector type don't exist	50H	07:00	10H	10H
Sector Type 3 erase Opcode		51H	15:08	D8H	D8H
	Sector/block size=2^N bytes		00:40	0011	0011
Sector Type 4 Size	0x00b: this sector type don't exist	52H	23:16	00H	00H

GD25Q127C

Table 7.5. Parameter Table (1): GigaDevice Flash Parameter Tables

	Transcer Table (1): Orgabetice Flash	1		1	
Description	Comment	Add(H) (Byte)	DW Add (Bit)	Data	Data
	2000H=2.000V				
Vcc Supply Maximum Voltage	2700H=2.700V	61H:60H	15:00	3600H	3600H
,	3600H=3.600V				
	1650H=1.650V				
V 0 1 M: V 16	2250H=2.250V	0011 0011	04.40	070011	070011
Vcc Supply Minimum Voltage	2350H=2.350V	63H:62H	31:16	2700H	2700H
	2700H=2.700V				
HW Reset# pin	0=not support 1=support		00	1b	
HW Hold# pin	0=not support 1=support		01	1b	
Deep Power Down Mode	0=not support 1=support		02	1b	
SW Reset	0=not support 1=support	=	03	1b	
000 0 1	Should be issue Reset Enable(66H)	05110411	44.04	1001 1001b	F99FH
SW Reset Opcode	before Reset cmd.	65H:64H	11:04	(99H)	
Program Suspend/Resume	0=not support 1=support		12	1b	
Erase Suspend/Resume	0=not support 1=support		13	1b	
Unused			14	1b	
Wrap-Around Read mode	0=not support 1=support	1	15	1b	
Wrap-Around Read mode Opcode		66H	23:16	77H	77H
	08H:support 8B wrap-around read				
Wrap-Around Read data length	16H:8B&16B	67H	31:24	CALL	64H
Wiap-Around Read data length	32H:8B&16B&32B	0/11	31.24	64H	0411
	64H:8B&16B&32B&64B				
Individual block lock	0=not support 1=support		00	0b	
Individual block lock bit	0=Volatile 1=Nonvolatile		01	0b	
(Volatile/Nonvolatile)	0=Volatile 1=IVoliVolatile		01	OD	
Individual block lock Opcode			09:02	FFH	CBFC/
Individual block lock Volatile	0=protect 1=unprotect		10	0b	EBFCH
protect bit default protect status	0-protect 1-unprotect	6BH:68H	10	OD	(1)
Secured OTP	0=not support 1=support		11	1b	(')
Read Lock	0=not support 1=support		12	0b	
Permanent Lock	0=not support 1=support		13	0b/1b(1)	
Unused			15:14	11b	
Unused			31:16	FFFFH	FFFFH
			_		

NOTE:

(1) GD25Q127CxxSx support Permanent Lock. Please contact GigaDevice for details.

8. ELECTRICAL CHARACTERISTICS

8.1. POWER-ON TIMING

Figure 42. Power-on Timing Sequence Diagram

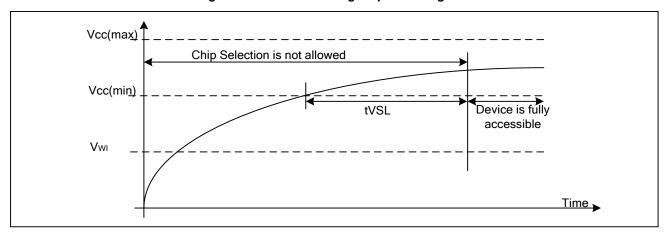


Table 8.1. Power-Up Timing and Write Inhibit Threshold

Symbol	Parameter	Min	Max	Unit
tVSL	VCC (min) To CS# Low	2.5		ms
VWI	Write Inhibit Voltage	1.5	2.5	V

8.2. INITIAL DELIVERY STATE

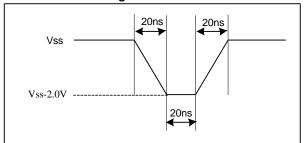
The device is delivered with the memory array erased: all bits are set to 1(each byte contains FFH). The Status Register bits are set to 0, except DRV1 bit (S22) is set to 1.

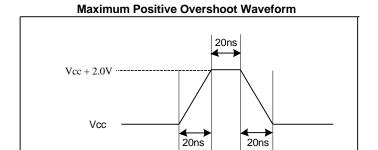
8.3. ABSOLUTE MAXIMUM RATINGS

Parameter	Value	Unit
Ambient Operating Temperature	-40 to 85	
	-40 to 105	°C
	-40 to 125	
Storage Temperature	-65 to 150	°C
Applied Input/Output Voltage	-0.6 to VCC+0.4	V
Transient Input/Output Voltage (note: overshoot)	-2.0 to VCC+2.0	V
VCC	-0.6 to 4.2	V

Figure 43. Maximum Negative/positive Overshoot Diagram

Maximum Negative Overshoot Waveform

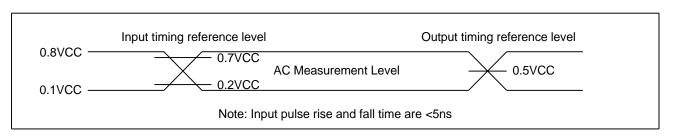


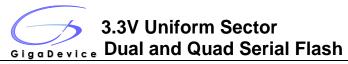


8.4. CAPACITANCE MEASUREMENT CONDITIONS

Symbol	Parameter	Min	Тур.	Max	Unit	Conditions
CIN	Input Capacitance			6	pF	VIN=0V
COUT	Output Capacitance			8	pF	VOUT=0V
C _L	Load Capacitance	30		pF		
	Input Rise And Fall time			5	ns	
	Input Pulse Voltage	0.1VC	C to 0.8VC	CC	V	
	Input Timing Reference Voltage	0.2VCC to 0.7VCC		V		
	Output Timing Reference Voltage	0.5VCC		V		

Figure 44. Input Test Waveform and Measurement Level





8.5. DC CHARACTERISTICS

(T= -40°C~85°C, VCC=2.7~3.6V, Normal Mode)

Symbol	Parameter	Test Condition	Min.	Тур.	Max.	Unit.
ILI	Input Leakage Current				±2	μA
ILO	Output Leakage Current				±2	μA
Icc1	Standby Current	CS#=VCC,		20	50	μA
		V _{IN} =VCC or VSS				
I _{CC2}	Deep Power-Down Current	CS#=VCC,		1	5	μA
		V _{IN} =VCC or VSS				
		CLK=0.1VCC /				
		0.9VCC		15	20	mA
		at 104MHz,		15	20	IIIA
lass	Operating Current (Read)	Q=Open(*1,*2,*4 I/O)				
I _{CC3}	Operating Current (Read)	CLK=0.1VCC /				
		0.9VCC		13	18	mA
		at 80MHz,		13	10	IIIA
		Q=Open(*1,*2,*4 I/O)				
I _{CC4}	Operating Current (PP)	CS#=VCC			27	mA
I _{CC5}	Operating Current (WRSR)	CS#=VCC			27	mA
Icc6	Operating Current (SE)	CS#=VCC			27	mA
Icc7	Operating Current (BE)	CS#=VCC			27	mA
I _{CC8}	Operating Current (CE)	CS#=VCC			27	mA
VIL	Input Low Voltage				0.2VCC	V
VIH	Input High Voltage		0.7VCC		VCC+0.4	V
V _{OL}	Output Low Voltage	I _{OL} =100μA			0.2	٧
Voн	Output High Voltage	Іон =-100μΑ	VCC-0.2			٧

- 1. Typical value tested at T = 25° C.
- 2. Value guaranteed by design and/or characterization, not 100% tested in production.

GD25Q127C

(T= -40°C~85°C, VCC=2.7~3.6V, Low Power Mode)

Symbol	Parameter	Test Condition	Min.	Тур.	Max.	Unit.
ILI	Input Leakage Current				±2	μΑ
ILO	Output Leakage Current				±2	μΑ
Icc1	Standby Current	CS#=VCC,		20	50	μΑ
		V _{IN} =VCC or VSS				
I _{CC2}	Deep Power-Down Current	CS#=VCC,		1	5	μA
		V _{IN} =VCC or VSS				
		CLK=0.1VCC /				
		0.9VCC		13	20	mA
		at 104MHz,		13	13 20	IIIA
lass	Operating Current (Read)	Q=Open(*1,*2,*4 I/O)				
I _{CC3}	Operating Current (Read)	CLK=0.1VCC /				
		0.9VCC		10	18	mA
		at 80MHz,		10	10	mA
		Q=Open(*1,*2,*4 I/O)				
Icc4	Operating Current (PP)	CS#=VCC			25	mA
I _{CC5}	Operating Current (WRSR)	CS#=VCC			25	mA
Icc6	Operating Current (SE)	CS#=VCC			25	mA
Icc7	Operating Current (BE)	CS#=VCC			25	mA
Icc8	Operating Current (CE)	CS#=VCC			25	mA
VIL	Input Low Voltage				0.2VCC	V
VıH	Input High Voltage		0.7VCC		VCC+0.4	V
VoL	Output Low Voltage	I _{OL} =100μA			0.2	V
Vон	Output High Voltage	Іон =-100μΑ	VCC-0.2			V

- 1. Typical value tested at $T = 25^{\circ}C$.
- 2. Value guaranteed by design and/or characterization, not 100% tested in production.

GD25Q127C

(T= -40°C~105°C, VCC=2.7~3.6V, Normal Mode)

Symbol	Parameter	Test Condition	Min.	Тур	Max.	Unit.
ILI	Input Leakage Current				±2	μA
ILO	Output Leakage Current				±2	μA
Icc1	Standby Current	CS#=VCC,		20	100	μA
		V _{IN} =VCC or VSS				
I _{CC2}	Deep Power-Down Current	CS#=VCC,		1	20	μA
		V _{IN} =VCC or VSS				
		CLK=0.1VCC /				
		0.9VCC		15	20	A
		at 80MHz,			20	mA
	One retire a Comment (Deed)	Q=Open(*1,*2,*4 I/O)				
I _{CC3}	Operating Current (Read)	CLK=0.1VCC /				
		0.9VCC		40	40	A
		at 60MHz,		13	18	mA
		Q=Open(*1,*2,*4 I/O)				
Icc4	Operating Current (PP)	CS#=VCC			30	mA
Icc5	Operating Current(WRSR)	CS#=VCC			30	mA
Icc6	Operating Current (SE)	CS#=VCC			30	mA
I _{CC7}	Operating Current (BE)	CS#=VCC			30	mA
Icc8	Operating Current (CE)	CS#=VCC			30	mA
VIL	Input Low Voltage				0.2VCC	V
VIH	Input High Voltage		0.7VCC		VCC+0.4	V
Vol	Output Low Voltage	I _{OL} =100μA			0.2	V
Voн	Output High Voltage	Іон =-100μΑ	VCC-0.2			V

- 1. Typical value tested at $T = 25^{\circ}C$.
- 2. Value guaranteed by design and/or characterization, not 100% tested in production.

GD25Q127C

(T= -40°C~105°C, VCC=2.7~3.6V, Low Power Mode)

Symbol	Parameter	Test Condition	Min.	Тур	Max.	Unit.				
lы	Input Leakage Current				±2	μΑ				
ILO	Output Leakage Current				±2	μA				
Icc1	Standby Current	CS#=VCC,		20	100	μA				
		V _{IN} =VCC or VSS								
I _{CC2}	Deep Power-Down Current	CS#=VCC,		1	20	μΑ				
		V _{IN} =VCC or VSS								
		CLK=0.1VCC /								
		0.9VCC		40	20	A				
		at 80MHz,		13	13	13	13	13	20	mA
	Operating Current (Deed)	Q=Open(*1,*2,*4 I/O)								
I _{CC3}	Operating Current (Read)	CLK=0.1VCC /								
		0.9VCC		10	18	m Λ				
		at 60MHz,		10	10	10	10	10	mA	
		Q=Open(*1,*2,*4 I/O)								
Icc4	Operating Current (PP)	CS#=VCC			25	mA				
Icc5	Operating Current(WRSR)	CS#=VCC			25	mA				
Icc ₆	Operating Current (SE)	CS#=VCC			25	mA				
Icc7	Operating Current (BE)	CS#=VCC			25	mA				
Icc8	Operating Current (CE)	CS#=VCC			25	mA				
VIL	Input Low Voltage				0.2VCC	V				
V _{IH}	Input High Voltage		0.7VCC		VCC+0.4	V				
VoL	Output Low Voltage	I _{OL} =100μA			0.2	V				
Vон	Output High Voltage	Іон =-100μΑ	VCC-0.2			V				

- 1. Typical value tested at $T = 25^{\circ}C$.
- 2. Value guaranteed by design and/or characterization, not 100% tested in production.

GD25Q127C

(T= -40°C~125°C, VCC=2.7~3.6V, Normal Mode)

Symbol	Parameter	Test Condition	Min.	Тур.	Max.	Unit.			
ILI	Input Leakage Current				±2	μA			
ILO	Output Leakage Current				±2	μA			
Icc1	Standby Current	CS#=VCC,		20	120	μA			
		V _{IN} =VCC or VSS							
I _{CC2}	Deep Power-Down Current	CS#=VCC,		1	25	μA			
		V _{IN} =VCC or VSS							
		CLK=0.1VCC /							
		0.9VCC		15	20	mA			
		at 80MHz,		15	15	15	15	20	IIIA
1	Operating Current (Read)	Q=Open(*1,*2,*4 I/O)							
I _{CC3}	Operating Current (Read)	CLK=0.1VCC /							
		0.9VCC		13	18	A			
		at 60MHz,		13	10	mA			
		Q=Open(*1,*2,*4 I/O)							
I _{CC4}	Operating Current (PP)	CS#=VCC			30	mA			
I _{CC5}	Operating Current (WRSR)	CS#=VCC			30	mA			
Icc6	Operating Current (SE)	CS#=VCC			30	mA			
Icc7	Operating Current (BE)	CS#=VCC			30	mA			
Icc8	Operating Current (CE)	CS#=VCC			30	mA			
VıL	Input Low Voltage				0.2VCC	V			
VIH	Input High Voltage		0.7VCC		VCC+0.4	V			
Vol	Output Low Voltage	I _{OL} =100μA			0.2	V			
Voн	Output High Voltage	Іон =-100μΑ	VCC-0.2			V			

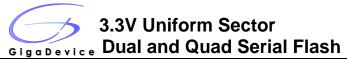
- 1. Typical value tested at $T = 25^{\circ}C$.
- 2. Value guaranteed by design and/or characterization, not 100% tested in production.

GD25Q127C

(T= -40°C~125°C, VCC=2.7~3.6V, Low Power Mode)

Symbol	Parameter	Test Condition	Min.	Тур.	Max.	Unit.				
lы	Input Leakage Current				±2	μΑ				
ILO	Output Leakage Current				±2	μA				
Icc1	Standby Current	CS#=VCC,		20	120	μA				
		V _{IN} =VCC or VSS								
I _{CC2}	Deep Power-Down Current	CS#=VCC,		1	25	μΑ				
		V _{IN} =VCC or VSS								
		CLK=0.1VCC /								
		0.9VCC		40		A				
		at 80MHz,		13	13	13	13	13	20	mA
	Operating Current (Deed)	Q=Open(*1,*2,*4 I/O)								
I _{CC3}	Operating Current (Read)	CLK=0.1VCC /								
		0.9VCC		10	18	Λ				
		at 60MHz,		10	10	mA				
		Q=Open(*1,*2,*4 I/O)								
I _{CC4}	Operating Current (PP)	CS#=VCC			25	mA				
I _{CC5}	Operating Current (WRSR)	CS#=VCC			25	mA				
Icc ₆	Operating Current (SE)	CS#=VCC			25	mA				
Icc7	Operating Current (BE)	CS#=VCC			25	mA				
Icc8	Operating Current (CE)	CS#=VCC			25	mA				
VIL	Input Low Voltage				0.2VCC	V				
VIH	Input High Voltage		0.7VCC		VCC+0.4	V				
Vol	Output Low Voltage	I _{OL} =100μA			0.2	V				
Vон	Output High Voltage	Іон =-100μΑ	VCC-0.2			V				

- 1. Typical value tested at $T = 25^{\circ}C$.
- 2. Value guaranteed by design and/or characterization, not 100% tested in production.



8.6. AC CHARACTERISTICS

(T= -40°C~85°C, VCC=2.7~3.6V, C_L =30pf, Normal Mode)

Symbol	Parameter	Min.	Тур.	Max.	Unit.
F-	Serial Clock Frequency For: Fast Read (0BH), on 2.7V-3.6V			104	MU
Fc	power supply			104	MHz
	Serial Clock Frequency For: Dual Output (3BH), Quad Output				
f _{C1}	(6BH), Dual I/O (BBH), Quad I/O (EBH), Quad I/O Word Fast			80	MHz
	Read (E7H), on 2.7V-3.0V power supply				
	Serial Clock Frequency For: Dual Output (3BH), Quad Output				
f _{C2}	(6BH), Dual I/O (BBH), Quad I/O (EBH), Quad I/O Word Fast			104	MHz
	Read (E7H), on 3.0V-3.6V power supply				
f_{R}	Serial Clock Frequency For: Read (03H), Read Manufacturer			80	MHz
IR	ID/device ID (90H), Read Identification (9FH)			80	IVIITZ
t _{CLH}	Serial Clock High Time	4.5			ns
tcll	Serial Clock Low Time	4.5			ns
tclch	Serial Clock Rise Time (Slew Rate)	0.1			V/ns
t _{CHCL}	Serial Clock Fall Time (Slew Rate)	0.1			V/ns
tslch	CS# Active Setup Time	5			ns
tchsh	CS# Active Hold Time	5			ns
tshch	CS# Not Active Setup Time	5			ns
tchsl	CS# Not Active Hold Time	5			ns
t _{SHSL}	CS# High Time (Read/Write)	20			ns
tshqz	Output Disable Time			6	ns
tcLQX	Output Hold Time	1.0			ns
t _{DVCH}	Data In Setup Time	2			ns
tchdx	Data In Hold Time	2			ns
t _{HLCH}	HOLD# Low Setup Time (Relative To Clock)	5			ns
t _{HHCH}	HOLD# High Setup Time (Relative To Clock)	5			ns
tchhl	HOLD# High Hold Time (Relative To Clock)	5			ns
t _{CHHH}	HOLD# Low Hold Time (Relative To Clock)	5			ns
thLQZ	HOLD# Low To High-Z Output			6	ns
thhqx	HOLD# Low To Low-Z Output			6	ns
t _{CLQV}	Clock Low To Output Valid			6.5	ns
twhsl	Write Protect Setup Time Before CS# Low	20			ns
tshwl	Write Protect Hold Time After CS# High	100			ns
t _{DP}	CS# High To Deep Power-Down Mode			20	μs
·-	CS# High To Standby Mode Without Electronic Signature				† .
t _{RES1}	Read			30	μs
t _{RES2}	CS# High To Standby Mode With Electronic Signature Read			30	μs
tsus	CS# High To Next Command After Suspend			20	μs
t _{RS}	Latency Between Resume And Next Suspend	100		1	μs



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t _{RST}	CS# High To Next Command After Reset (Except From Erase)		30	μs
t _{RST_E}	CS# High To Next Command After Reset (From Erase)		12	ms
t _W	Write Status Register Cycle Time	5	30	ms
t _{BP1}	Byte Program Time (First Byte)	30	50	μs
t _{BP2}	Additional Byte Program Time (After First Byte)	2.5	12	μs
t _{PP}	Page Programming Time	0.5	2.4	ms
tse	Sector Erase Time	50	400	ms
t _{BE1}	Block Erase Time (32K Bytes)	0.16	0.8	s
t _{BE2}	Block Erase Time (64K Bytes)	0.3	1.2	S
tce	Chip Erase Time (GD25Q127C)	50	120	S

- 1. Typical value tested at $T = 25^{\circ}C$.
- 2. Value guaranteed by design and/or characterization, not 100% tested in production.



(T= -40°C~85°C, VCC=2.7~3.6V, C_L=30pf, Low Power Mode)

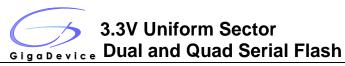
Symbol	Parameter	Min.	Тур.	Max.	Unit
F	Serial Clock Frequency For: Fast Read (0BH), on 2.7V-3.6V			404	N 41 1-
Fc	power supply			104	MHz
	Serial Clock Frequency For: Dual Output (3BH), Quad Output				
f _{C1}	(6BH), Dual I/O (BBH), Quad I/O (EBH), Quad I/O Word Fast			80	MHz
	Read (E7H), on 2.7V-3.0V power supply				
	Serial Clock Frequency For: Dual Output (3BH), Quad Output				
f _{C2}	(6BH), Dual I/O (BBH), Quad I/O (EBH), Quad I/O Word Fast			104	MHz
	Read (E7H), on 3.0V-3.6V power supply				
f_R	Serial Clock Frequency For: Read (03H), Read Manufacturer			80	MHz
IK	ID/device ID (90H), Read Identification (9FH)			00	1011 12
tclh	Serial Clock High Time	4.5			ns
tcll	Serial Clock Low Time	4.5			ns
t _{CLCH}	Serial Clock Rise Time (Slew Rate)	0.1			V/ns
tchcl	Serial Clock Fall Time (Slew Rate)	0.1			V/ns
tslch	CS# Active Setup Time	5			ns
tcнsн	CS# Active Hold Time	5			ns
tshch	CS# Not Active Setup Time	5			ns
t _{CHSL}	CS# Not Active Hold Time	5			ns
tshsl	CS# High Time (Read/Write)	20			ns
t shqz	Output Disable Time			6	ns
t _{CLQX}	Output Hold Time	1.0			ns
tovch	Data In Setup Time	2			ns
tchdx	Data In Hold Time	2			ns
thlch	HOLD# Low Setup Time (Relative To Clock)	5			ns
tннсн	HOLD# High Setup Time (Relative To Clock)	5			ns
t _{CHHL}	HOLD# High Hold Time (Relative To Clock)	5			ns
tсннн	HOLD# Low Hold Time (Relative To Clock)	5			ns
thlqz	HOLD# Low To High-Z Output			6	ns
t _{HHQX}	HOLD# Low To Low-Z Output			6	ns
tclqv	Clock Low To Output Valid			6.5	ns
t _{WHSL}	Write Protect Setup Time Before CS# Low	20			ns
tshwl	Write Protect Hold Time After CS# High	100			ns
t _{DP}	CS# High To Deep Power-Down Mode			50	μs
	CS# High To Standby Mode Without Electronic Signature				F-5
t _{RES1}	Read			50	μs
t _{RES2}	CS# High To Standby Mode With Electronic Signature Read			50	μs
tsus	CS# High To Next Command After Suspend			50	μs
t _{RS}	Latency Between Resume And Next Suspend	100			μs
trst	CS# High To Next Command After Reset (Except From				PO
-1.01	Erase)			50	μs



GD25Q127C

t _{RST_E}	CS# High To Next Command After Reset (From Erase)		30	ms
tw	Write Status Register Cycle Time	15	80	ms
t _{BP1}	Byte Program Time (First Byte)	60	150	μs
t _{BP2}	Additional Byte Program Time (After First Byte)	8	40	μs
t PP	Page Programming Time	1.6	5	ms
tse	Sector Erase Time	100	600	ms
t _{BE1}	Block Erase Time (32K Bytes)	0.3	1.4	S
t _{BE2}	Block Erase Time (64K Bytes)	0.5	2.6	S
tce	Chip Erase Time (GD25Q127C)	150	300	S

- 1. Typical value tested at T = 25° C.
- 2. Value guaranteed by design and/or characterization, not 100% tested in production.



(T= -40°C~105°C, VCC=2.7~3.6V, C_L=30pf, Normal Mode)

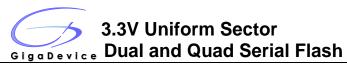
Symbol	Parameter	Min.	Тур.	Max.	Unit.
F-	Serial Clock Frequency For: Fast Read (0BH), on 2.7V-3.6V			104	NALI
Fc	power supply			104	MHz
	Serial Clock Frequency For: Dual Output (3BH), Quad Output				
f _{C1}	(6BH), Dual I/O (BBH), Quad I/O (EBH), Quad I/O Word Fast			70	MHz
	Read (E7H), on 2.7V-3.0V power supply				
	Serial Clock Frequency For: Dual Output (3BH), Quad Output				
f _{C2}	(6BH), Dual I/O (BBH), Quad I/O (EBH), Quad I/O Word Fast			80	MHz
	Read (E7H), on 3.0V-3.6V power supply				
f_{R}	Serial Clock Frequency For: Read (03H), Read Manufacturer			60	MHz
IK	ID/device ID (90H), Read Identification (9FH)			00	IVII IZ
tclh	Serial Clock High Time	4.5			ns
tcll	Serial Clock Low Time	4.5			ns
t _{CLCH}	Serial Clock Rise Time (Slew Rate)	0.1			V/ns
tchcl	Serial Clock Fall Time (Slew Rate)	0.1			V/ns
tslch	CS# Active Setup Time	5			ns
tchsh	CS# Active Hold Time	5			ns
tsнсн	CS# Not Active Setup Time	5			ns
t _{CHSL}	CS# Not Active Hold Time	5			ns
tshsl	CS# High Time (Read/Write)	20			ns
tshqz	Output Disable Time			6	ns
t _{CLQX}	Output Hold Time	1.0			ns
tovch	Data In Setup Time	2			ns
tchdx	Data In Hold Time	2			ns
thlch	HOLD# Low Setup Time (Relative To Clock)	5			ns
tннсн	HOLD# High Setup Time (Relative To Clock)	5			ns
t _{CHHL}	HOLD# High Hold Time (Relative To Clock)	5			ns
tсннн	HOLD# Low Hold Time (Relative To Clock)	5			ns
thLQZ	HOLD# Low To High-Z Output			6	ns
t _{HHQX}	HOLD# Low To Low-Z Output			6	ns
tclqv	Clock Low To Output Valid			7	ns
twhsl	Write Protect Setup Time Before CS# Low	20			ns
tshwl	Write Protect Hold Time After CS# High	100			ns
t _{DP}	CS# High To Deep Power-Down Mode			20	μs
-21	CS# High To Standby Mode Without Electronic Signature				F
t _{RES1}	Read			30	μs
t _{RES2}	CS# High To Standby Mode With Electronic Signature Read			30	μs
tsus	CS# High To Next Command After Suspend			20	μs
t _{RS}	Latency Between Resume And Next Suspend	100			μs
rk9	CS# High To Next Command After Reset (Except From	100			μο
t _{RST}	Erase)			30	μs



GD25Q127C

t _{RST_E}	CS# High To Next Command After Reset (From Erase)		12	ms
tw	Write Status Register Cycle Time	5	30	ms
t _{BP1}	Byte Program Time (First Byte)	30	60	μs
t _{BP2}	Additional Byte Program Time (After First Byte)	2.5	15	μs
t PP	Page Programming Time	0.5	4	ms
tse	Sector Erase Time	50	400	ms
t _{BE}	Block Erase Time (32K Bytes)	0.16	2	S
t _{BE}	Block Erase Time (64K Bytes)	0.3	3	S
tce	Chip Erase Time (GD25Q127C)	50	150	S

- 1. Typical value tested at $T = 25^{\circ}C$.
- 2. Value guaranteed by design and/or characterization, not 100% tested in production.



(T= -40°C~105°C, VCC=2.7~3.6V, C_L=30pf, Low Power Mode)

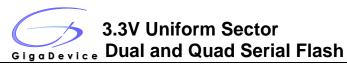
Symbol	Parameter	Min.	Тур.	Max.	Unit.
_	Serial Clock Frequency For: Fast Read (0BH), on 2.7V-3.6V			404	NAL 1-
Fc	power supply			104	MHz
	Serial Clock Frequency For: Dual Output (3BH), Quad Output				
f _{C1}	(6BH), Dual I/O (BBH), Quad I/O (EBH), Quad I/O Word Fast			70	MHz
	Read (E7H), on 2.7V-3.0V power supply				
	Serial Clock Frequency For: Dual Output (3BH), Quad Output				
f _{C2}	(6BH), Dual I/O (BBH), Quad I/O (EBH), Quad I/O Word Fast			80	MHz
	Read (E7H), on 3.0V-3.6V power supply				
f _R	Serial Clock Frequency For: Read (03H), Read Manufacturer			60	MHz
IR	ID/device ID (90H), Read Identification (9FH)			00	IVII IZ
tсьн	Serial Clock High Time	4.5			ns
tcll	Serial Clock Low Time	4.5			ns
tclch	Serial Clock Rise Time (Slew Rate)	0.1			V/ns
tchcl	Serial Clock Fall Time (Slew Rate)	0.1			V/ns
tslch	CS# Active Setup Time	5			ns
tcнsн	CS# Active Hold Time	5			ns
tshch	CS# Not Active Setup Time	5			ns
t _{CHSL}	CS# Not Active Hold Time	5			ns
tshsl	CS# High Time (Read/Write)	20			ns
tshqz	Output Disable Time			6	ns
t _{CLQX}	Output Hold Time	1.0			ns
tоvсн	Data In Setup Time	2			ns
tchdx	Data In Hold Time	2			ns
thich	HOLD# Low Setup Time (Relative To Clock)	5			ns
tннсн	HOLD# High Setup Time (Relative To Clock)	5			ns
t _{CHHL}	HOLD# High Hold Time (Relative To Clock)	5			ns
tсннн	HOLD# Low Hold Time (Relative To Clock)	5			ns
thlqz	HOLD# Low To High-Z Output			6	ns
t _{HHQX}	HOLD# Low To Low-Z Output			6	ns
tclqv	Clock Low To Output Valid			7	ns
t _{WHSL}	Write Protect Setup Time Before CS# Low	20			ns
tshwl	Write Protect Hold Time After CS# High	100			ns
t _{DP}	CS# High To Deep Power-Down Mode			50	μs
	CS# High To Standby Mode Without Electronic Signature				<u> </u>
t _{RES1}	Read			50	μs
t _{RES2}	CS# High To Standby Mode With Electronic Signature Read			50	μs
tsus	CS# High To Next Command After Suspend			50	μs
t _{RS}	Latency Between Resume And Next Suspend	100			μs
-	CS# High To Next Command After Reset (Except From				<u> </u>
t _{RST}	9			50	μs



GD25Q127C

t _{RST_E}	CS# High To Next Command After Reset (From Erase)		30	ms
tw	Write Status Register Cycle Time	15	80	ms
t _{BP1}	Byte Program Time (First Byte)	60	180	μs
t _{BP2}	Additional Byte Program Time (After First Byte)	8	50	μs
t PP	Page Programming Time	1.6	6	ms
tse	Sector Erase Time	100	600	ms
t _{BE}	Block Erase Time (32K Bytes)	0.3	3	S
t _{BE}	Block Erase Time (64K Bytes)	0.5	4	S
tce	Chip Erase Time (GD25Q127C)	150	360	S

- 1. Typical value tested at $T = 25^{\circ}C$.
- 2. Value guaranteed by design and/or characterization, not 100% tested in production.



(T= -40°C~125°C, VCC=2.7~3.6V, C_L=30pf, Normal Mode)

Symbol	Parameter	Min.	Тур.	Max.	Unit.
F	Serial Clock Frequency For: Fast Read (0BH), on 2.7V-3.6V			404	N41.1-
Fc	power supply			104	MHz
	Serial Clock Frequency For: Dual Output (3BH), Quad Output				
f _{C1}	(6BH), Dual I/O (BBH), Quad I/O (EBH), Quad I/O Word Fast			70	MHz
	Read (E7H), on 2.7V-3.0V power supply				
	Serial Clock Frequency For: Dual Output (3BH), Quad Output				
f _{C2}	(6BH), Dual I/O (BBH), Quad I/O (EBH), Quad I/O Word Fast			80	MHz
	Read (E7H), on 3.0V-3.6V power supply				
f _	Serial Clock Frequency For: Read (03H), Read Manufacturer			60	MHz
f _R	ID/device ID (90H), Read Identification (9FH)			60	IVITZ
tclh	Serial Clock High Time	4.5			ns
tcll	Serial Clock Low Time	4.5			ns
t _{CLCH}	Serial Clock Rise Time (Slew Rate)	0.1			V/ns
tchcl	Serial Clock Fall Time (Slew Rate)	0.1			V/ns
tslch	CS# Active Setup Time	5			ns
tchsh	CS# Active Hold Time	5			ns
tsнсн	CS# Not Active Setup Time	5			ns
t _{CHSL}	CS# Not Active Hold Time	5			ns
tshsl	CS# High Time (Read/Write)	20			ns
tshqz	Output Disable Time			6	ns
t _{CLQX}	Output Hold Time	1.0			ns
tovch	Data In Setup Time	2			ns
tchdx	Data In Hold Time	3			ns
thlch	HOLD# Low Setup Time (Relative To Clock)	5			ns
tннсн	HOLD# High Setup Time (Relative To Clock)	5			ns
t _{CHHL}	HOLD# High Hold Time (Relative To Clock)	5			ns
tсннн	HOLD# Low Hold Time (Relative To Clock)	5			ns
tHLQZ	HOLD# Low To High-Z Output			6	ns
t _{HHQX}	HOLD# Low To Low-Z Output			6	ns
tclqv	Clock Low To Output Valid			7	ns
twhsl	Write Protect Setup Time Before CS# Low	20			ns
tshwl	Write Protect Hold Time After CS# High	100			ns
t _{DP}	CS# High To Deep Power-Down Mode			20	μs
-51	CS# High To Standby Mode Without Electronic Signature				F
t _{RES1}	Read			30	μs
t _{RES2}	CS# High To Standby Mode With Electronic Signature Read			30	μs
tsus	CS# High To Next Command After Suspend			20	μs
t _{RS}	Latency Between Resume And Next Suspend	100			μs
rk9	CS# High To Next Command After Reset (Except From	100			μο
t _{RST}	Erase)			30	μs



GD25Q127C

t _{RST_E}	CS# High To Next Command After Reset (From Erase)		12	ms
tw	Write Status Register Cycle Time	5	30	ms
t _{BP1}	Byte Program Time (First Byte)	30	60	μs
t _{BP2}	Additional Byte Program Time (After First Byte)	2.5	15	μs
tpp	Page Programming Time	0.5	4	ms
tse	Sector Erase Time	50	500	ms
t _{BE1}	Block Erase Time (32K Bytes)	0.16	2.5	S
t _{BE2}	Block Erase Time (64K Bytes)	0.3	4	S
tce	Chip Erase Time (GD25Q127C)	50	180	S

- 1. Typical value tested at $T = 25^{\circ}C$.
- 2. Value guaranteed by design and/or characterization, not 100% tested in production.



(T= -40°C~125°C, VCC=2.7~3.6V, C_L=30pf, Low Power Mode)

Symbol	Parameter	Min.	Тур.	Max.	Unit.
_	Serial Clock Frequency For: Fast Read (0BH), on 2.7V-3.6V			404	NAL 1-
Fc	power supply			104	MHz
	Serial Clock Frequency For: Dual Output (3BH), Quad Output				
f _{C1}	(6BH), Dual I/O (BBH), Quad I/O (EBH), Quad I/O Word Fast			70	MHz
	Read (E7H), on 2.7V-3.0V power supply				
	Serial Clock Frequency For: Dual Output (3BH), Quad Output				
f _{C2}	(6BH), Dual I/O (BBH), Quad I/O (EBH), Quad I/O Word Fast			80	MHz
	Read (E7H), on 3.0V-3.6V power supply				
f_	Serial Clock Frequency For: Read (03H), Read Manufacturer			60	MUZ
f _R	ID/device ID (90H), Read Identification (9FH)			60	MHz
tclh	Serial Clock High Time	4.5			ns
tcll	Serial Clock Low Time	4.5			ns
t _{CLCH}	Serial Clock Rise Time (Slew Rate)	0.1			V/ns
tchcl	Serial Clock Fall Time (Slew Rate)	0.1			V/ns
tslch	CS# Active Setup Time	5			ns
tснsн	CS# Active Hold Time	5			ns
tshch	CS# Not Active Setup Time	5			ns
t _{CHSL}	CS# Not Active Hold Time	5			ns
tshsl	CS# High Time (Read/Write)	20			ns
tshqz	Output Disable Time			6	ns
t _{CLQX}	Output Hold Time	1.0			ns
tovch	Data In Setup Time	2			ns
tchdx	Data In Hold Time	3			ns
thlch	HOLD# Low Setup Time (Relative To Clock)	5			ns
tннсн	HOLD# High Setup Time (Relative To Clock)	5			ns
t _{CHHL}	HOLD# High Hold Time (Relative To Clock)	5			ns
tсннн	HOLD# Low Hold Time (Relative To Clock)	5			ns
thlqz	HOLD# Low To High-Z Output			6	ns
t _{HHQX}	HOLD# Low To Low-Z Output			6	ns
tcLQV	Clock Low To Output Valid			7	ns
t _{WHSL}	Write Protect Setup Time Before CS# Low	20			ns
tshwl	Write Protect Hold Time After CS# High	100			ns
top	CS# High To Deep Power-Down Mode			50	μs
	CS# High To Standby Mode Without Electronic Signature				1
t _{RES1}	Read			50	μs
t _{RES2}	CS# High To Standby Mode With Electronic Signature Read			50	μs
tsus	CS# High To Next Command After Suspend			50	μs
trs	Latency Between Resume And Next Suspend	100			μs
trst	CS# High To Next Command After Reset (Except From				100
-11.01	Erase)			50	μs



GD25Q127C

t _{RST_E}	CS# High To Next Command After Reset (From Erase)		30	ms
tw	Write Status Register Cycle Time	15	80	ms
t _{BP1}	Byte Program Time (First Byte)	60	180	μs
t _{BP2}	Additional Byte Program Time (After First Byte)	8	50	μs
t PP	Page Programming Time	1.6	6	ms
tse	Sector Erase Time	100	600	ms
t _{BE1}	Block Erase Time (32K Bytes)	0.3	4	S
t _{BE2}	Block Erase Time (64K Bytes)	0.5	5	S
tce	Chip Erase Time (GD25Q127C)	150	400	S

- 1. Typical value tested at T = 25° C.
- 2. Value guaranteed by design and/or characterization, not 100% tested in production.

Figure 45. Serial Input Timing

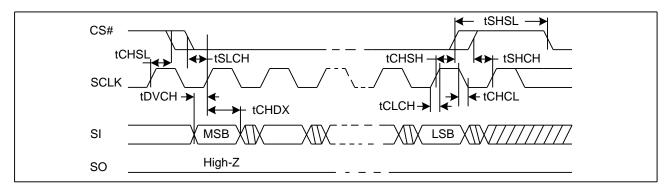


Figure 46. Output Timing

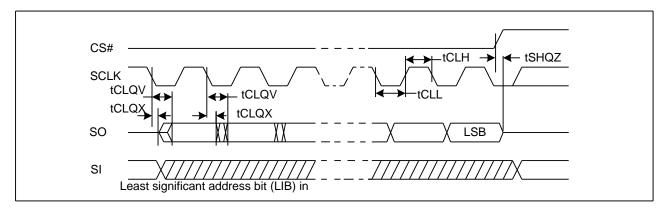


Figure 47. Resume to Suspend Timing Diagram

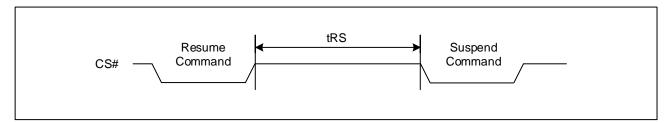


Figure 48. Hold Timing

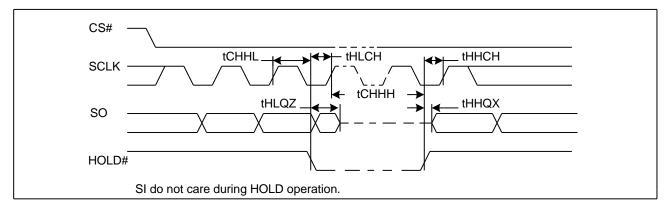
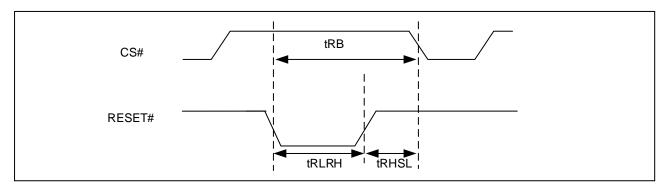


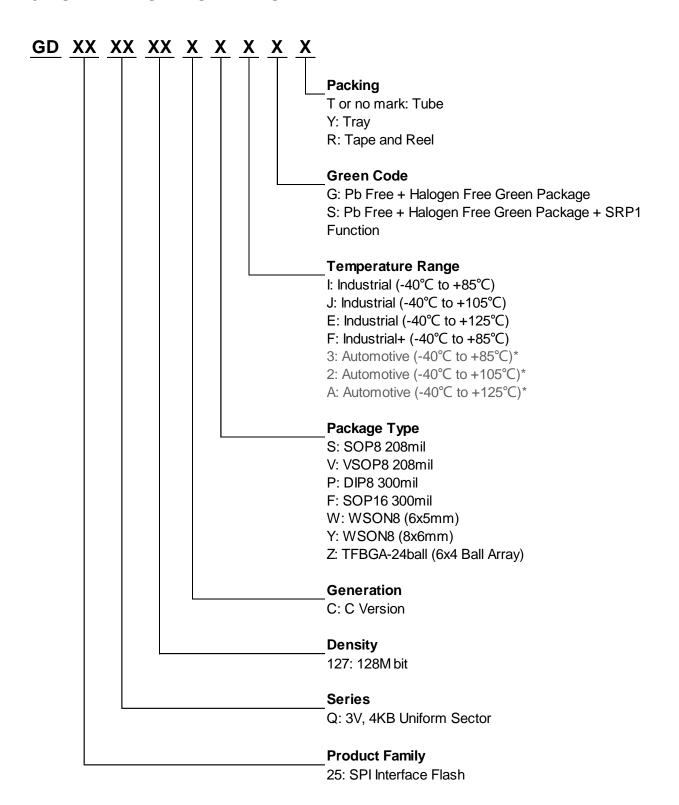
Figure 49. RESET Timing



Reset Timing

	_				
Symbol	Parameter	Min.	Тур.	Max.	Unit.
tRLRH	Reset Pulse Width	1			μs
tRHSL	Reset High Time Before Read	50			ns
tRB	Reset Recovery Time			12	ms

9. ORDERING INFORMATION



^{*} Please contact GigaDevice sales for automotive products.

9.1. Valid Part Numbers

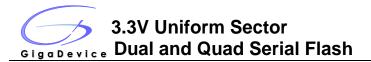
Please contact GigaDevice regional sales for the latest product selection and available form factors.

Temperature Range I: Industrial (-40°C to +85°C)

Product Number	Density	Package Type			
GD25Q127CSIG	120Mbit	SOD9 200mil			
GD25Q127CSIS	128Mbit	SOP8 208mil			
GD25Q127CVIG	1 2 0 M h i t	VCOD9 209mil			
GD25Q127CVIS	128Mbit	VSOP8 208mil			
GD25Q127CPIG	4.00Mb;t	DIDO 200mil			
GD25Q127CPIS	128Mbit	DIP8 300mil			
GD25Q127CFIG	4.00Mb;t	COD4C 200mil			
GD25Q127CFIS	128Mbit	SOP16 300mil			
GD25Q127CWIG	4.00M/b;4	MCONG (CyEmm)			
GD25Q127CWIS	128Mbit	WSON8 (6x5mm)			
GD25Q127CYIG	1.20Mb;t	\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\			
GD25Q127CYIS	128Mbit	WSON8 (8x6mm)			
GD25Q127CZIG	4.00Mb;t	TEDCA 24hall (Cv.4 Dall Arres)			
GD25Q127CZIS	128Mbit	TFBGA-24ball (6x4 Ball Array)			

Temperature Range J: Industrial (-40°C to +105°C)

Product Number	Density	Package Type
GD25Q127CSJG	128Mbit	SOP8 208mil
GD25Q127CSJS	1 ZOIVIDIL	30F6 206Hill
GD25Q127CVJG	4.00Mb;t	\/COD0 200m;l
GD25Q127CVJS	128Mbit	VSOP8 208mil
GD25Q127CPJG	120Mbit	DID9 200mil
GD25Q127CPJS	128Mbit	DIP8 300mil
GD25Q127CFJG	120Mbit	SOD16 200mil
GD25Q127CFJS	128Mbit	SOP16 300mil
GD25Q127CWJG	120Mbit	WSONG (SyEmm)
GD25Q127CWJS	128Mbit	WSON8 (6x5mm)
GD25Q127CYJG	4.00Mb;t	\\\CON(\0,\0\cdot\0\cdo
GD25Q127CYJS	128Mbit	WSON8 (8x6mm)
GD25Q127CZJG	120Mb;t	TEDCA 24ball (Cv4 Dall Array)
GD25Q127CZJS	128Mbit	TFBGA-24ball (6x4 Ball Array)



Temperature Range E: Industrial (-40°C to +125°C)

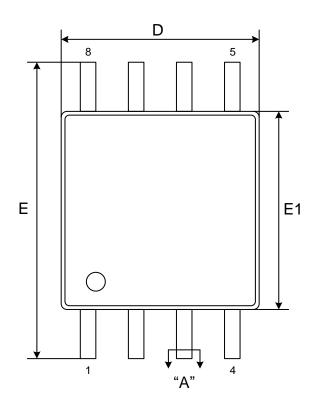
Product Number	Density	Package Type			
GD25Q127CSEG	4.00N/lb:t	COD0 200mil			
GD25Q127CSES	128Mbit	SOP8 208mil			
GD25Q127CVEG	4.00M/h:t	\/COD9 200m;I			
GD25Q127CVES	128Mbit	VSOP8 208mil			
GD25Q127CPEG	128Mbit	DID9 200mil			
GD25Q127CPES	1 ZOIVIDIL	DIP8 300mil			
GD25Q127CFEG	4.00M/h:t	COD4C 200mil			
GD25Q127CFES	128Mbit	SOP16 300mil			
GD25Q127CWEG	128Mbit	WSON9 (SyEmm)			
GD25Q127CWES	1 ZOIVIDIL	WSON8 (6x5mm)			
GD25Q127CYEG	1.20Mb;t	\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\			
GD25Q127CYES	128Mbit	WSON8 (8x6mm)			
GD25Q127CZEG	400046:4	TERCA CALCULATION ASSESSED.			
GD25Q127CZES	128Mbit	TFBGA-24ball (6x4 Ball Array)			

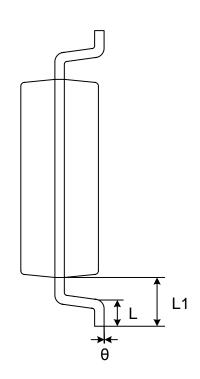
Temperature Range F: Industrial+ (-40°C to +85°C)

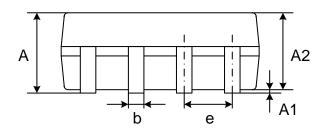
Product Number	Density	Package Type			
GD25Q127CSFG	128Mbit	SOP8 208mil			
GD25Q127CSFS	120MDIL	SOP6 20611111			
GD25Q127CVFG	4.00Mb;t	\(COD9.209m;			
GD25Q127CVFS	128Mbit	VSOP8 208mil			
GD25Q127CPFG	4.00Mb;t	DIDO 200mil			
GD25Q127CPFS	128Mbit	DIP8 300mil			
GD25Q127CFFG	4.00Mb;t	COD4C 200mil			
GD25Q127CFFS	128Mbit	SOP16 300mil			
GD25Q127CWFG	4.00Mb;t	MCONG (CVF mm)			
GD25Q127CWFS	128Mbit	WSON8 (6x5mm)			
GD25Q127CYFG	4.000 Mb :4	\\(CON(0./0x/Cro.ro.)			
GD25Q127CYFS	128Mbit	WSON8 (8x6mm)			
GD25Q127CZFG	4.000 Mb :4	TEDCA DANGIL (C. A Dell Arres)			
GD25Q127CZFS	128Mbit	TFBGA-24ball (6x4 Ball Array)			

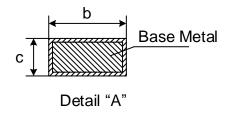
10. PACKAGE INFORMATION

10.1. Package SOP8 208MIL





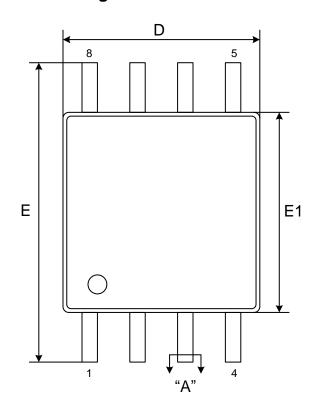


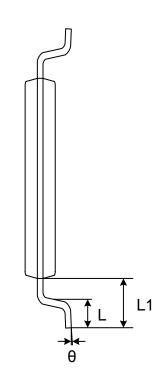


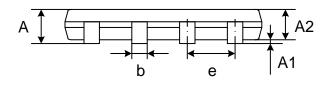
Dimensions

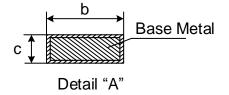
Symbol		٨	A.1	42	L	_	D	E	E4			1.4	0
U	Unit		A 1	A2	b	С		_	E1	е	L	L1	θ
	Min	-	0.05	1.70	0.31	0.15	5.13	7.70	5.18		0.50		0°
mm	Nom	-	0.15	1.80	0.41	0.20	5.23	7.90	5.28	1.27	-	1.31	-
'''''	Max	2.16	0.25	1.90	0.51	0.25	5.33	8.10	5.38		0.85		8°

- 1. Both the package length and width do not include the mold flash.
- 2. Seating plane: Max. 0.1mm.





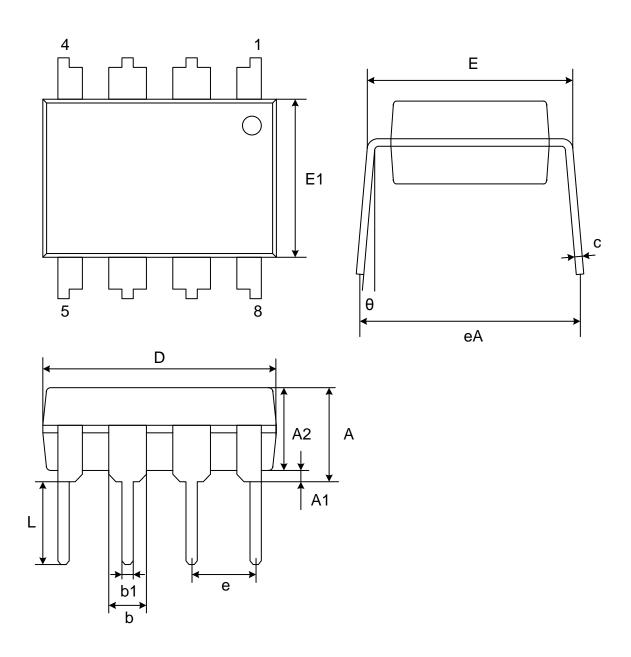




Dimensions

Symbol			A4	40	L		,	Е	F4			1.4	
U	Init	A	A1	A2	b	С	D	E	E1	е	L	L1	θ
	Min	-	0.05	0.75	75 0.35 0.09 5.18 7.70 5.18		0.50	0.50					
mm	Nom	-	0.10	0.80	0.42	0.15	5.28	7.90	5.28	1.27	-	1.31	-
	Max	1.00	0.15	0.85	0.50	0.20	5.38	8.10	5.38		0.80		10°

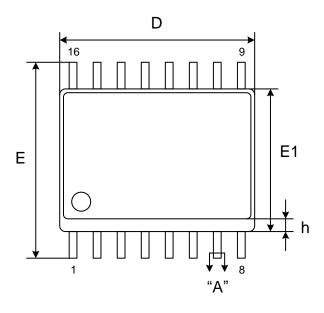
- 1. Both the package length and width include the mold flash.
- 2. Seating plane: Max. 0.1mm.

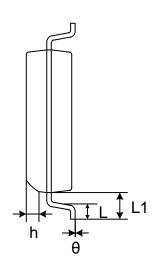


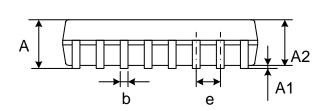
Dimensions

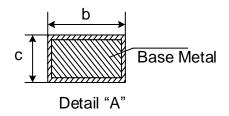
Syı	mbol	۸	A1	A2	b	b1	С	D	Е	E1	•		eA	θ
U	Jnit	Α	AI	AZ	Б	ы	C		_	EI	е	L	CA	"
	Min	-	0.38	3.00	1.14	0.36	0.20	9.02	7.62	6.10		2.92	8.45	0°
mm	Nom	-	-	3.30	1.52	0.46	0.25	9.27	7.87	6.35	2.54	3.30	8.90	-
	Max	3.88	-	3.50	1.78	0.56	0.35	9.59	8.26	6.60		3.81	9.35	11°

Note: Both the package length and width do not include the mold flash.







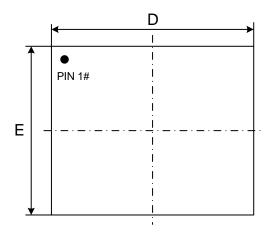


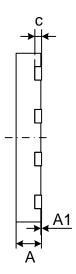
Dimensions

Syı	Symbol A Unit		A 4	A2	L		_	Е	E1			L1	b	0
U			A1	AZ	b	С	D		LI	е	_		n	θ
	Min	-	0.10	2.05	0.31	0.10	10.20	10.10	7.40		0.40		0.25	0
mm	Nom	-	0.20	-	0.41	0.25	10.30	10.30	7.50	1.27	-	1.40	-	-
	Max	2.65	0.30	2.55	0.51	0.33	10.40	10.50	7.60		1.27		0.75	8

- 1. Both the package length and width do not include the mold flash.
- 2. Seating plane: Max. 0.1mm.

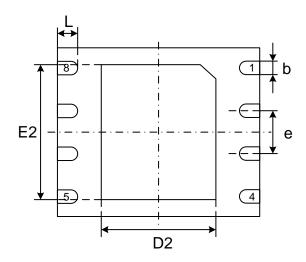
10.5. Package WSON8 (6*5mm)





Top View

Side View



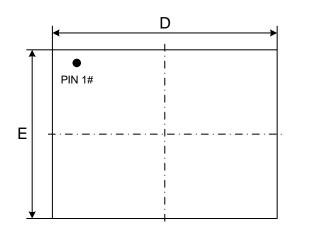
Bottom View

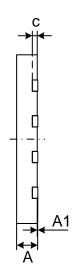
Dimensions

Symbol			A1		h	D	D2	Е	Ea		
L	Jnit	Α	AI	С	b	U	DZ		E2	е	
	Min	0.70	0.00	0.180	0.35	5.90	3.30	4.90	3.90		0.50
mm	Nom	0.75	0.02	0.203	0.40	6.00	3.40	5.00	4.00	1.27	0.60
	Max	0.80	0.05	0.250	0.50	6.10	3.50	5.10	4.10		0.75

- 1. Both the package length and width do not include the mold flash.
- 2. The exposed metal pad area on the bottom of the package is floating.
- 3. Coplanarity \leq 0.08mm. Package edge tolerance \leq 0.10mm.
- 4. The lead shape may be of little difference according to different package lead frames. These lead shapes are compatible with each other.

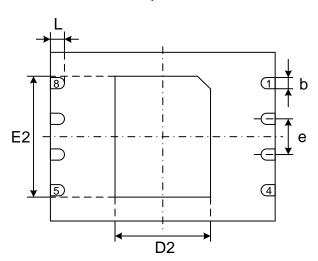
10.6. Package WSON8 (8*6mm)





Top View

Side View



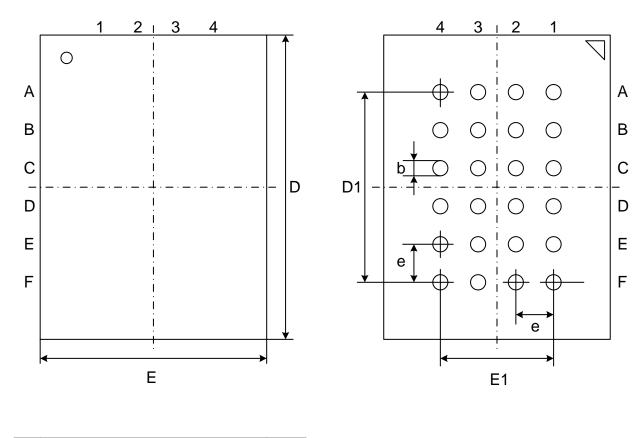
Bottom View

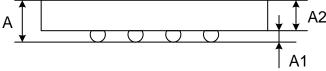
Dimensions

	mbol Jnit	Α	A 1	С	b	D	D2	E	E2	е	L
	Min	0.70	0.00	0.180	0.35	7.90	3.30	5.90	4.20		0.45
mm	Nom	0.75	0.02	0.203	0.40	8.00	3.40	6.00	4.30	1.27	0.50
	Max	0.80	0.05	0.250	0.45	8.10	3.50	6.10	4.40		0.55

- 1. Both the package length and width do not include the mold flash.
- 2. The exposed metal pad area on the bottom of the package is floating.
- 3. Coplanarity \leq 0.08mm. Package edge tolerance \leq 0.10mm.
- 4. The lead shape may be of little difference according to different package lead frames. These lead shapes are compatible with each other.

10.7. Package TFBGA-24BALL (6*4 ball array)





Dimensions

<u> </u>	mbol Jnit	Α	A1	A2	b	E	E1	D	D1	е
	Min	-	0.25	0.75	0.35	5.90		7.90		
mm	Nom	-	0.30	0.80	0.40	6.00	3.00	8.00	5.00	1.00
	Max	1.20	0.35	0.85	0.45	6.10		8.10		

Note: Both the package length and width do not include the mold flash.

11. REVISION HISTORY

Version No	Description	Page	Date		
1.0	Initial Release	All	2016-03-17		
1.1	Modify SFDP table	P40-43	2016-05-31		
	Modify TFBGA-24Ball (6*4 ball array)	P60			
	Delete Data Retention and endurance	P4			
1.2	Modify POWER-ON TIMING: VWI Min 1V Change to 1.5V.	P44	2016-07-20		
	Add Valid Part Numbers	P53			
	Modify Features: Add Allows XIP(execute in place)operation	P4			
1.3	Update Table7.5. Parameter Table (1): GigaDevice Flash	P43	2016-08-26		
1.3	Parameter Tables		2010-06-26		
1.4	Modify Package WSON8 8x6mm	P59	2016-12-15		
	Modify SRP1, SRP0 bits Notes	P13			
4.5	Modify ORDERING INFORMATION	P51	2047 02 22		
1.5	Update WSON8(6*5mm)	P57	2017-02-23		
	Update WOSN8(8*6mm)	P58			
1.6	Update ORDERING INFORMATION	P51	2017-03-08		
1.7	Add Packing Type of "T or no mark: Tube" in the Ordering	P52			
	Information		2017-09-26		
	Update the Package descriptions	P54-56, 58-60			
	Modify VCC from "-0.6 to 4.0" to "-0.6 to 4.2"	P44			
	Add Icc8. The max value of Icc8 is 25mA for Normal Mode and	P46, 47			
1.8	15mA for Low Power Mode		2017-10-23		
1.0	Delete tRST_R and tRST_P	P48, 50	2017-10-23		
	Add tRST. The max of tRST is 30us for Normal Mode and 50us	P48, 50			
	for Low Power Mode				
	Add 4BH command	P39			
	Modify tVSL min value from 5ms to 2.5ms	P45			
	Add tRS, min = 100us	P53, 55			
	Modify tRB from 5/60us to 12ms	P49			
	Update the description of all the packages	P58-64			
	Normal Mode -40°C~85°C :				
	Modify Icc4-8 max. value from 25mA to 27mA	P47			
1.9	Modify tPP typ. value from 0.6s to 0.5s	P50	2018-07-11		
	Modify tBE1 from 0.2s~1s to 0.16s~0.8s	P50			
	Modify tCE from typ. value from 60s to 50s	P50			
	Low Power Mode -40°C~85°C :				
	Modify Deep Power-Down Current from 0.1~1uA to 1~5uA	P48			
	Modify Icc3@104MHz max value from 18mA to 20mA	P48			
	Modify Icc3@80MHz max value from 15mA to 18mA	P48			
	Modify Icc4-8 max value from 15mA to 25mA	P48			



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	Modify Figure 32. Program Security Registers command	P37	
	Sequence Diagram		
2.0	Add DC/AC characteristics @-40°C~105°C	P49-50/P57-60	2018-8-2
	Add DC/AC characteristics @-40°C~125°C	P51-52/P61-64	
	Modify Ordering Information	P67	
2.1	Modify AC characteristics@Fc,fc1,fc2,fR	P53,55,57,59,61,63	2018-8-21

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