



Answer Key

Chapter 1

Exercise 1.2

1. Where is the documentation for the PWM API located?

It is in the WICED API Reference. The path in that document is:

Cypress WICED API Reference Guide
Components
Hardware Drivers
PWM

Exercise 1.3

1. What is the organization of the spec?

Volumes, Parts, Sections

2. On what page does the Attribute protocol specification start?

2169

Chapter 2

Exercise 2.1

1. What is the name of the first user application function that is executed? What does it do?

The first user function is `application_start()`.

It just initializes the Bluetooth stack and registers the callback.

2. What is the purpose of the function `app_bt_management_callback`? When does the `BTM_ENABLED_EVT` case occur?

It is the Bluetooth stack management callback function. It is called whenever there is a management event from the stack.

The `BTM_ENABLED_EVT` case occurs once the stack has completed initialization.

3. What controls the rate of the LED blinking?

The first parameter to the RTOS delay function `wiced_rtos_delay_milliseconds` specifies the delay which controls the rate of the LED blinking.

Exercise 2.9

1. How many bytes does the NVRAM read function get before you press the button the first time?

0

2. What is the return status value before you press the button the first time?

The return value is 40 (0x28).

1. What does the return value mean?

The return value of 40 (0x28) means ERROR. This is defined in the file `wiced_result.h`.

Chapter 3

Exercise 3.1

1. Do you need *wiced_rtos_delay_milliseconds()* in the LED thread? Why or why not?

No, because the *wiced_rtos_get_semaphore* will cause the thread to suspend each time through the infinite loop while it waits for another button press.

Exercise 3.2

Before you added the mutex, how did the LED behave when you pressed the button?

The LED flashes in an irregular pattern.

What changed when you added the mutex?

The LED flashes slowly (2Hz) when the button is not pressed and then flashes quickly (5Hz) when the button is pressed.

What happens if you forget to unlock the mutex in one of the threads? Why?

The other thread will never execute. That is:

If you don't unlock the mutex in the fast LED thread, the slow LED thread will not execute. The LED will blink fast when the button is pressed but will not blink when the button is not pressed.

If you don't unlock the mutex in the slow LED thread, the fast LED thread will never execute so the LED will blink slowly no matter what happens with the button.

Chapter 4A

Exercise 4A.3

1. How many bytes is the advertisement packet?

The advertisement packet is 19 bytes. They are:

Flags (3)

Length (1)

Type (1)

Data (1)

Local Name (9)

Length (1)

Type (1)

Data (7)

Appearance (4)

Length (1)

Type (1)

Data (2)

Manufacturer Specific Data (3)

Length (1)

Type (1)

Data (1)

Exercise 4A.4

1. What function is called when there is a Stack event? Where is it registered?

The function is *ex03_ble_con_management_callback*. It is registered using *wiced_bt_stack_init* in *application_start*.

2. What function is called when there is a GATT database event? Where is it registered?

The function is *ex03_ble_con_event_handler*. It is registered using *wiced_bt_gatt_register* in *ex03_ble_con_app_init*.

3. Which GATT events are implemented? What other GATT events exist? (Hint: right click and select Open Declaration on one of the implemented events)

Implemented:

GATT_CONNECTION_STATUS_EVT
GATT_ATTRIBUTE_REQUEST_EVT

Others:

GATT_OPERATION_CPLT_EVT
GATT_DISCOVERY_RESULT_EVT
GATT_DISCOVERY_CPLT_EVT
GATT_CONGESTION_EVT

4. In the GATT "GATT_ATTRIBUTE_REQUEST_EVT", what request types are implemented? What other request types exist?

Implemented:

GATTS_REQ_TYPE_READ
GATTS_REQ_TYPE_WRITE

Others:

GATTS_REQ_TYPE_PREP_WRITE
GATTS_REQ_TYPE_WRITE_EXEC
GATTS_REQ_TYPE_MTU
GATTS_REQ_TYPE_CONF

Chapter 4B

Exercise 4B.3

1. How long does the device stay in high duty cycle advertising mode? How long does it stay in low duty cycle advertising mode? Where are these values set?

High: 30 seconds

Low: 60 seconds

These are specified in the `wiced_bt_cfg.c` file in
`wiced_bt_cfg_settings.ble_advert_cfg.high_duty_duration` and
`wiced_bt_cfg_settings.ble_advert_cfg.low_duty_duration`

Exercise 4B.4

1. What items are stored in NVRAM?

Hostinfo (Remote BDADDR and Button CCCD state)

Local Keys (Privacy Information)

Paired Device Keys (Encryption Information)

2. Which event stores each piece of information?

Hostinfo is stored during BTM_PAIRING_COMPLETE_EVT and in
`ex03_ble_bond_set_value` if the Button CCCD value was written

Local Keys are stored during BTM_LOCAL_IDENTITY_KEYS_UPDATE_EVT

Paired Keys are stored during BTM_PAURED_DEVICE_LINK_KEYS_UPDATE_EVT

All three are cleared out (i.e. reset) in the `button_cback` function to allow re-pairing.

3. Which event retrieves each piece of information?

Hostinfo is retrieved by BTM_ENCRYPTION_STATUS_EVT (if the device was previously bonded)

Local Keys are retrieved by BTM_LOCAL_IDENTITY_KEYS_REQUEST_EVT

Paired Keys are retrieved by `ex03_ble_bond_app_init` (at startup) and by
BTM_PAURED_DEVICE_LINK_KEYS_REQUEST_EVT

4. In what event is the privacy info read from NVRAM?

BTM_LOCAL_IDENTITY_KEYS_REQUEST_EVT

5. Which event is called if privacy information is not retrieved after new keys have been generated by the stack?

BTM_LOCAL_IDENTITY_KEYS_UPDATE_EVT

Exercise 4B.5

1. Other than BTM_IO_CAPABILITIES_NONE and BTM_IO_CAPABILITIES_DISPLAY_ONLY, what other choices are available? What do they mean?

BTM_IO_CAPABILITIES_DISPLAY_AND_YES_NO_INPUT

Device can display values (e.g. 6-digit numbers) and can accept a Yes/No input from the user.

BTM_IO_CAPABILITIES_KEYBOARD_ONLY

Device can accept input (e.g. numbers) but cannot display any values.

BTM_IO_CAPABILITIES_BLE_DISPLAY_AND_KEYBOARD_INPUT

Device can display values (e.g. 6-digit numbers) and can accept input (e.g. numbers).

2. What additional stack callback event occurs compared to the previous exercise? At what point does it get called?

BTM_PASSKEY_NOTIFICATION_EVT

This event is called between

BTM_PAIRING_IO_CAPABILITIES_BLE_REQUEST_EVT and
BTM_ENCRYPTION_STATUS_EVT.

Chapter 4C

Exercise 4C.1

1. Which lines in the code are used to configure sleep?

Lines 177 – 188:

```
/* Configure and initialize sleep */
sleep_config.sleep_mode           = WICED_SLEEP_MODE_NO_TRANSPORT;
sleep_config.device_wake_mode     = WICED_SLEEP_WAKE_ACTIVE_LOW;
sleep_config.device_wake_source   = WICED_SLEEP_WAKE_SOURCE_GPIO;
sleep_config.device_wake_gpio_num = WICED_GPIO_PIN_BUTTON_1;
sleep_config.host_wake_mode       = WICED_SLEEP_WAKE_ACTIVE_LOW;
sleep_config.sleep_permit_handler = low_power_sleep_callback;

if(WICED_BT_SUCCESS != wiced_sleep_configure(&sleep_config))
{
    WICED_BT_TRACE("Sleep Configure failed!\n\r");
}
```

2. When in the code is sleep configured (i.e. after which event)?

Sleep configuration is done right after the BT stack initialization (wiced_bt_stack_init).

3. What is used as a wakeup source?

WICED_GPIO_PIN_BUTTON_1 is used as a wakeup source.

4. What is the name of the sleep permit handler function?

low_power_sleep_callback

5. What character is printed to the UART for:

- a. The PMU requests sleep permission and it is allowed without shutdown: __\$__
- b. The PMU indicates that it is time to sleep: __e__

6. When are the connection interval min, max, latency, and timeout values updated and what values are used?

The values are updated in the GATT connect callback function when a connection is established. The code is:

```
wiced_bt_l2cap_update_ble_conn_params( p_conn_status->bd_addr, 200, 200, 3, 512 );
```


The values are set to:

Min Interval: 250ms	(200 * 1.25ms)
Max Interval: 250ms	(200 * 1.25ms)
Latency: 3	
Timeout: 5120ms	(512 * 10ms)

Exercise 4C.7

1. Which variable is used to control sleep permissions? What are its states?

The variable is `sleep_type`. It can be:

`WICED_SLEEP_NOT_ALLOWED`
`WICED_SLEEP_ALLOWED_WITHOUT_SHUTDOWN`
`WICED_SLEEP_ALLOWED_WITH_SHUTDOWN`

2. What is printed to the UART when:
 - a. A sleep request is denied: x
 - b. A sleep request is allowed without shutdown: \$
 - c. A sleep request is allowed with shutdown: .
 - d. Sleep is entered: e
 - e. A fast boot occurs: f
3. When is sleep not allowed? When is sleep allowed but without shutdown (PDS)? When is sleep allowed with shutdown (SDS)?

Sleep is not allowed from powerup until advertising is started.

PDS is allowed once the GATT connection is made
 (GATT_CONNECTION_STATUS_EVT with status of connected) until pairing is complete (BTM_ENCRYPTION_STATUS_EVT with result of WICED_SUCCESS).

SDS is allowed during advertising and during a connection once pairing is complete.

4. When does SDS occur (Hint: you can determine that SDS occurred when you see a fast boot)?

SDS occurs during low duty cycle advertising (because the timeout is set to 0) and during a connection once pairing is complete.

5. What is done differently for a cold boot vs. a fast boot? Why?

For a cold boot, the GPIO for button 1 is configured. That isn't needed for a fast boot since the GPIO configuration is retained. Also, more debug information is printed during

a cold boot to get initial startup information without flooding the screen with values during fast boot.

For a fast boot, we check the `connection_id`. If the device is connected, then we read `hostinfo` (paring information) from the NVRAM, restore the previous CapSense button value and CCCD value in the GATT database. This allows the firmware to determine if a notification must be sent the next time a CapSense scan is done (i.e. if the CapSense value has changed and notifications are enabled).

6. What is AON RAM? What values is it used for and why?

AON is Always ON RAM. It is RAM that is retained during SDS. It is used for `connection_id`, `prevVal`, and `advert_mode`.

`connection_id` allows us to tell if we were connected when we went to sleep so that the bonding information can be restored on a fast boot.

`prevVal` is used to restore the CapSense button value. This is done so that the firmware can tell if the button value changed while the device was asleep.

`Advert_mode` is saved so that on a fast boot advertising can start up where it left off. If this wasn't done, the device would start high duty cycle advertisements again as soon as it did a fast boot.

Chapter 4D

Exercise 4D.1

1. What is the cause of “Unhandled Bluetooth Management Event: 0x16 (22)”?. How could you fix it?

The "Unhandled Bluetooth Management Event: 0x16 (22)" occurs when the scan state changes. The default configuration in `wiced_bt_cft.c` has the high duty and low duty scan duration both set to 5 seconds. So, after 5 seconds it goes from high to low duty scan and then after another 5 seconds it stops scanning.

To fix this, I could change the high duty scan duration to 0 which would prevent scanning from timing out. In this case, I would still get one call to this event when scanning first starts. To eliminate that, I could just implement a case for that event and print out an appropriate message or do nothing.

Chapter 7B

Exercise 7B.1

1. What is the endianness for the network layer, lower transport layer, upper transport layer, and access layer?

Answer:

Network is big endian

Lower Transport is big endian

Upper Transport is big endian

Access is little endian

2. What is a mesh gateway?

Answer: A mesh gateway is a node that is able to translate messages between the mesh network and a non-Bluetooth technology. A node may be able to send and receive mesh messages through a mesh gateway while not in range of any of the Relay nodes.

For example, a smartphone may use a cell network or a WiFi network to communicate with a mesh network via a gateway.

3. For a Mesh Proxy Service, what characteristics are required and what properties must they have?

Answer:

Characteristic: Mesh Proxy Data In Properties: Write Without Response

Characteristic: Mesh Proxy Data Out Properties: Notify

Exercise 7B.2

1. What is the difference between the states "Light Lightness Actual" and "Light Lightness Linear"? How are they related?

Answer: Light Lightness Linear is just a linear value of the brightness of a light. For example, it may represent the duty-cycle for a PWM driving an LED. Light Lightness Linear is adjusted so that it represents perception of brightness. This mapping is done because the human eye does not perceive brightness linearly. Therefore, to make a light appear a certain percentage of its maximum brightness a translation must be done. Light Lightness Linear allows the user to specify an intended brightness for human perception which is then translated to Light Lightness Actual to drive a PWM.

The relationship is: $\text{Light Lightness Actual} = 65535 \sqrt{\frac{\text{Light Lightness Linear}}{65535}}$

2. How many lighting server models are defined? Where can you find them described in the Mesh model spec?

Answer: There are 11 Lighting Server models. They can be found in sections 6.4.1 – 6.4.11 of the Mesh Model specification.

3. List one set of messages that can be used for setting the Hue, Saturation (i.e. color) and Lightness of a light. Is this the only way to do it?

Answer: There are many ways to do this depending on the client and server implemented. For example:

- 1. Light HSL Set*
- 2. Light HSL Hue Set, Light HSL Saturation Set, and Light Lightness Linear Set*
- 3. Generic Level Set (use individually on each element assuming different colors are different elements)*
- 4. Generic Delta Set (use individually on each element assuming different colors are different elements)*
- 5. Generic Move Set (use individually on each element assuming different colors are different elements)*