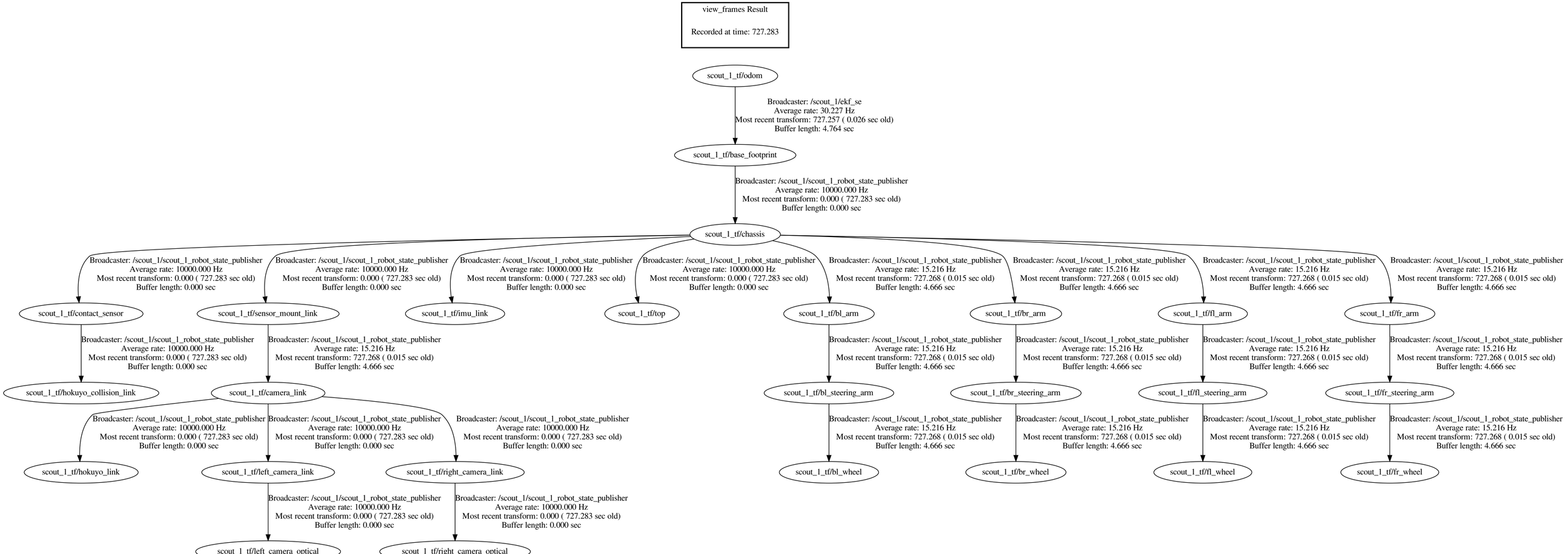
view_frames Result
Recorded at time: 727.283
scout_1_tf/odom
Broadcaster: /scout_1/ekf_se
Average rate: 30.227 Hz
Most recent transform: 727.257 (0.026 sec old)
Buffer length: 4.764 sec
scout_1_tf/base_footprint
Broadcaster: /scout_1/scout_1_robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (727.283 sec old)
Buffer length: 0.000 sec
scout_1_tf/chassis
Broadcaster: /scout_1/scout_1_robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (727.283 sec old)
Buffer length: 0.000 sec
scout_1_tf/contact_sensor
Broadcaster: /scout_1/scout_1_robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (727.283 sec old)
Buffer length: 0.000 sec
scout_1_tf/sensor_mount_link
Broadcaster: /scout_1/scout_1_robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (727.283 sec old)
Buffer length: 0.000 sec
scout_1_tf/imu_link
Broadcaster: /scout_1/scout_1_robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (727.283 sec old)
Buffer length: 0.000 sec
scout_1_tf/top
Broadcaster: /scout_1/scout_1_robot_state_publisher
Average rate: 15.216 Hz
Most recent transform: 727.268 (0.015 sec old)
Buffer length: 4.666 sec
scout_1_tf/bl_arm
Broadcaster: /scout_1/scout_1_robot_state_publisher
Average rate: 15.216 Hz
Most recent transform: 727.268 (0.015 sec old)
Buffer length: 4.666 sec
scout_1_tf/br_arm
Broadcaster: /scout_1/scout_1_robot_state_publisher
Average rate: 15.216 Hz
Most recent transform: 727.268 (0.015 sec old)
Buffer length: 4.666 sec
scout_1_tf/fl_arm
Broadcaster: /scout_1/scout_1_robot_state_publisher
Average rate: 15.216 Hz
Most recent transform: 727.268 (0.015 sec old)
Buffer length: 4.666 sec
scout_1_tf/fr_arm
Broadcaster: /scout_1/scout_1_robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (727.283 sec old)
Buffer length: 0.000 sec
scout_1_tf/hokuyo_collision_link
Broadcaster: /scout_1/scout_1_robot_state_publisher
Average rate: 15.216 Hz
Most recent transform: 727.268 (0.015 sec old)
Buffer length: 4.666 sec
scout_1_tf/camera_link
Broadcaster: /scout_1/scout_1_robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (727.283 sec old)
Buffer length: 0.000 sec
scout_1_tf/hokuyo_link
Broadcaster: /scout_1/scout_1_robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (727.283 sec old)
Buffer length: 0.000 sec
scout_1_tf/left_camera_link
Broadcaster: /scout_1/scout_1_robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (727.283 sec old)
Buffer length: 0.000 sec
scout_1_tf/right_camera_link
Broadcaster: /scout_1/scout_1_robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (727.283 sec old)
Buffer length: 0.000 sec
scout_1_tf/left_camera_optical
Broadcaster: /scout_1/scout_1_robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (727.283 sec old)
Buffer length: 0.000 sec
scout_1_tf/right_camera_optical
scout_1_tf/bl_steering_arm
Broadcaster: /scout_1/scout_1_robot_state_publisher
Average rate: 15.216 Hz
Most recent transform: 727.268 (0.015 sec old)
Buffer length: 4.666 sec
scout_1_tf/br_steering_arm
Broadcaster: /scout_1/scout_1_robot_state_publisher
Average rate: 15.216 Hz
Most recent transform: 727.268 (0.015 sec old)
Buffer length: 4.666 sec
scout_1_tf/fl_steering_arm
Broadcaster: /scout_1/scout_1_robot_state_publisher
Average rate: 15.216 Hz
Most recent transform: 727.268 (0.015 sec old)
Buffer length: 4.666 sec
scout_1_tf/fr_steering_arm
Broadcaster: /scout_1/scout_1_robot_state_publisher
Average rate: 15.216 Hz
Most recent transform: 727.268 (0.015 sec old)
Buffer length: 4.666 sec
scout_1_tf/bl_wheel
Broadcaster: /scout_1/scout_1_robot_state_publisher
Average rate: 15.216 Hz
Most recent transform: 727.268 (0.015 sec old)
Buffer length: 4.666 sec
scout_1_tf/br_wheel
Broadcaster: /scout_1/scout_1_robot_state_publisher
Average rate: 15.216 Hz
Most recent transform: 727.268 (0.015 sec old)
Buffer length: 4.666 sec
scout_1_tf/fl_wheel
Broadcaster: /scout_1/scout_1_robot_state_publisher
Average rate: 15.216 Hz
Most recent transform: 727.268 (0.015 sec old)
Buffer length: 4.666 sec
scout_1_tf/fr_wheel