



Editorial

Tasks, test data and solutions were prepared by: Adrian Beker, Marin Kišić, Daniel Paleka, Ivan Paljak, Tonko Sabolčec, Bojan Štetić i Paula Vidas. Implementation examples are given in attached source code files.



Task: Pastiri

Prepared by: Adrian Beker, Paula Vidas, Daniel Paleka

Necessary skills: graphs, breadth/depth-first search (BFS/DFS)

Denote the nodes of the tree by V . We will identify a sheep/shepherd with the node it occupies.

Notice that the task can be seen as an instance of the so called *set cover* problem: For every node $v \in V$, consider the set S_v of sheep which would be protected if we put a shepherd in node v . Then we need to find the smallest subset $P \subseteq V$ of nodes such that $\bigcup_{v \in P} S_v$ equals the set of all sheep. The general set cover problem is NP-complete, but the specific tree structure here will help us to solve the problem in polynomial time.

Let's start with the first subtask, the case when the tree is a chain. A shepherd can protect only the first sheep to the left and/or to the right, so the family $\{S_v \mid v \in V\}$ contains the following subsets:

- $\{x\}$ for every sheep x ;
- $\{x, y\}$ for consecutive sheep x, y such that $x - y$ is even.

We proceed with the following greedy algorithm: look at the first sheep. if the second one has the same parity, place a shepherd on the node halfway between them, otherwise place a shepherd in the same node as the first sheep. Next, remove the protected sheep and repeat the same algorithm. This solution has complexity $\mathcal{O}(N + K)$.

To solve the second subtask, we make use of representing the subsets of sheep by bitmasks in $\{0, 1, \dots, 2^K - 1\}$. We first find the sets S_v for every node $v \in V$ in $\mathcal{O}(K \cdot N)$ by running breadth-first search from every sheep.

We can then solve this set cover instance by dynamic programming. For each bitmask $mask$, let $f(mask)$ denote the minimum number of sets S_v which cover $mask$. We iterate through the states $mask$ in increasing order. When calculating $f(mask)$, we iterate over all $submask \subseteq mask$, and each time $submask$ corresponds to some of the sets S_v , we recalculate $f(mask) := f(mask \wedge submask) + 1$. To finish the transition, we put $f(submask) := f(mask)$ for all $submask \subseteq mask$,

Memory complexity is $\mathcal{O}(N + 2^K)$, and time complexity is $\mathcal{O}(K \cdot N + 3^K)$. (We leave the proof as exercise.)

For the remaining subtasks, we first pick an arbitrary node as the root. For each sheep x , we will refer to the set $\{v \in V \mid x \in S_v\}$ as its *territory*. We say that two sheep x and y are *friends* if their territories have nonempty intersection. The main idea is to greedily place a shepherd that protects some sheep and all of the (currently) unprotected friends of that sheep. The following claim will help us with that:

Claim 1. For some sheep x , let $a(x)$ be its highest ancestor that is in its territory. Then, $S_{a(x)}$ contains all friends of x that are not deeper than x . *Proof.* Let y be a friend of x that is not deeper than x . If y is in the subtree of $a(x)$, the claim is obvious, so assume the contrary. Take some node z that is not part of territories of x and y , and let w be the midpoint of the path between x and y . We have

$$d(z, x) = d(z, y) = d(z, w) + d(w, x) = d(z, w) + d(w, y),$$

where $d(u, v)$ denotes the distance between nodes u and v . Also, for every sheep t it's true that

$$d(z, w) + d(w, x) = d(z, x) \leq d(z, t) \leq d(z, w) + d(w, t),$$

which implies $d(w, x) \leq d(w, t)$, and $d(w, y) \leq d(w, t)$ is proved analogously. Hence, w is contained in the intersection of territories of x and y . Moreover, since y is not deeper than x , w is an ancestor of x , so it must be located on the path from x to $a(x)$. Since y is not contained in the subtree of $a(x)$, we have

$$d(a(x), y) \leq d(w, y) = d(w, x) \leq d(a(x), x),$$



so a shepherd in $a(x)$ protects y , as needed. \square

According to Claim 1, the following algorithm is correct:

- Repeat until all sheep are protected:
 - Place a shepherd in $a(x)$, where x is (one of) the deepest currently unprotected sheep.

The straightforward implementation in the complexity $\mathcal{O}(N(N+K))$, is sufficient to solve the third subtask. To solve the fourth subtask, we need to speed up the algorithm. For each node v , let $dep(v)$ and $dist(v)$ denote the depth of the node and the distance to the closest sheep, respectively. We can calculate $dist$ by running a BFS starting from each sheep. Alternatively, we can imagine that we added a *dummy* node connected to all the sheep and run the BFS starting in that node. The following fact will help us to efficiently determine $a(x)$ for each sheep x :

TODO: Observation 2. If v is an ancestor of x , then $dist(v) \leq dep(x) - dep(v)$, where equality is attained if and only if v is in the territory of x .

Due to the above, $a(x)$ is the index of first maximum of $dist(v) + dep(v)$ over all v on the path from the root to x . Thus we can calculate $a(x)$ for each sheep x by a simple depth-first search from the root.

The only thing left is maintaining the deepest unprotected sheep efficiently.

If we sort the sheep by decreasing depth, we can reduce this problem to maintaining the set of protected sheep.

U tu svrhu za početni BFS promotrimo pripadajući *graf najkraćih putova*. To je usmjeren graf G sa skupom vrhova V te bridovima (u, v) gdje je $\{u, v\}$ brid stabla takav da je $dist(v) = dist(u) + 1$.

Opservacija 3. Za svaki čvor $v \in V$, S_v je skup ovaca x takvih da postoji put od x do v u G .

Kad god postavimo novog pastira, proširimo se DFS-om iz njega unatrag po grafu G te pritom pazimo da obilazimo samo dosad neposjećene čvorove. Prema Obzervaciji 3, ovca je pokrivena ako i samo smo ju posjetili u DFS-u. Budući da svaki čvor posjećujemo najviše jednom, održavanje pokrivenih ovaca ima ukupno linearnu složenost.

Complexity of the solution is $\mathcal{O}(N + K \log K)$. Notice that the factor $\log K$ comes from sorting the sheep by depth, which is of course possible to do with complexity $\mathcal{O}(N + K)$ because the depths are at most N . Therefore it's possible to solve the task in linear complexity. For implementation details, see the official source codes.



Task: Semafor

Prepared by: Bojan Štetić, Ivan Paljak, Daniel Paleka

Necessary skills: matrix multiplication, graph theory, binary exponentiation

We will solve the harder case $M=2$.

We represent a state of the board by a bitmask of 10 bytes. Call a bitmask *nice* if the represented board shows a valid number.

It is well known that the vertices of the *hypercube graph* are all bitmasks of some size (10 here), and the edges connect bitmasks which differ in exactly one place. Let H denote the adjacency matrix of the hypercube.

Then the problem, formally, asks for the following: for each nice bitmask, find the number of walks of length N in the hypercube, starting from the state X , such that the walk visits the set of nice bitmasks every K steps.

Claim 1: The number of walks of length D in the hypercube, starting in X and ending in Y , equals the (X, Y) -th entry in the matrix H^D .

Proof: Look into Daniel A. Spielman's "Spectral and Algebraic Graph Theory", brilliant stuff. For an elementary proof, it's Lemma 3 on the link:

<https://courses.grainger.illinois.edu/cs598cci/sp2020/LectureNotes/lecture1.pdf> \square

Definition 2: Let B be the principal submatrix of H^K indexed by only the rows and columns of the nice bitmasks.

Claim 3: The number of walks (from X to Y) of length N in the hypercube, where K divides N , such that every K steps the walk visits a nice bitmask, equals the (X, Y) -th entry in the matrix $B^{N/K}$.

Proof: Left as exercise. \square

There are several steps in the solution. We need to calculate the matrix B , then calculate $B^{N/K}$, and then multiply it with the matrix corresponding to the last $N \bmod K$ steps. We omit the third because it is very similar to the first step, so we assume K divides N in the rest of the exposition.

Let us solve the second step (raising B to the N/K -th power) first. It is enough to use naive binary exponentiation and multiply two matrices in the ordinary cubic complexity, because for $M = 2$ we are dealing with 100×100 matrices.

The first step is tougher, because B is a submatrix of H^K , and H is a 1024×1024 matrix for $M = 2$. Naive calculation of H^K passes only the subtask $M = 1$. For smaller K and $M = 2$, it can be done with clever dynamic programming, and this should give the first four subtasks.

For the full problem, we need to raise the hypercube matrix to some power faster.

Claim 4: The (X, Y) -th entry of the matrix B depends only on the number of bits in which the bitmasks X and Y differ.

Proof: Without loss of generality, we can *XOR* all vertices of the hypercube with some fixed bitmask. Thus, we can assume $X = 0$. It's also clear that the order of the bits doesn't matter at all. Hence, the number of walks from 0 to Y depends only on the bitcount of Y .

Claim 4 shows that it's enough to calculate the first row of the matrix H^K . Depending on the exact implementation, it can pass the first five subtasks, or even pass the whole problem. (Ask Dorijan Lendvaj for the XOR-convolution solution of quadratic complexity that runs faster than the official solution.)

The official solution calculates the numbers of walks starting in $X = 0$ in a smarter way. It's enough to calculate, for every $0 \leq r \leq 10$, the number of walks starting from bitcount 0 and ending in bitcount r .



The number of ways in which we can get from one bitcount $0 \leq r \leq 10$ to another is given by the following 11×11 matrix:

$$C = \begin{bmatrix} 0 & 10 & 0 & 0 & \dots & 0 & 0 & 0 \\ 1 & 0 & 9 & 0 & \dots & 0 & 0 & 0 \\ 0 & 2 & 0 & 8 & \dots & 0 & 0 & 0 \\ \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots \\ 0 & 0 & 0 & 0 & \dots & 9 & 0 & 1 \\ 0 & 0 & 0 & 0 & \dots & 0 & 10 & 0 \end{bmatrix}$$

By raising the matrix C to a suitable power, we can get the number of walks of length K from bitcount 0 to each bitcount $0 \leq r \leq 10$. To get the actual number of walks in the hypercube, we just need to divide by a suitable binomial coefficient, due to symmetry. For implementation details, see the official source codes.

There is an even faster solution, which uses *exponential generating functions*. The number of walks of length K from the bitmask 0 to some mask with $10 - r$ bits equals the coefficient next to $\frac{x^K}{K!}$ of the following expression:

$$\left(\sum_{i=0}^{\infty} \frac{x^{2i}}{(2i)!} \right)^r \left(\sum_{i=0}^{\infty} \frac{x^{2i+1}}{(2i+1)!} \right)^{10-r} = \left(\frac{e^x + e^{-x}}{2} \right)^r \left(\frac{e^x - e^{-x}}{2} \right)^{10-r}.$$

By expanding the expression carefully, we get a solution of the complexity $O((5 \cdot M)^2 + (5 \cdot M) \log K)$, that is, entries of the $n \times n$ hypercube matrix raised to some power K is possible in $O(\log n \log K)$ time.

For similar ideas, look into Herbert Wilf's free book *generatingfunctionology*.



Task: Zagrade

Prepared by: Paula Vidas

Necessary skills: stack, parentheses, ad hoc

We first describe the solution for the case when the whole password is a valid sequence. In the first subtask we have $Q = \frac{N^2}{4}$, so we can query every even length interval (note that it makes no sense to query odd length intervals). One possible solution is the following: we ask for the first two characters, first four, and so on until we get a positive answer. We then know the position of the close parenthesis which is paired up with the first open parenthesis. Now we can recursively solve the same task for the interval between these parentheses, and for the interval that is on the right of the close parenthesis.

In the third subtask, we can ask $Q = N - 1$ queries. We will use a stack, which is empty at the beginning. We traverse the positions in order. If the stack is empty, push the current position on the stack. Otherwise, ask the query for the interval between the position on the top of the stack and the current position. If the answer is positive, those parentheses are paired up (left is open and right is close), and we pop the stack. If the answer is negative, we push the current position on the stack. In the end, the stack will be empty.

What if the whole password is not a valid sequence? The algorithm is the same, but the stack doesn't have to be empty in the end. First half of the remaining positions must have a close parenthesis, and the second half an open parenthesis. We leave the proof of this fact as exercise.