



# Deep Learning 1

2025-2026 – Pascal Mettes

## Lecture 12

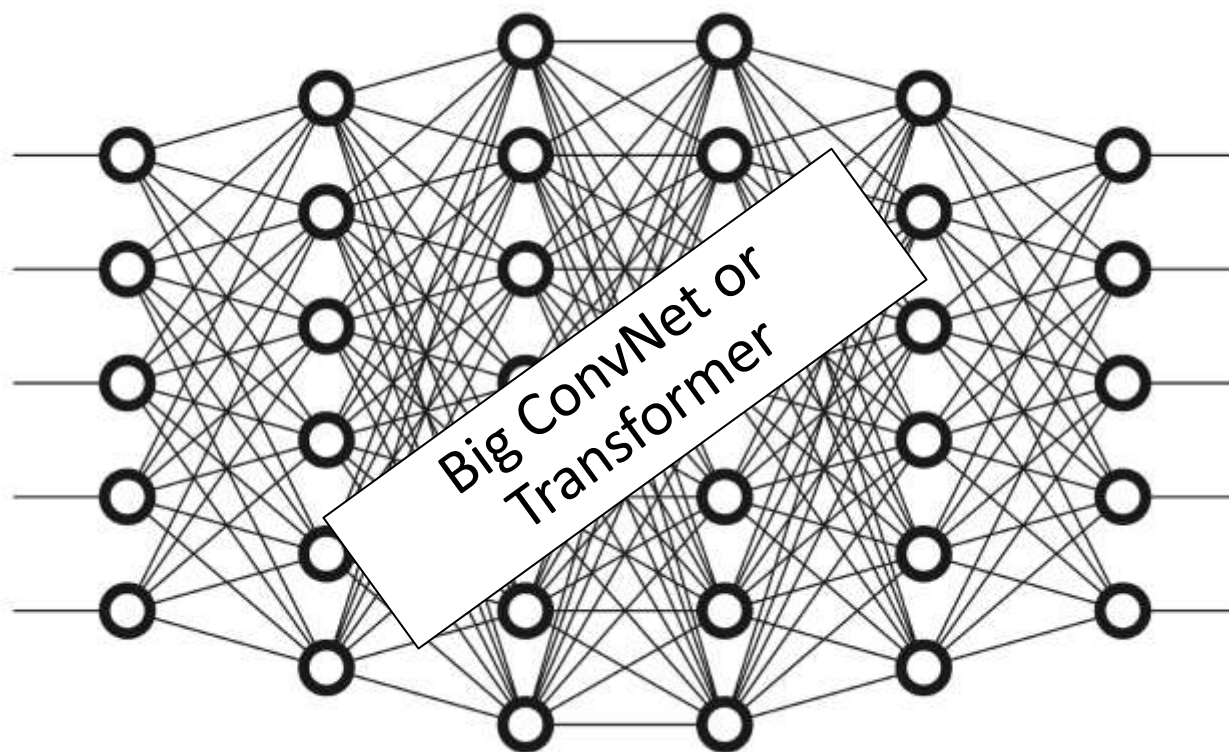
*Non-Euclidean deep learning*

# Previous lecture

Lecture	Title
1	Intro and history of deep learning
3	Deep learning optimization I
5	Convolutional deep learning
7	Graph deep learning
9	Multi-modal deep learning
11	What doesn't work in deep learning
13	Q&A

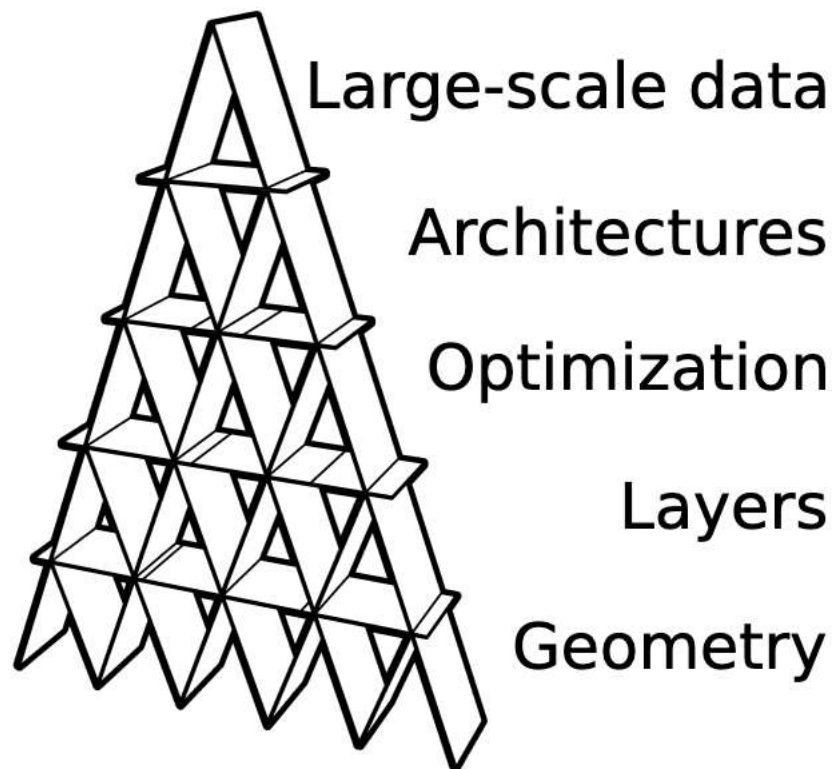
Lecture	Title
2	AutoDiff
4	Deep learning optimization II
6	Attention-based deep learning
8	From supervised to unsupervised deep learning
10	Generative deep learning
12	Non-Euclidean deep learning
14	Deep learning for videos

# Canonical deep learning



Person with dog

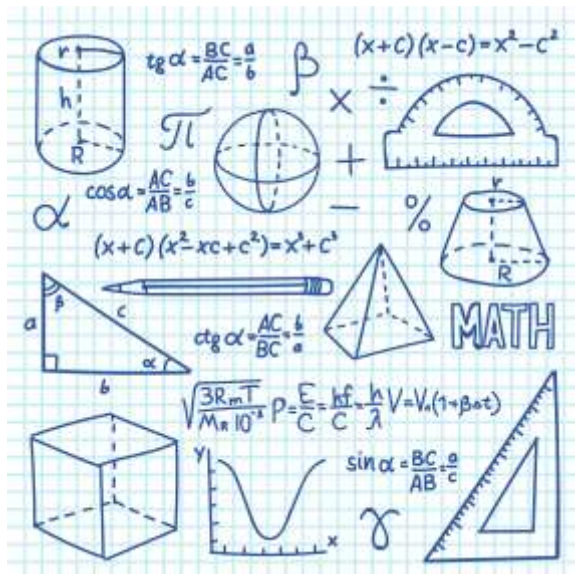
# House of cards in deep learning



Our default choice of geometry in deep learning is Euclidean, but should it be?

# Non-Euclidean geometry

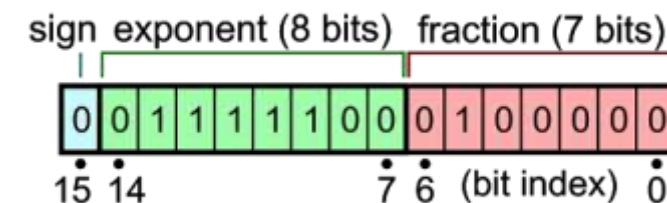
# We have a Euclidean bias in deep learning



Our school curricula  
are Euclidean



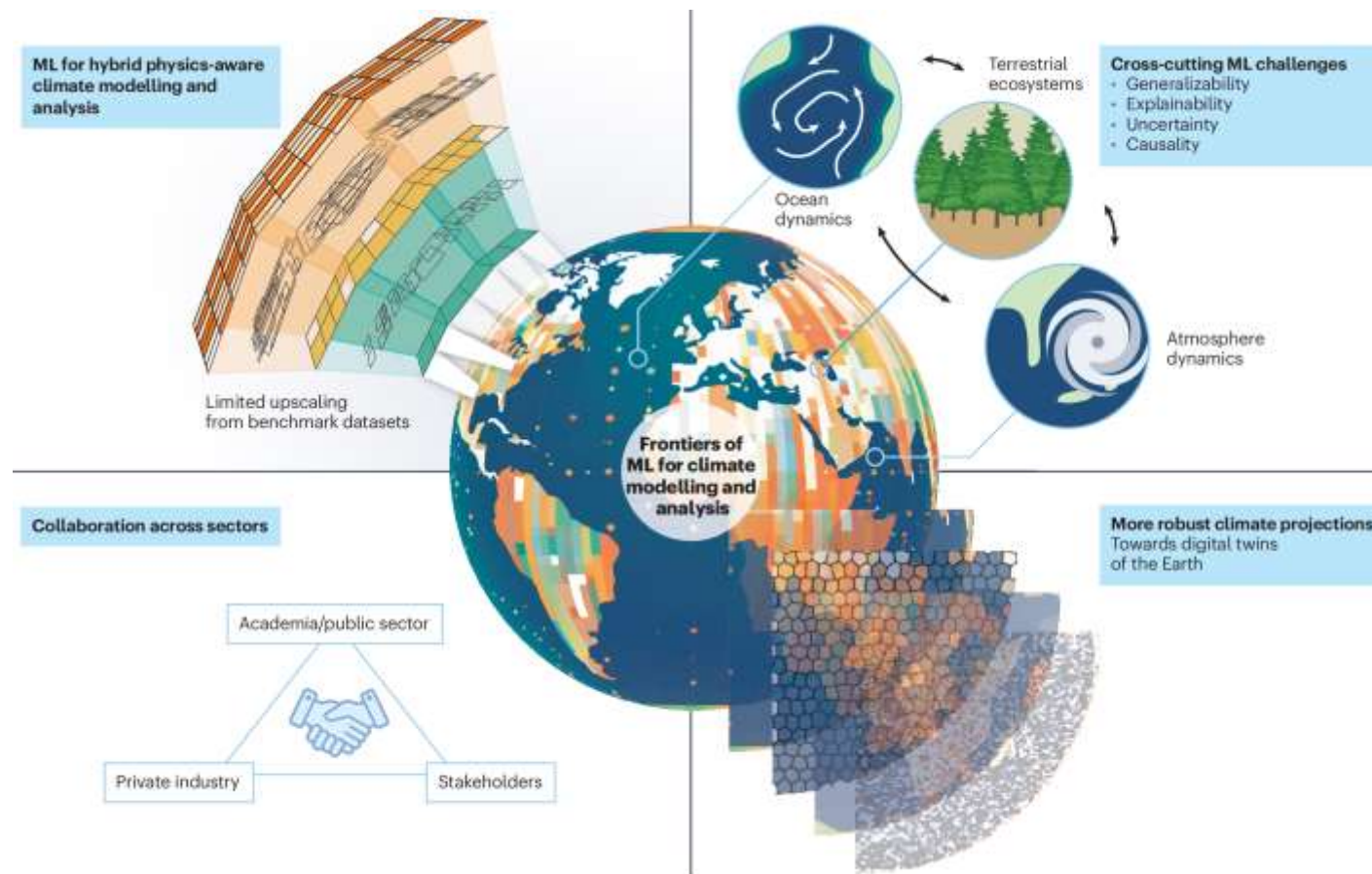
Our deep learning tools  
are Euclidean



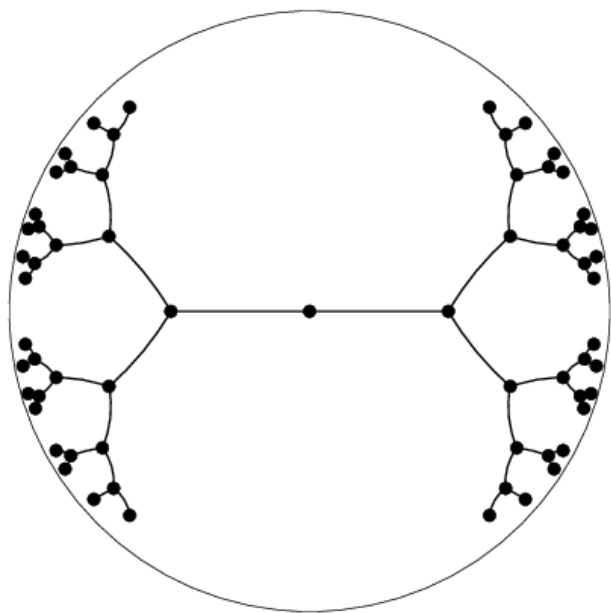
Our computers are built  
for Euclidean space



# But is Euclidean always the answer?



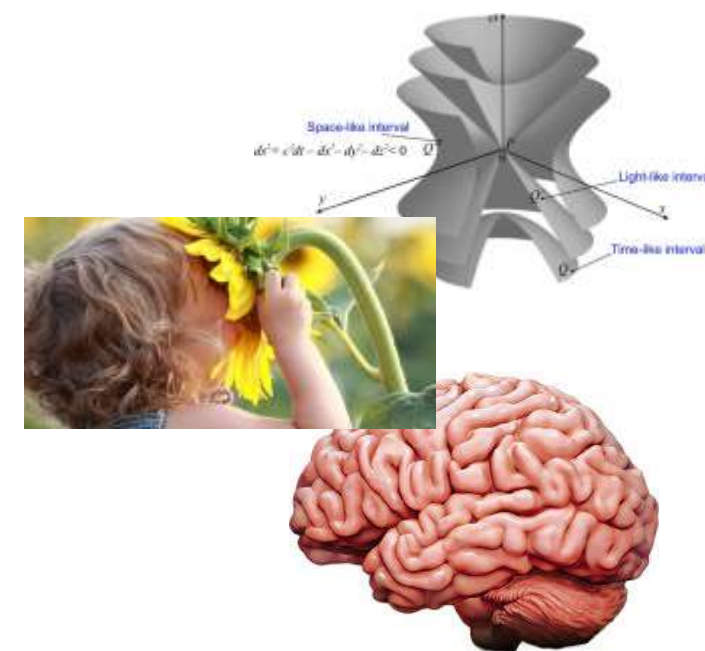
# But is Euclidean always the answer?



Euclidean is not hierarchical



Euclidean is not compact



The world is not always Euclidean



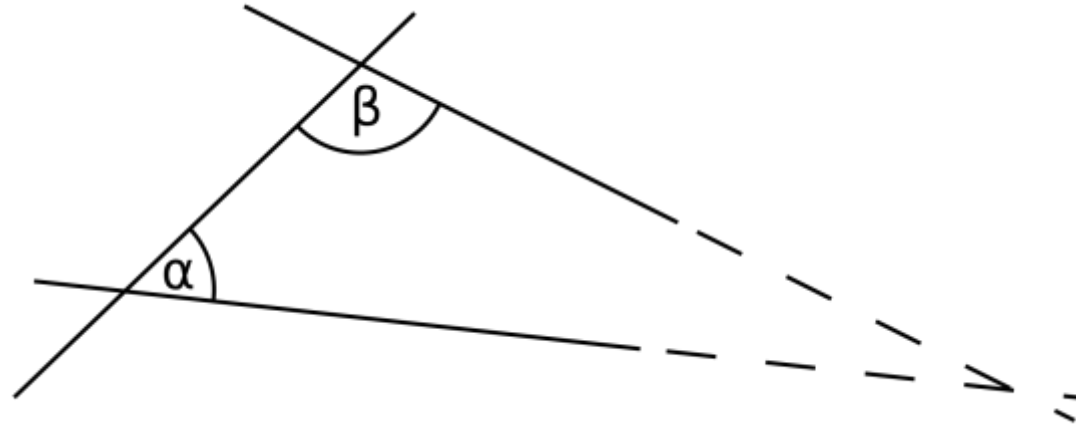
# Origins of non-Euclidean geometry

Euclid's 5 postulates:

1. *A straight-line segment can be drawn joining any two points.*
2. *Any straight-line segment can be extended indefinitely in a straight line.*
3. *Given any straight lines segment, a circle can be drawn having the segment as radius and one endpoint as center.*
4. *All Right Angles are congruent.*
5. *If two lines are drawn which intersect a third in such a way that the sum of the inner angles on one side is less than two Right Angles, then the two lines inevitably must intersect each other on that side if extended far enough. This postulate is equivalent to what is known as the Parallel Postulate.*

# Origins of non-Euclidean geometry

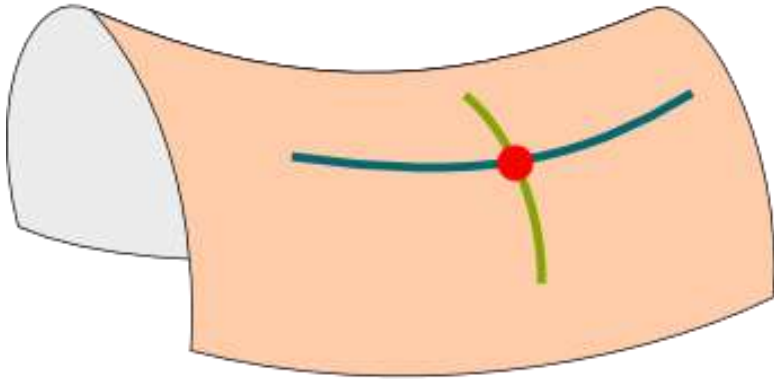
Euclid's 5th postulate:



Did Euclid make a mistake by making it a postulate? Shouldn't it be a theorem?

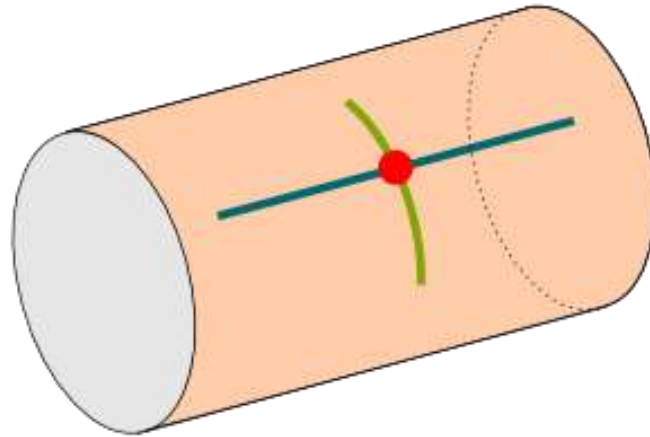
# Curving space

Extremal directions curve  
in opposite directions



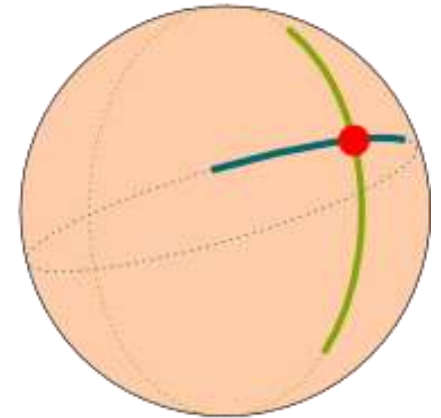
*Negative Curvature*

One extremal direction  
has zero curvature



*Zero Curvature*

Extremal directions curve  
in the same directions



*Positive Curvature*

# Hyperspherical deep learning

# About spherical deep learning

Many real-world problems have data that lie on a sphere.

*climate/weather modelling, world-wide patterns, 360 degree cameras, ...*

Even in standard neural networks, we often rely on spherical operations.

*Cosine similarity!*

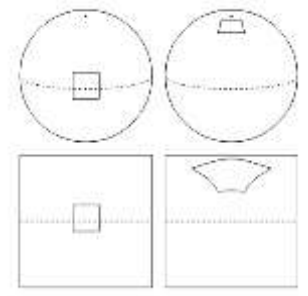
*L2 data normalization*

*Classifiers*

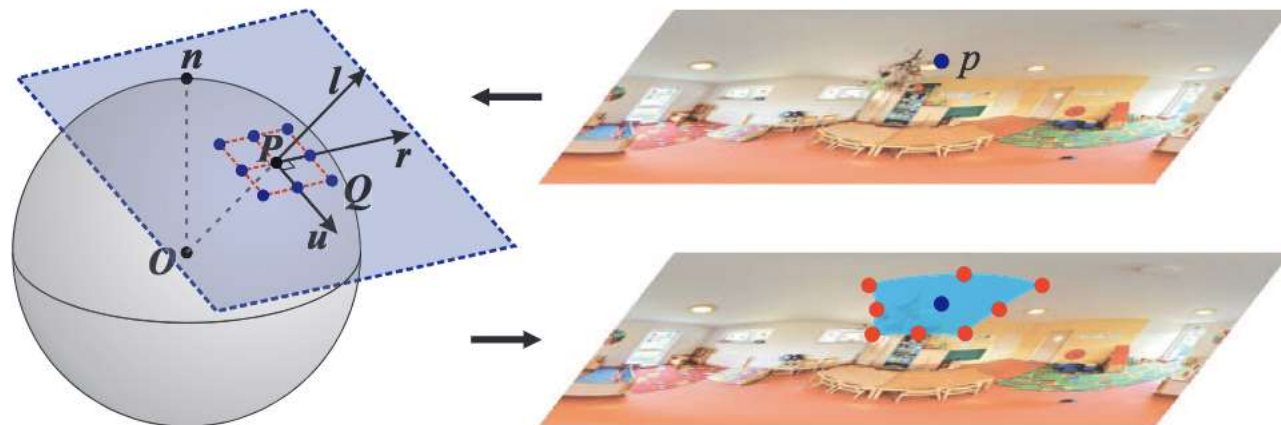
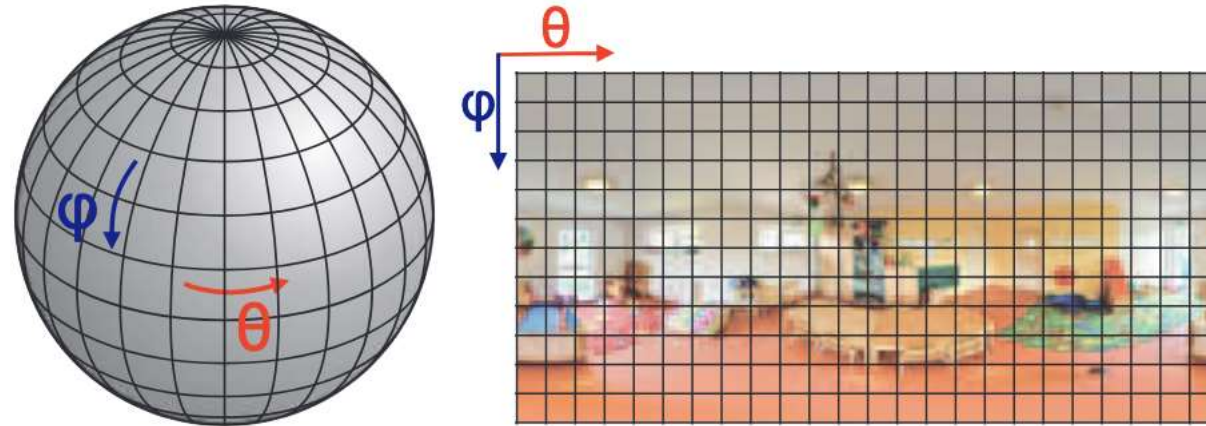
In standard networks, a spherical perspective can bring new insights.



# Deep learning on spherical inputs



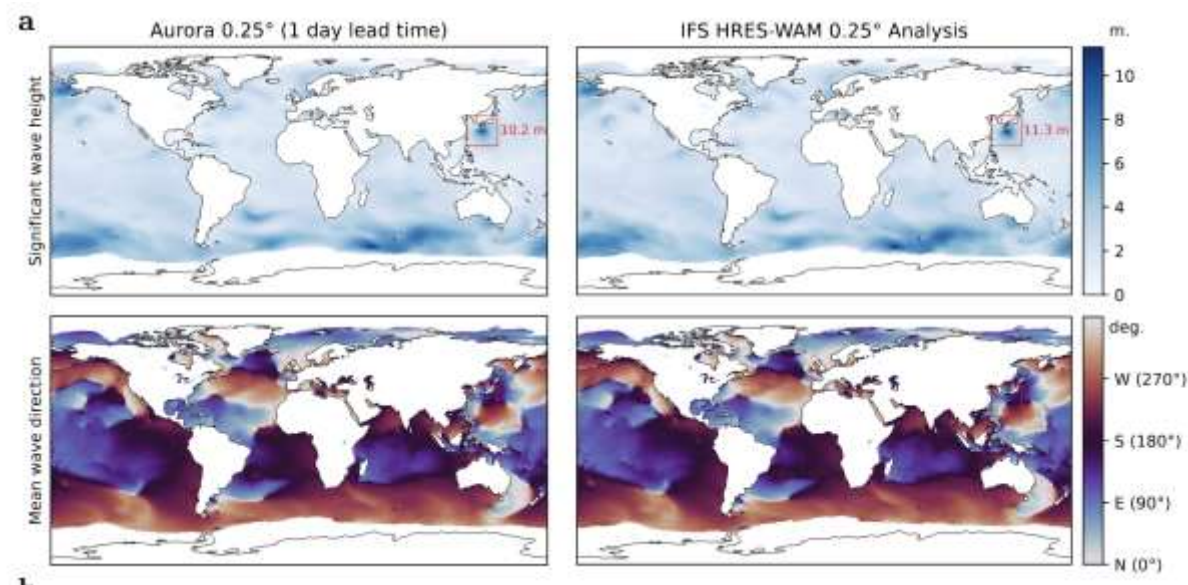
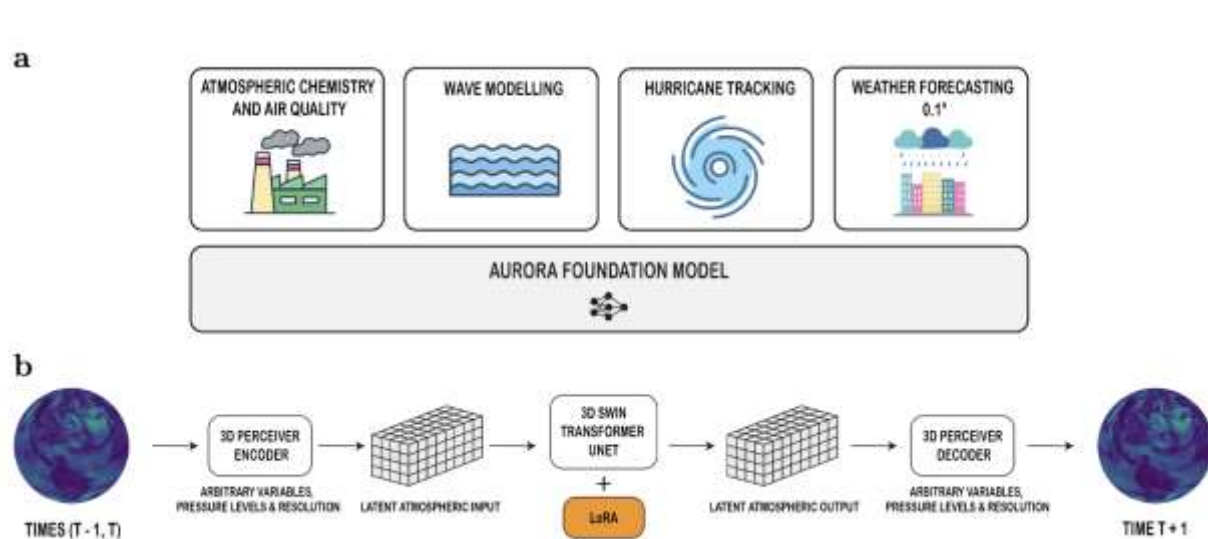
Cohen et al. (2018)



Zhao et al. (2018)



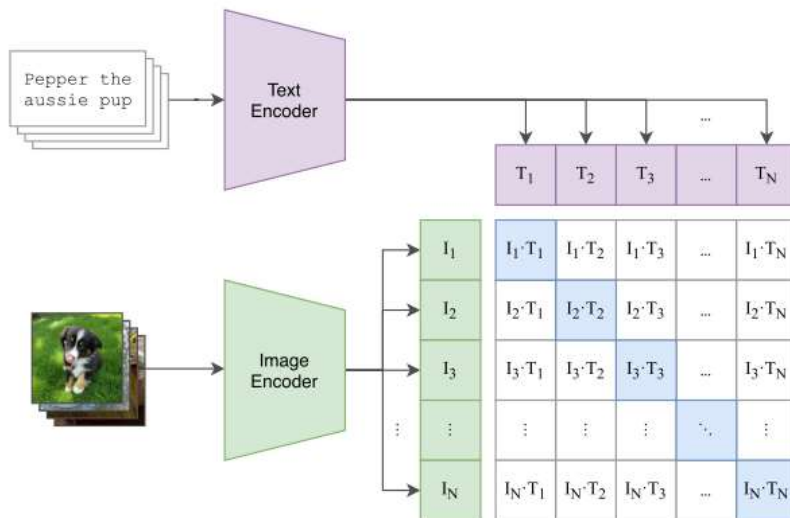
# Yet spherical distortion can also be ignored



# Spherical losses are everywhere in deep learning

“On the Surprising Behavior of Distance Metrics in High Dimensional Space” – Aggarwal et al. (2001)

“What is the nearest neighbor in high-dimensional spaces?” – Hinneburg et al. (2000)



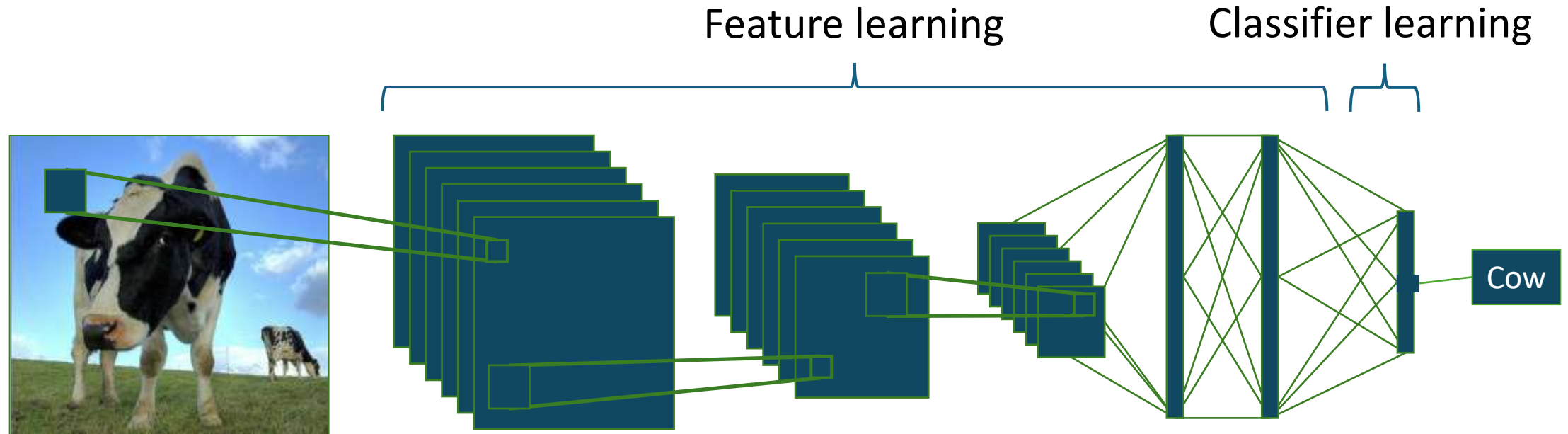
```
# extract feature representations of each modality
I_f = image_encoder(I) #[n, d_i]
T_f = text_encoder(T)  #[n, d_t]
```

```
# joint multimodal embedding [n, d_e]
I_e = l2_normalize(np.dot(I_f, W_i), axis=1)
T_e = l2_normalize(np.dot(T_f, W_t), axis=1)
```

```
# scaled pairwise cosine similarities [n, n]
logits = np.dot(I_e, T_e.T) * np.exp(t)
```

```
# symmetric loss function
labels = np.arange(n)
loss_i = cross_entropy_loss(logits, labels, axis=0)
loss_t = cross_entropy_loss(logits, labels, axis=1)
loss = (loss_i + loss_t)/2
```

# Classifiers in deep networks are spherical



Recall this decoupling from before.

If we think of classifiers as angularly separated, what makes an optimal classifier?

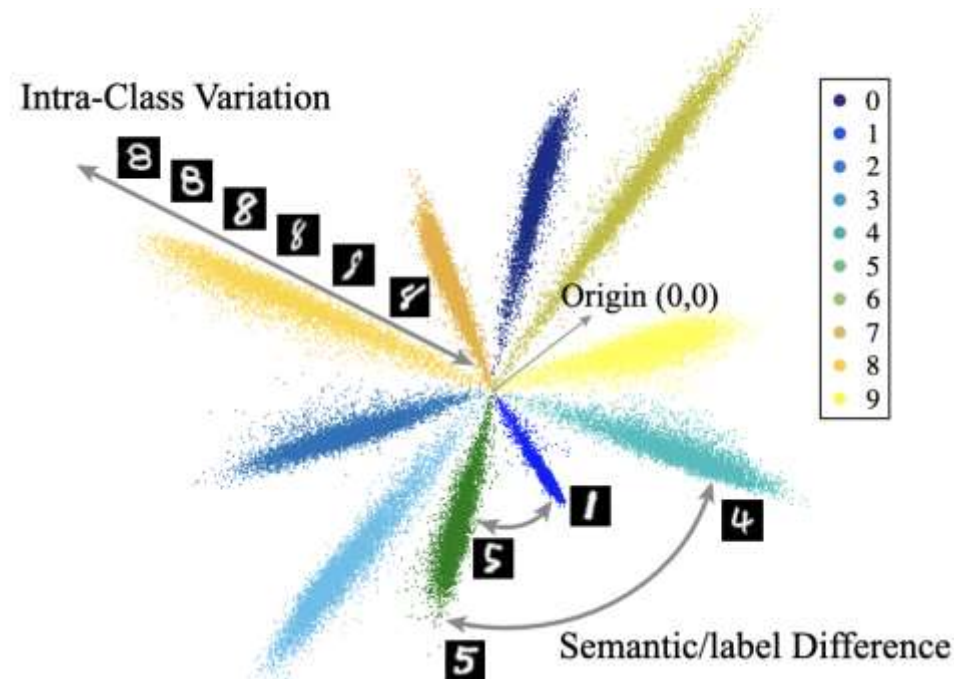


# Decoupled Networks – Liu et al. (2018)

Each class-specific classifier is a vector in the last layer of the network.

Similarity to sample is given by the dot-product.

Hence: high similarity of classifier and sample point in the same direction!





# Maximum Class Separation – Kasarla et al. (2022)

If classes are separated by angles, there is a theoretical optimal last layer.

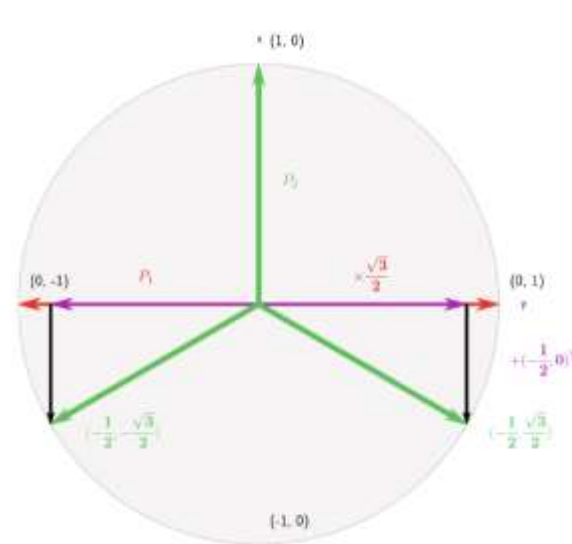
Separate all classes uniformly on the hypersphere.

General problem known as Tammes problem.

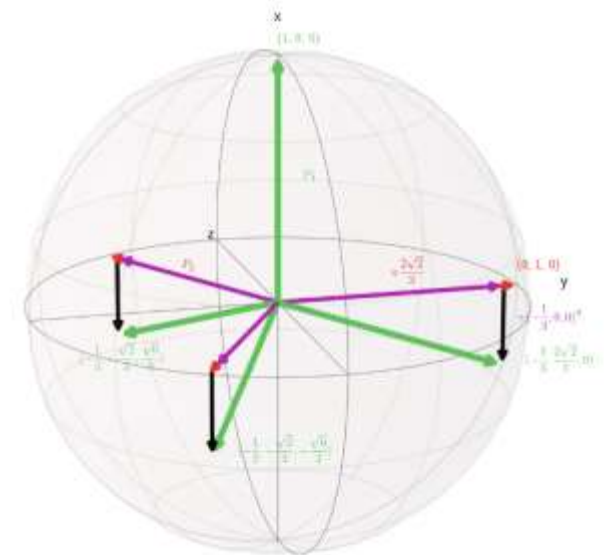
Specifically, for N classes in N-1 space, there is a solution:

$$P_1 = \begin{pmatrix} 1 & -1 \end{pmatrix} \in \mathbb{R}^{1 \times 2}$$

$$P_k = \begin{pmatrix} 1 & -\frac{1}{k} \mathbf{1}^T \\ \mathbf{0} & \sqrt{1 - \frac{1}{k^2} P_{k-1}} \end{pmatrix} \in \mathbb{R}^{k \times (k+1)}$$

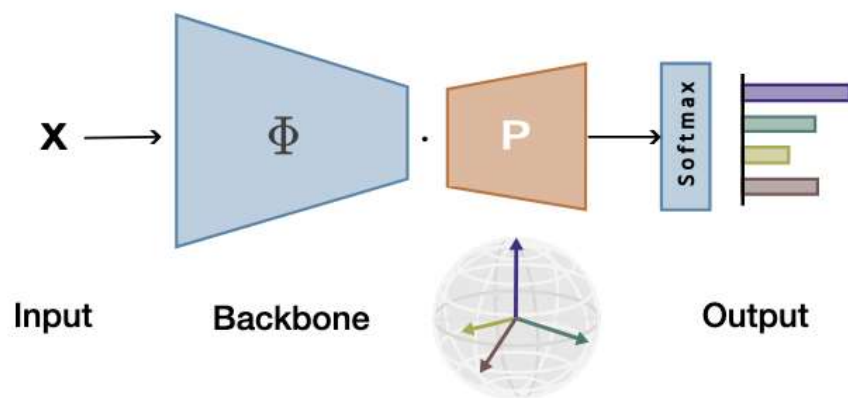


(a) Recursive update from 2 to 3 classes.



(b) Recursive update from 3 to 4 classes.

# Maximum Class Separation – Kasarla et al. (2022)



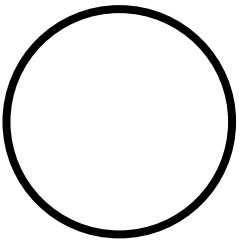
	Resnet-50				Resnet-152			
	top 1		top 5		top 1		top 5	
	Base	+ Ours	Base	+ Ours	Base	+ Ours	Base	+ Ours
Imagenet	73.2	<b>74.8</b>	92.4	<b>94.9</b>	77.9	<b>78.5</b>	94.3	<b>95.1</b>
Imagenet-LT	43.8	<b>47.3</b>	70.4	<b>73.6</b>	48.3	<b>49.7</b>	73.9	<b>74.8</b>

	Imbalance factor				Imbalance factor		
	0.1	0.02	0.01		0.1	0.02	0.01
LDAM-SGD	55.05	43.85	39.87	MiSLAS (stage 1)	58.36	44.69	40.29
+ This paper	<b>57.72</b>	<b>45.14</b>	<b>42.02</b>	+ This paper	<b>59.63</b>	<b>45.65</b>	<b>40.56</b>
	+2.67	+1.29	+2.20		+1.27	+0.96	+0.27
LDAM-DRW	57.45	47.56	42.37	MiSLAS (stage 2)	61.93	52.53	48.00
+ This paper	<b>58.37</b>	<b>48.02</b>	<b>43.19</b>	+ This paper	<b>63.52</b>	<b>53.36</b>	<b>48.42</b>
	+0.92	+0.46	+0.82		+1.59	+0.83	+0.42

	CIFAR-100					CIFAR-10				
	-	0.2	0.1	0.02	0.01	-	0.2	0.1	0.02	0.01
ConvNet	56.70	45.97	40.34	27.35	16.59	86.68	79.47	73.90	51.40	43.67
+ This paper	<b>57.05</b>	<b>46.59</b>	<b>40.44</b>	<b>28.27</b>	<b>18.40</b>	<b>86.76</b>	<b>79.63</b>	<b>75.88</b>	<b>55.25</b>	<b>48.05</b>
	+0.35	+0.62	+0.10	+0.92	+1.81	+0.08	+0.16	+1.98	+3.85	+4.38
ResNet-32	75.77	65.74	58.98	42.71	35.02	94.63	88.17	83.10	68.64	56.98
+ This paper	<b>76.54</b>	<b>66.01</b>	<b>60.54</b>	<b>45.12</b>	<b>38.85</b>	<b>95.09</b>	<b>91.42</b>	<b>88.16</b>	<b>77.02</b>	<b>69.70</b>
	+0.77	+0.27	+1.56	+2.41	+3.83	+0.46	+3.25	+5.06	+8.38	+12.72

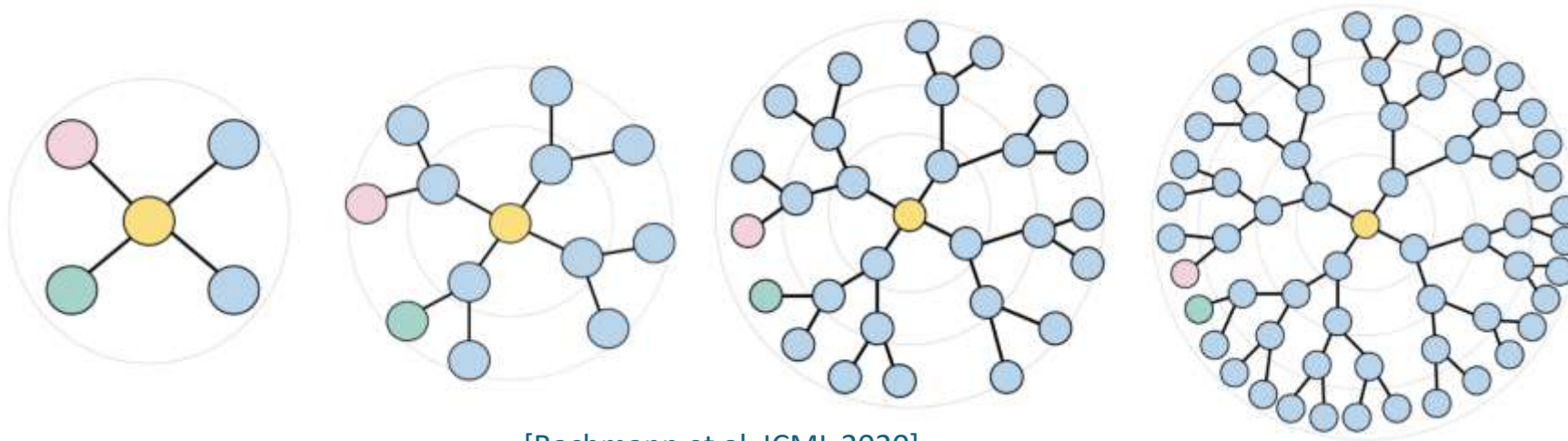
# Hyperbolic deep learning

# The geometry of hierarchies



$$v = \pi r^2$$

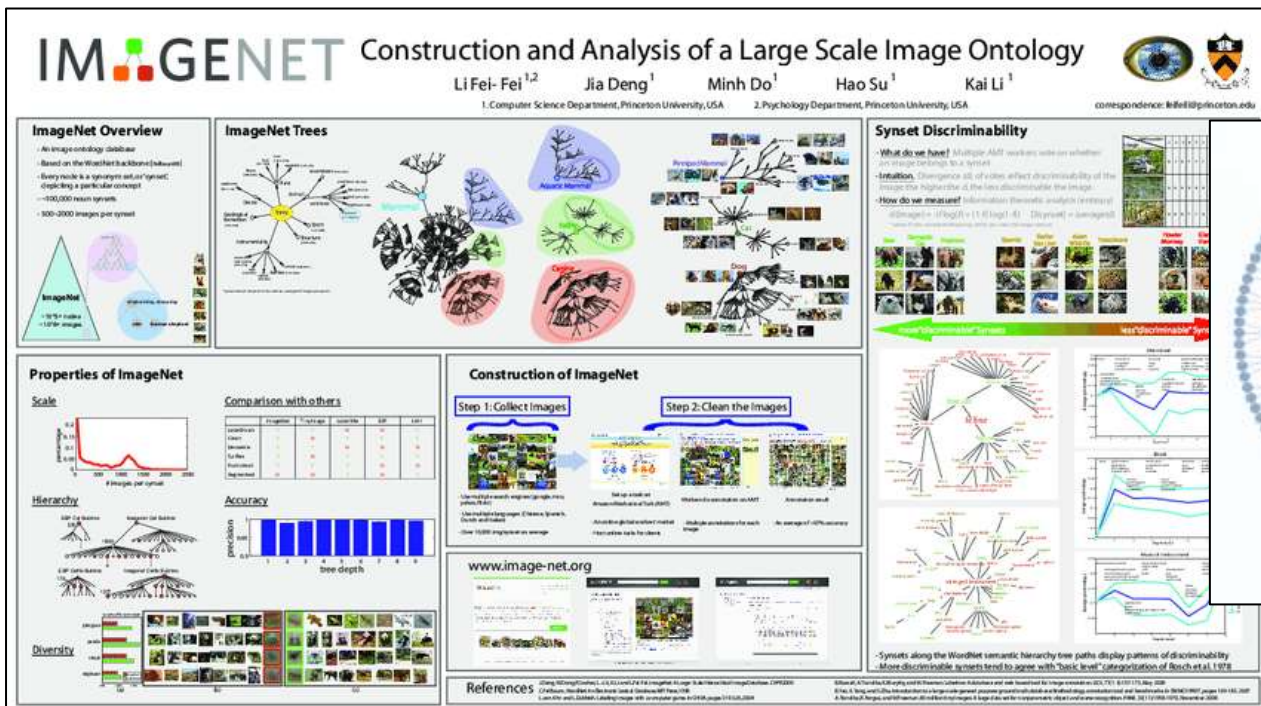
Euclidean space and hierarchies are a mismatch: linear vs. exponential growth.



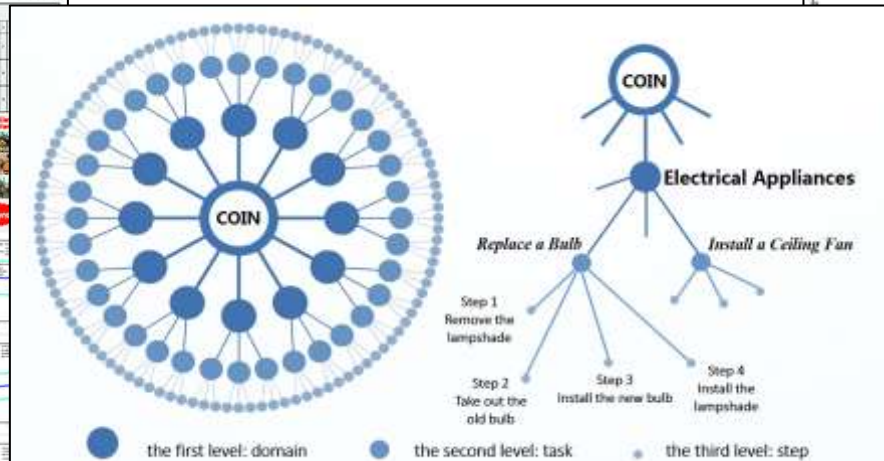
[Bachmann et al. ICML 2020]

What we need is a hierarchical geometry for representation learning!

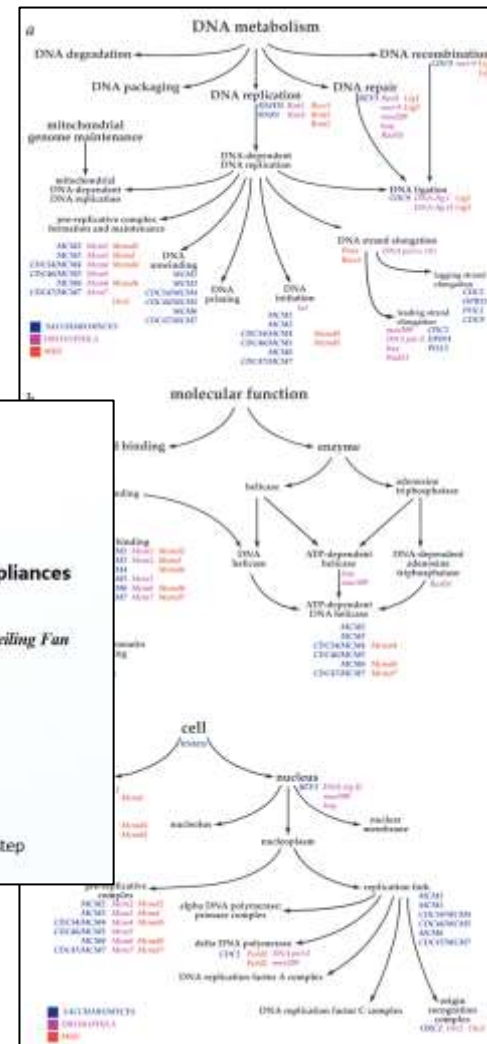
# The importance of hierarchies



[Li et al. 2009]



[Tang et al. CVPR 2019]

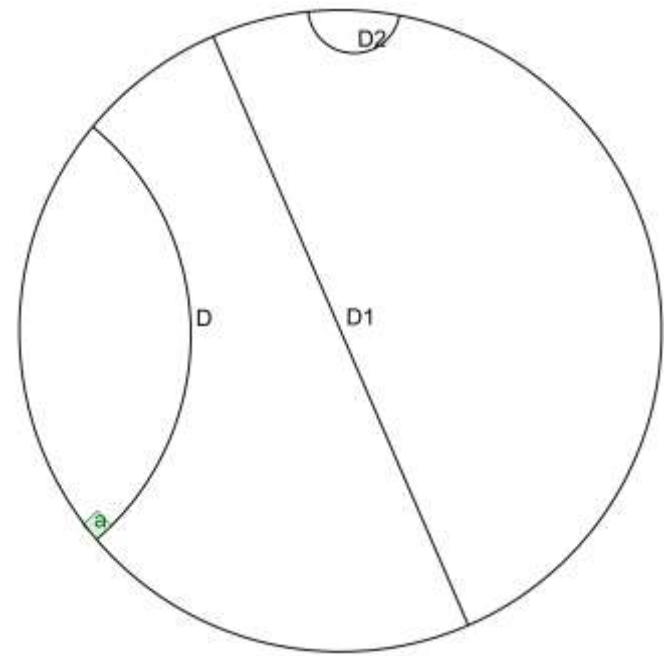
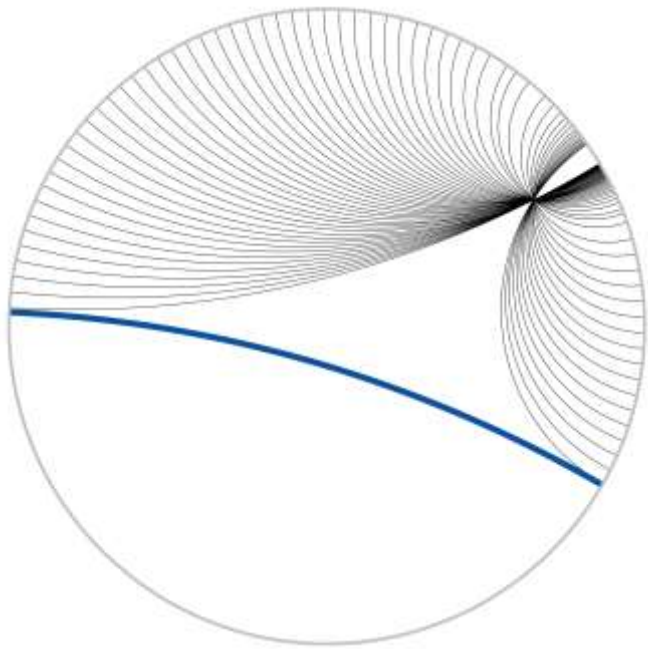


[Ashburner et al. Nature 2000]

Hierarchies allow us to look beyond samples and their individual labels.

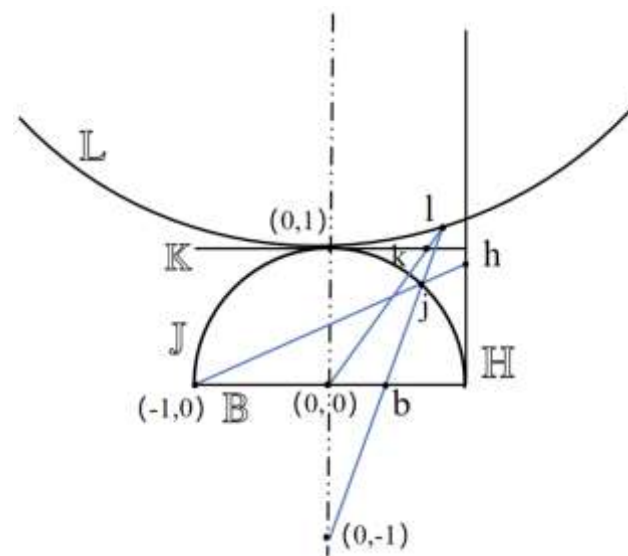
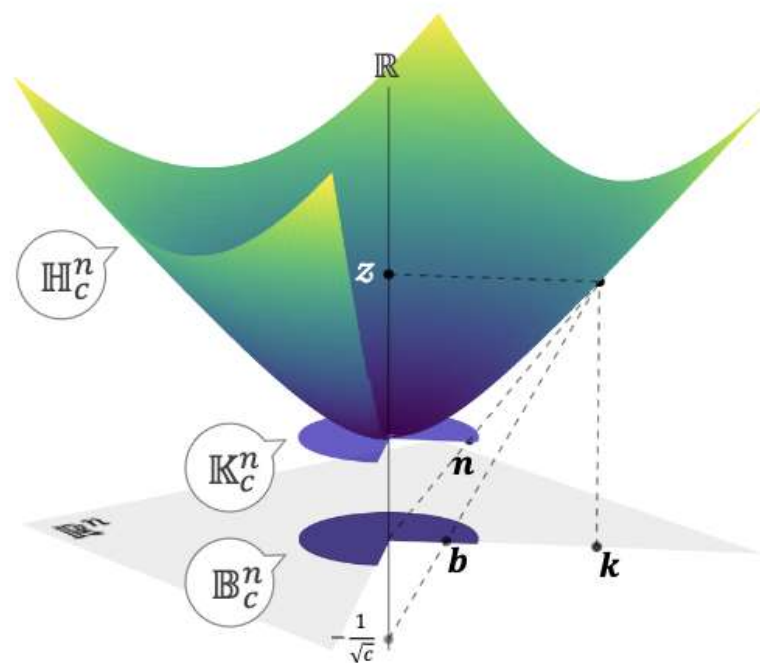


# Poincaré ball model



# Models of hyperbolic geometry

To perform numerical operations, we need to operate in a model of hyperbolic geometry.



Multiple isometric models exist, with different pros and cons for numerical complexity, stability, and visualization prowess.

# Numerical operation in Poincaré model

Points inside unit ball

Tensor metric

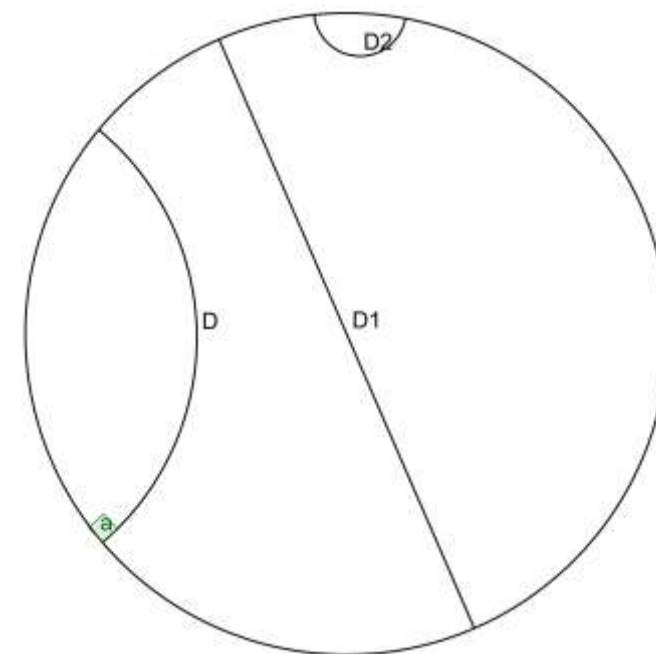
$$\mathbb{D}^n = \{x \in \mathbb{R}^n : \|x\| < 1\} \quad g_x^{\mathbb{D}} = \lambda_x^2 g^E, \quad \text{where } \lambda_x := \frac{2}{1 - \|x\|^2}$$

Distance between two points:

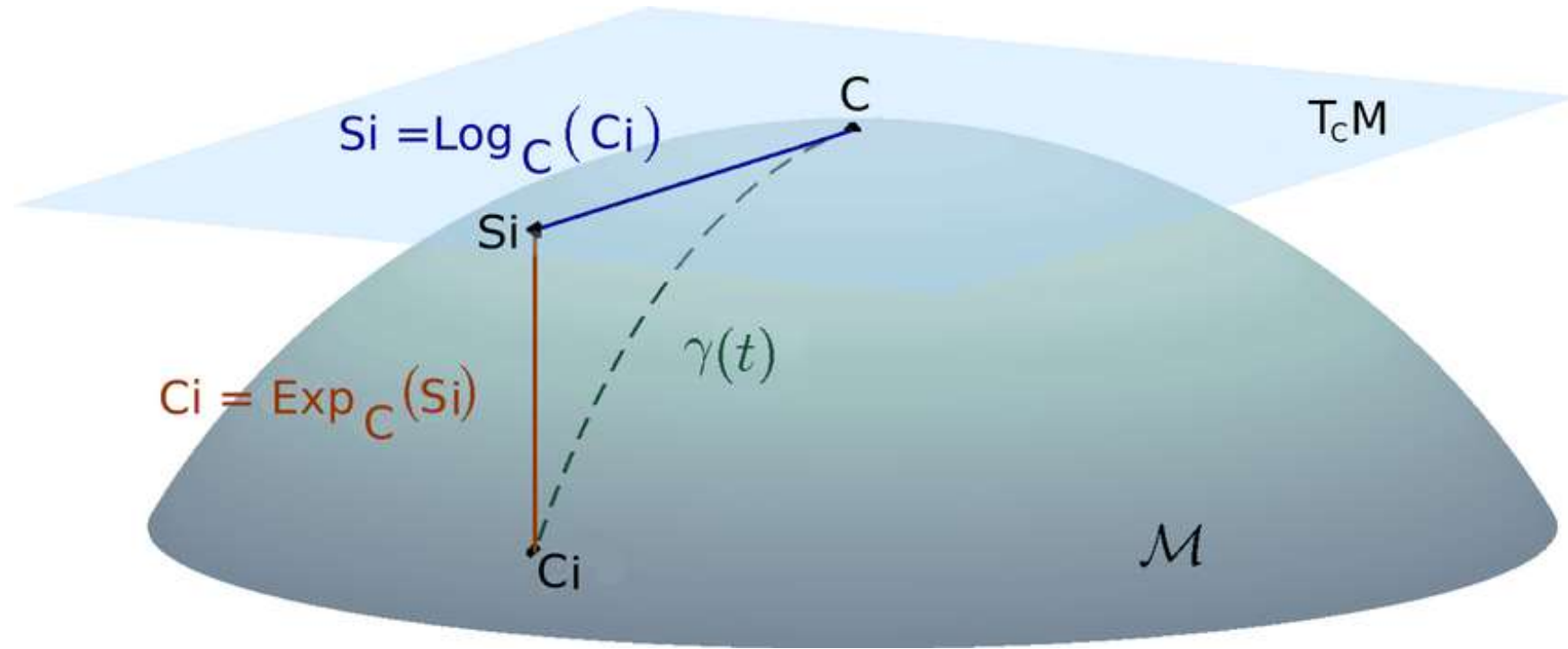
$$d_{\mathbb{D}}(x, y) = \cosh^{-1} \left( 1 + 2 \frac{\|x - y\|^2}{(1 - \|x\|^2)(1 - \|y\|^2)} \right)$$

Möbius addition:

$$x \oplus_c y := \frac{(1 + 2c\langle x, y \rangle + c\|y\|^2)x + (1 - c\|x\|^2)y}{1 + 2c\langle x, y \rangle + c^2\|x\|^2\|y\|^2},$$



# From tangent space to Poincaré ball (and back)



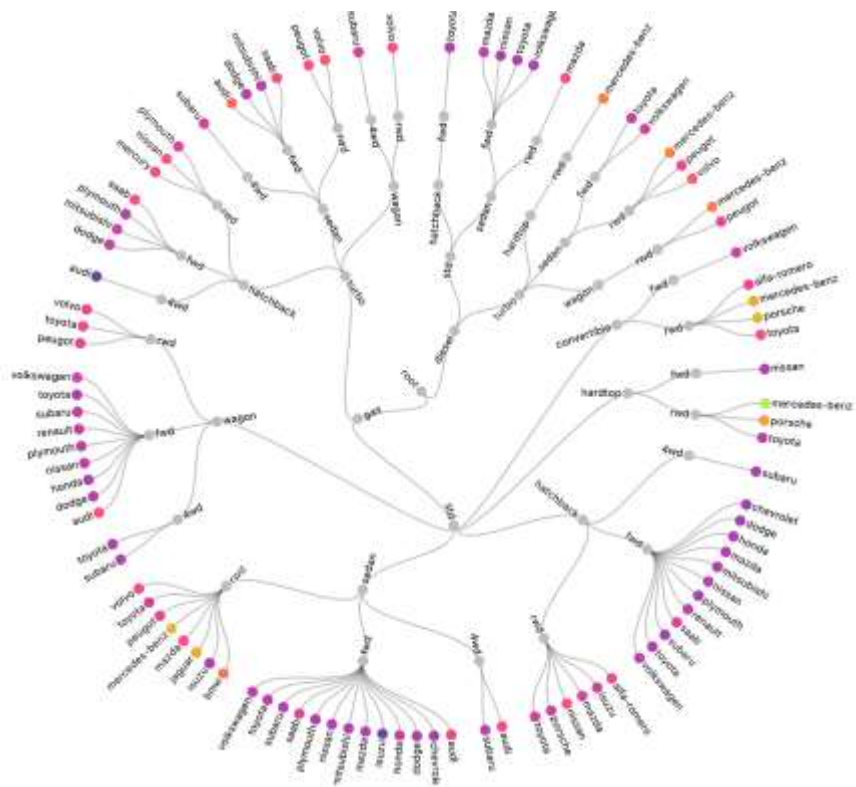
$$\exp_{\mathbf{0}}^c(v) = \tanh(\sqrt{c}\|v\|) \frac{v}{\sqrt{c}\|v\|}$$

$$\log_{\mathbf{0}}^c(y) = \tanh^{-1}(\sqrt{c}\|y\|) \frac{y}{\sqrt{c}\|y\|}$$

# First hyperbolic success: Poincaré Embeddings

[Nickel and Kiela. NeurIPS 2017]

Embed nodes as hyperbolic points and optimize with contrastive learning.



$$\mathcal{L}(\Theta) = \sum_{(u,v) \in \mathcal{D}} \log \frac{e^{-d(u,v)}}{\sum_{v' \in \mathcal{N}(u)} e^{-d(u,v')}} ,$$

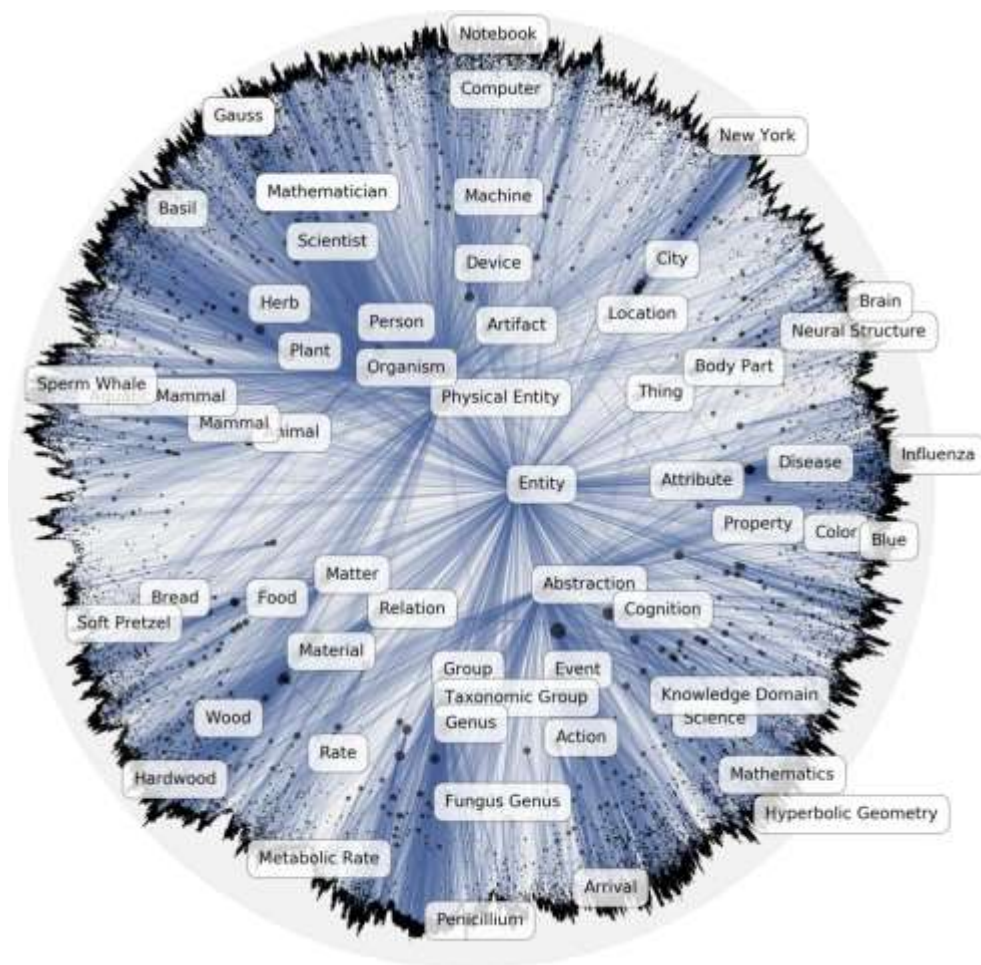
Parent-child links

Non parent-child links

Hyperbolic distance



# Poincaré Embeddings



			Dimensionality					
			5	10	20	50	100	200
WORDNET Reconstruction	Euclidean	Rank MAP	3542.3 0.024	2286.9 0.059	1685.9 0.087	1281.7 0.140	1187.3 0.162	1157.3 0.168
	Translational	Rank MAP	205.9 0.517	179.4 0.503	95.3 0.563	92.8 0.566	92.7 0.562	91.0 0.565
	Poincaré	Rank MAP	4.9 0.823	4.02 0.851	3.84 0.855	3.98 0.86	3.9 0.857	<b>3.83</b> <b>0.87</b>
WORDNET Link Pred.	Euclidean	Rank MAP	3311.1 0.024	2199.5 0.059	952.3 0.176	351.4 0.286	190.7 0.428	81.5 0.490
	Translational	Rank MAP	65.7 0.545	56.6 0.554	52.1 0.554	47.2 0.56	43.2 0.562	40.4 0.559
	Poincaré	Rank MAP	5.7 0.825	<b>4.3</b> 0.852	4.9 0.861	4.6 <b>0.863</b>	4.6 0.856	4.6 0.855

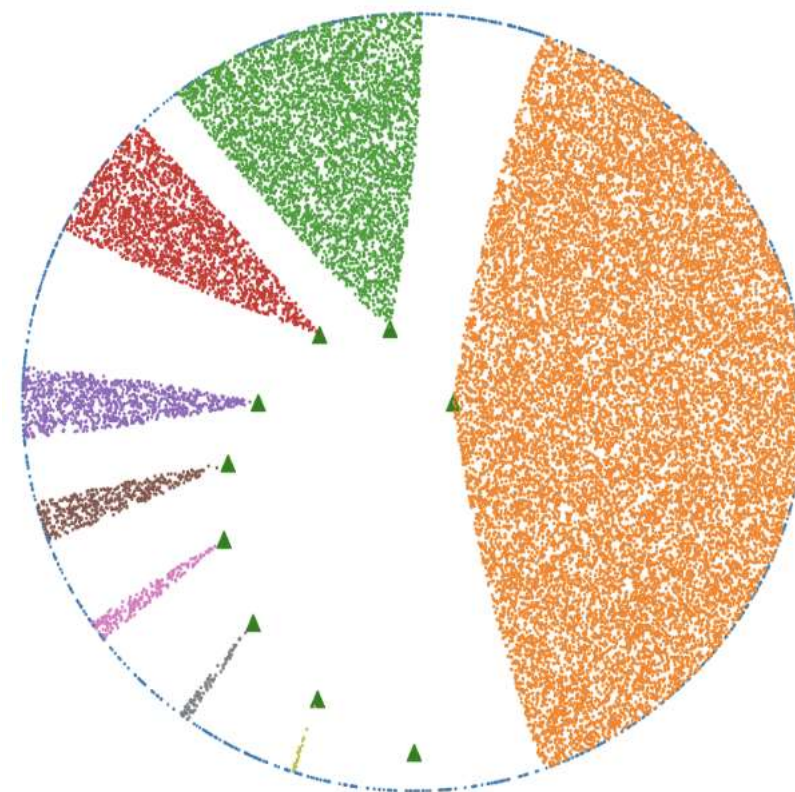
# Hyperbolic Entailment Cones

[Ganea et al. ICML 2018]

Pairwise contrastive learning has trouble enforcing hierarchical depth.  
They propose to view points as cones of entailment.

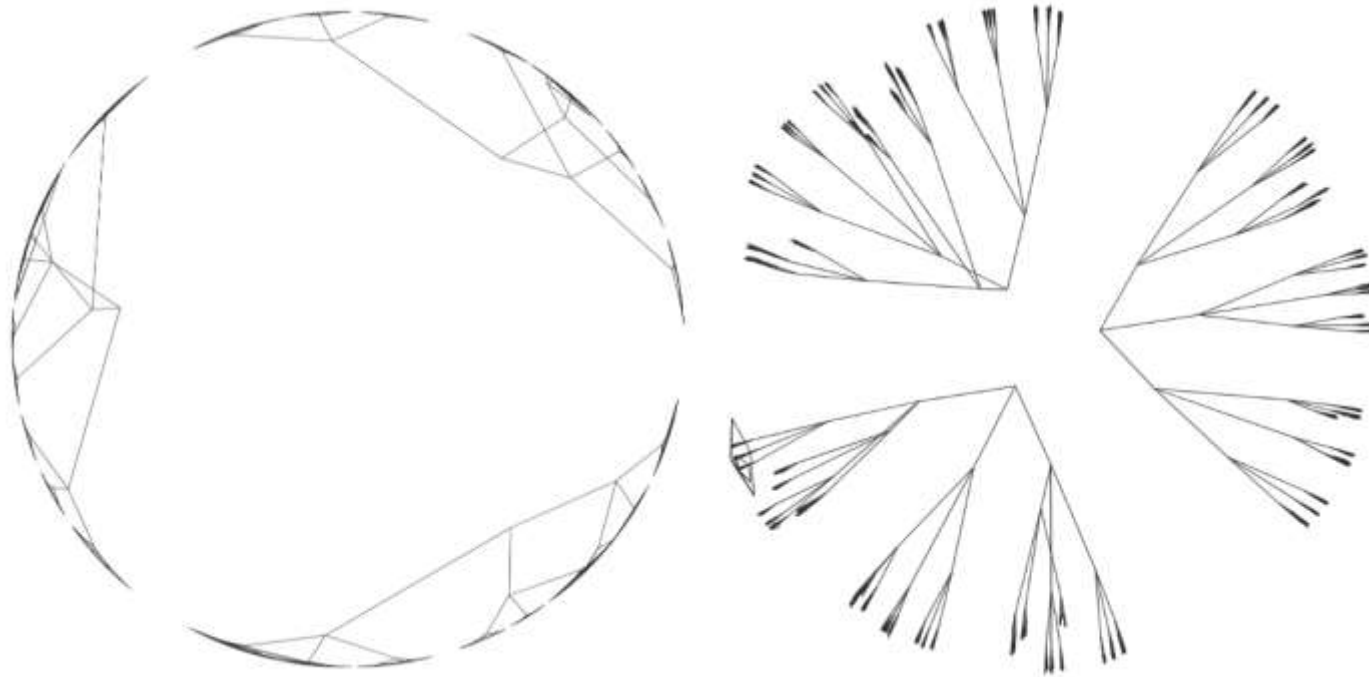
## Required properties:

1. Axial symmetry
2. Rotation invariance
3. Aperture of cone is continuous function
4. Nested angular cones preserve partial order



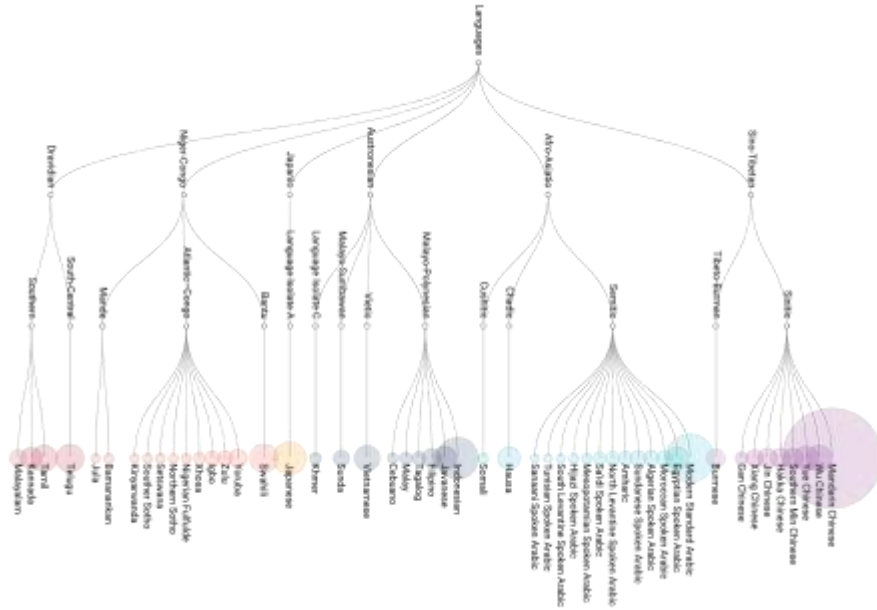
# Hyperbolic Entailment Cones

[Ganea et al. ICML 2018]



Poincaré Embeddings (left) vs Hyperbolic Entailment Cones (right)

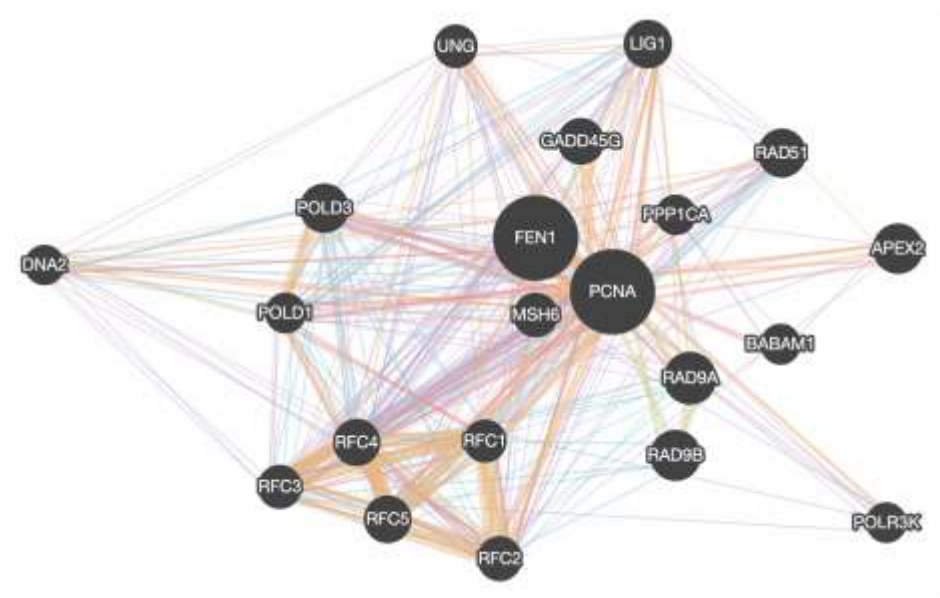
# From hierarchies to graphs



Nodes and edges

Embed to preserve edge distances

One layer



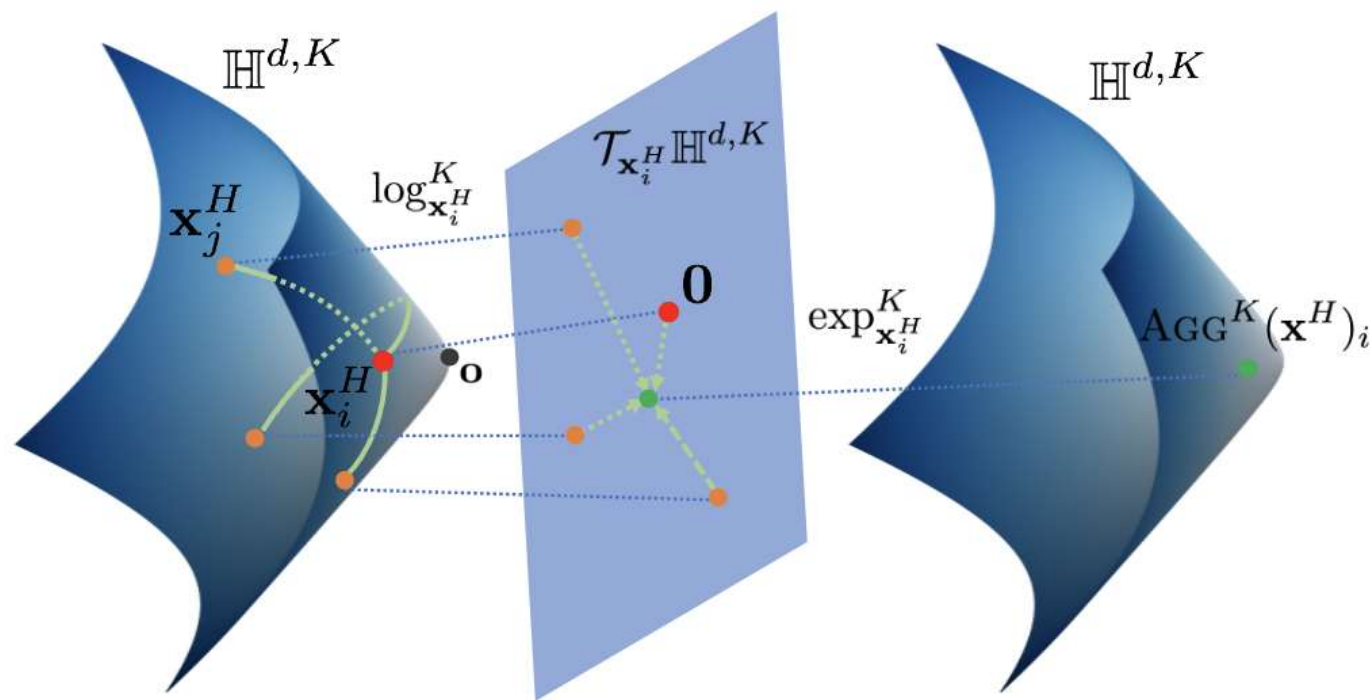
Nodes and edges

Embed for node/edge/graph inference

Multiple layers



# First generation hyperbolic graph networks



Project hyperbolic nodes to Euclidean space, do normal graph layer, project back.

[Chami et al., NeurIPS 2019, Liu et al., NeurIPS 2019]

# First generation hyperbolic graph networks

Standard graph layer

$$\mathbf{h}_u^{k+1} = \sigma \left( \sum_{v \in \mathcal{I}(u)} \tilde{\mathbf{A}}_{uv} \mathbf{W}^k \mathbf{h}_v^k \right)$$

$$\tilde{\mathbf{A}} = \mathbf{D}^{-\frac{1}{2}} (\mathbf{A} + \mathbf{I}) \mathbf{D}^{-\frac{1}{2}}$$

Normalized affinity matrix

Weights to learn

Current node embeddings

Hyperbolic graph layer

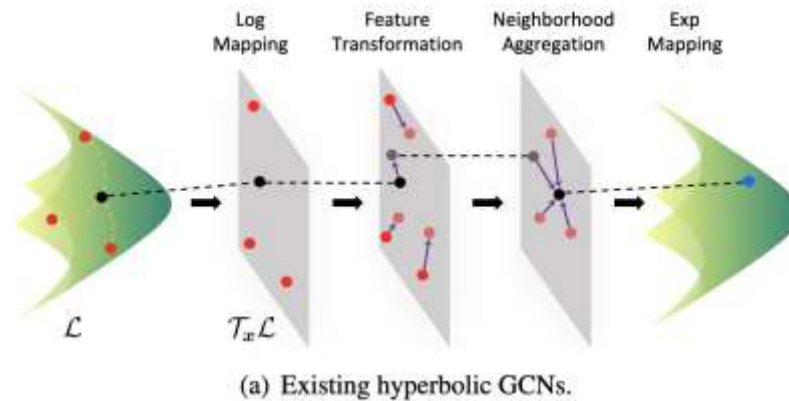
$$\mathbf{h}_u^{k+1} = \sigma \left( \exp_{\mathbf{x}'} \left( \sum_{v \in \mathcal{I}(u)} \tilde{\mathbf{A}}_{uv} \mathbf{W}^k \log_{\mathbf{x}'}(\mathbf{h}_v^k) \right) \right)$$

Projection steps

$$\exp_{\mathbf{x}}(\mathbf{v}) = \mathbf{x} + \mathbf{v} \quad \log_{\mathbf{x}}(\mathbf{y}) = \mathbf{y} - \mathbf{x}$$

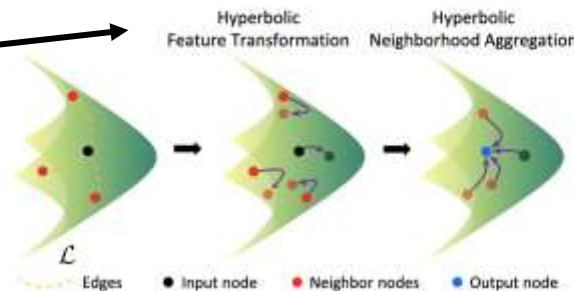
# Second generation hyperbolic graph networks

Perform transformations also in hyperbolic space.



Aggregation in Klein model.

Transformations in Lorentz model.

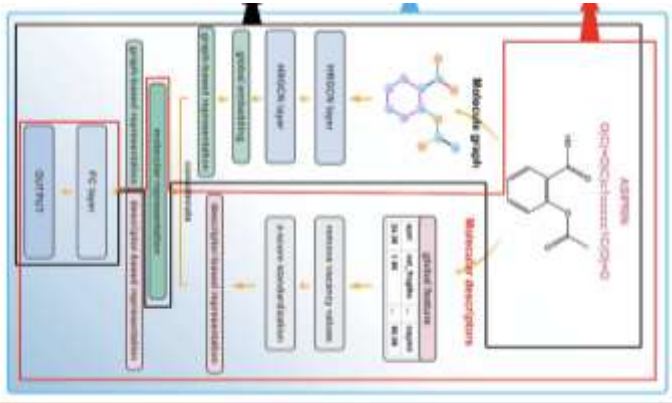


Non-linearities in Poincaré ball model.

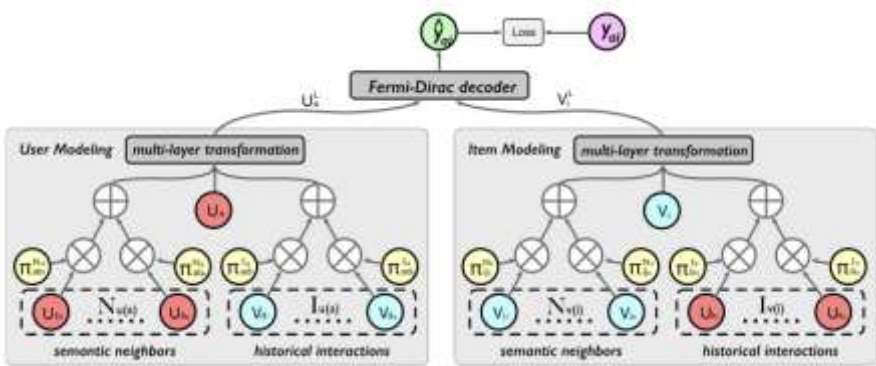
[Dai et al. CVPR 2021]

# Applications of hyperbolic graph networks

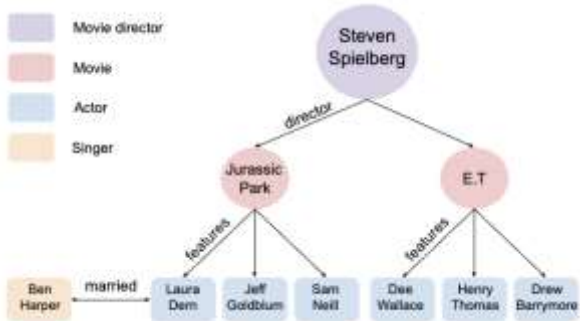
## Molecules



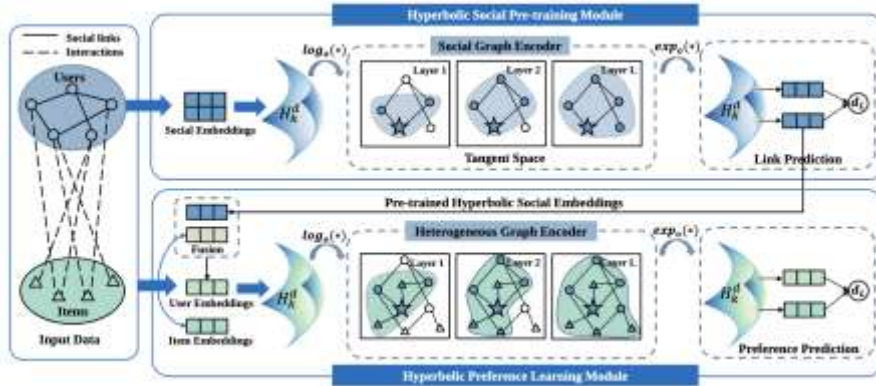
## Recommendation systems



## Knowledge graphs



## Social networks



[Wu et al. BiB 2021]

[Li et al. TKDE 2023]

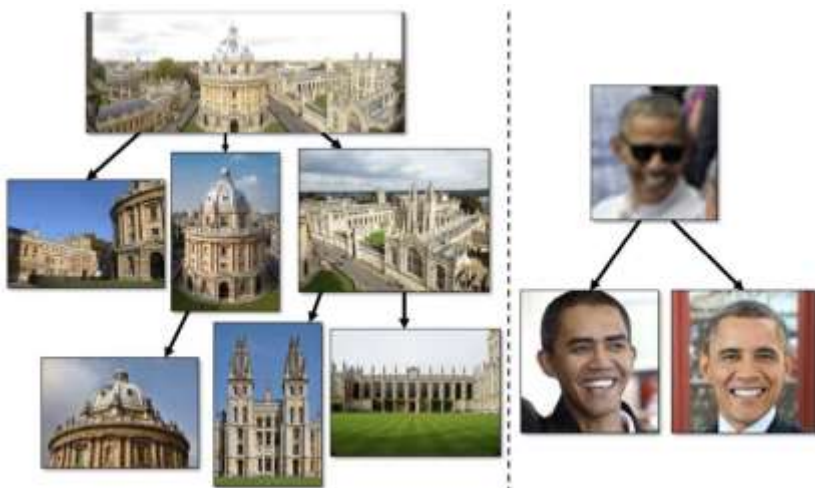
[Chami et al. 2020]

[Yang et al. TKDE 2023]

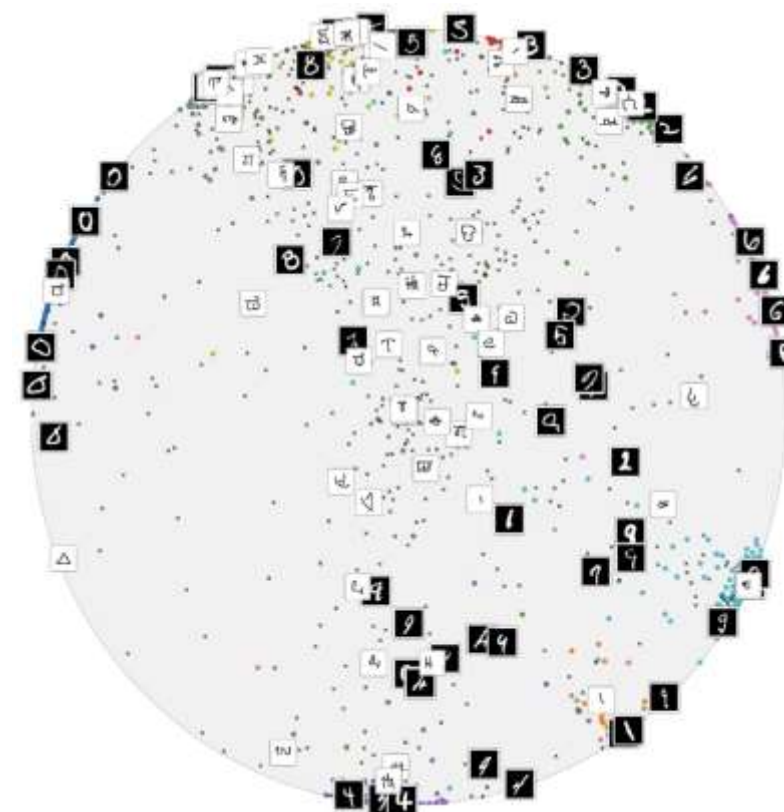


# Hyperbolic Image Embeddings

[Khrulkov et al. CVPR 2020]



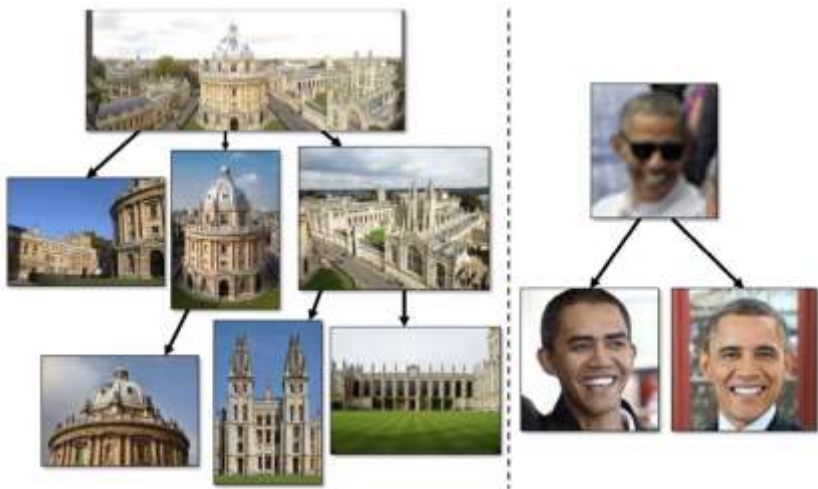
Encoder	Dataset			
	CIFAR10	CIFAR100	CUB	MiniImageNet
Inception v3 [49]	0.25	0.23	0.23	0.21
ResNet34 [14]	0.26	0.25	0.25	0.21
VGG19 [42]	0.23	0.22	0.23	0.17



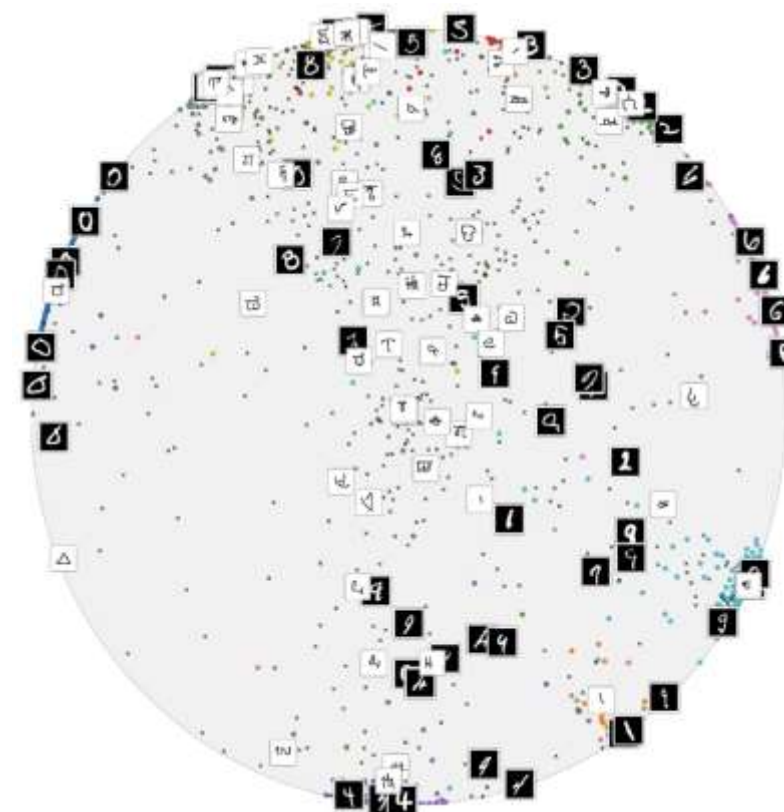
Images are naturally hierarchical, hyperbolic embeddings improve few-shot learning.

# Hyperbolic Image Embeddings

[Khrulkov et al. CVPR 2020]



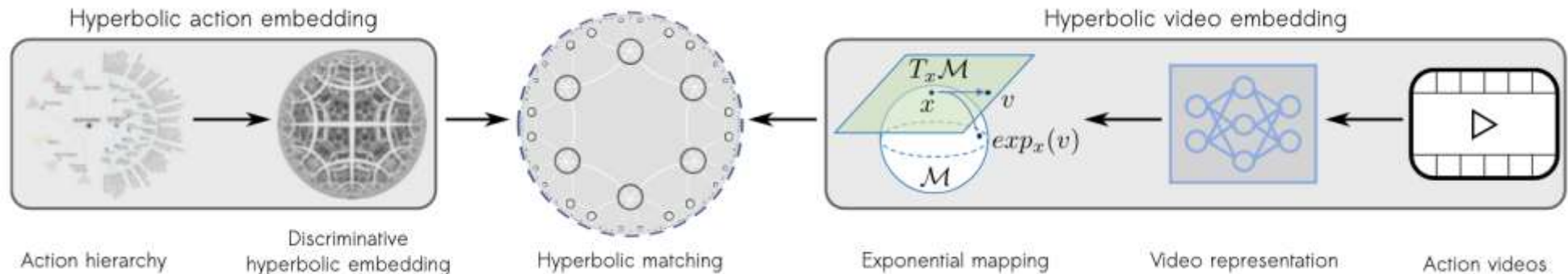
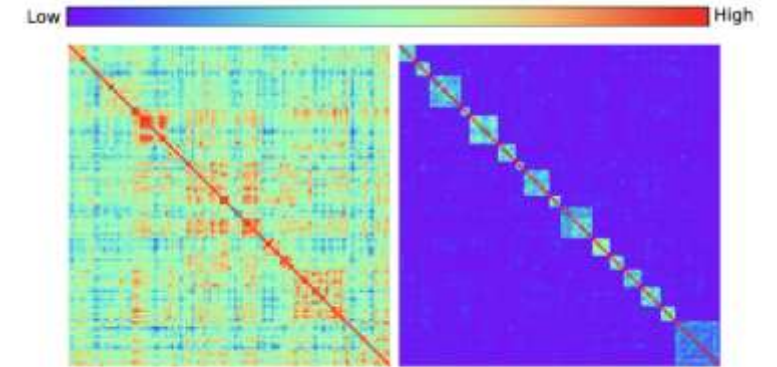
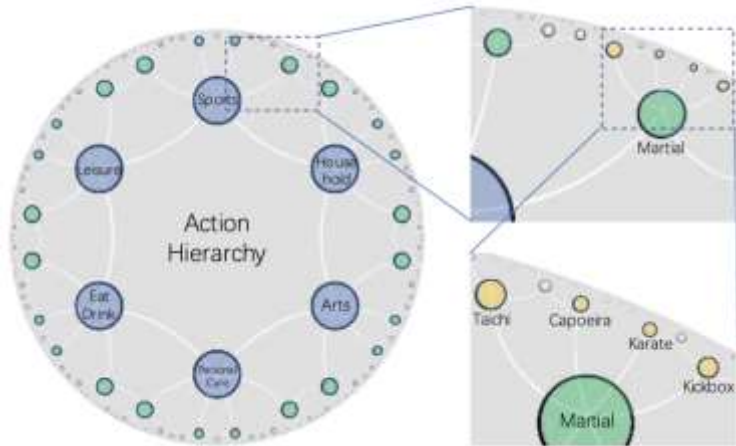
Encoder	Dataset			
	CIFAR10	CIFAR100	CUB	MiniImageNet
Inception v3 [49]	0.25	0.23	0.23	0.21
ResNet34 [14]	0.26	0.25	0.25	0.21
VGG19 [42]	0.23	0.22	0.23	0.17



Images are naturally hierarchical, hyperbolic embeddings improve few-shot learning.

# Hyperbolic actions

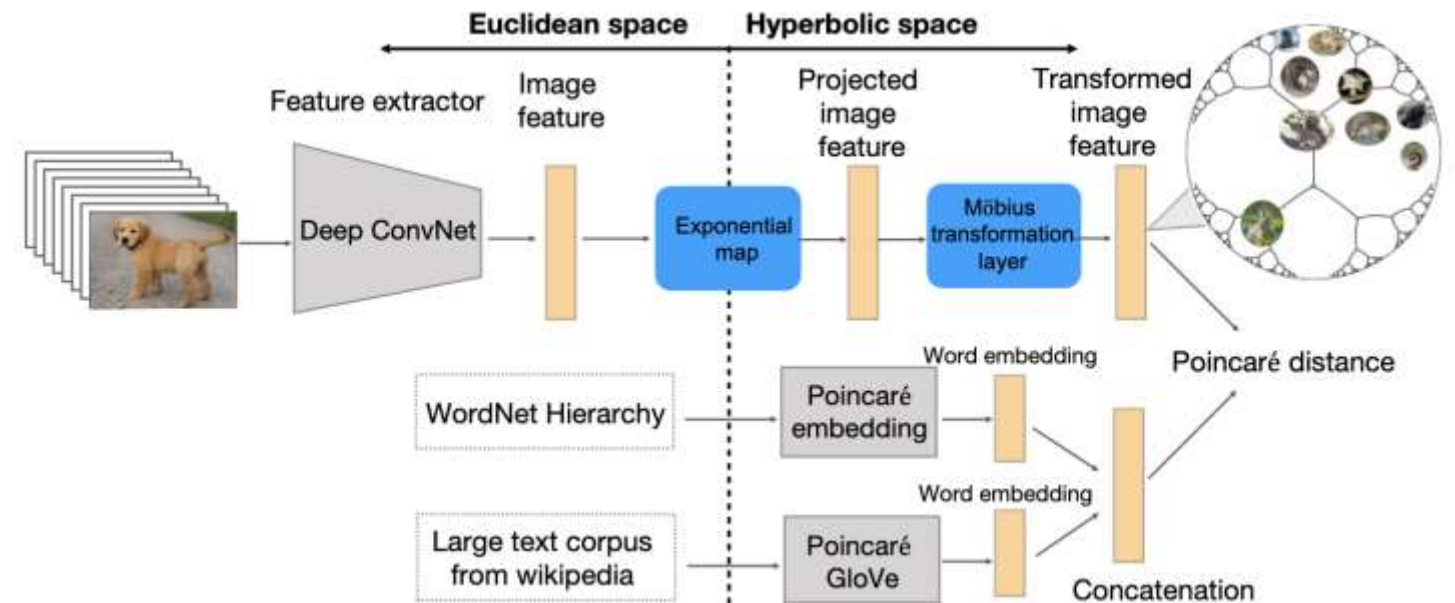
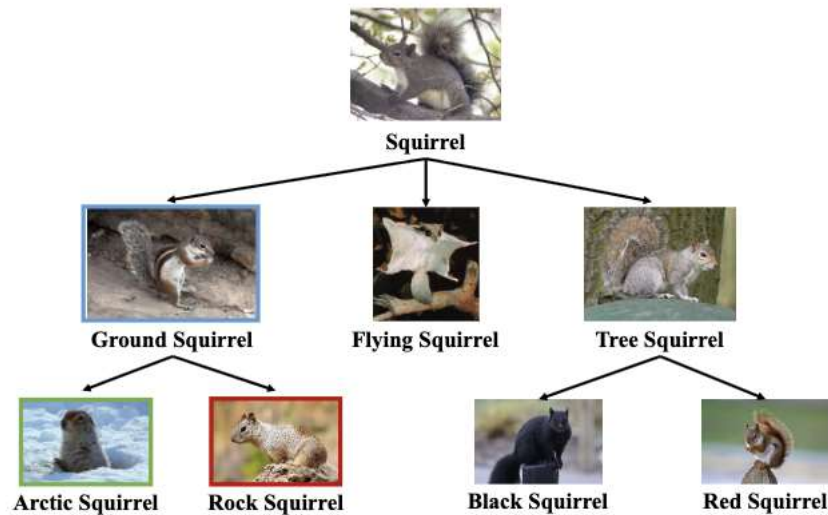
[Long et al., CVPR 2020]



Videos are naturally hierarchical, hyperbolic embeddings improve action recognition.

# Hyperbolic zero-shot learning

[Liu et al. CVPR 2020]

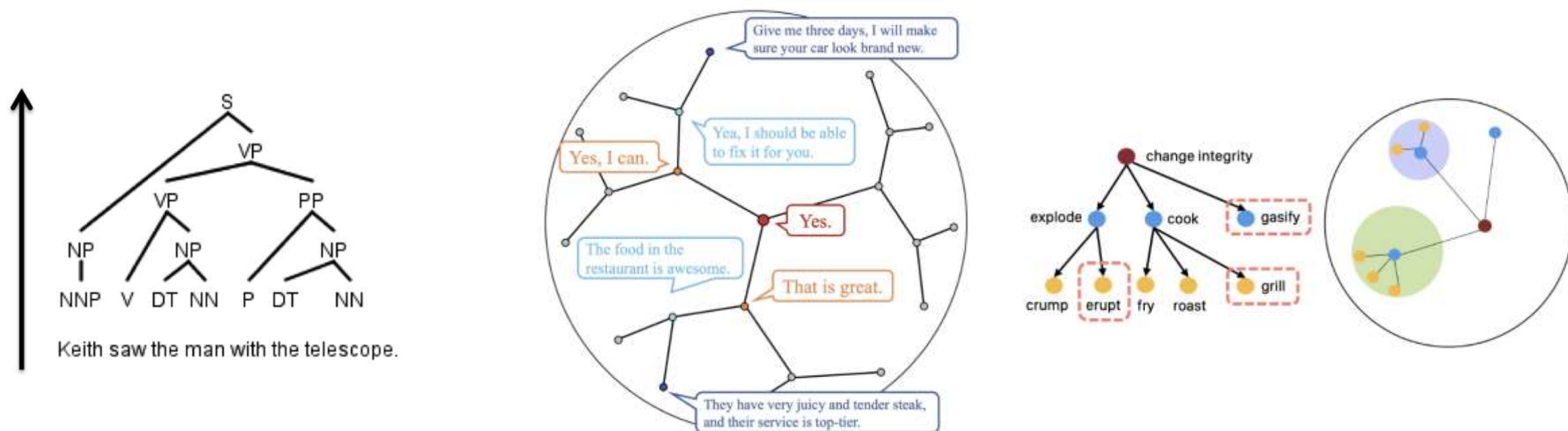


Semantics is naturally hierarchical, hyperbolic embeddings improve zero-shot recognition.



# Hyperbolic embeddings for text

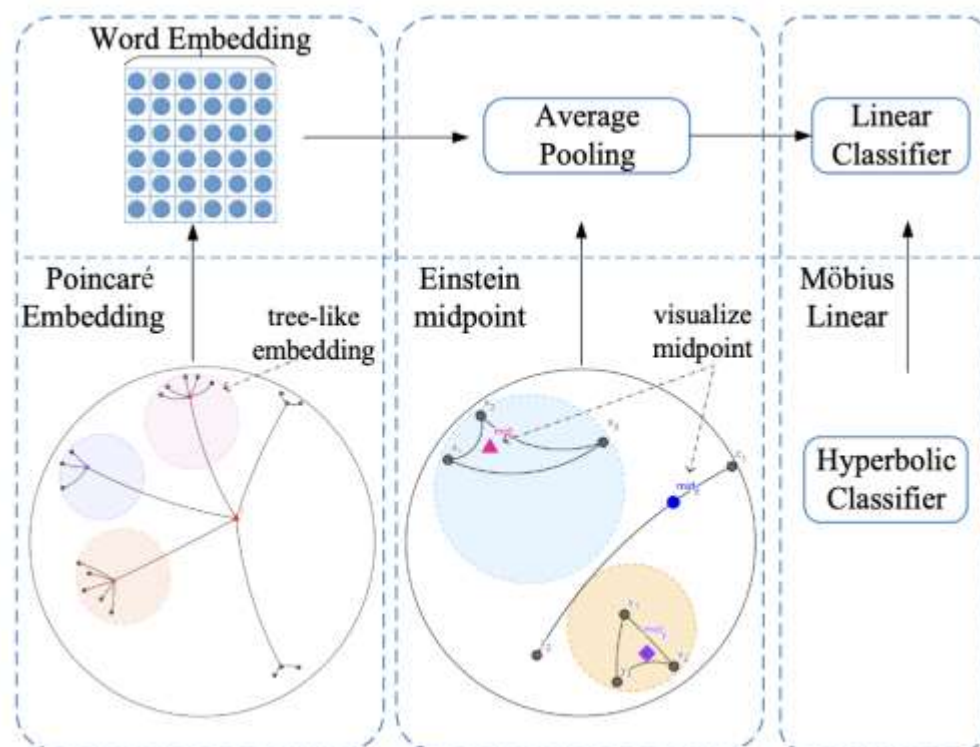
Text is well-known to be hierarchical at multiple levels.



Should representations of text then also be embedded in a hierarchical geometry?

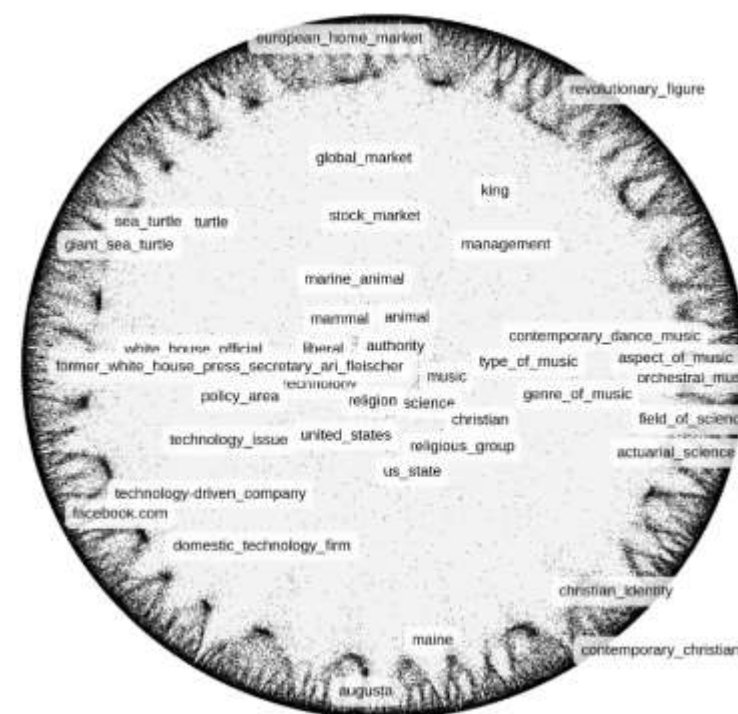
# Hyperbolic word embeddings

[Zhu et al. 2021]



Hyperbolic FastText

[Le et al. 2019]

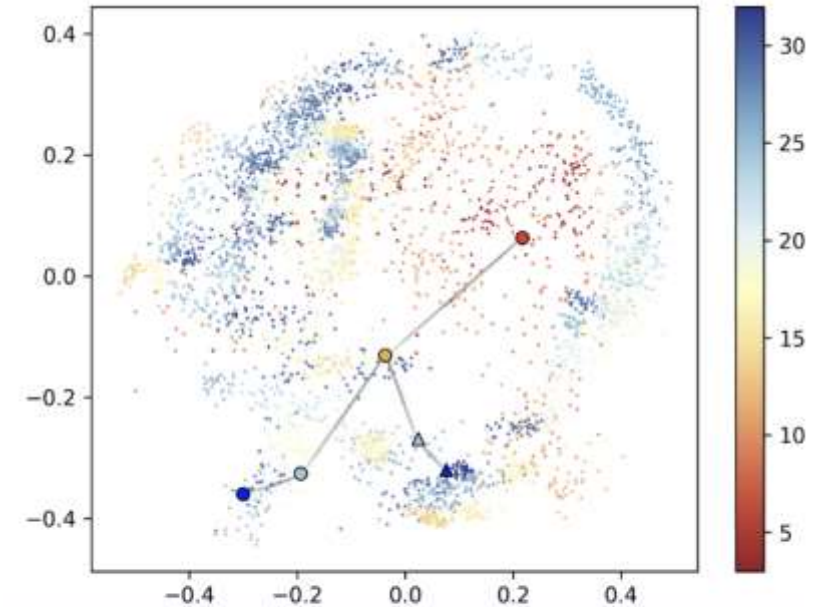
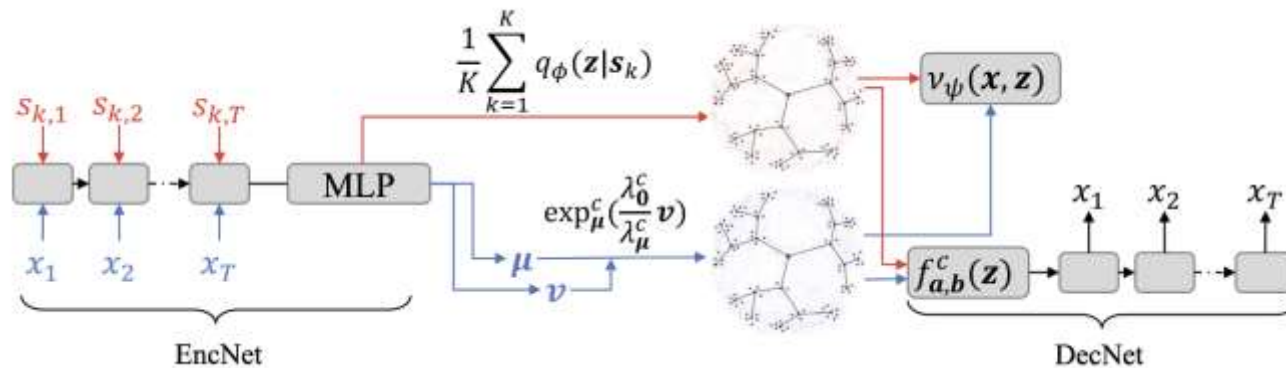
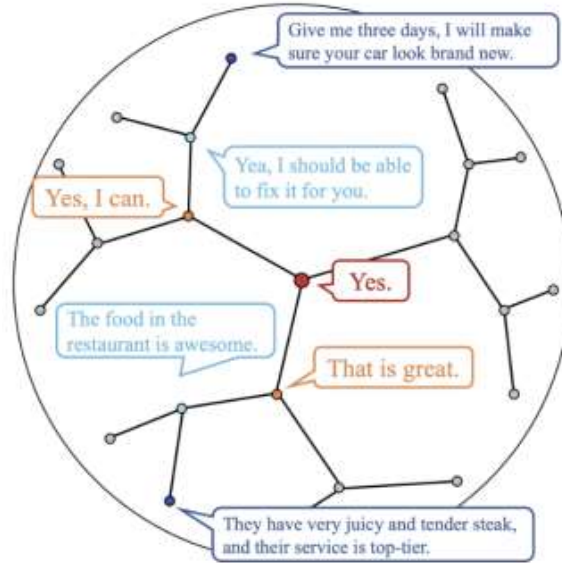


Inferring concept hierarchies from text in hyperbolic space



# Hyperbolic generation of text

[Dai et al. 2020]



- the national cancer institute ban smoking
- the national cancer institute warns citizens to avoid smoking cigarette
- the national cancer institute claims that smoking cigarette too often would increase the chance of getting lung cancer
- ▲ the national cancer institute study the effect of chemical in cigarette on different group of workers.
- the national cancer institute also projected that overall u.s. mortality rates from lung cancer should begin to drop in several years if cigarette smoking continues to decrease
- ▲ the national cancer institute report a form of asbestos once used to make cigarette filters has caused a high percentage of cancer deaths among a group of workers exposed to it

# Hyperbolic vision-language models

[Desai et al. ICML 2023]

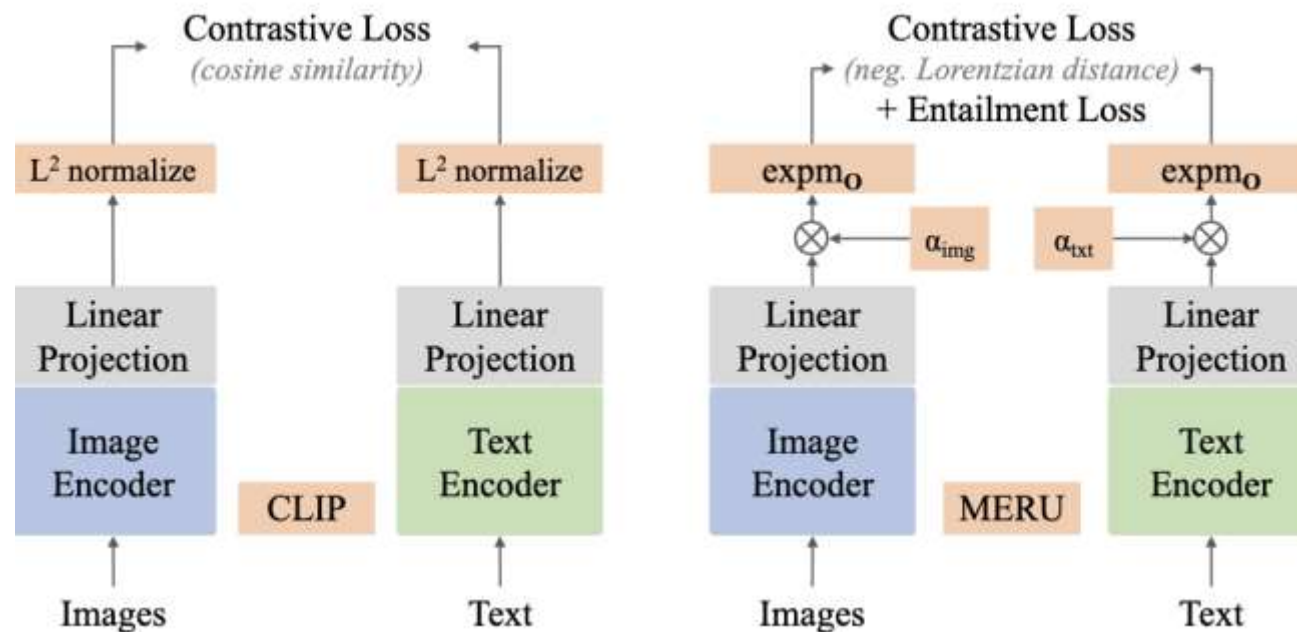


Image-text representation learning wants to collapse image and text embeddings.

# Issue 1: image-text asymmetry

Vision-language models explicitly assume that image and text are equal.

Both are points in a shared space, contrastive learning wants to collapse them.

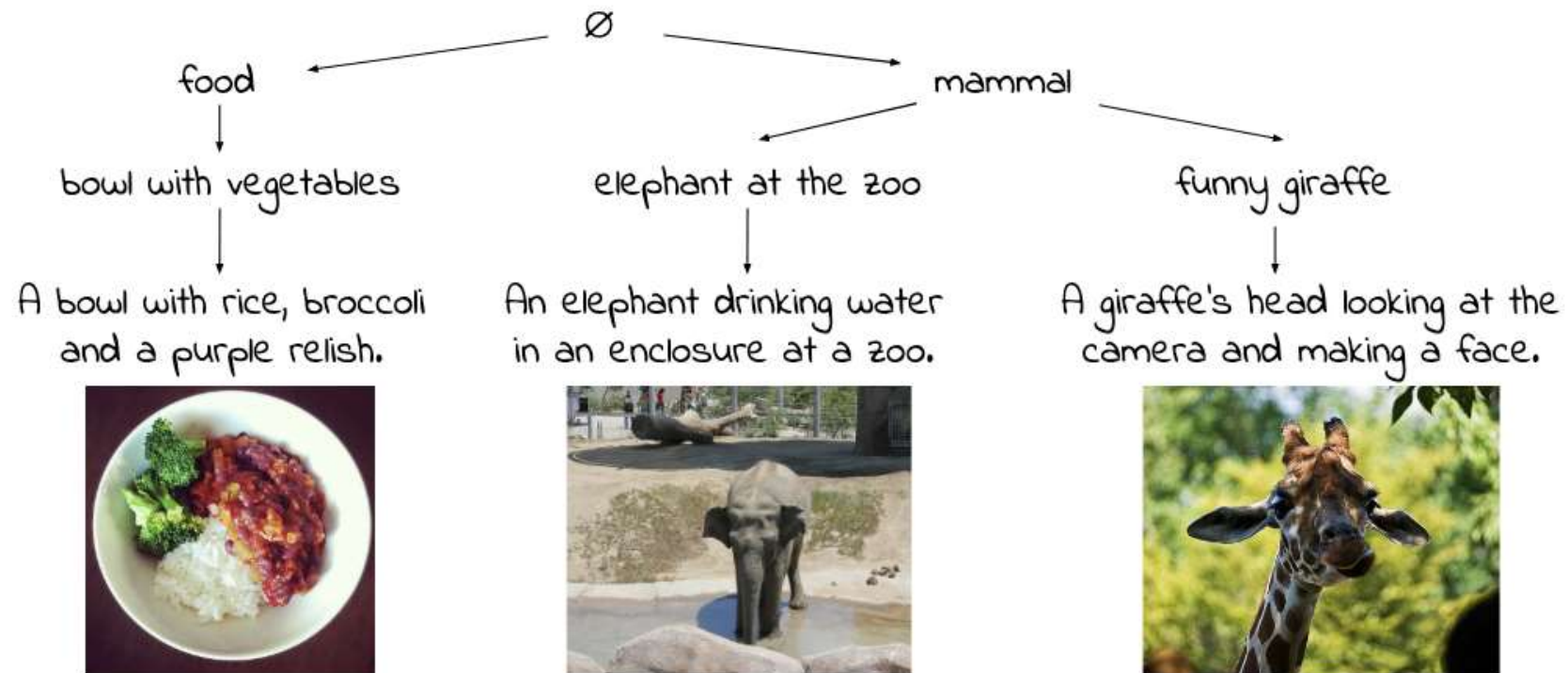
But one sentence does not unique define an image.

Text is more general than images.



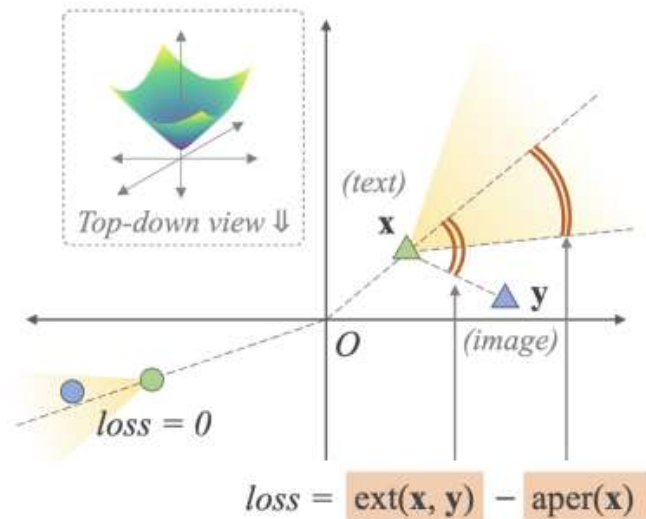
# Issue 2: vision-language is hierarchical

"Foundation VLMs exhibit zero-shot hierarchical understanding" – Alper et al. (2024)



# Hyperbolic vision-language models

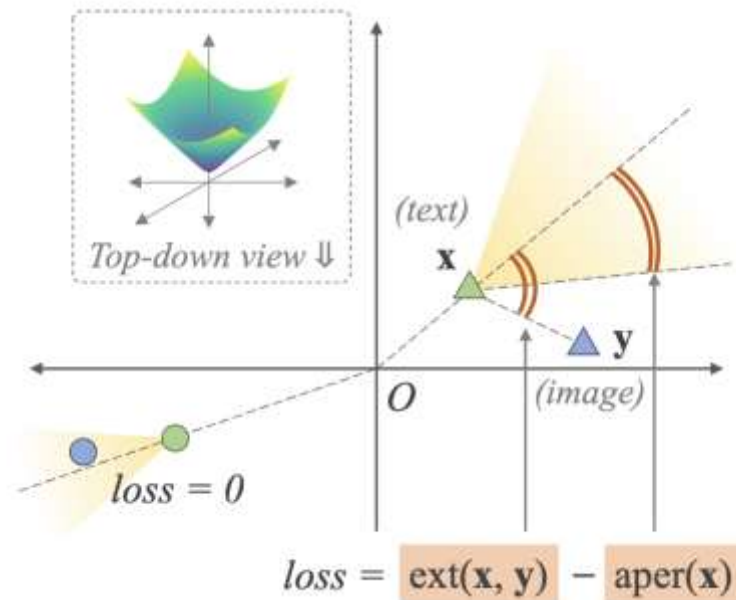
Intuitively, image and text embeddings are unequal!



Hyperbolic entailments allow to model this imbalance and learn the hierarchical nature of image-text representations.

# Entailment as a loss

Main objective: model the asymmetry between image and text.



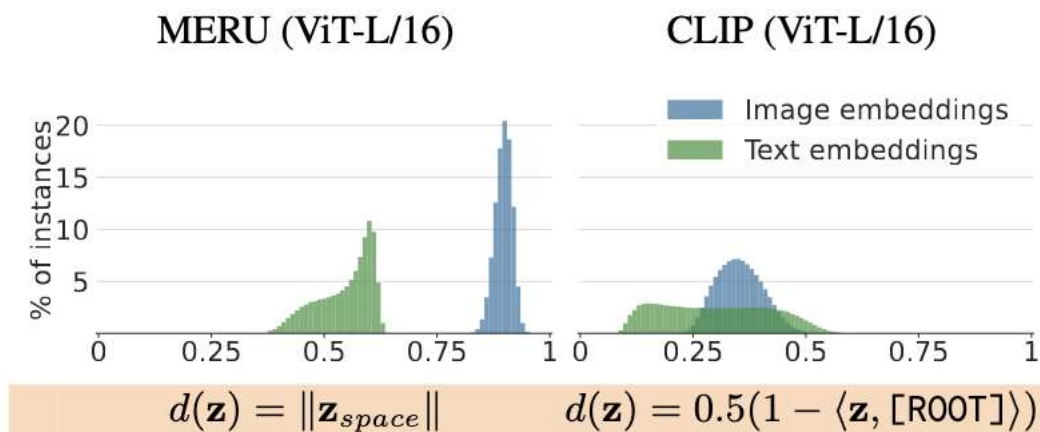
Hyperbolic entailments allow to model this imbalance and (implicitly) learn the hierarchical nature of image-text representations.



# Empirical effect

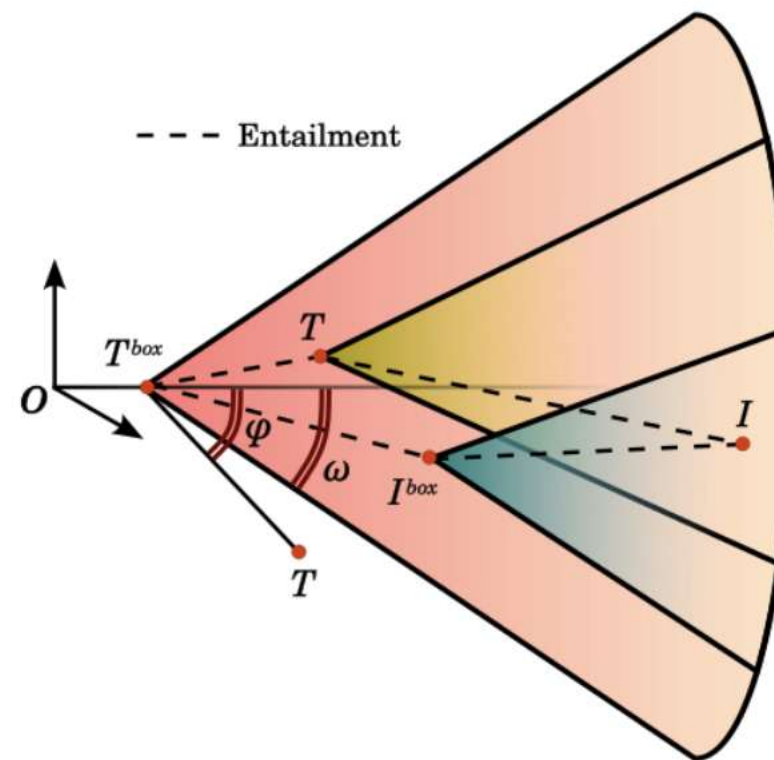
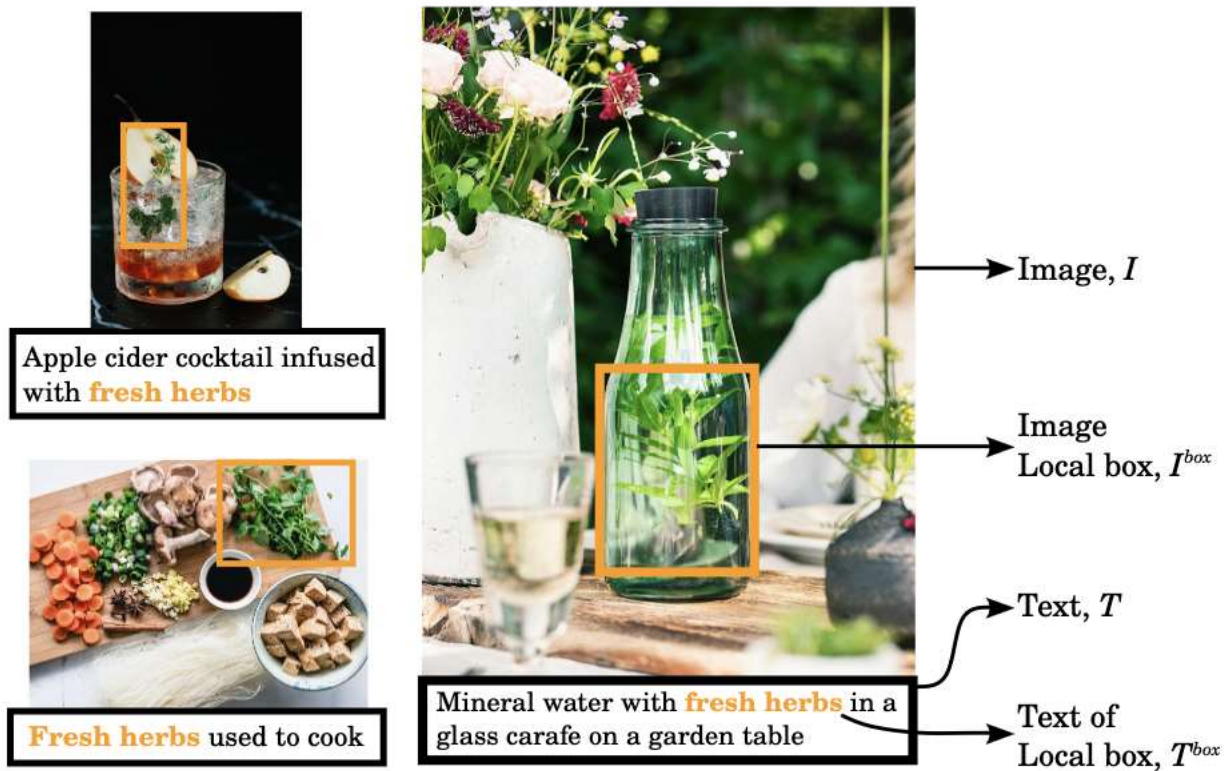
		<i>text</i> $\rightarrow$ <i>image</i>				<i>image</i> $\rightarrow$ <i>text</i>			
		COCO		Flickr		COCO		Flickr	
		R5	R10	R5	R10	R5	R10	R5	R10
ViT S/16	CLIP	29.9	40.1	35.3	46.1	37.5	48.1	42.1	54.7
	MERU	<b>30.5</b>	<b>40.9</b>	<b>37.1</b>	<b>47.4</b>	<b>39.0</b>	<b>50.5</b>	<b>43.5</b>	<b>55.2</b>
ViT B/16	CLIP	32.9	43.3	40.3	51.0	41.4	52.7	<b>50.2</b>	<b>60.2</b>
	MERU	<b>33.2</b>	<b>44.0</b>	<b>41.1</b>	<b>51.6</b>	<b>41.8</b>	<b>52.9</b>	48.1	58.9
ViT L/16	CLIP	31.7	42.2	39.0	49.3	40.6	51.3	47.8	58.5
	MERU	<b>32.6</b>	<b>43.0</b>	<b>39.6</b>	<b>50.3</b>	<b>41.9</b>	<b>53.3</b>	<b>50.3</b>	<b>60.6</b>

		Embedding width				
		512	256	128	96	64
COCO <i>text</i> $\rightarrow$ <i>image</i>	CLIP	31.7	31.8	31.4	29.6	25.7
	MERU	<b>32.6</b>	<b>32.7</b>	<b>32.7</b>	<b>31.0</b>	<b>26.5</b>
COCO <i>image</i> $\rightarrow$ <i>text</i>	CLIP	40.6	41.0	40.4	37.9	33.3
	MERU	<b>41.9</b>	<b>42.5</b>	<b>42.6</b>	<b>40.5</b>	<b>34.2</b>
ImageNet	CLIP	38.4	38.3	37.9	35.2	30.2
	MERU	<b>38.8</b>	<b>38.8</b>	<b>38.8</b>	<b>37.3</b>	<b>32.3</b>

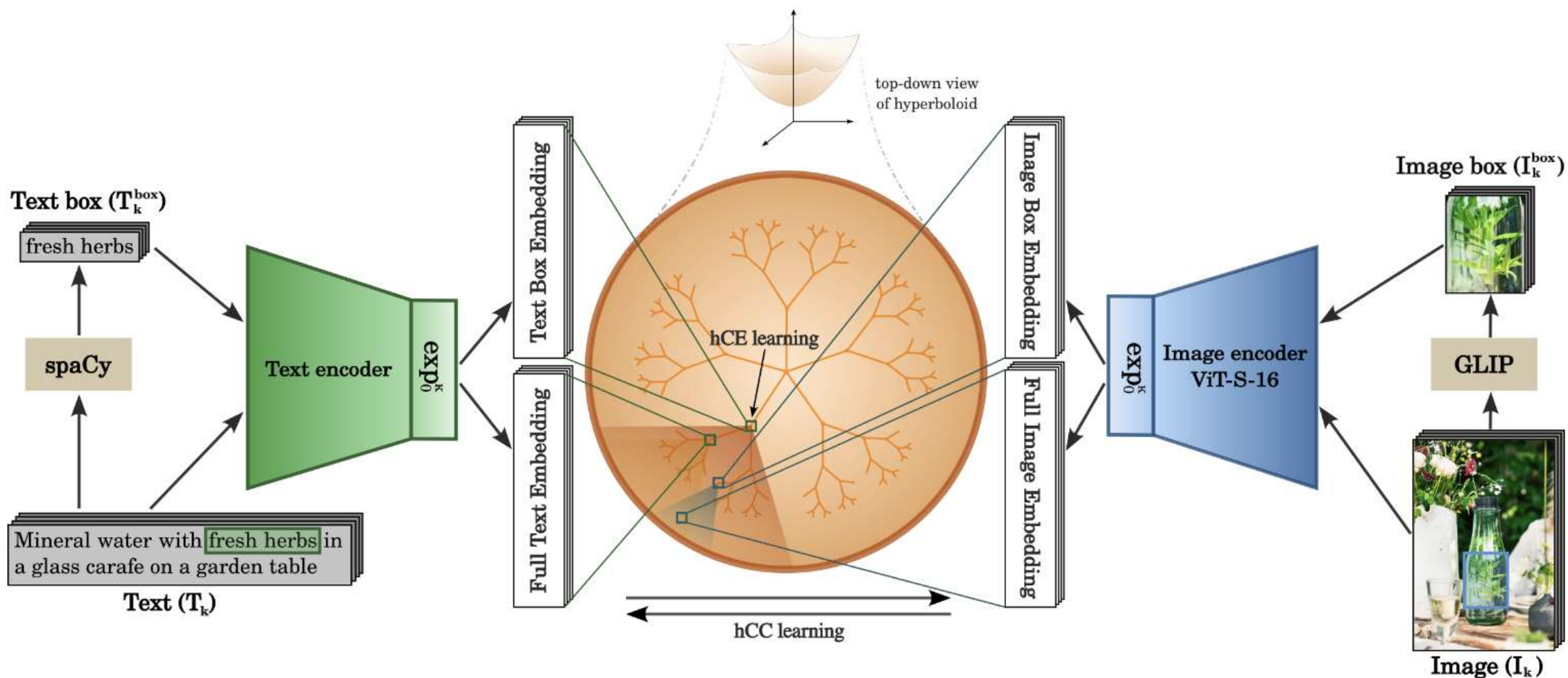


# Compositional vision-language models

[Pal et al. ICLR 2025 (oral)]



# Multi-modal network

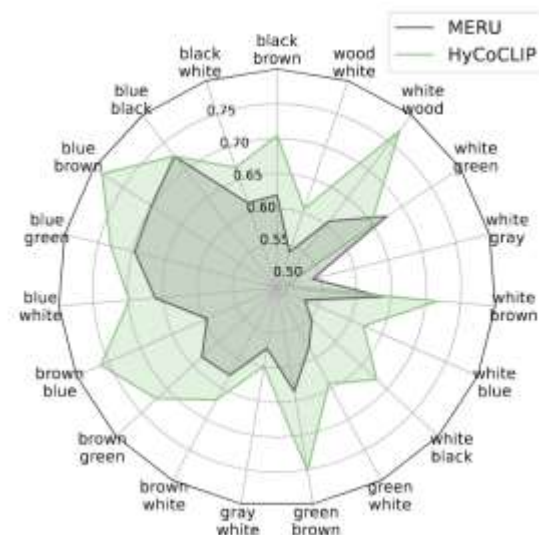
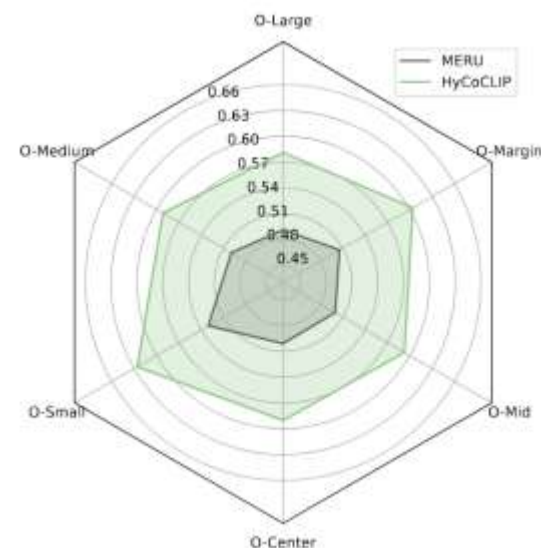




# Entailment compositions work

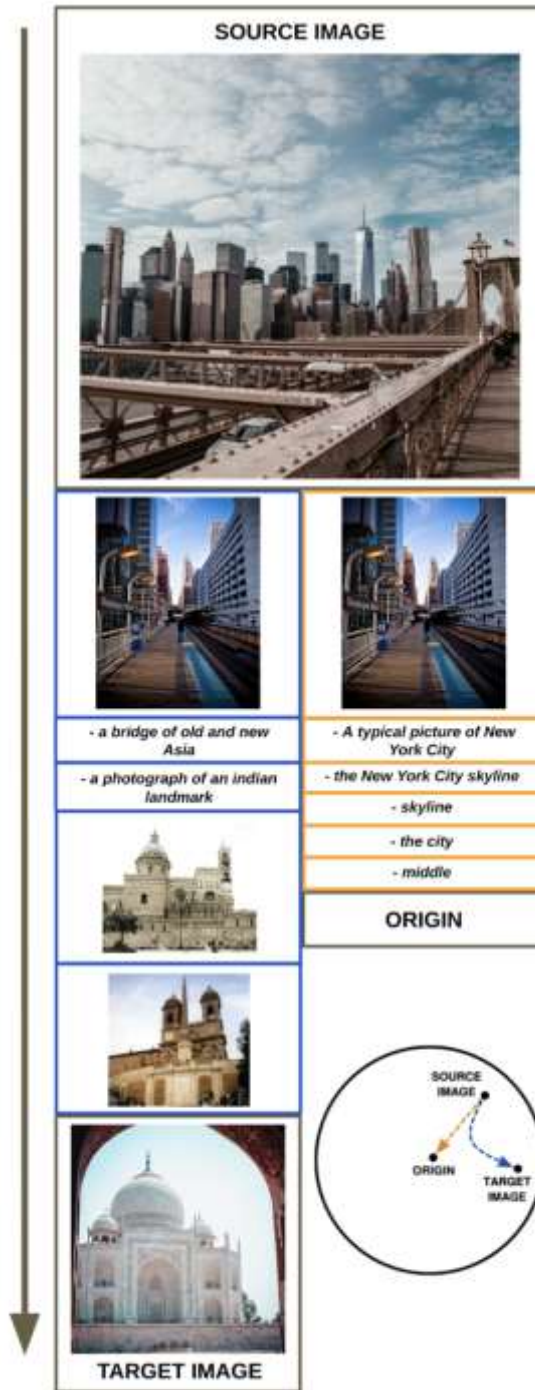
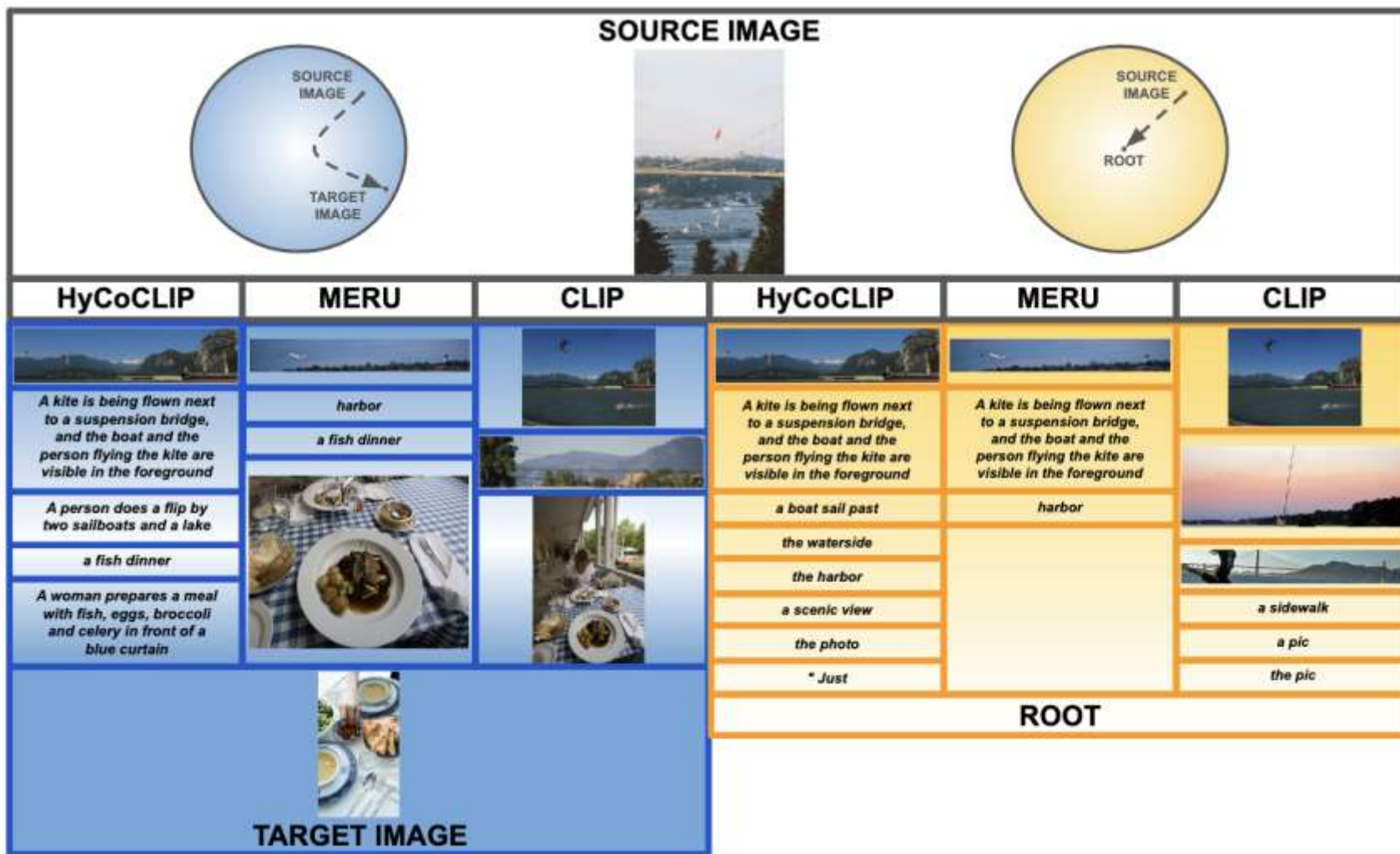
			General datasets						Fine-grained datasets						Misc. datasets			
			ImageNet	CIFAR-10	CIFAR-100	SUN397	Caltech-101	STL-10	Food-101	CUB	Cars	Aircraft	Pets	Flowers	DTD	EuroSAT	RESISC45	Country211
		w/ boxes    samples (M)																
<b>RedCaps</b>																		
ViT S/16	CLIP <sup>†</sup>	✗	11.4	32.5	66.7	35.8	26.7	60.8	89.8	72.5	29.8	11.1	1.3	72.5	44.9	16.4	30.1	27.7
	CLIP	✓	11.4 [6.3]	30.2	76.5	42.4	25.8	62.3	89.5	69.6	25.7	8.5	2.2	65.3	38.6	13.6	36.6	28.5
	MERU <sup>†</sup>	✗	11.4	31.4	65.9	35.2	26.8	58.1	89.3	71.4	29.0	8.3	1.6	71.0	40.9	17.0	29.9	29.3
	MERU	✓	11.4 [6.3]	29.9	76.4	39.9	26.6	62.3	89.5	68.4	25.4	8.9	1.2	67.2	37.6	13.0	30.5	27.6
	HyCoCLIP	✓	5.8 [6.3]	31.9	77.4	37.7	27.6	64.5	90.9	71.1	28.8	9.7	1.1	70.5	41.4	13.4	22.7	30.7
<b>GRIT</b>																		
ViT S/16	CLIP	✗	20.5	36.7	70.2	42.6	49.5	73.6	89.7	44.7	9.8	6.9	2.0	44.6	14.8	22.3	40.7	40.1
	CLIP	✓	20.5 [35.9]	36.2	84.2	54.8	46.1	74.1	91.6	43.2	11.9	6.0	2.5	45.9	18.1	24.0	32.4	35.5
	MERU	✗	20.5	35.4	71.2	42.0	48.6	73.0	89.8	48.8	10.9	6.5	2.3	42.7	17.3	18.6	39.1	38.9
	MERU	✓	20.5 [35.9]	35.0	85.0	54.0	44.6	73.9	91.6	41.1	10.1	5.6	2.2	43.9	15.9	24.5	39.3	33.5
	HyCoCLIP	✓	20.5 [35.9]	41.7	85.0	53.6	52.5	75.7	92.5	50.2	14.7	8.1	4.2	52.0	20.5	22.3	33.8	45.7
ViT B/16	CLIP	✗	20.5	40.6	78.9	48.3	53.0	76.7	92.4	48.6	10.0	9.0	3.4	45.9	21.3	23.4	37.1	42.7
	MERU	✗	20.5	40.1	78.6	49.3	53.0	72.8	93.2	51.5	11.9	8.6	3.7	48.5	21.2	22.2	31.7	44.2
	HyCoCLIP	✓	20.5 [35.9]	45.8	88.8	60.1	57.2	81.3	95.0	59.2	16.4	11.6	3.7	56.8	23.9	29.4	35.8	45.6

			Text retrieval				Image retrieval				Hierarchical metrics				
			COCO		Flickr		COCO		Flickr		WordNet				
Vision encoder	Model	w/ boxes	R@5	R@10	R@5	R@10	R@5	R@10	R@5	R@10	TIE(↓)	LCA(↓)	J(↑)	P <sub>H</sub> (↑)	R <sub>H</sub> (↑)
ViT S/16	CLIP	✗	69.3	79.1	90.2	95.2	53.7	65.2	81.1	87.9	4.02	2.39	0.76	0.83	0.84
	CLIP	✓	60.7	71.8	84.2	91.3	47.1	58.6	73.1	82.1	4.03	2.38	0.76	0.83	0.83
	MERU	✗	68.8	78.8	89.4	94.8	53.6	65.3	80.4	87.5	4.08	2.39	0.76	0.83	0.83
	MERU	✓	72.7	81.9	83.5	90.1	46.6	58.3	60.0	71.7	4.08	2.39	0.75	0.83	0.83
	HyCoCLIP	✓	69.5	79.5	89.1	93.9	55.2	66.6	81.5	88.1	3.55	2.17	0.79	0.86	0.85
ViT B/16	CLIP	✗	71.4	81.5	93.6	96.9	57.4	68.5	83.5	89.9	3.60	2.21	0.79	0.85	0.85
	MERU	✗	72.3	82.0	93.5	96.2	57.4	68.6	84.0	90.0	3.63	2.22	0.78	0.85	0.85
	HyCoCLIP	✓	72.0	82.0	92.6	95.4	58.4	69.3	84.9	90.3	3.17	2.05	0.81	0.87	0.87



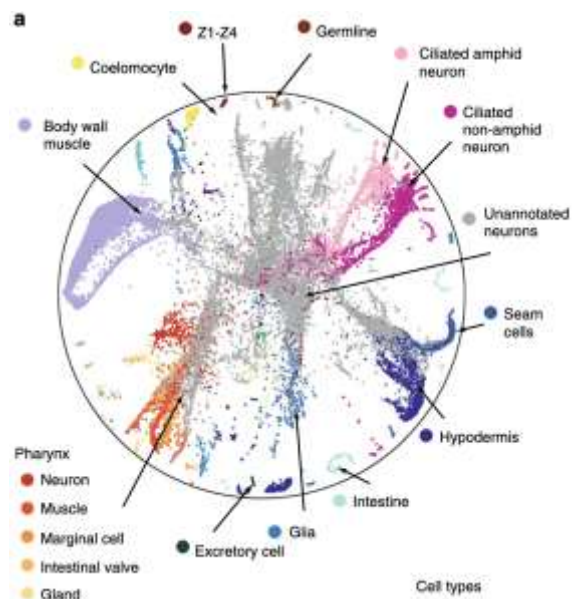
Model	AP
CLIP	51.2
MERU	55.8
RegionCLIP	65.2
HyCoCLIP	68.5

# Embedding traversal



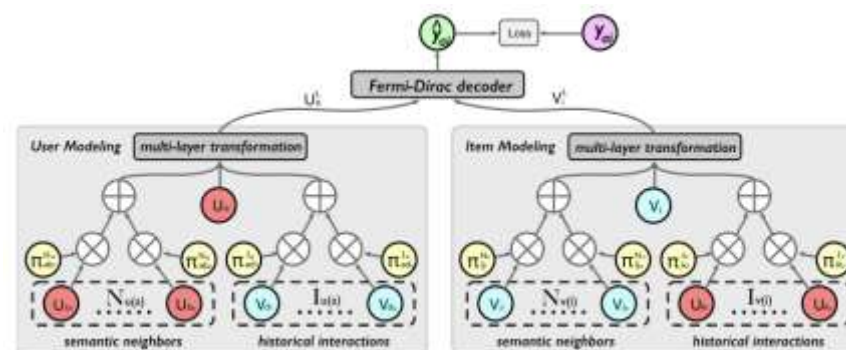
# Hyperbolic embeddings for other data types

[Klimovskaia et al. Nature Comm. 2020]



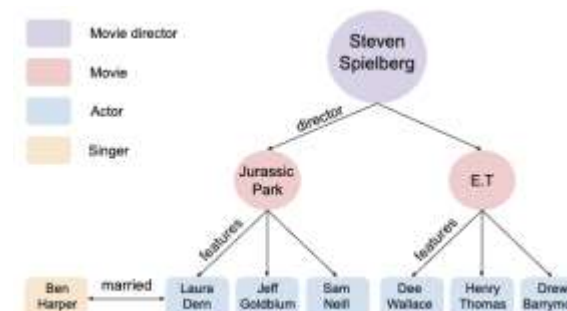
Hyperbolic embeddings of single-cell data.

[Li et al. TKDD 2023]



Hyperbolic recommender systems

[Chami et al. 2020]



Hyperbolic knowledge graphs

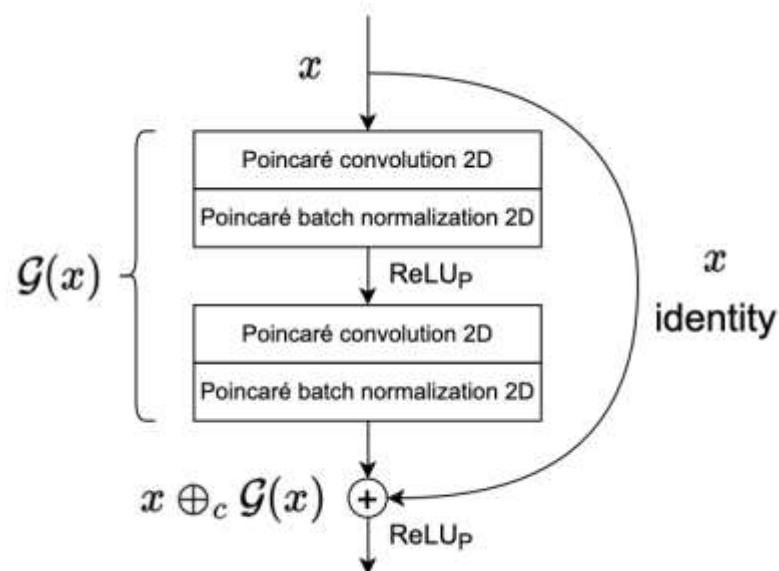
And more for music, 3D skeletons, phylogenetic placement, social networks, clustering...



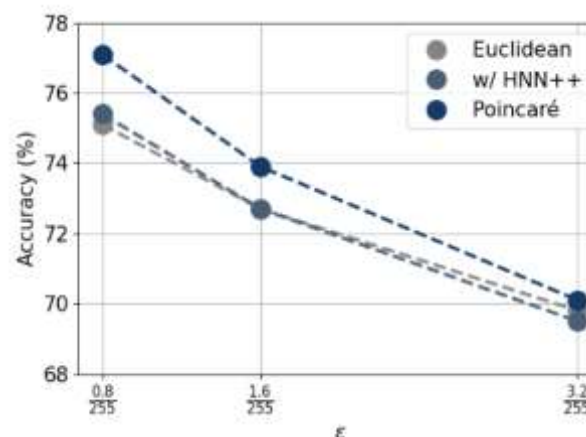
# What if every layer becomes hyperbolic?

[van Spengler et al. ICCV 2023]

First convolutional network for images fully in hyperbolic space.



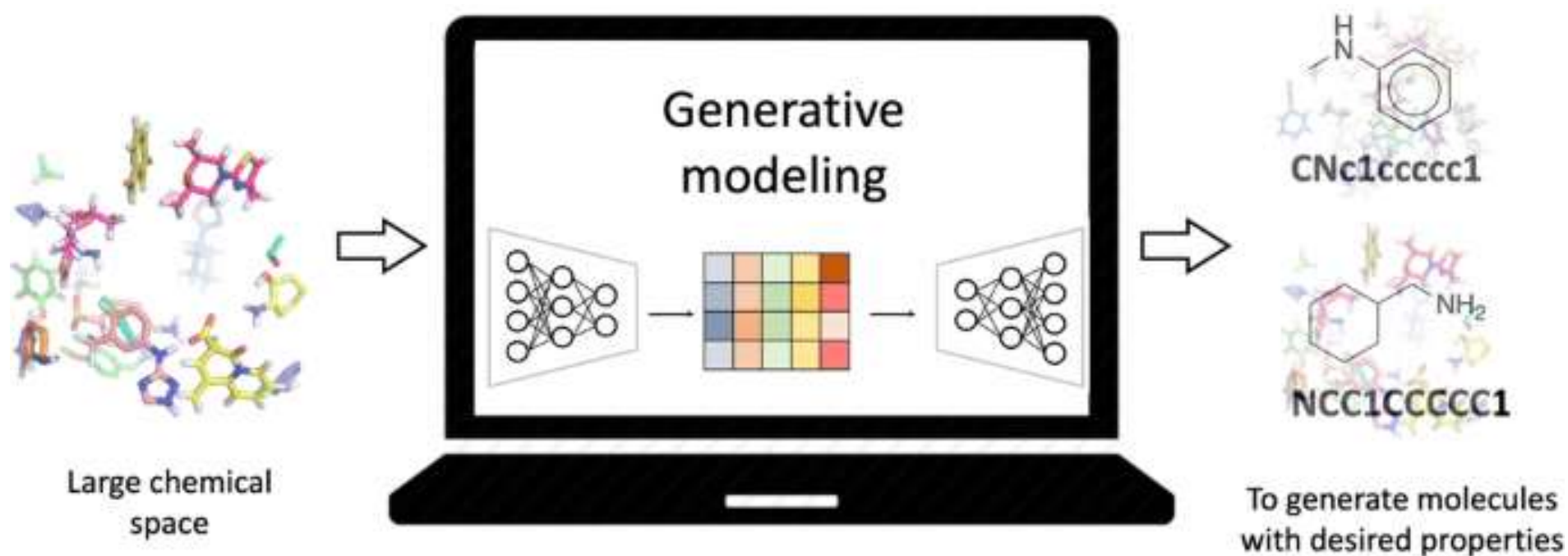
Manifold		CIFAR-10						CIFAR-100					
		FPR95 ↓		AUROC ↑		AUPR ↑		FPR95 ↓		AUROC ↑		AUPR ↑	
		R20	R32	R20	R32	R20	R32	R20	R32	R20	R32	R20	R32
Places-365	Euclidean	64.2	72.3	<b>84.7</b>	82.0	<b>96.2</b>	95.6	89.5	93.9	62.5	57.9	89.3	87.9
	w/ HNN++	<b>63.8</b>	72.7	79.6	77.7	94.5	94.2	93.2	86.3	63.3	66.6	89.8	91.1
	Poincaré	70.2	<b>70.7</b>	82.3	<b>82.6</b>	95.7	<b>95.9</b>	<b>82.8</b>	<b>83.8</b>	<b>71.5</b>	<b>71.1</b>	<b>92.3</b>	<b>92.2</b>
	Euclidean	68.8	73.4	92.8	94.1	99.5	98.8	43.7	54.6	83.7	88.2		
	w/ HNN++	<b>85.5</b>	82.2	<b>96.9</b>	96.1	92.1	88.6	66.4	68.9	91.1	92.0		
	Poincaré	85.0	<b>83.6</b>	96.6	<b>96.3</b>	<b>76.9</b>	<b>83.0</b>	<b>76.8</b>	<b>72.6</b>	<b>94.1</b>	<b>92.9</b>		
	Euclidean	73.6	77.3	93.2	94.7	98.1	96.0	33.5	42.9	75.9	79.4		
	w/ HNN++	79.6	<b>85.8</b>	94.5	<b>96.6</b>	85.9	<b>77.5</b>	58.9	65.7	86.8	89.0		
	Poincaré	<b>82.1</b>	82.3	<b>95.5</b>	95.6	<b>83.9</b>	84.2	<b>67.7</b>	<b>68.8</b>	<b>91.0</b>	<b>91.5</b>		



It works! Also better OOD and adversarial robustness, but scaling remain challenging.

# Hyperbolic generative learning

[Bian and Xie, JMM 2021]

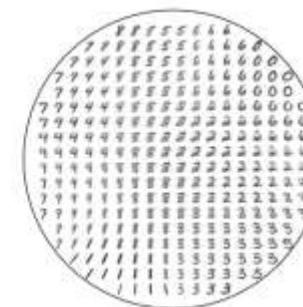
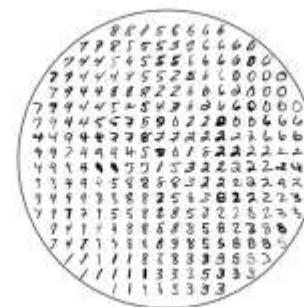
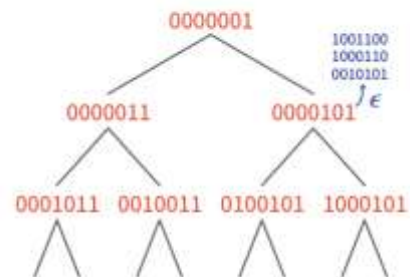


So far, we focused on discriminative learning. What about generation in hyperbolic space?

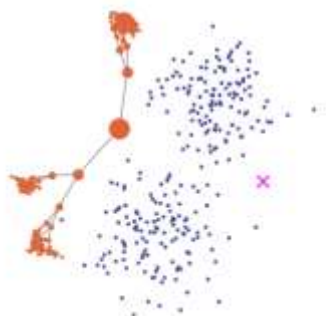
# Hyperbolic Variational Autoencoders

[Nagano et al. ICML 2019, Mathieu et al. NeurIPS 2019]

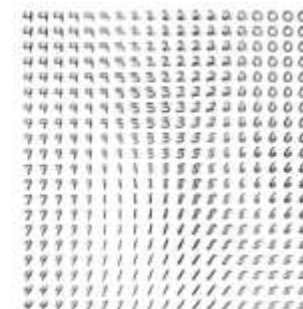
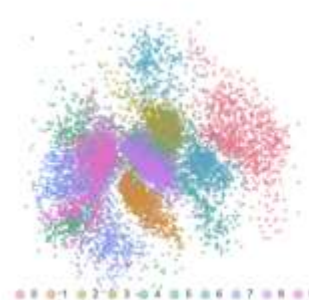
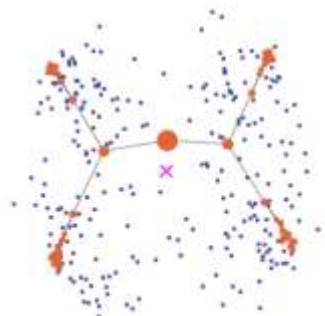
(a) A tree representation of the training dataset



(b) Vanilla VAE ( $\beta = 1.0$ )



(c) Hyperbolic VAE

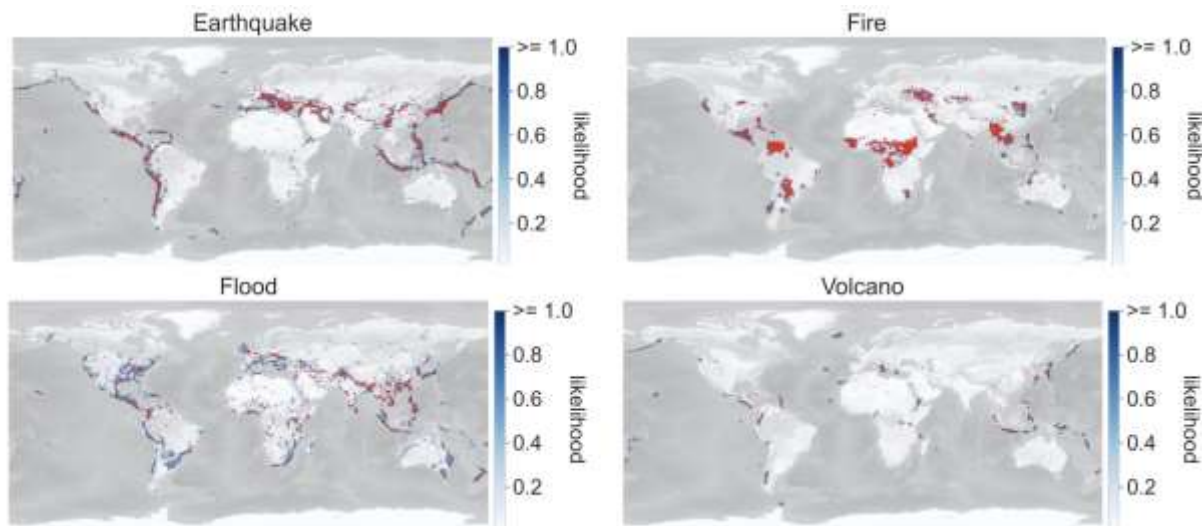


Hyperbolic latent spaces with wrapped normals enable learning latent hierarchical distributions.

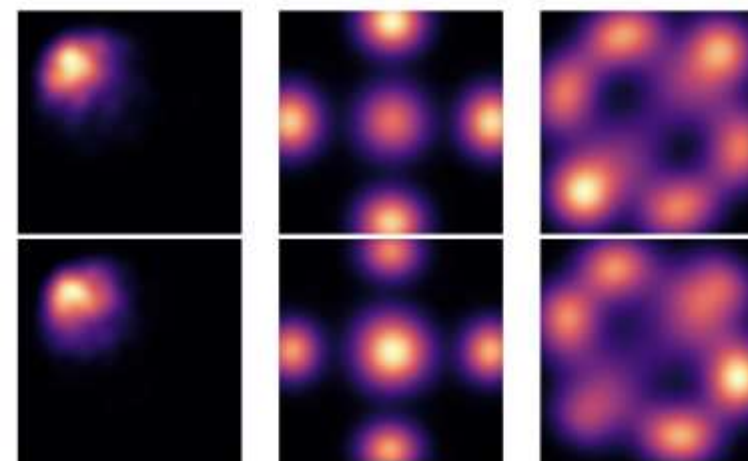
# Riemannian diffusion models

[Huang et al. NeurIPS 2022]

Generalize diffusion process to any Riemannian manifold.



Spherical



Hyperbolic

Allows us to adapt diffusion process to the real underlying data distribution.

# The big potential of hyperbolic learning

<b>Hierarchical learning</b>	model the hierarchies of semantics and data.
<b>Robust learning</b>	handle new distributions and adversarial samples.
<b>Low-dimensional learning networks.</b>	hyperbolic space is dense, allowing for smaller
<b>Brain-like networks</b>	brains are likely hyperbolic, <a href="#">big links with neuroscience</a>



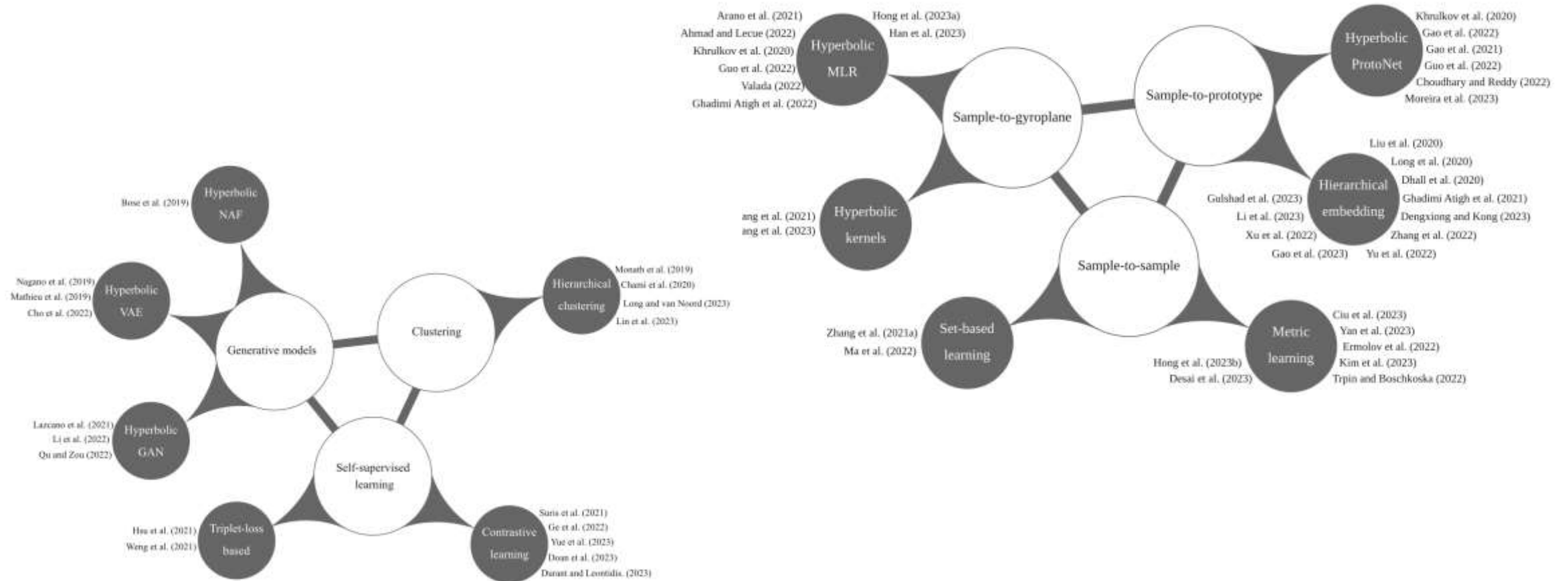
# The grand challenges of hyperbolic learning

<b>Fully hyperbolic learning</b>	which hyperbolic model is best? and how to optimize?
<b>Computational challenges</b>	numerical stability and speed of computation.
<b>Open source community</b>	where is hyperbolic PyTorch?
<b>Learning at scale</b>	we need an ImageNet/CLIP moment for hyperbolic learning.

# Where to start?

Pascal Mettes, Mina Ghadimi, Martin Keller-Ressel, Jeffrey Gu, Serena Yeung. IJCV 2024

*Hyperbolic Deep Learning in Computer Vision: A Survey*





# Where to start?

Max van Spengler, Philipp Wirth, Pascal Mettes. ACM MM 2024

*HypLL: The Hyperbolic Learning Library*

```
import hypll.nn as hnn
from hypll.manifolds.poincare_ball import (
    Curvature, PoincareBall
)

ball = PoincareBall(Curvature(1.0))
class HNet(nn.Module):
    def __init__(self):
        super().__init__()
        self.conv1 = hnn.HConvolution2d(3, 6, 5, ball)
        self.pool = hnn.HMaxPool2d(2, ball, 2)
        self.conv2 = hnn.HConvolution2d(6, 16, 5, ball)
        self.fc1 = hnn.HLinear(16 * 5 * 5, 120, ball)
        self.fc2 = hnn.HLinear(120, 84, ball)
        self.fc3 = hnn.HLinear(84, 10, ball)
        self.relu = hnn.HReLU(ball)

    def forward(self, x):
        x = self.pool(self.relu(self.conv1(x)))
        x = self.pool(self.relu(self.conv2(x)))
        x = x.flatten(1)
        x = self.relu(self.fc1(x))
        x = self.relu(self.fc2(x))
        x = self.fc3(x)
        return x
```

```
import torch.nn as nn

class Net(nn.Module):
    def __init__(self):
        super().__init__()
        self.conv1 = nn.Conv2d(3, 6, 5)
        self.pool = nn.MaxPool2d(2, 2)
        self.conv2 = nn.Conv2d(6, 16, 5)
        self.fc1 = nn.Linear(16 * 5 * 5, 120)
        self.fc2 = nn.Linear(120, 84)
        self.fc3 = nn.Linear(84, 10)
        self.relu = nn.ReLU()

    def forward(self, x):
        x = self.pool(self.relu(self.conv1(x)))
        x = self.pool(self.relu(self.conv2(x)))
        x = x.flatten(1)
        x = self.relu(self.fc1(x))
        x = self.relu(self.fc2(x))
        x = self.fc3(x)
        return x
```

[https://github.com/maxvanspengler/hyperbolic\\_learning\\_library](https://github.com/maxvanspengler/hyperbolic_learning_library)

# Where to start?

Max van Spengler, Philipp Wirth, Pascal Mettes. ACM MM 2024

*HypLL: The Hyperbolic Learning Library*

```
from hypll.tensors import TangentTensor

for data in trainloader:
    inputs, labels = data

    tangents = TangentTensor(
        inputs, man_dim=1, manifold=ball
    )
    inputs_on_ball = ball.expmap(tangents)

    outputs = hnet(inputs_on_ball)
```

[https://github.com/maxvanspengler/hyperbolic\\_learning\\_library](https://github.com/maxvanspengler/hyperbolic_learning_library)



# Where to start?

EUROPEAN CONFERENCE  
ON COMPUTER VISION  
TEL AVIV 2022  
October 25-27

ECV

chical.

Why should you care about hyperbolic deep learning

Hyperbolic geometry is the natural geometry of hierarchies.

ImageNet Trees

Hierarchical knowledge

Hierarchical data

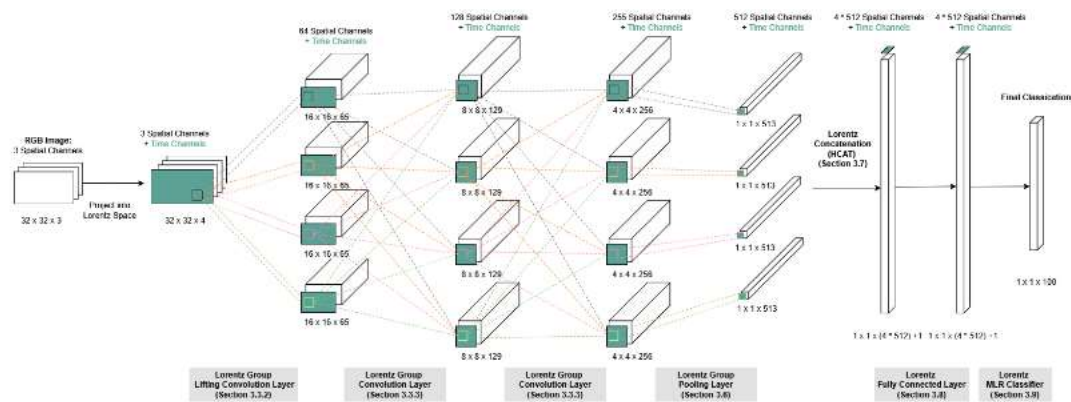
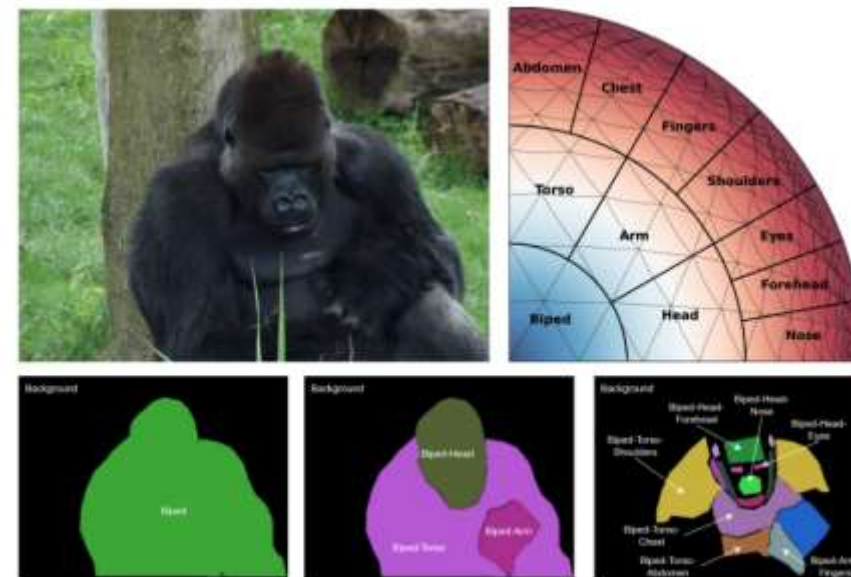
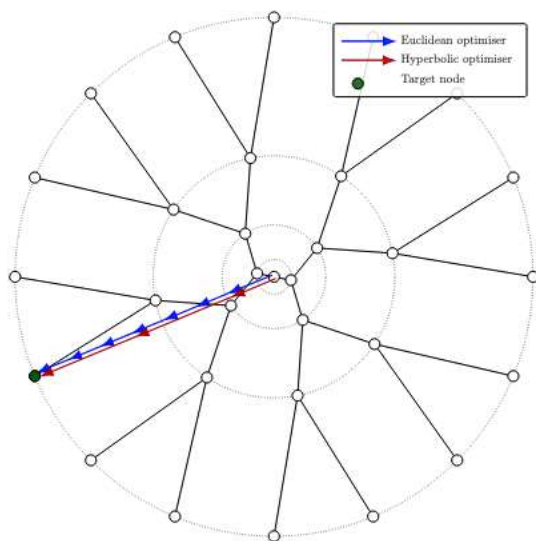
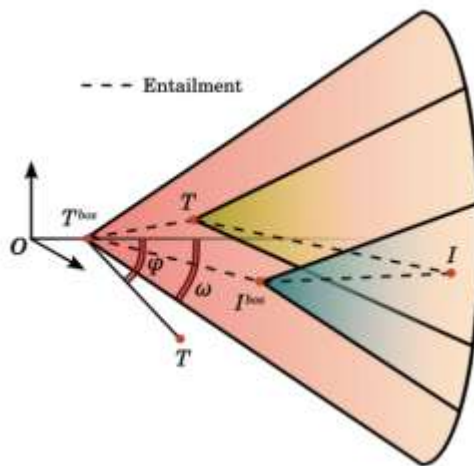
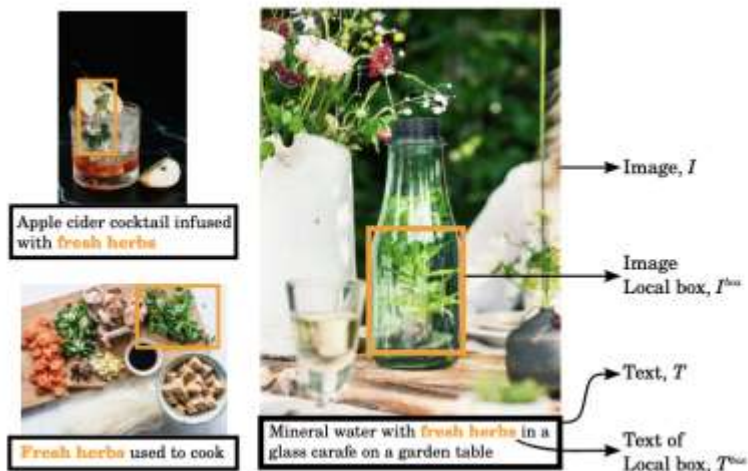
In vision and deep learning our data and knowledge is commonly hierarchical.

ECV ECV

<https://www.youtube.com/@hyperboliclearningforcv/playlists>



Interested? Let's write a hyperbolic thesis!



# Next lecture

Lecture	Title
1	Intro and history of deep learning
3	Deep learning optimization I
5	Convolutional deep learning
7	Graph deep learning
9	Multi-modal deep learning
11	What doesn't work in deep learning
13	Q&A

Lecture	Title
2	AutoDiff
4	Deep learning optimization II
6	Attention-based deep learning
8	From supervised to unsupervised deep learning
10	Generative deep learning
12	Non-Euclidean deep learning
14	Deep learning for videos