

Missing Data Imputation and Acquisition with Deep Hierarchical Models and Hamiltonian Monte Carlo

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Challenges

Enhance information acquisition with VAEs

- Discovery of high-value information.
- Bayesian reward function [2] as an expected gain of information:

$$R(i, \mathbf{x}_O) = \mathbb{E}_{\mathbf{x}_i \sim p(\mathbf{x}_i | \mathbf{x}_O)} D_{\text{KL}} [p(\mathbf{x}_\phi | \mathbf{x}_i, \mathbf{x}_O) \| p(\mathbf{x}_\phi | \mathbf{x}_O)]$$

- Approximated in [3,4] by transforming into \mathbf{z} space:

$$\begin{aligned} \hat{R}_I(\mathbf{x}_i, \mathbf{x}_O) = & \mathbb{E}_{p_\theta(\mathbf{x}_i, \mathbf{z}_i, \mathbf{z}_O | \mathbf{x}_O)} \{ \mathbb{KLL} [q_\lambda(\mathbf{h} | \mathbf{z}_i, \mathbf{z}_O) || q_\lambda(\mathbf{h} | \mathbf{z}_O)] - \\ & \mathbb{E}_{p_\theta(\mathbf{x}_\phi, \mathbf{z}_\Phi, | \mathbf{x}_O)} \mathbb{KLL} [q_\lambda(\mathbf{h} | \mathbf{z}_\Phi, \mathbf{z}_i, \mathbf{z}_O) || q_\lambda(\mathbf{h} | \mathbf{z}_\Phi, \mathbf{z}_O)] \} \end{aligned}$$

- These methods are based on **Gaussian** approximations of the true posterior.

[2] Bernardo et al., 1979

[3] Ma et al., 2018

[4] Ma et al., 2020

Challenges

Improve missing data imputation with VAEs

- Imputation under a VAE framework [3,4,5,6]:

$$p(\mathbf{x}_U | \mathbf{x}_O) = \mathbb{E}_{p(\mathbf{z} | \mathbf{x}_O)}[p(\mathbf{x}_U | \mathbf{z})] \approx \mathbb{E}_{q(\mathbf{z} | \mathbf{x}_O)}[p(\mathbf{x}_U | \mathbf{z})]$$

- Also based on **Gaussian** approximations of the true posterior.

[3] Ma et al., 2018

[4] Ma et al., 2020

[5] Nazabal et al., 2020

[6] Mattei et al., 2020

Challenges

Jointly increase flexibility and improve inference

- Hierarchical VAEs are successful at modeling flexibility.

$$p(z_1) \prod_{l=2}^L p(z_l | z_{l-1})$$

- Complicated posteriors -> **Delicate inference** (posterior collapse).
- Gaussian approximate inference worsens.

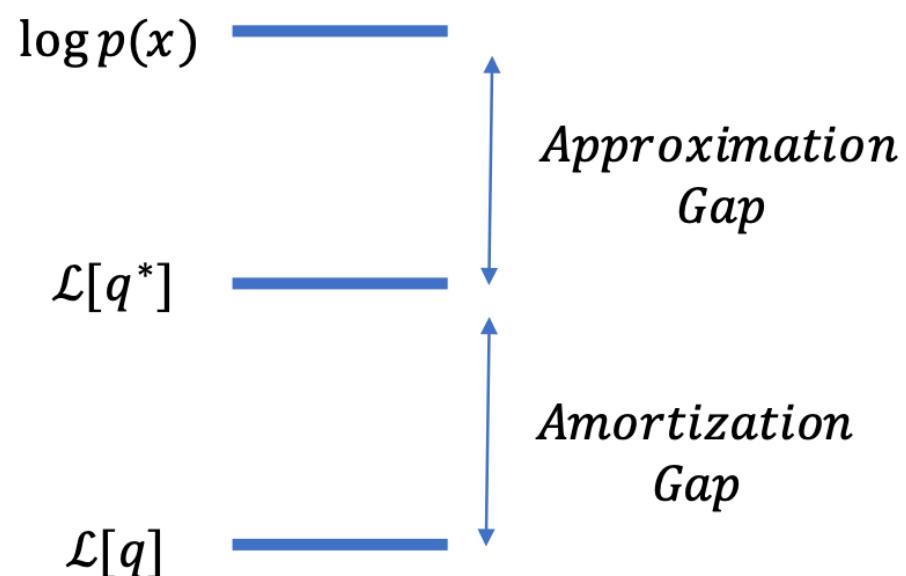
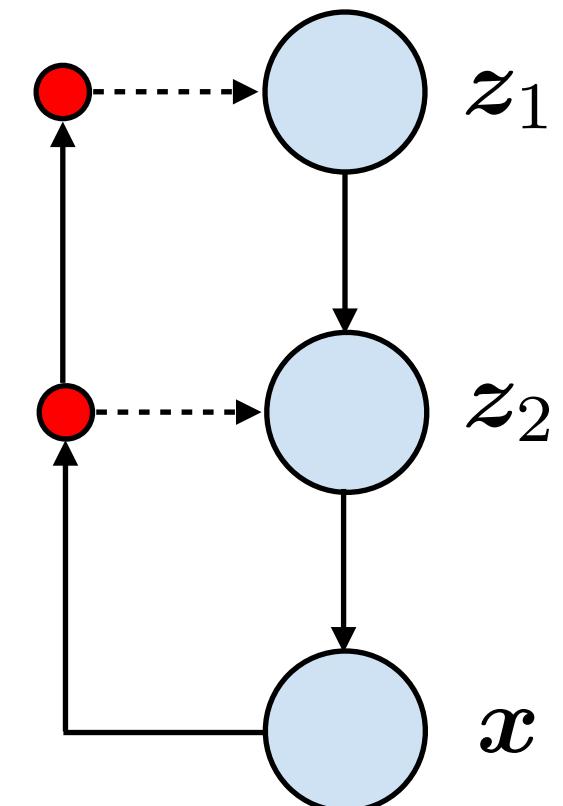


Figure 1. Gaps in Inference

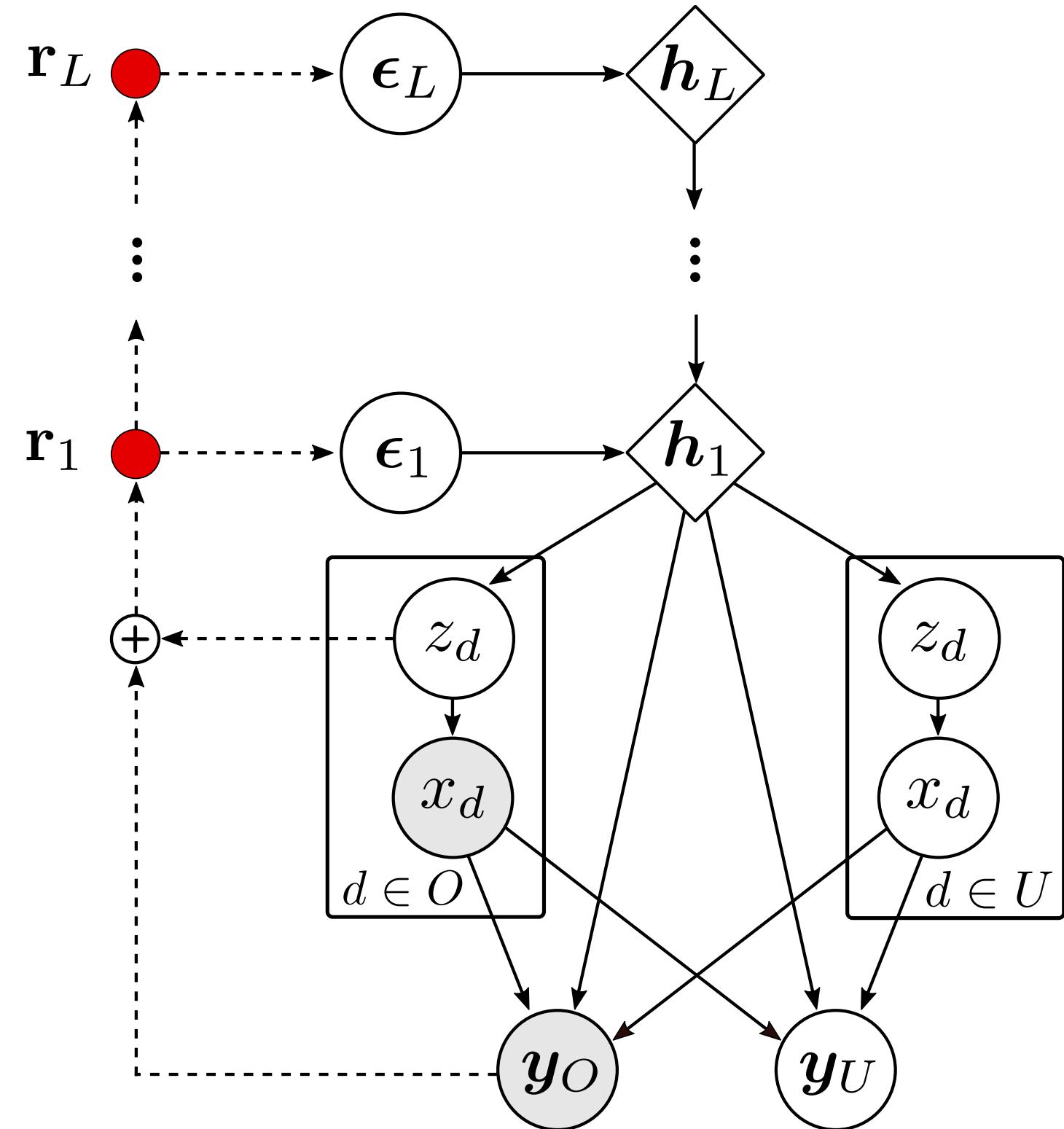
[6]



Contributions

Hierarchical Hamiltonian VAE for mixed-type incomplete data (HH-VAEM)

- Increased flexibility by using hierarchical latent space.
- Improved inference by means of automatically tuned HMC.
- Reparameterization for well-posed HMC on relaxed posterior.
- More accurate imputation and prediction.
- More effective information acquisition.





Information acquisition

Sampling-based method

- **Sampling**-based estimator [11] of the Mutual Information:

$$\begin{aligned} R(i, \mathbf{x}_O) &= D_{\text{KL}} [p(\mathbf{y}, x_i | \mathbf{x}_O) || p(\mathbf{y} | \mathbf{x}_O)p(x_i | \mathbf{x}_O)] = \mathcal{I}(\mathbf{y}; x_i | \mathbf{x}_O) = \\ &= \iint_{x_i, \mathbf{y}} p_{x_i, \mathbf{y} | \mathbf{x}_O}(x_i, \mathbf{y} | \mathbf{x}_O) \log \left(\frac{p_{x_i, \mathbf{y} | \mathbf{x}_O}(x_i, \mathbf{y} | \mathbf{x}_O)}{p_{x_i | \mathbf{x}_O}(x_i | \mathbf{x}_O)p_{\mathbf{y} | \mathbf{x}_O}(\mathbf{y} | \mathbf{x}_O)} \right) \end{aligned}$$

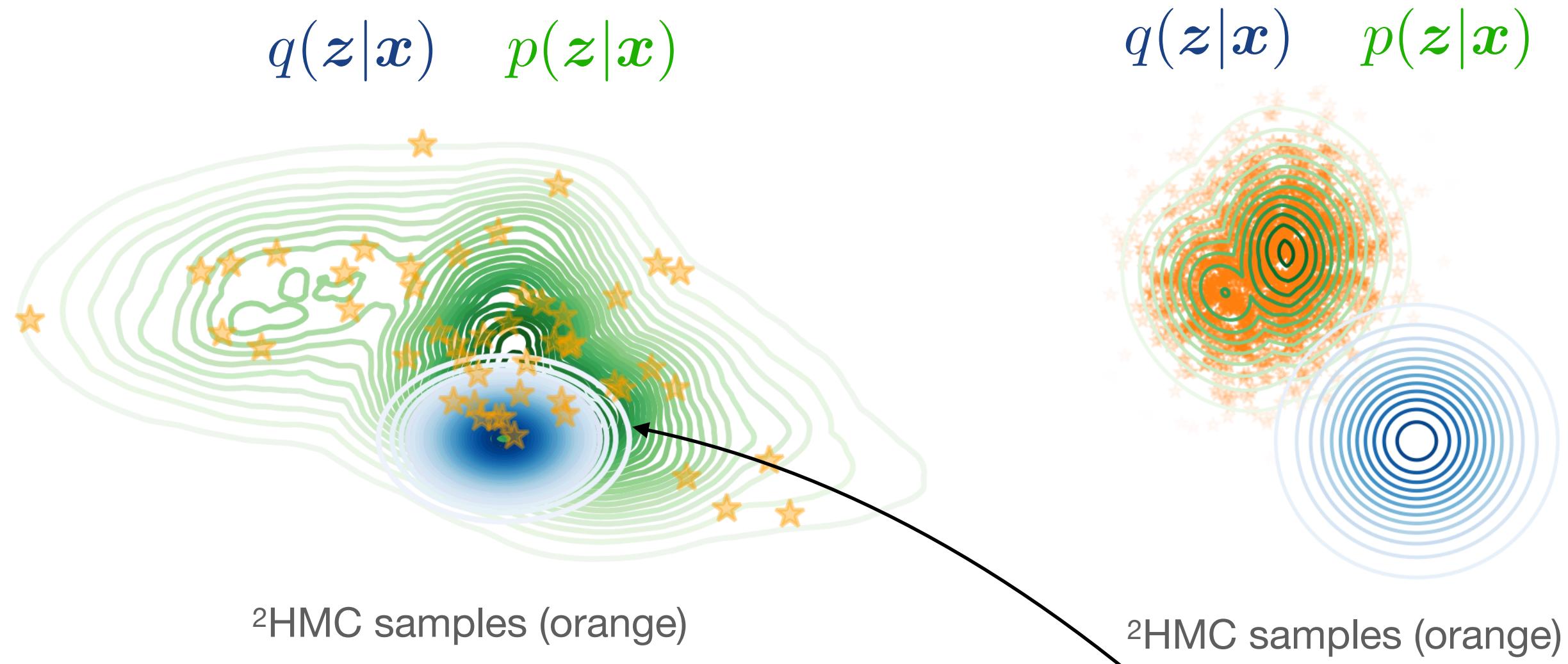
$$\hat{I}(\mathbf{y}; x_i | \mathbf{x}_O) \approx \sum_{ij} p_{x_i, \mathbf{y} | \mathbf{x}_O}(i, j) \log \frac{p_{x_i, \mathbf{y} | \mathbf{x}_O}(i, j)}{p_{x_i | \mathbf{x}_O}(i)p_{\mathbf{y} | \mathbf{x}_O}(j)}$$

- ✓ Avoids the Gaussian approximation
- ✓ Efficient, easy parallelization.

[11] Kraskov et al., 2004

HH-VAEM

Improving inference



$$\mathcal{L}(\mathbf{x}; \theta, \phi) = \mathbb{E}_{q_\phi(\mathbf{z}|\mathbf{x})} [\log p_\theta(\mathbf{x} \mid \mathbf{z})] - D_{KL} (q_\phi(\mathbf{z} \mid \mathbf{x}) \| p(\mathbf{z}))$$

$$\approx \frac{1}{S} \sum_{s=1}^S \log p_\theta(\mathbf{x} \mid \mathbf{z}^{(s)}) - D_{KL} (q_\phi(\mathbf{z} \mid \mathbf{x}) \| p(\mathbf{z}))$$

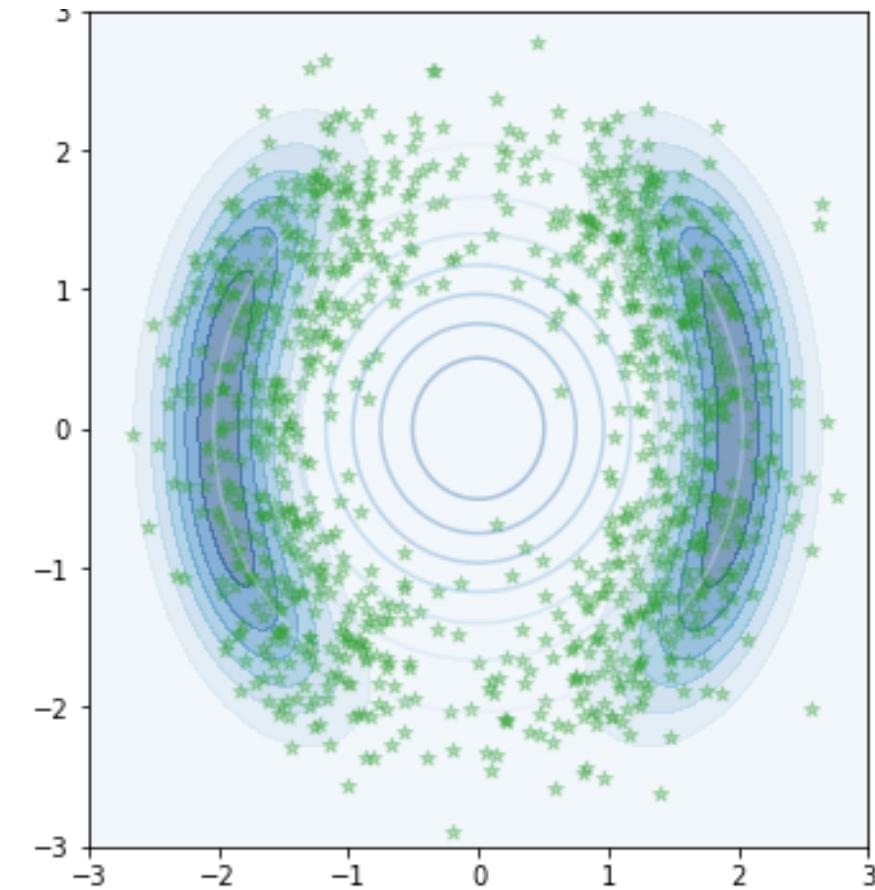
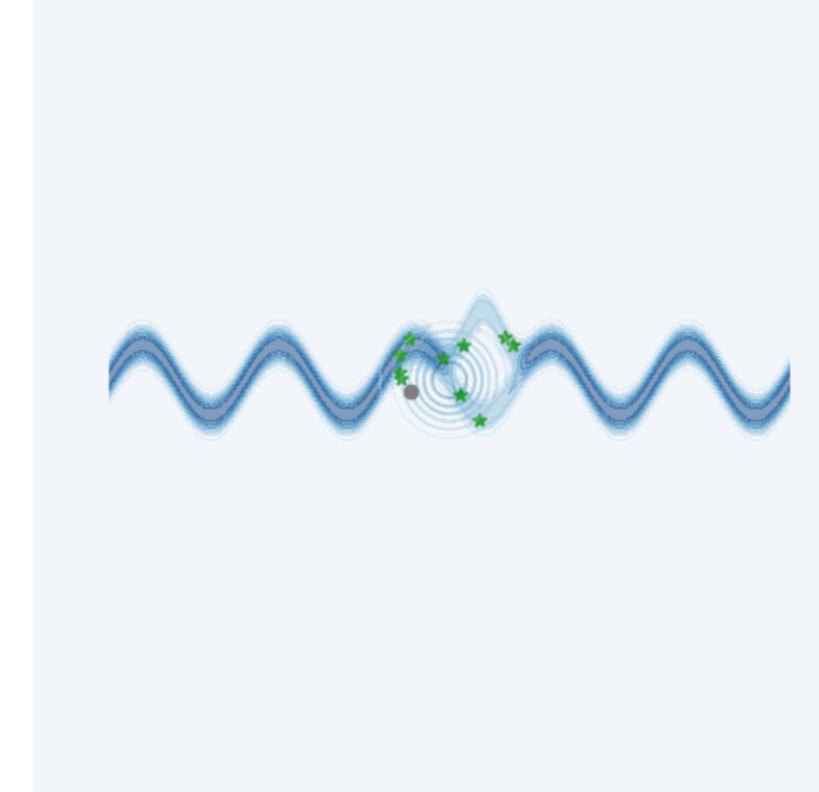
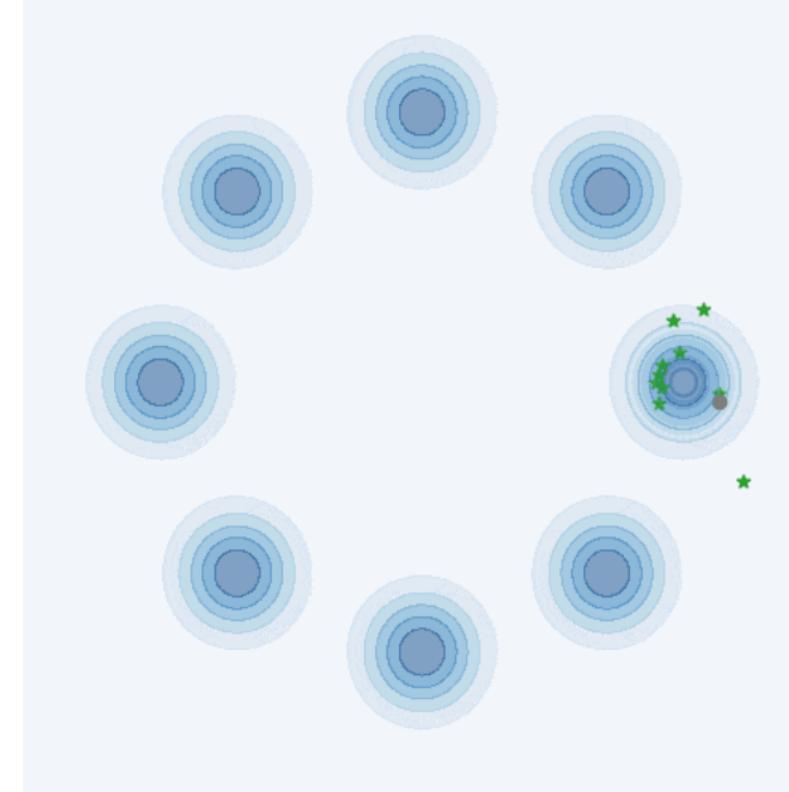
Hamiltonian Monte Carlo

Improving inference

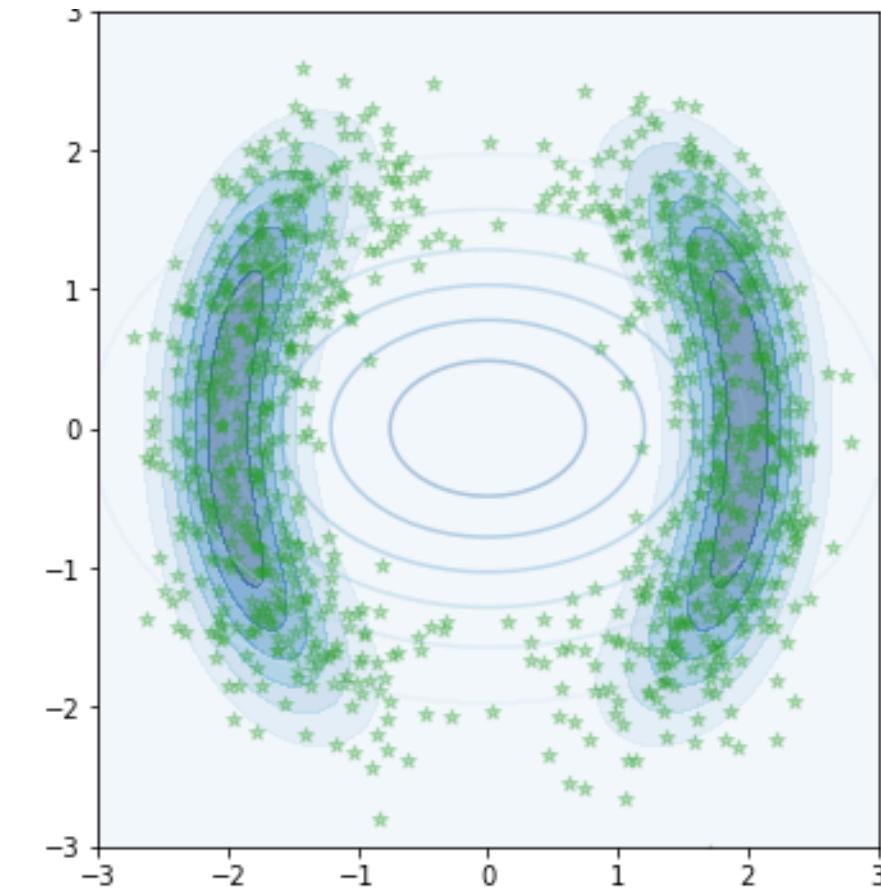
- Discrete trajectories (*chains*) of T updates, ending in:

$$q^{(T)}(\mathbf{z}|\mathbf{x}) \approx p(\mathbf{z}|\mathbf{x})$$

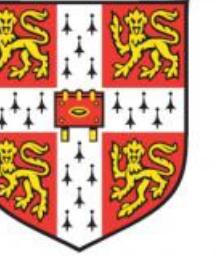
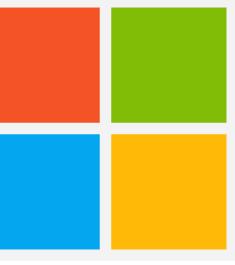
- Target: true posterior density.
- Needed:
 - 1. Good initial proposal (encoder).
 - 2. Well-defined hyperparameters.



Random hyperparameters



Tuned hyperparameters



Hamiltonian Monte Carlo

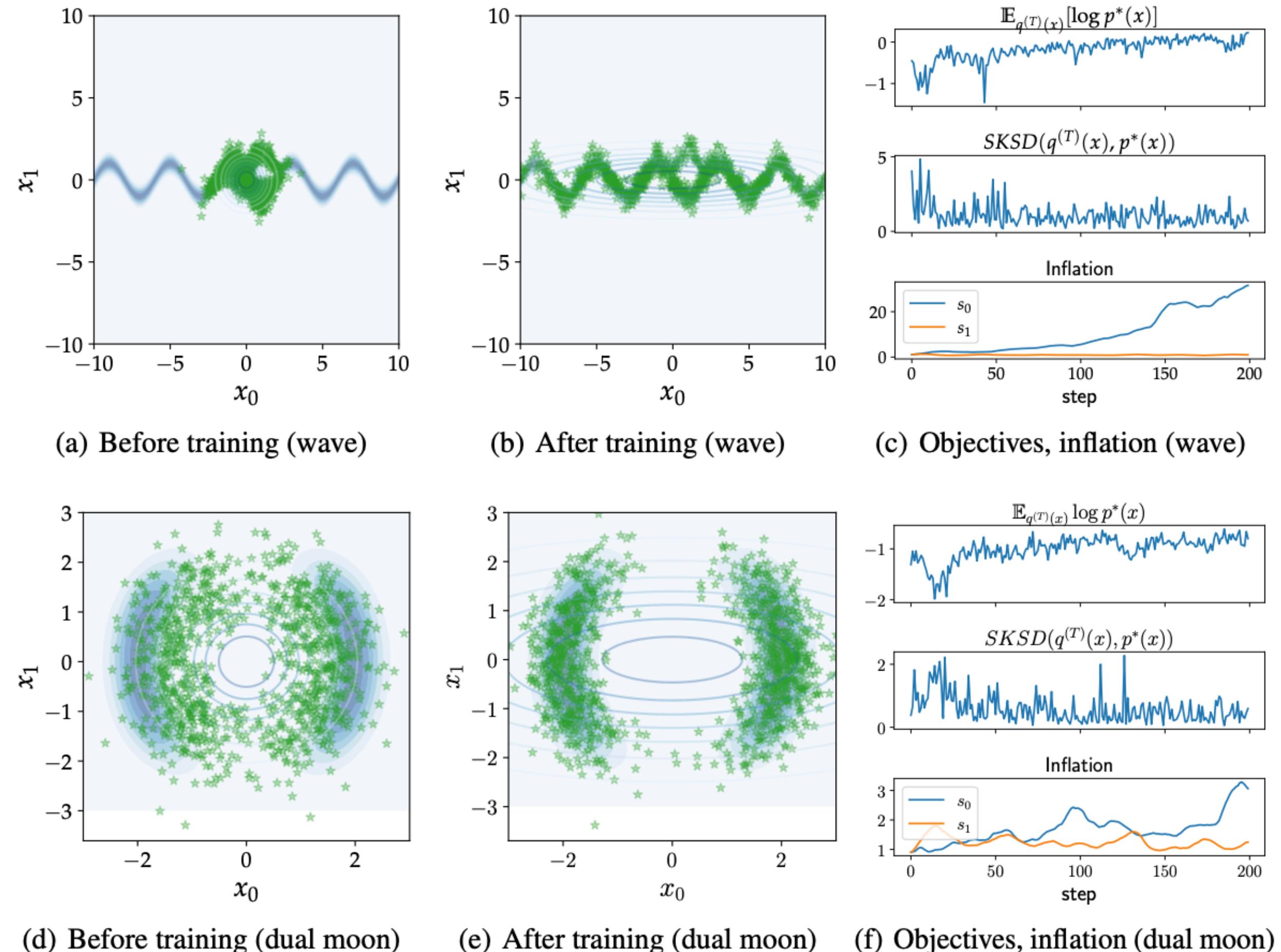
Hyperparameter tuning [7]

- Tuning the **hyperparameters** via Variational Inference:

$$\phi^* = \operatorname{argmax}_{\phi} \mathbb{E}_{q_{\phi}^{(T)}(\mathbf{z})} [\log p^*(\mathbf{z})] + H[q_{\phi}^{(T)}(\mathbf{z})]$$

- Add an **inflation** parameter for scaling the proposal [8]

$$s^* = \operatorname{argmin}_s \text{SKSD}(z^{(T)}, \nabla_z \log p^*(z))$$



[7] Campbell et al., 2021

[8] Gong et al., 2020

Hierarchical latent space

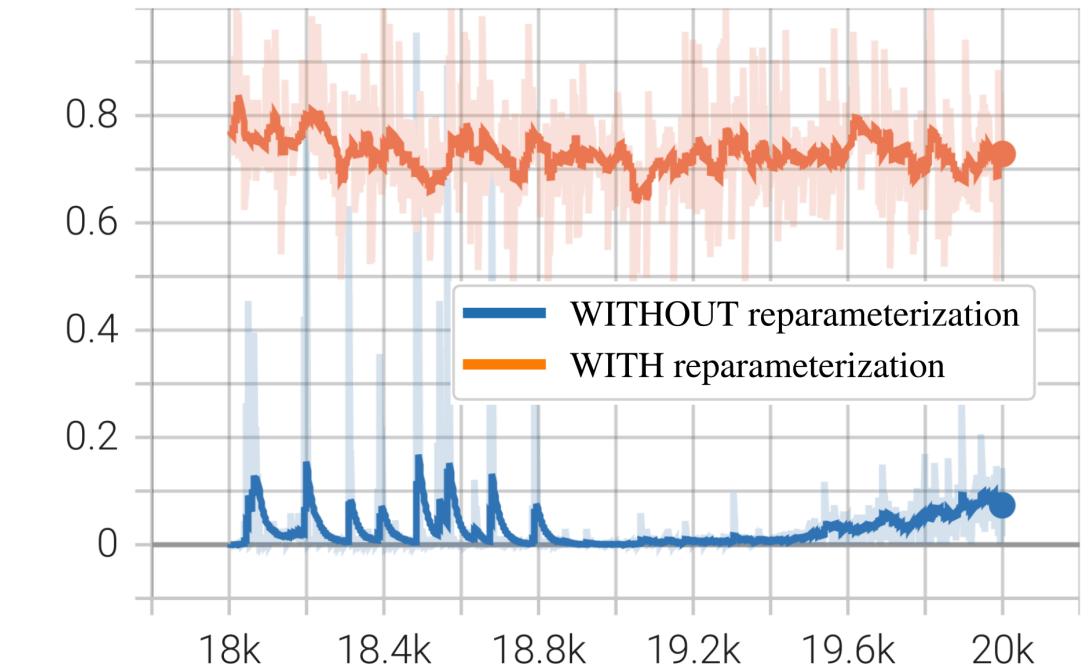
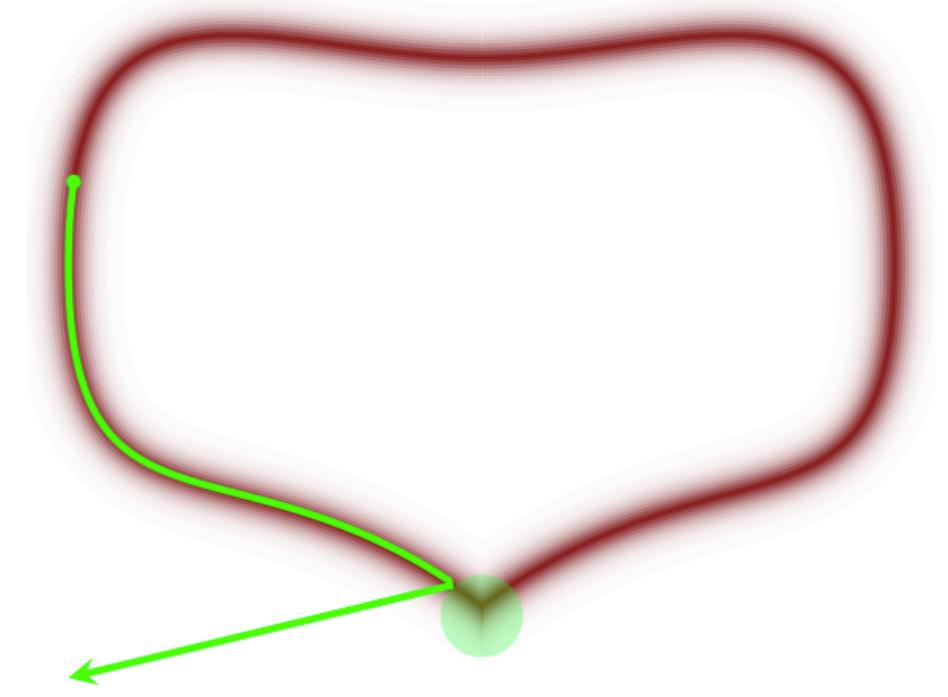
III-posed for HMC

- Hierarchical dependencies lead to **huge gradients [11, 12]**

$$\mathbf{r}_{l+\frac{1}{2}} = \mathbf{r}_l + \frac{1}{2} \boldsymbol{\phi} \odot \nabla_{z_l} \log p^*(\mathbf{z}_l),$$

$$\mathbf{z}_{l+1} = \mathbf{z}_k + \mathbf{r}_{l+\frac{1}{2}} \odot \boldsymbol{\phi} \odot \frac{1}{\mathbf{M}},$$

$$\mathbf{r}_{l+1} = \mathbf{r}_{l+\frac{1}{2}} + \frac{1}{2} \boldsymbol{\phi} \odot \nabla_{z_{l+1}} \log p^*(\mathbf{z}_{l+1}),$$



[9] Betancourt et al., 2017

[10] Betancourt et al., 2015

Hierarchical latent space

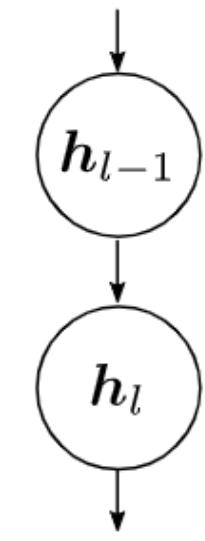
III-posed for HMC

- **Solution:**

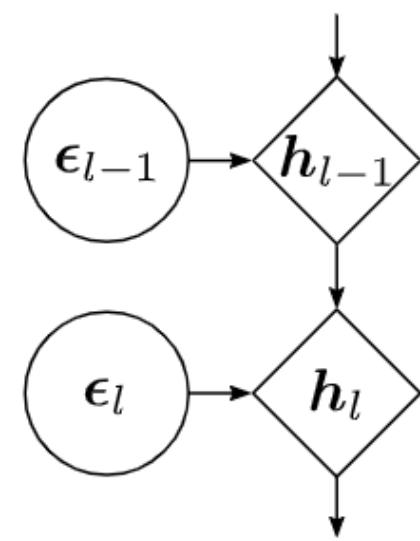
✓ Reparameterization for relaxed posterior:

$$\mathbf{h}_l = f_{\mu_l}(\mathbf{h}_{l+1}) + f_{\sigma_l}(\mathbf{h}_{l+1}) \cdot \boldsymbol{\epsilon}_l$$

NNs with parameters $\theta_{\mu_l} \rightarrow f_{\mu_l}$, $\theta_{\sigma_l} \rightarrow f_{\sigma_l}$



(a) AR hierarchy



(b) Reparameterization

Hierarchical latent space

III-posed for HMC

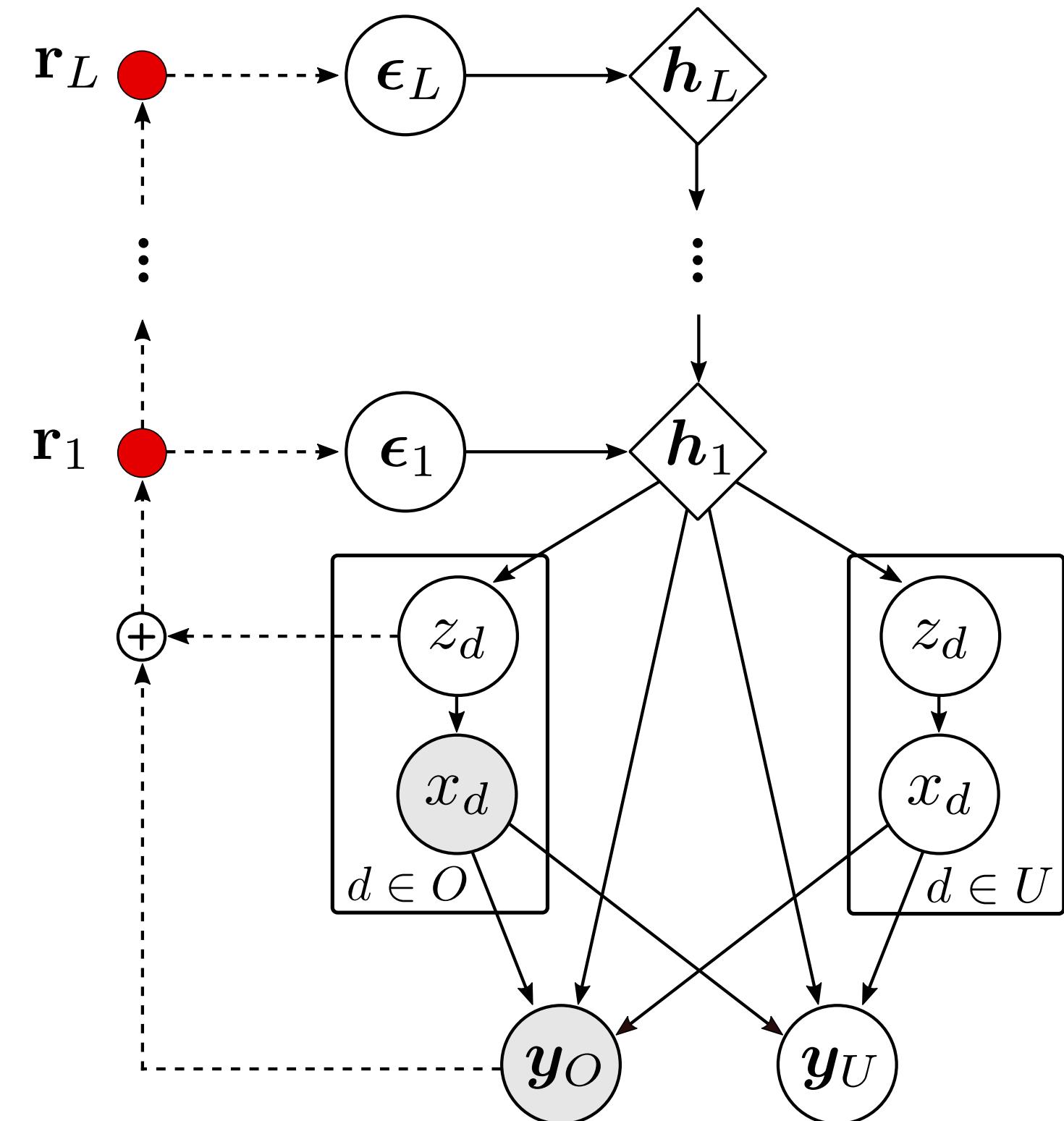
- **Solution:**

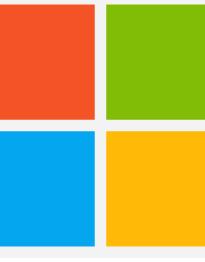
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NNs with parameters $\theta_{\mu_l} \rightarrow f_{\mu_l}$, $\theta_{\sigma_l} \rightarrow f_{\sigma_l}$

- ✓ Perform inference on $\boldsymbol{\epsilon} = \{\boldsymbol{\epsilon}_1, \dots, \boldsymbol{\epsilon}_L\}$ with standard Gaussian prior.
- ✓ No residual distributions needed.





Hierarchical latent space

III-posed for HMC

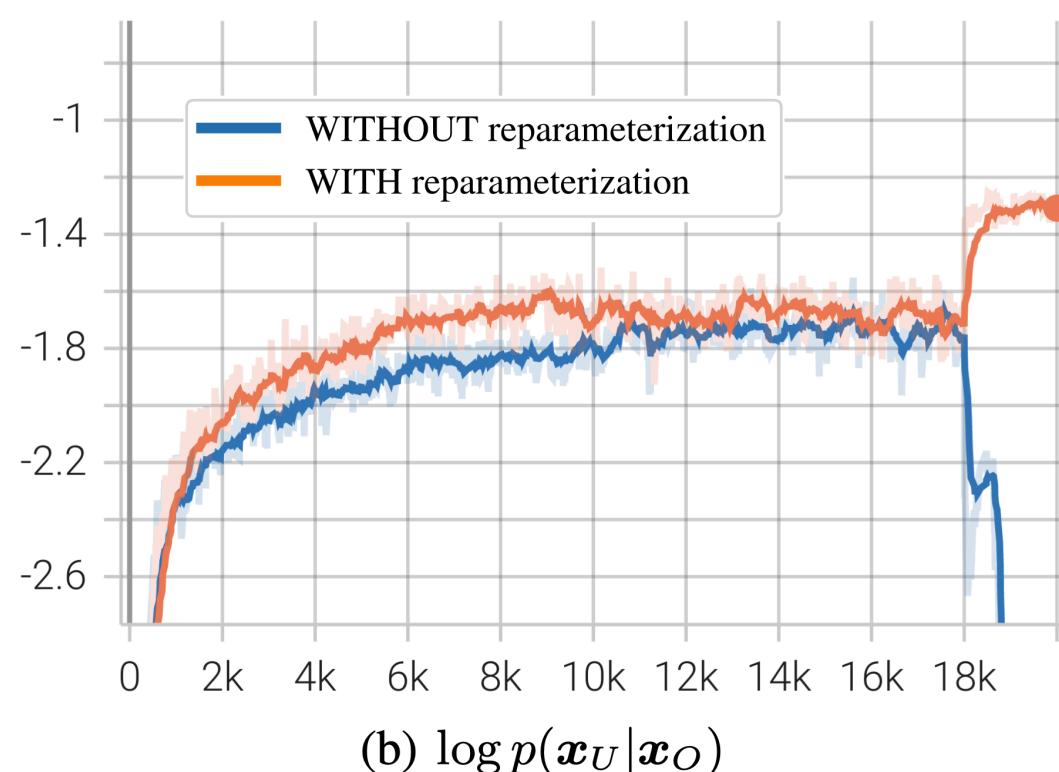
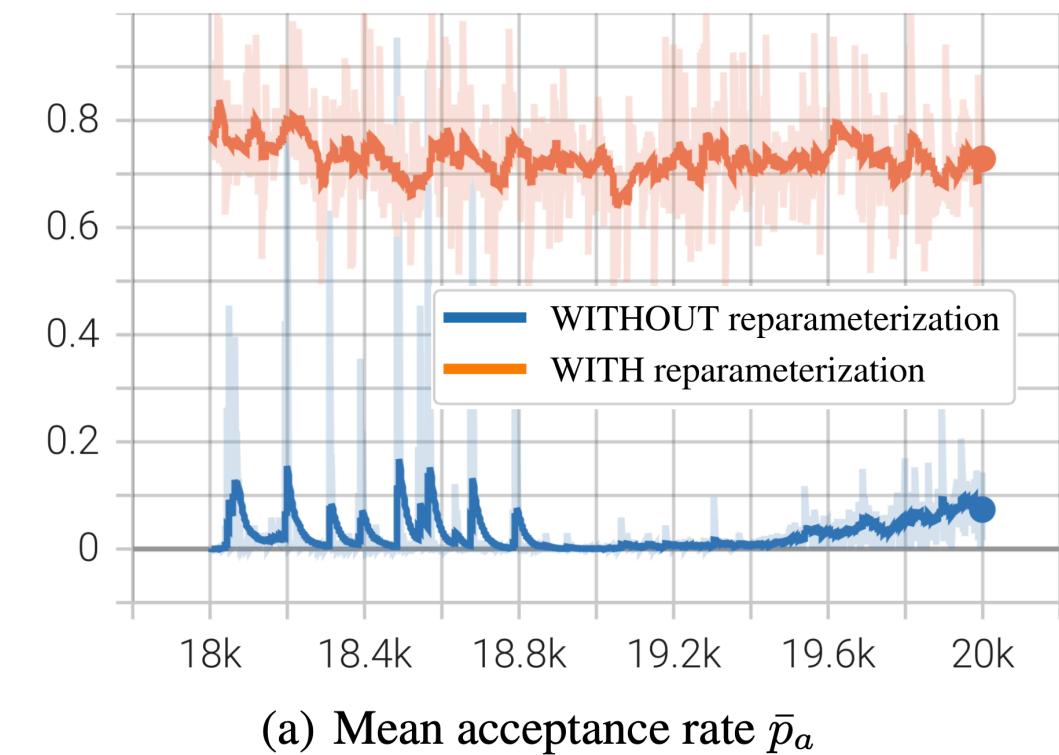
- **Solution:**

- ✓ Reparameterization for relaxed posterior:

$$\mathbf{h}_l = f_{\mu_l}(\mathbf{h}_{l+1}) + f_{\sigma_l}(\mathbf{h}_{l+1}) \cdot \boldsymbol{\epsilon}_l$$

NNs with parameters $\theta_{\mu_l} \rightarrow f_{\mu_l}$, $\theta_{\sigma_l} \rightarrow f_{\sigma_l}$

- ✓ Perform inference on $\boldsymbol{\epsilon} = \{\boldsymbol{\epsilon}_1, \dots, \boldsymbol{\epsilon}_1\}$ with standard Gaussian prior.
- ✓ No residual distributions needed.
- ✓ No need to increase complexity of the HMC method.



HH-VAEM

Optimization algorithm

Algorithm 1 Training algorithm for HH-VAEM

Input: data $(\mathbf{x}_O^{(1:N)}, \mathbf{y}_O^{(1:N)})$, steps: T_d, T_{VI}, T_{HMC}

Parameters: $\gamma, \theta, \psi, \phi, s$

STAGE 1: MARGINAL VAEs

for $d = 1$ **to** D **do**

 Initialize marginal VAE $\{\theta_d, \gamma_d\}$

for $t = 1$ **to** T_d **do**

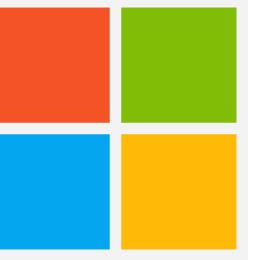
$\gamma_d^{t+1}, \theta_d^{t+1} \leftarrow \text{Adam}_{\gamma_d^t, \theta_d^t}(\mathcal{L}_d)$

end for

end for

- 1. Train marginal VAEs using:

$$\mathcal{L}_d(x_d; \{\theta_d, \gamma_d\}) = \mathbb{I}(x_d \in \mathbf{x}_O) \mathbb{E}_{q_{\gamma_d}(z_d|x_d)} \log \frac{p_{\theta_d}(x_d, z_d)}{q_{\gamma_d}(z_d | x_d)}$$



HH-VAEM

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Input: data $(\mathbf{x}_O^{(1:N)}, \mathbf{y}_O^{(1:N)})$, steps: T_d, T_{VI}, T_{HMC}

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STAGE 1: MARGINAL VAEs

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for $t = 1$ to T_d **do**

$\gamma_d^{t+1}, \theta_d^{t+1} \leftarrow \text{Adam}_{\gamma_d^t, \theta_d^t}(\mathcal{L}_d)$

end for

end for

STAGE 2: DEPENDENCY VAE

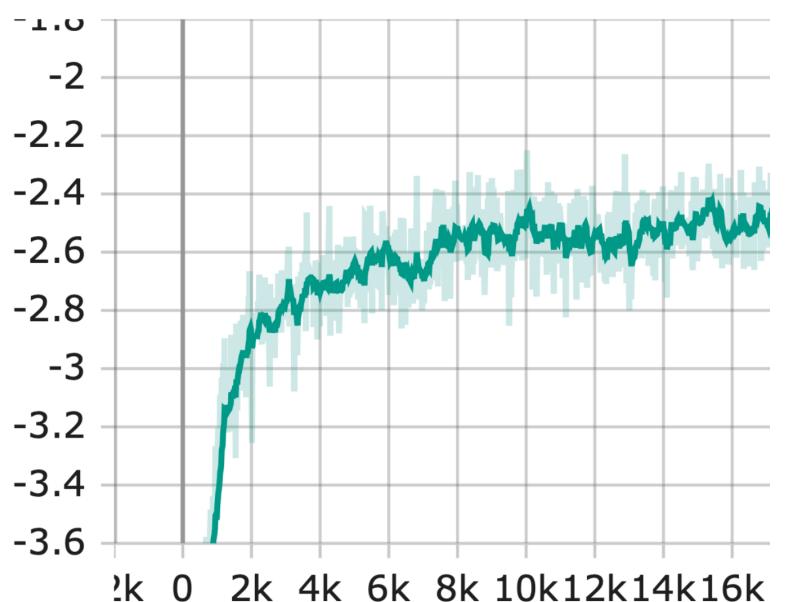
for $t = 1$ to T_{VAE} **do**

$\theta^{t+1}, \psi^{t+1} \leftarrow \text{Adam}_{\theta^t, \psi^t}(\mathcal{L}_{VI})$

end for

- 2. Training Hierarchical VAE using the ELBO:

$$\mathcal{L}_{VI} (\mathbf{x}_O, \mathbf{y}_O; \{\theta, \psi\}) = \mathbb{E}_{q_\psi} [\log p_\theta (\mathbf{z}_O | \mathbf{h}_1) + \log p_\theta (\mathbf{y}_O | \hat{\mathbf{x}}, \mathbf{h}_1)] - \sum_{l=1}^L D_{\text{KL}} (q_\psi (\boldsymbol{\epsilon}_l | \mathbf{x}_O, \mathbf{y}_O) \| p (\boldsymbol{\epsilon}_l))$$



(a) $\log p(\mathbf{x}_U | \mathbf{x}_O)$

HH-VAEM

Optimization algorithm

Algorithm 1 Training algorithm for HH-VAEM

Input: data $(\mathbf{x}_O^{(1:N)}, \mathbf{y}_O^{(1:N)})$, steps: T_d, T_{VI}, T_{HMC}

Parameters: $\gamma, \theta, \psi, \phi, s$

STAGE 1: MARGINAL VAEs

```

for  $d = 1$  to  $D$  do
    Initialize marginal VAE  $\{\theta_d, \gamma_d\}$ 
    for  $t = 1$  to  $T_d$  do
         $\gamma_d^{t+1}, \theta_d^{t+1} \leftarrow \text{Adam}_{\gamma_d^t, \theta_d^t}(\mathcal{L}_d)$ 
    end for
end for

```

STAGE 2: DEPENDENCY VAE

```

for  $t = 1$  to  $T_{VAE}$  do
     $\theta^{t+1}, \psi^{t+1} \leftarrow \text{Adam}_{\theta^t, \psi^t}(\mathcal{L}_{VI})$ 
end for

```

STAGE 3: JOINTLY OPTIMIZING VAE + HMC

```

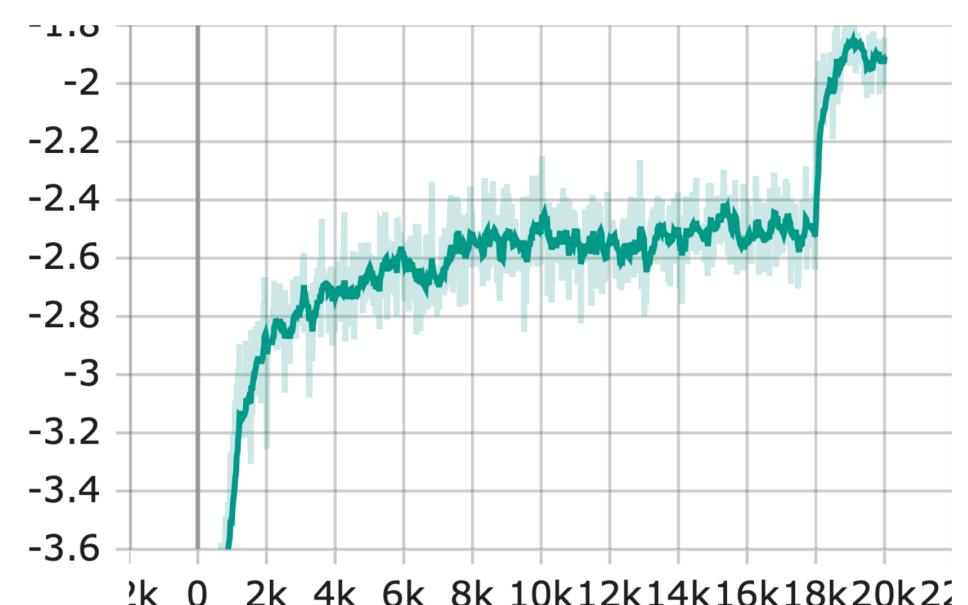
for  $t = 1$  to  $T_{HMC}$  do
     $\psi^{t+1} \leftarrow \text{Adam}_{\psi^t}(\mathcal{L}_{VI})$ 
     $\theta^{t+1}, \phi^{t+1} \leftarrow \text{Adam}_{\theta^t, \phi^t}(\mathcal{L}_{HMC})$ 
     $s^{t+1} \leftarrow \text{Adam}_{s^t}(\mathcal{L}_{SKSD})$ 
end for

```

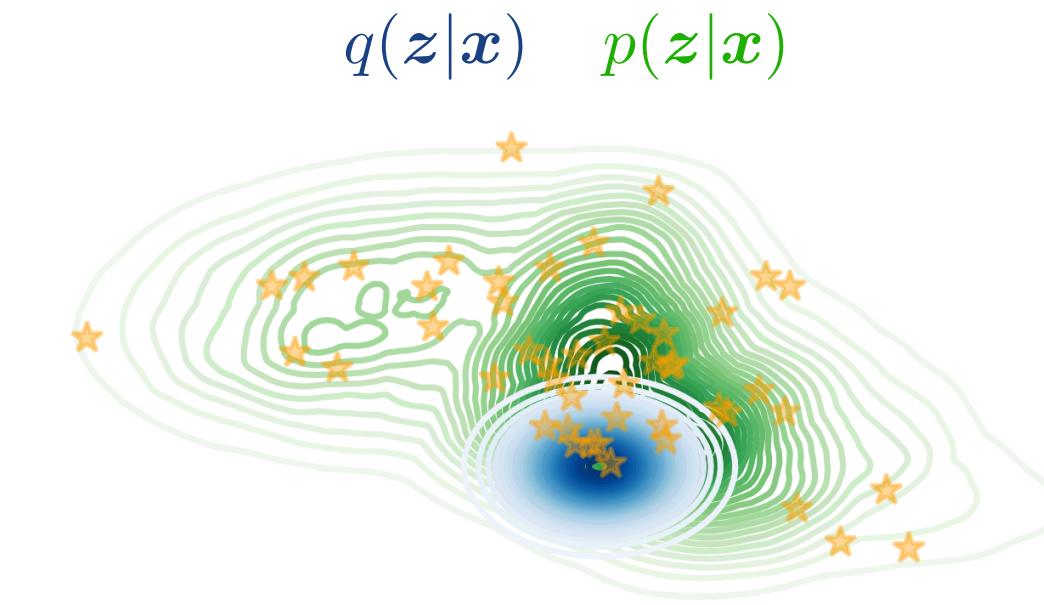
3. Train a) encoder using ELBO, b) HMC hyperparams, decoder and predictor parameters using HMC objective and c) scale using SKSD.

$$\mathcal{L}_{HMC}(\mathbf{z}_O, \mathbf{y}_O; \{\theta, \psi, \phi\}) = \mathbb{E}_{q_\phi^{(T)}(\epsilon)}[\log p_\theta(\mathbf{z}_O | \mathbf{h}_1) + \log p_\theta(\mathbf{y}_O | \hat{\mathbf{x}}, \mathbf{h}_1) + \sum_{l=1}^L p(\epsilon_l^{(T)})]$$

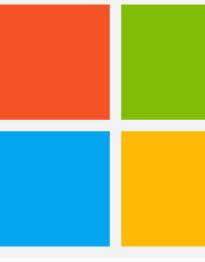
$$\mathcal{L}_{SKSD}(\mathbf{x}_O, \mathbf{y}_O; \mathbf{s}) = \text{SKSD}\left(q_\phi^{(T)}(\epsilon | \mathbf{z}_O, \mathbf{x}_O, \mathbf{y}_O; \mathbf{s}), p(\epsilon | \mathbf{z}_O, \mathbf{x}_O, \mathbf{y}_O)\right)$$



(a) $\log p(\mathbf{x}_U | \mathbf{x}_O)$



²HMC samples (orange)



Experiments

Mixed-type data

$$\log p(\mathbf{x}_U | \mathbf{x}_O) = \log \mathbb{E}_{\epsilon \sim q^{(T)}(\epsilon | \mathbf{x}_O)} [p(\mathbf{x}_U | \epsilon)] \approx \log \frac{1}{k} \sum_i^k p(\mathbf{x}_U | \epsilon_i)$$

	Bank	Insurance	Avocado	Naval	Yatch	Diabetes	Concrete	Wine	Energy	Boston
VAEM	2.84 ± 0.07	1.81 ± 0.03	1.89 ± 0.01	0.55 ± 0.05	3.15 ± 0.28	2.78 ± 0.16	2.45 ± 0.26	3.01 ± 0.61	2.09 ± 0.10	2.01 ± 0.23
MIWAEM	2.74 ± 0.05	1.88 ± 0.04	1.92 ± 0.04	0.57 ± 0.03	2.66 ± 0.11	2.55 ± 0.09	2.34 ± 0.51	2.76 ± 0.48	2.06 ± 0.14	1.94 ± 0.23
H-VAEM	2.82 ± 0.06	1.80 ± 0.04	1.89 ± 0.01	0.48 ± 0.06	3.06 ± 0.31	2.74 ± 0.09	2.42 ± 0.21	2.85 ± 0.56	1.72 ± 0.11	1.89 ± 0.24
HMC-VAEM	2.69 ± 0.05	1.77 ± 0.06	1.89 ± 0.02	0.49 ± 0.07	2.21 ± 0.24	2.72 ± 0.20	2.28 ± 0.29	2.83 ± 0.46	1.73 ± 0.05	1.83 ± 0.16
HH-VAEM	2.63 ± 0.04	1.75 ± 0.03	1.88 ± 0.05	0.40 ± 0.05	2.47 ± 0.27	2.54 ± 0.13	2.28 ± 0.09	1.90 ± 0.17	1.71 ± 0.04	1.83 ± 0.11

Table 1: Test negative log likelihood of the unobserved features for our model and baselines.

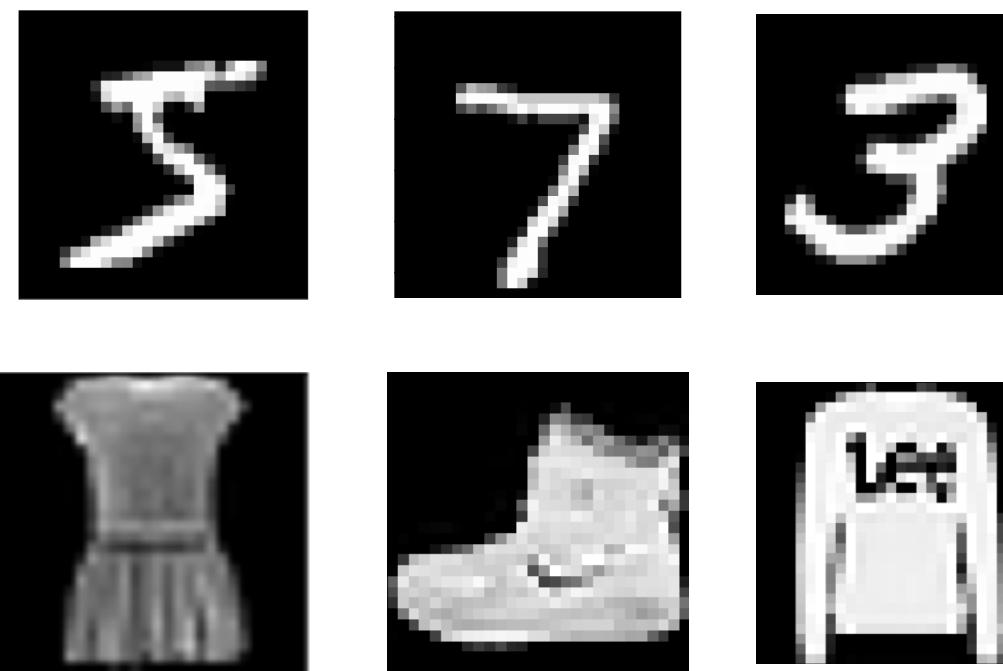
$$\log p(\mathbf{y} | \mathbf{x}_O) = \log \mathbb{E}_{\epsilon \sim q^{(T)}(\epsilon | \mathbf{x}_O)} [p(\mathbf{y} | \epsilon)] \approx \log \frac{1}{k} \sum_i^k p(\mathbf{y} | \epsilon_i),$$

	Bank	Insurance	Avocado	Naval	Yatch	Diabetes	Concrete	Wine	Energy	Boston
VAEM	0.56 ± 0.06	1.20 ± 0.03	1.18 ± 0.02	2.69 ± 0.01	0.61 ± 0.02	1.59 ± 0.19	1.07 ± 0.09	0.28 ± 0.09	0.61 ± 0.14	0.85 ± 0.21
MIWAEM	0.51 ± 0.03	1.15 ± 0.03	1.15 ± 0.03	2.70 ± 0.01	0.60 ± 0.03	1.36 ± 0.10	0.95 ± 0.22	0.28 ± 0.13	0.54 ± 0.12	0.80 ± 0.21
H-VAEM	0.50 ± 0.03	1.06 ± 0.02	1.18 ± 0.02	2.68 ± 0.01	0.60 ± 0.02	1.71 ± 0.14	1.02 ± 0.09	0.26 ± 0.11	0.46 ± 0.14	0.90 ± 0.22
HMC-VAEM	0.52 ± 0.02	1.00 ± 0.03	1.12 ± 0.03	2.71 ± 0.01	0.52 ± 0.15	1.55 ± 0.29	0.95 ± 0.26	0.28 ± 0.09	0.41 ± 0.07	0.71 ± 0.13
HH-VAEM	0.49 ± 0.03	0.93 ± 0.06	1.10 ± 0.01	2.62 ± 0.01	0.56 ± 0.02	1.38 ± 0.18	0.95 ± 0.08	0.20 ± 0.04	0.32 ± 0.05	0.55 ± 0.04

Table 2: Test negative log likelihood of the predicted target for our model and baselines.

Experiments

MNIST datasets



	VAE	MIWAE	H-VAE	HMC-VAE	HH-VAE
MNIST	0.124 ± 0.001	0.121 ± 0.001	0.119 ± 0.001	0.101 ± 0.004	0.094 ± 0.003
F-MNIST	0.162 ± 0.002	0.160 ± 0.002	0.156 ± 0.002	0.150 ± 0.002	0.144 ± 0.002

Table 3: Test negative log likelihood of the unobserved features for the MNIST datasets.

	VAE	MIWAE	H-VAE	HMC-VAE	HH-VAE
MNIST	0.153 ± 0.009	0.151 ± 0.007	0.146 ± 0.006	0.067 ± 0.007	0.056 ± 0.019
F-MNIST	0.501 ± 0.012	0.496 ± 0.008	0.494 ± 0.007	0.357 ± 0.060	0.337 ± 0.069

Table 4: Test negative log likelihood of the predicted target for the MNIST datasets.

	VAE	MIWAE	H-VAE	HMC-VAE	HH-VAE
MNIST	0.953 ± 0.004	0.953 ± 0.003	0.953 ± 0.003	0.978 ± 0.003	0.981 ± 0.005
F-MNIST	0.824 ± 0.005	0.824 ± 0.004	0.824 ± 0.004	0.869 ± 0.015	0.876 ± 0.017

Table 5: Test accuracy of the predicted digits for the MNIST datasets.

Experiments

Sequential Active Information Acquisition (SAIA)

- Sequentially acquiring high-value information by selecting features that maximize

$$\hat{I}(\mathbf{y}; \mathbf{x}_i \mid \mathbf{x}_O) \approx \sum_{ij} p_{x_i, \mathbf{y} | \mathbf{x}_O}(i, j) \log \frac{p_{x_i, \mathbf{y} | \mathbf{x}_O}(i, j)}{p_{x_i | \mathbf{x}_O}(i)p_{\mathbf{y} | \mathbf{x}_O}(j)}$$

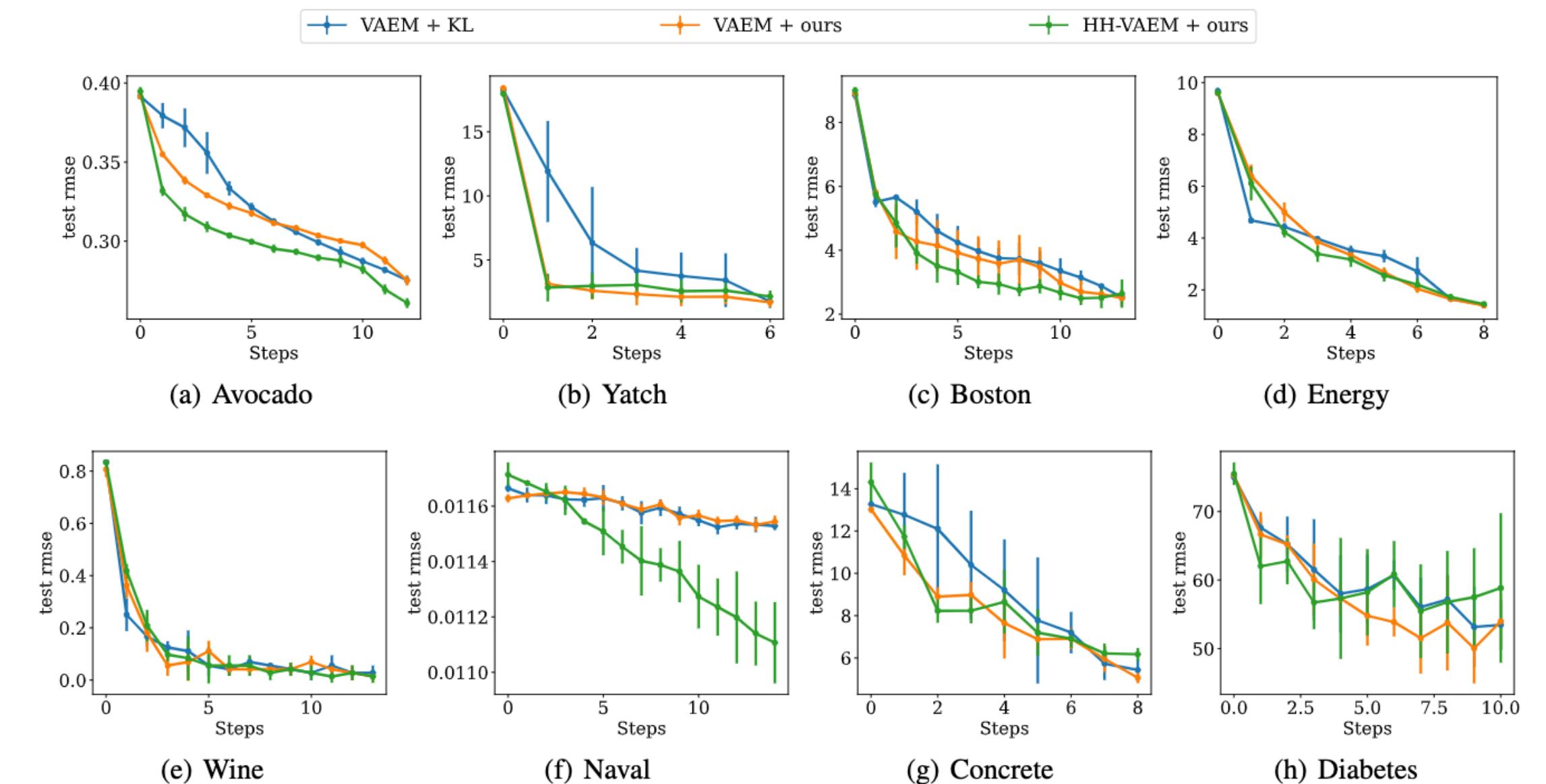


Figure 5: SAIA metric curves. Horizontal axis shows acquisition steps (number of discovered features). Vertical axis is the RMSE.

Experiments

Conditional image inpainting

1. Encode to $q_{\phi}^{(0)}(\epsilon | z_O, x_O, y_O)$
2. Using HMC, sample from $q_{\phi}^{(T)}(\epsilon | z_O, x_O, y_O)$
3. Decode to $p(x_U | \epsilon^{(T)})$



	Original	Observed	VAE	H-VAE	HMC-VAE	HH-VAE
Original						
Observed						
VAE						
H-VAE						
HMC-VAE						
HH-VAE						

Conclusion

- We presented:
 1. **HH-VAEM**: novel Hierarchical VAE improved with HMC with automatic hyperparameter optimization.
 2. Novel **sampling-based technique** based on the Mutual Information estimation for efficient information acquisition.
- Based on the provided experiments, we demonstrate that our methods:
 - ✓ Improve approximate inference in hierarchical VAEs wrt to the Gaussian approximation.
 - ✓ Improve missing data imputation task.
 - ✓ Improve prediction task.
 - ✓ Improve active information acquisition task.

References

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