

Missing Data Imputation and Acquisition with Deep Hierarchical Models and Hamiltonian Monte Carlo

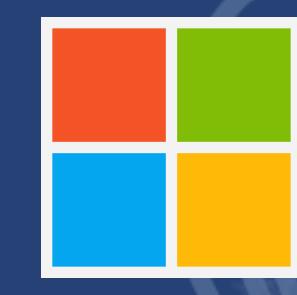
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Summary

- Goal: impute, predict, acquire information from heterogeneous incomplete data using $p(x_i, \mathbf{y} | \mathbf{x}_O) \approx \mathbb{E}_{q^{(T)}(\mathbf{h} | \mathbf{x}_O)} [p(x_i, \mathbf{y} | \mathbf{h})]$, where samples from $q^{(T)}(\mathbf{h} | \mathbf{x}_O)$ approximately follow the true posterior.
- We present **HH-VAEM**, a deep hierarchical model for handling mixed-type incomplete data with automatically tuned HMC.
- We propose a sampling-based strategy for feature acquisition that benefits from the improved inference of HH-VAEM.

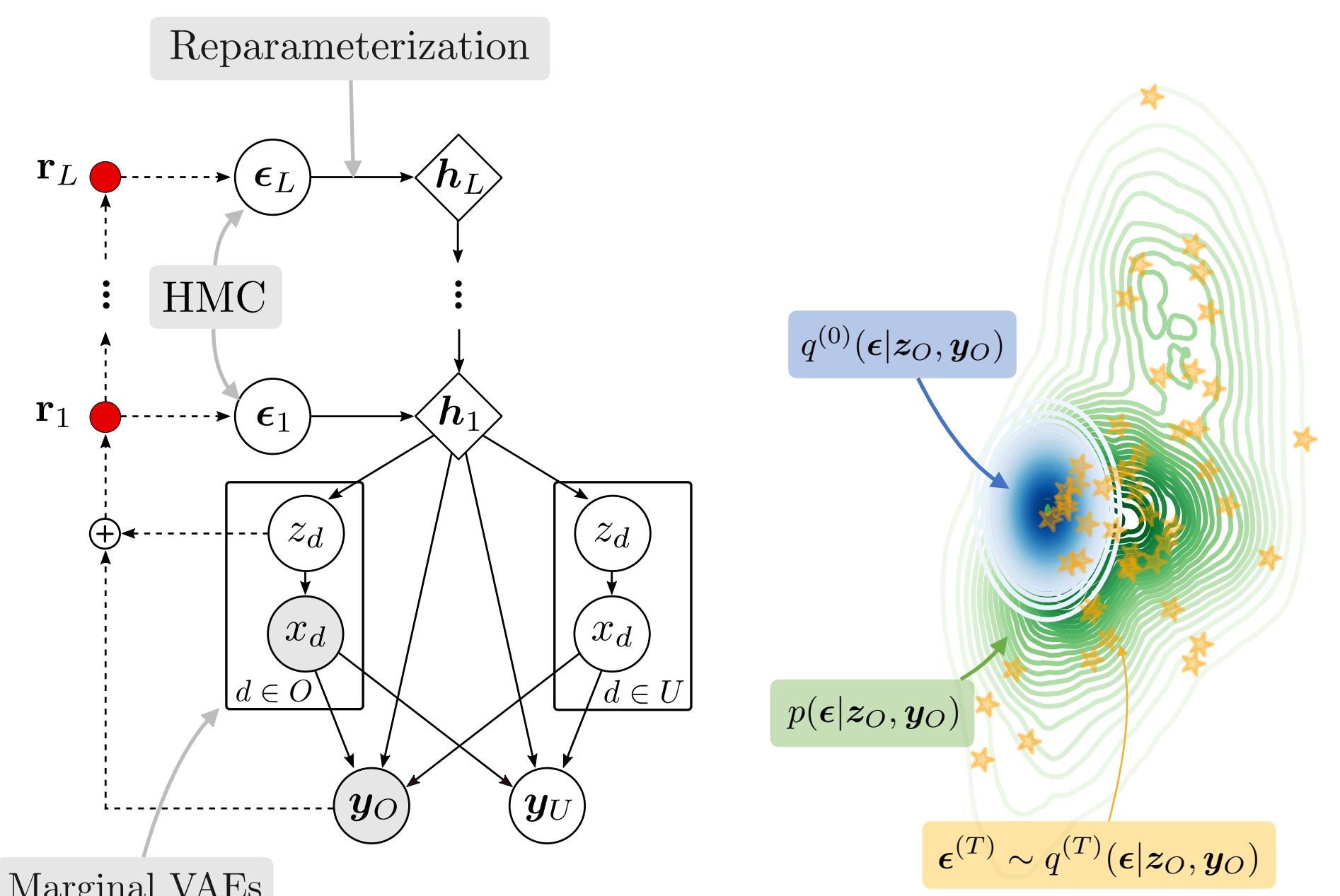


Figure 1: HH-VAEM model (left) and HMC example (right).

Hierarchical VAE and HMC

- Increase model flexibility with a **hierarchical latent space** $\mathbf{h} = \{\mathbf{h}_1, \dots, \mathbf{h}_L\}$ where $\mathbf{h}_l \sim p(\mathbf{h}_l | \mathbf{h}_{l+1})$.
- Reparameterization** for reducing strong curvature regions where $\nabla_{\mathbf{h}_{1:L}} \log p^*(\mathbf{h}_{1:L}) \uparrow\uparrow$:

$$\mathbf{h}_l = f_{\mu_l}(\mathbf{h}_{l+1}) + f_{\sigma_l}(\mathbf{h}_{l+1}) \cdot \epsilon_l$$

- Improving posterior approximation by means of **well-posed HMC** to sample $\epsilon^{(T)} \sim q^{(T)}(\epsilon | z_O, y_O)$.
- Automatically tune HMC hyperparams** for efficiently explore posterior distribution.

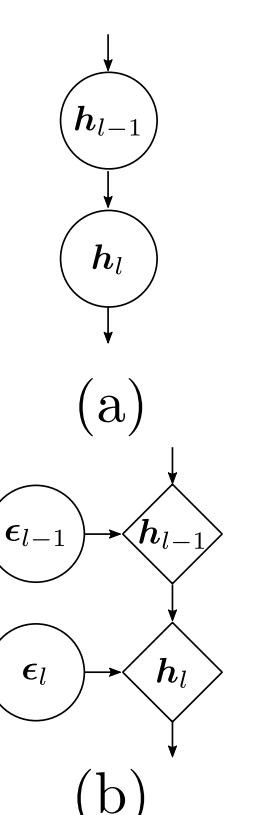


Figure 2: AR (a),
Reparam. (b).

Motivation

Low bias samples from HMC and hierarchically enriched model improve the three considered tasks:

- Imputation:** $p(\mathbf{x}_U | \mathbf{x}_O) \approx \mathbb{E}_{q^{(T)}(\epsilon | \mathbf{x}_O)} [p(\mathbf{x}_U | \epsilon)]$.
- Prediction:** $p(\mathbf{y} | \mathbf{x}_O) \approx \mathbb{E}_{q^{(T)}(\epsilon | \mathbf{x}_O)} [p(\mathbf{y} | \epsilon, \mathbf{x}_O, \hat{\mathbf{x}}_U)]$.
- Sampling-based active learning.**

Training

- Train **marginal VAEs** $\{\theta_d, \gamma_d\}_{d=1}^D$ to standardize heterogeneous data.
- Pre-train **dependency VAE** $\{\psi, \theta_z, \theta_y\}$ using \mathcal{L}_{VI} .
- Fine-tune encoder using \mathcal{L}_{VI} , decoder, predictor and **HMC hyperparams** ϕ using \mathcal{L}_{HMC} with initial proposal $q^{(0)}$ inflated by s , and **inflation parameter** s using \mathcal{L}_{SKSD} .

$$\begin{aligned}\mathcal{L}_{VI}(\mathbf{z}_O, \mathbf{y}_O; \{\theta, \psi\}) &= \mathbb{E}_{q_\psi} \left[\log \frac{p_\theta(\mathbf{z}_O, \mathbf{y}_O, \epsilon)}{q_\psi(\epsilon | \mathbf{z}_O, \mathbf{y}_O)} \right] \\ \mathcal{L}_{HMC}(\mathbf{z}_O, \mathbf{y}_O; \{\theta, \phi\}) &= \mathbb{E}_{q_\phi^{(T)}(\epsilon)} [\log p_\theta(\mathbf{z}_O, \mathbf{y}_O, \epsilon)] \\ \mathcal{L}_{SKSD}(\mathbf{z}_O, \mathbf{y}_O; s) &= SKSD \left(q_\phi^{(T)}(\epsilon | \mathbf{z}_O, \mathbf{y}_O; s), p(\epsilon | \mathbf{z}_O, \mathbf{y}_O) \right)\end{aligned}$$

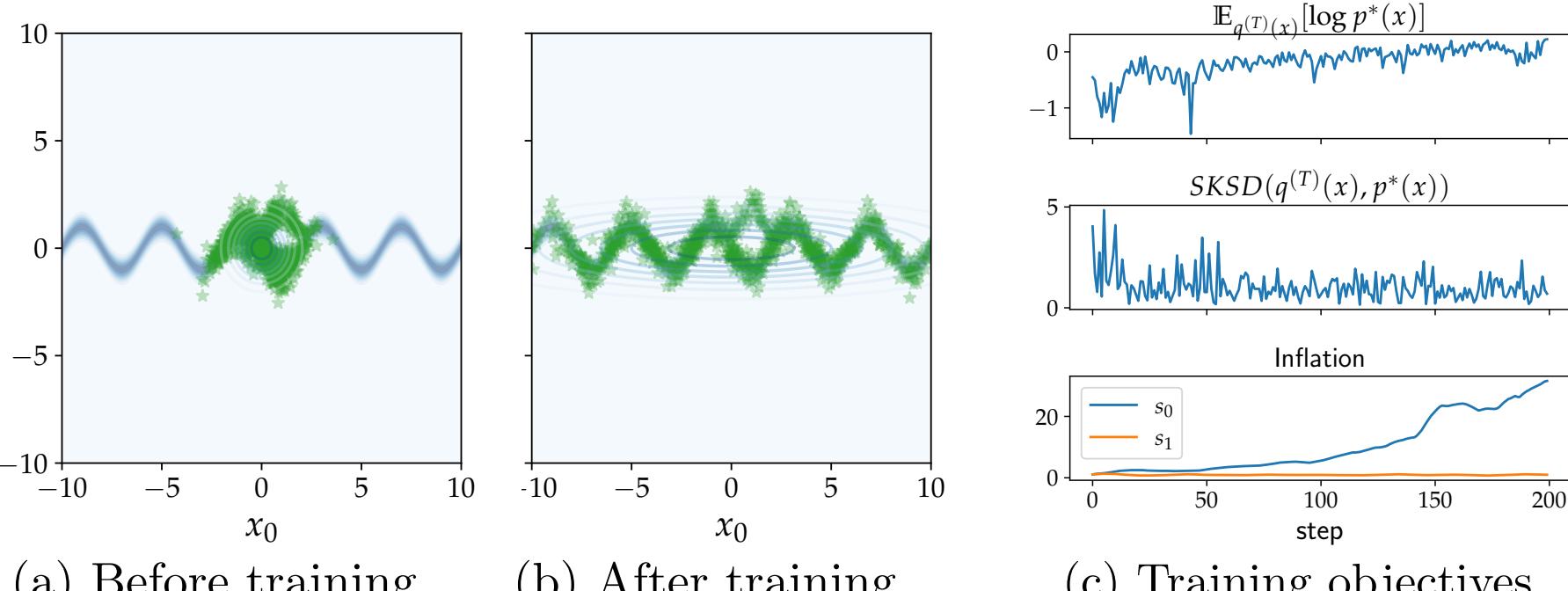


Figure 3: HMC training example.

Sampling-Based Active Learning

- Sampling-based** information reward estimator for acquiring variables x_i to accurately predict \mathbf{y} :

$$\hat{R}_I = \hat{I}(\mathbf{y}, x_i | \mathbf{x}_O) \approx \sum_{ij} \hat{p}_{x_i, \mathbf{y} | \mathbf{x}_O}(i, j) \log \frac{\hat{p}_{x_i, \mathbf{y} | \mathbf{x}_O}(i, j)}{\hat{p}_{x_i | \mathbf{x}_O}(i) \hat{p}_{\mathbf{y} | \mathbf{x}_O}(j)}$$

that uses **HMC** in $p(x_i, \mathbf{y} | \mathbf{x}_O) \approx \mathbb{E}_{q^{(T)}(\epsilon | \mathbf{x}_O)} [p(x_i, \mathbf{y} | \epsilon)]$, instead of the Gaussian alternative (Figure 1).

Experiments

	VAE(M)	MIWAE(M)	H-VAE(M)	HMC-VAE(M)	HH-VAE(M)
MNIST	0.124 ± 0.001	0.121 ± 0.001	0.119 ± 0.001	0.101 ± 0.004	0.094 ± 0.00
F-MNIST	0.162 ± 0.002	0.160 ± 0.002	0.156 ± 0.002	0.150 ± 0.002	0.144 ± 0.00
Avocado	1.89 ± 0.01	1.92 ± 0.04	1.89 ± 0.01	1.89 ± 0.02	1.88 ± 0.0
Bank	2.84 ± 0.07	2.74 ± 0.05	2.82 ± 0.06	2.69 ± 0.05	2.63 ± 0.0
MNIST	0.153 ± 0.009	0.151 ± 0.007	0.146 ± 0.006	0.067 ± 0.007	0.056 ± 0.01
F-MNIST	0.501 ± 0.012	0.496 ± 0.008	0.494 ± 0.007	0.357 ± 0.060	0.337 ± 0.06
Bank	1.18 ± 0.02	1.15 ± 0.03	1.18 ± 0.02	1.12 ± 0.03	1.10 ± 0.0
Accuracy	0.953 ± 0.004	0.953 ± 0.003	0.953 ± 0.003	0.978 ± 0.003	0.981 ± 0.00
F-MNIST	0.824 ± 0.005	0.824 ± 0.004	0.824 ± 0.004	0.869 ± 0.015	0.876 ± 0.01

Table 1: Imputation and prediction evaluation.

$$\begin{aligned}\log p(\mathbf{x}_U | \mathbf{x}_O) &\approx \log \mathbb{E}_{q^{(T)}(\epsilon | \mathbf{x}_O)} [p(\mathbf{x}_U | \epsilon)] \approx \log \frac{1}{k} \sum_i^k p(\mathbf{x}_U | \epsilon_i^{(T)}) \\ \log p(\mathbf{y} | \mathbf{x}_O) &\approx \log \mathbb{E}_{q^{(T)}(\epsilon | \mathbf{x}_O)} [p(\mathbf{y} | \epsilon, \hat{\mathbf{x}})] \approx \log \frac{1}{k} \sum_i^k p(\mathbf{y} | \epsilon_i^{(T)}, \hat{\mathbf{x}})\end{aligned}$$

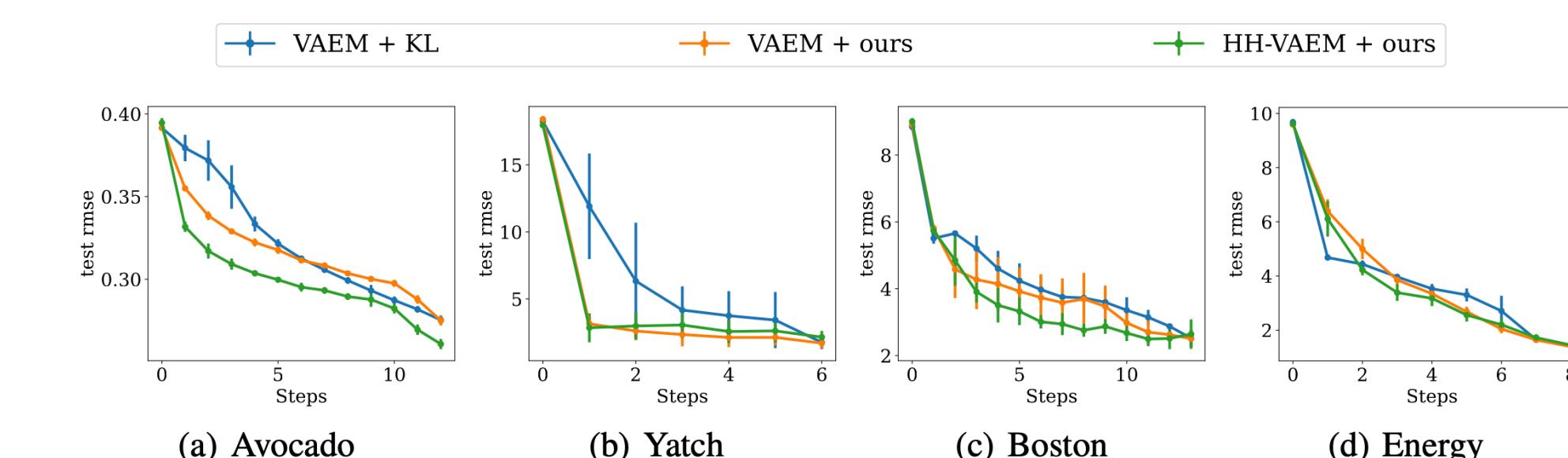


Figure 4: SAIA curves. RMSE vs number of discovered features.



Figure 5: Image conditional inpainting on CelebA (left) and MNIST (right)

Acknowledgements

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