




ISAAC S. PERPER

Dillon Beach, CA 94929
415-308-2791 (cell)

 isaacperper.com
 isaac.perper@gmail.com
 [isaac-perper-01](https://www.linkedin.com/in/isaac-perper-01)

EDUCATION

Massachusetts Institute of Technology

Cambridge, MA

B.Sc. Mechanical Engineering and B.Sc. EECS; Minor in Economics - 5.0/5.0 GPA

June 2020

Pi Tau Sigma | Tau Beta Pi

Relevant Coursework: Visual Navigation for Autonomous Vehicles, Underactuated Robotics, Signals and Systems, Product Engineering Process, Probability, Statistics, Intro to Machine Learning, Intro to Algorithms

RESEARCH EXPERIENCE

MIT SeaGrant & CSAIL – AUV Lab

Cambridge, MA

Student Researcher

Summer 2018, Spring 2019, Spring 2020

- Currently developing and testing marine object detection algorithms, focusing on robustness in different weather conditions and environments
- Previously researched machine learning techniques for object detection using thermal imagery, including image segmentation and boundary detection of the water
- Created battery management application for front-seat computer and sensors on REX unmanned surface vehicle

MIT Dept. of Nuclear Science and Engineering – Green Lab

Cambridge, MA

Student Researcher

Spring 2017

- Experimentally researched a quantifiable approach to improving the critical heat flux of various materials used in nuclear energy production through surface engineering
- Designed, machined, and fabricated test boiling chamber to use in tests

16.485 – Visual Navigation for Autonomous Vehicles

Cambridge, MA

Class Project: Visual Inertial Odometry + Vehicle Dynamics

Fall 2019

- Implemented Kimera visual inertial odometry on a ground track robot
- Worked with two teammates to design and test dynamics model to improve position estimation via Kalman filter

WORK EXPERIENCE

Ford Research and Innovation Center

Palo Alto, CA

Intern

Summer 2019

- Worked on a self-contained project integrating vehicle control and vision system with simulation tools to test new research features in a simulated environment
- Engaged with multiple engineers responsible for specific components of the controls and simulation
- Won first place out of six teams at the office-wide summer hackathon

Augmenta Bioworks

Mountain View, CA

Intern

Summer 2017

- Designed and fabricated a prototype automation system independently that will enable analysis of lab processes
- Created Python-based control script to interface with several devices over serial communication protocol

LEADERSHIP

Phi Sigma Kappa Fraternity

Boston, MA

President, Treasurer

2018 - 2019

- Oversaw operations of each sub-department and housing, including serving as semester's risk manager
- Conducted weekly house meetings and reviewed day-to-day issues such fulfillment of weekly jobs and fines
- Developed \$450K yearly budget including expenditures for rent, recruitment, food preparation, and events

MIT Rocketry Club

Cambridge, MA

Treasurer 2017-18

2016 - 2018

- Designed and built test stand for solid rocket motors as a part of Ground Support Systems
- Oversaw spending and fundraising for a \$40K budget, with the goal of reaching a record 80,000 ft flight

Eagle Scout

Tiburon, CA

SKILLS

Software: C++, Python, Linux, MATLAB, SolidWorks, Windows, CMake, Arduino, OpenCV

Building/Design: Prototyping, Laser Cutting, 3D-Printing, Machining and Fabrication, Waterjet

EXTRACURRICULAR ACTIVITIES

MIT Varsity Soccer Team, MIT Sandbox, Hackathons, Entrepreneurship