




# ISAAC S. PERPER

Dillon Beach, CA 94929  
415-308-2791 (cell)

 [isaacperper.com](http://isaacperper.com)  
 [isaac.perper@gmail.com](mailto:isaac.perper@gmail.com)  
 [isaac-perper-01](https://www.linkedin.com/in/isaac-perper-01)

## EDUCATION

### Massachusetts Institute of Technology

Cambridge, MA

*B.Sc. Mechanical Engineering - 5.0/5.0 GPA - Pi Tau Sigma | Tau Beta Pi Eligible*

*June 2020*

Relevant Coursework: Automatic Controls, Signals and Sys., Fund. of Programming, Manufacturing and Design I, Fund. of Statistics, Prob. and Random Variables, Lin. Algebra, Intro. to Machine Learning, Intro. to Algorithms

## WORK EXPERIENCE

### Ford Research and Innovation Center

Palo Alto, CA

*Intern*

*Summer 2019*

- Worked on a self-contained project integrates vehicle control and vision system with simulation tools to test new research features in a simulated environment instead of relying on in-vehicle test.
- Engaged with multiple engineers responsible for specific components of the controls and simulation
- Won first place out of six teams at the office-wide summer hackathon

### MIT CSAIL - PavLab

Cambridge, MA

*Student Researcher*

*Summer 2018, Spring 2019*

- Researching machine learning techniques for object detection using thermal imagery, including image segmentation and boundary detection for use in adverse lighting conditions
- Created battery management application for front-seat computer and sensors on REX unmanned surface vehicle
- Improved camera hardware with better mounting, camera, and lens selection
- Developed geo-location-based object identification to detect stoplights on preplanned autonomous routes

### Augmenta Bioworks

Mountain View, CA

*Intern*

*Summer 2017*

- Developed a prototype automation system independently that will enable analysis of lab processes
- Built the system from the ground up, working on the design, fabrication, and controls side of the device
- Created Python-based control script to interface with several devices over serial communication protocols
- Used computer vision library to automate procedure commands

### MIT Dept. of Nuclear Science and Engineering – Green Lab

Cambridge, MA

*Student Researcher*

*Spring 2017*

- Experimentally researched a quantifiable approach to improving the critical heat flux of various materials used in nuclear energy production through surface engineering
- Designed, machined, and fabricated test boiling chamber to use in tests

### Vecna Robotics

Cambridge, MA

*Intern*

*January 2019*

- Updated primarily C++ software stack to run on latest Linux and ROS systems
- Merging proprietary changes with latest community updates and fixing unsupported software to work with newest libraries and other dependencies

## LEADERSHIP

### Phi Sigma Kappa Fraternity

Boston, MA

*President*

*Spring 2019*

- Oversee operations of each sub-department and housing, including serving as semester's risk manager
- Conduct weekly house meetings and review day-to-day issues such fulfillment of weekly jobs and fines

### MIT Rocketry Club

Cambridge, MA

*Treasurer 2017-18*

*2016- 2018*

- Designed and built test stand for solid rocket motors as a part of Ground Support Systems
- Oversaw spending and fundraising for a \$40K budget, with the goal of reaching a record 80K flight

### Eagle Scout

Tiburon, CA

*Scout*

*August 2009-June 2016*

- Collaborated with the local church to build and implement a user-friendly recycling and compost system
- Lead the troop on outings as Assistant Senior Patrol Leader and Patrol Leader

## SKILLS

**Software:** SolidWorks, C++, Python, MATLAB, AutoCAD, Linux, Windows, CMake, Arduino, OpenCV

**Building/Design:** Prototyping, Laser Cutting, 3D-Printing, Machining and Fabrication, Waterjet

## EXTRACURRICULAR ACTIVITIES

MIT Varsity Soccer Team, MIT Sandbox, Redwood Rocketry Club (9<sup>th</sup> Place Nationally), MATE ROV