

Problem 1

cas.

$$Q(u) = \frac{1}{6} [u^3 \ u^2 \ u \ 1] \begin{bmatrix} -1 & 3 & -3 & 1 \\ 3 & -6 & 3 & 0 \\ -3 & 0 & 3 & 0 \\ 1 & 4 & 1 & 0 \end{bmatrix} \begin{bmatrix} P_0 \\ P_1 \\ P_2 \\ P_3 \end{bmatrix}$$

$$Q'(u) = \frac{1}{6} [3u^2 \ 2u \ 1 \ 0] \begin{bmatrix} -1 & 3 & -3 & 1 \\ 3 & -6 & 3 & 0 \\ -3 & 0 & 3 & 0 \\ 1 & 4 & 1 & 0 \end{bmatrix} \begin{bmatrix} P_0 \\ P_1 \\ P_2 \\ P_3 \end{bmatrix}$$

$$Q''(u) = \frac{1}{6} [6u \ 2 \ 0 \ 0] \begin{bmatrix} -1 & 3 & -3 & 1 \\ 3 & -6 & 3 & 0 \\ -3 & 0 & 3 & 0 \\ 1 & 4 & 1 & 0 \end{bmatrix} \begin{bmatrix} P_0 \\ P_1 \\ P_2 \\ P_3 \end{bmatrix}$$

$$Q(u) = \frac{1}{6} \underbrace{[u^3 \ u^2 \ u \ 1]}_{\text{B-spline matrix}} \begin{bmatrix} -1 & 3 & -3 & 1 \\ 3 & -6 & 3 & 0 \\ -3 & 0 & 3 & 0 \\ 1 & 4 & 1 & 0 \end{bmatrix} \begin{bmatrix} P_0 \\ P_1 \\ P_2 \\ P_3 \end{bmatrix}$$

B-spline matrix
(from slides)

(b). For $P_0 P_1 P_2 P_3$

$$\Rightarrow Q_1(u) = \frac{1}{6}((1-u)^3 P_0 + (3u^3 - 6u^2 + 4) P_1 + (-3u^3 + 3u^2 + 3u + 1) P_2 + u^3 P_3)$$

$$Q_1'(u) = \frac{1}{6}(-3(1-u)^2 P_0 + (9u^2 - 12u) P_1 + (-9u^2 + 6u + 3) P_2 + 3u^2 P_3)$$

$$Q_1''(u) = \frac{1}{6}(6(1-u) P_0 + (18u - 12) P_1 + (-18u + 6) P_2 + 6u P_3)$$

At joint, $u=1$,

$$Q_1(1) = \frac{1}{6}(P_1 + 4P_2 + P_3)$$

$$Q_1'(1) = \frac{1}{6}(-3P_1 + 3P_3)$$

$$Q_1''(1) = \frac{1}{6}(6P_1 - 12P_2 + 6P_3)$$

As for $P_1 P_2 P_3 P_4$, we substitute $P_0 P_1 P_2 P_3$ in the above equations by $P_1 P_2 P_3 P_4$ and use $u=0$ instead: $\{1-0\}^3, 0-0+4, 0+0+0+1$

$$Q_2(0) = \frac{1}{6}(P_1 + 4P_2 + P_3)$$

$$Q_2'(0) = Q_1'(1)$$

$$Q_2''(0) = Q_1''(1) \text{ by simple substitutions.}$$

And it is obvious that the two curves' joint is C^2 continuous.

cc2

Consider $u=1$

$$\begin{aligned} N_0(u) &= \frac{1}{6}(1-u)^3 = 0 \\ \textcircled{1} \quad N_0'(u) &= -\frac{1}{2}(1-u)^2 = 0 \\ N_0''(u) &= (1-u) = 0 \end{aligned}$$

$$\begin{aligned} N_1(u) &= \frac{1}{6}(3u^3 - 6u^2 + 4) = \frac{1}{6} \\ \textcircled{2} \quad N_1'(u) &= \frac{1}{6}(9u^2 - 12u) = -\frac{1}{2} \\ N_1''(u) &= \frac{1}{6}(18u - 12) = 1 \end{aligned}$$

$$\begin{aligned} N_2(u) &= \frac{1}{6}(-3u^3 + 3u^2 + 3u + 1) = \frac{2}{3} \\ \textcircled{3} \quad N_2'(u) &= \frac{1}{6}(-9u^2 + 6u + 3) = 0 \\ N_2''(u) &= \frac{1}{6}(-18u + 6) = -2 \end{aligned}$$

$$\begin{aligned} N_3(u) &= \frac{1}{6}u^3 = \frac{1}{6} \\ \textcircled{4} \quad N_3'(u) &= \frac{1}{2}u^2 = \frac{1}{2} \\ N_3''(u) &= u = 1 \end{aligned}$$

Consider $u=0$

$$\begin{aligned} \textcircled{a} \quad \begin{cases} N_0(u) = \frac{1}{6} \\ N_0'(u) = -\frac{1}{2} \\ N_0''(u) = 1 \end{cases} & \quad \textcircled{b} \quad \begin{cases} N_1(u) = \frac{2}{3} \\ N_1'(u) = 0 \\ N_1''(u) = -2 \end{cases} & \quad \textcircled{c} \quad \begin{cases} N_2(u) = \frac{1}{6} \\ N_2'(u) = \frac{1}{2} \\ N_2''(u) = 1 \end{cases} \end{aligned}$$

$$\textcircled{d} \quad \begin{cases} N_3(u) = 0 \\ N_3'(u) = 0 \\ N_3''(u) = 0 \end{cases}$$

And we Notice that:

at $u=1$,

function set ① = function set ①

② = ②

③ = ③

④ = ④

up to second derivative of the basis functions.

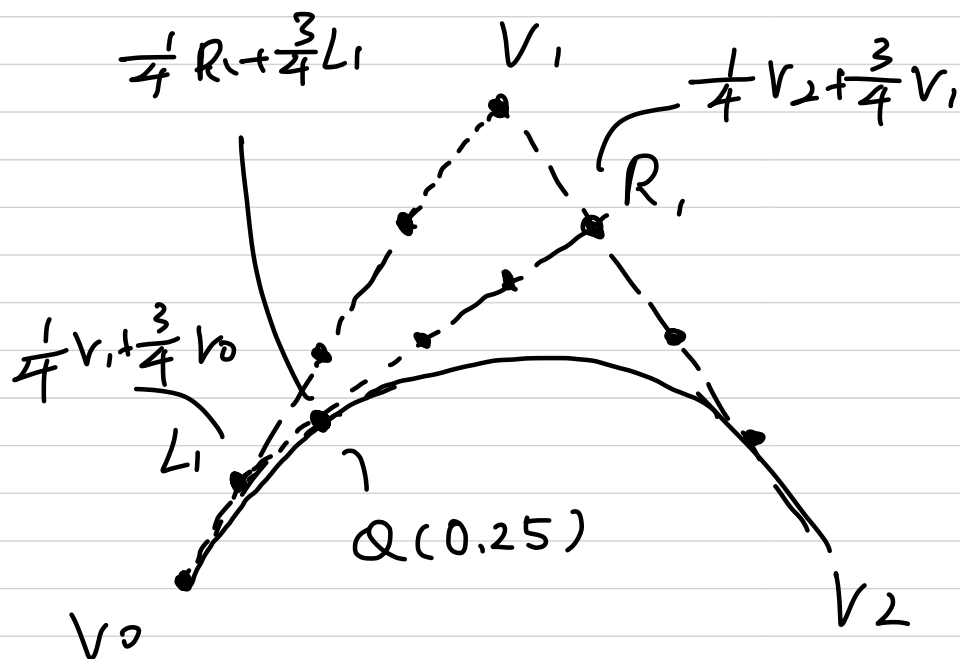
∴ The basis functions are C^2 continuous at knots following

$$\left. \begin{matrix} N_i(1) \\ N_i'(1) \\ N_i''(1) \end{matrix} \right\} = \left\{ \begin{matrix} N_{i+1}(0) \\ N_{i+1}'(0) \\ N_{i+1}''(0) \end{matrix} \right.$$

↳ (If $i=0$, RHS is 3, and all 3 values 0)

Problem 2.

(a).



$$B_0^2(u) = \begin{pmatrix} 2 \\ 0 \end{pmatrix} x^0 (1-x)^2$$

$$B_1^2(u) = \begin{pmatrix} 2 \\ 1 \end{pmatrix} x^1 (1-x)^1$$

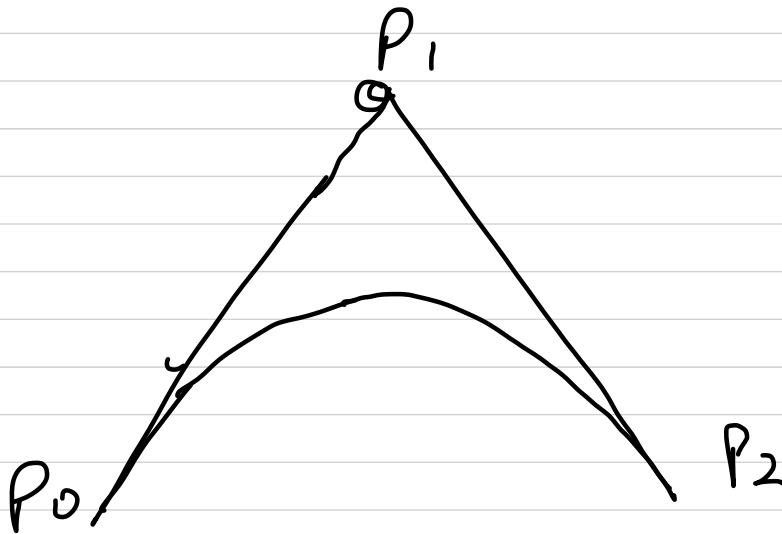
$$B_2^2(u) = \begin{pmatrix} 2 \\ 2 \end{pmatrix} x^2 (1-x)^0$$

$$\hookrightarrow [(1-x)^2 P_0 + (x-x^2) P_1 + x^2 P_2]$$

$$\text{or } P_1 + (1-t)^2 (P_0 - P_1) + t^2 (P_2 - P_1)$$

Side Note

$$(b). \sum_{i=0}^2 B_i(u) P_i$$



$$L(u) = P_0 + u(P_1 - P_0) = (1-u)P_0 + uP_1$$

$$R(u) = P_1 + u(P_2 - P_1) = (1-u)P_1 + uP_2$$

$$Q(u) = L(u) + u(R(u) - L(u))$$

$$= (1-u)P_0 + uP_1 + u((1-u)P_1 + uP_2 - ((1-u)P_0 + uP_1))$$

$$= (1-u)P_0 + uP_1 + u((1-2u)P_1 + uP_2 + (u-1)P_0)$$

$$= ((1-u) + (u^2-u))P_0 + (u + u-2u^2)P_1 + u^2P_2$$

$$= (u-1)^2 P_0 + 2u(1-u)P_1 + u^2 P_2$$

$$\therefore B_0(u) = (u-1)^2$$

$$B_1(u) = 2u(1-u)$$

$$B_2(u) = u^2$$

(C). Suppose the first segment is controlled by P_0, P_1, P_2 and second segment controlled by V_0, V_1, V_2 .

Since they are joined, we have $P_2 = V_0$ which represents $Q_p(1) = Q_v(0)$ already.

$$\therefore Q'(u) = 2(u-1)P_0 + 2(1-2u)P_1 + 2uP_2$$

We need to ensure $Q_p'(1) = Q_v'(0)$ in order to achieve C^1 -continuity

$$\Rightarrow 2(-1)P_1 + 2P_2 = -2V_0 + 2V_1$$

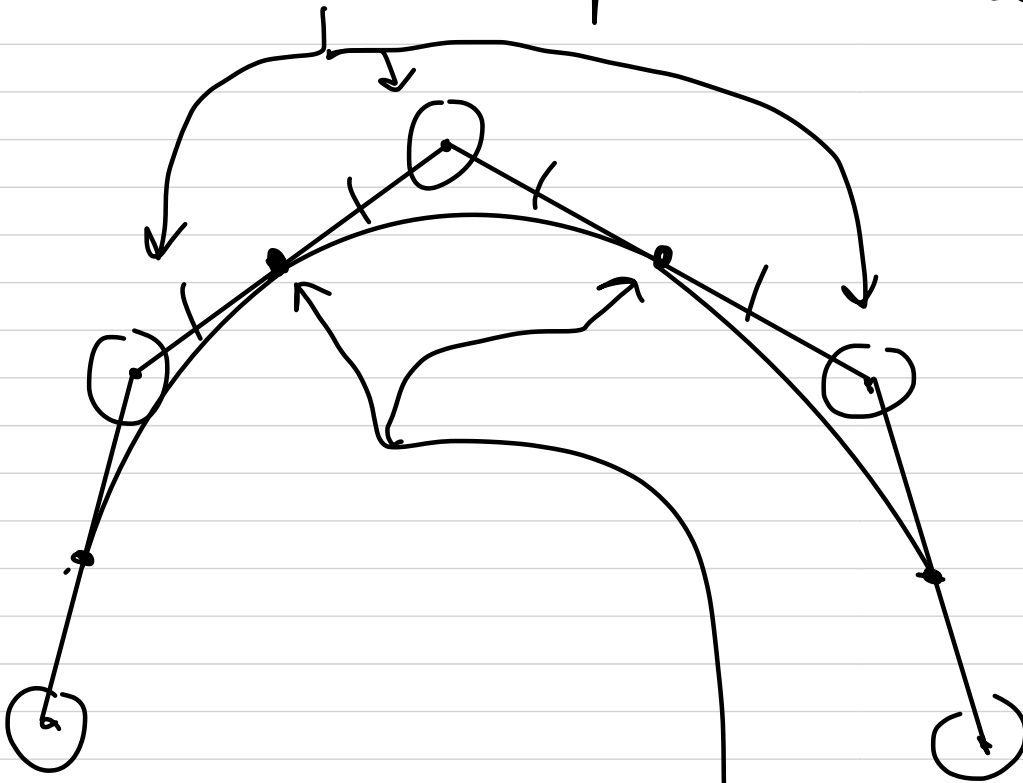
$$\Leftrightarrow -P_1 + P_2 = -V_0 + V_1$$

$$\Leftrightarrow \text{Condition } \underline{2P_2 - P_1 = V_1} \text{ needed}$$

Apart from $V_0 = P_2$

(d). From (c), we know we need
 $V_1 - V_0 = P_2 - P_1$ suppose we start with 5

points circled in the below image, we connect them first and get the connecting lines' midpoints, the midpoints, together with the middle 3 control points, constitute the



3 Bezier curves with C^1 continuity
guaranteed by the midpoints we picked.

(e). Firstly, we have the basis functions for cubic Bezier curves as:

$$B_0(u) = (1-u)^3$$

$$B_1(u) = 3u(1-u)^2$$

$$B_2(u) = 3u^2(1-u)$$

$$B_3(u) = u^3$$

from the Bernstein Basis.

$$\therefore Q(u) = (1-u)^3 P_0 + 3u(1-u)^2 P_1 + 3u^2(1-u) P_2 + u^3 P_3$$

$$Q'(u) = -3(1-u)^2 P_0 + 3(3u^2 - 4u + 1) P_1 + 3(2u - 3u^2) P_2 + 3u^2 P_3$$

$$Q''(u) = 3 \cdot 2(1-u) P_0 + 3(6u - 4) P_1 + 3(2 - 6u) P_2 + 6u P_3$$

In order to satisfy: (Suppose $P_0, P_1, P_2, P_3 + V_0, V_1, V_2, V_3$)

$$C^0 \text{ continuity} \Rightarrow P_3 = V_0$$

$$C^1 \text{ continuity} \Rightarrow Q'_p(1) = Q'_v(0)$$

$$\Leftrightarrow P_3 - P_2 = V_1 - V_0$$

$$C^2 \text{ continuity} \Rightarrow Q''_p(1) = Q''_v(0)$$

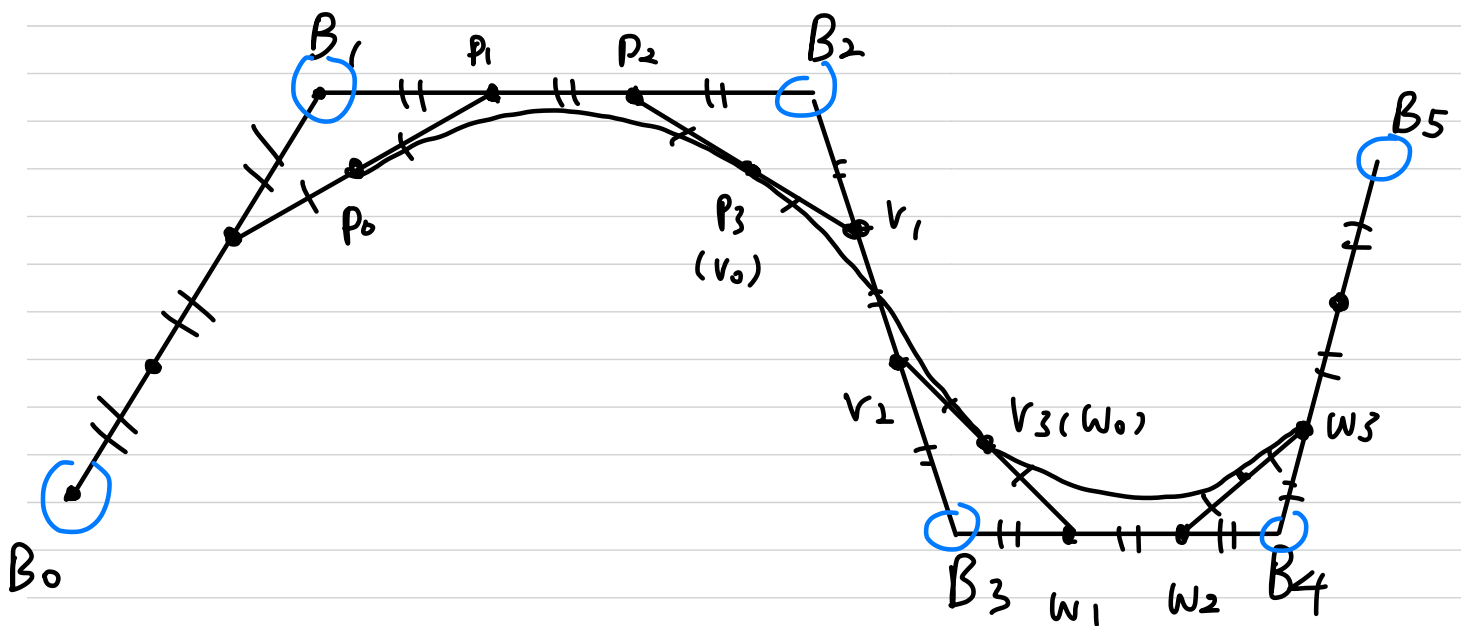
$$\Leftrightarrow 2P_1 - 4P_2 + 2P_3$$

$$= 2V_0 - 4V_1 + 2V_2$$

$$\Leftrightarrow (P_1 - P_2) + (P_3 - P_2) = (V_0 - V_1) + (V_2 - V_1)$$

$$\Leftrightarrow (P_2 - P_1) + (P_2 - P_3) = (V_1 - V_0) + (V_1 - V_2)$$

Just like in class, firstly we connect all 6 de Boor points given, then cut these connecting lines into three equal parts, and construct letter "A" by connecting the $\frac{2}{3}$ point from the previous connecting line to the $\frac{1}{3}$ point from the next connecting line, and then halve the " $\frac{2}{3} - \frac{1}{3}$ " line to produce our Bezier curves' starting/end control points, " $\frac{1}{3}$ ", " $\frac{2}{3}$ " points will be the middle control points for our Bezier curves. And done like below:



Problem 3.

$$\text{Vertex } A : K_A = K_{ABD} + K_{ABC} + K_{ACD}$$

$$\text{Vertex } B : K_B = K_{BAC} + K_{BAD} + \underline{K_{BCD}}$$

$$\text{Vertex } C : K_C = K_{CAB} + K_{CAD} + \underline{K_{CBD}}$$

$$\text{Vertex } D : K_D = K_{DAB} + K_{DAC} + \underline{K_{DBC}}$$

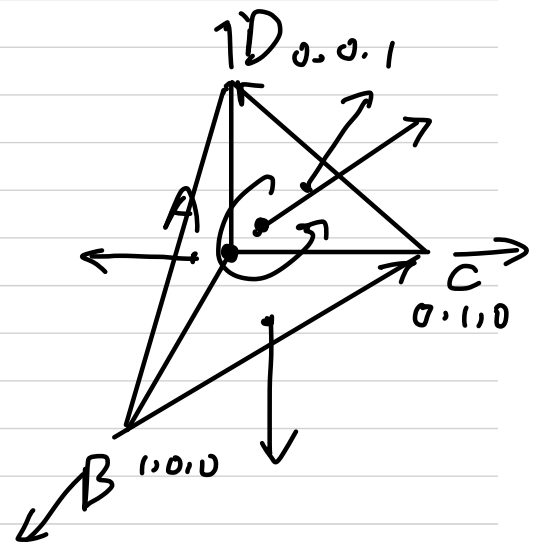
Normals to planes are:

$$n_{ABC} = (0, 0, -1)$$

$$n_{ABD} = (0, -1, 0)$$

$$n_{ACD} = (-1, 0, 0)$$

$$\begin{aligned} n_{BCD} &= (\vec{BC} \times \vec{CD})_{\text{normalize}} \\ &= \frac{1}{\sqrt{3}} (1, 1, 1) \end{aligned}$$



We then compute offset d s:

$$(0, 0, 0)$$

$$\begin{cases} d_A - ABC = 0 \\ d_A - ABD = 0 \\ d_A - ACD = 0 \end{cases}$$

$$(0, 1, 0)$$

$$\begin{cases} d_C - ABC = 0 \\ d_C - ACD = 0 \\ d_C - BCD = \frac{1}{\sqrt{3}} \end{cases}$$

$$(1, 0, 0)$$

$$\begin{cases} d_B - ABC = 0 \\ d_B - ABD = 0 \\ d_B - BCD = \frac{1}{\sqrt{3}} \end{cases}$$

$$(0, 0, 1)$$

$$\begin{cases} d_D - ABD = 0 \\ d_D - ACD = 0 \\ d_D - BCD = \frac{1}{\sqrt{3}} \end{cases}$$

Now we notice:

$$K_{ABC}$$

$$K_{ABD}$$

$$K_{ACD}$$

$$K_{BCD}$$

All have same offsets at different vertices, so we can compute K_{A-D} using subtraction after $K_{sum} = K_{ABC} + K_{ABD} + K_{ACD} + K_{BCD}$ are computed, because for example, K_{ABC} at A is same to K_{ABC} at rest of the vertices.

$$K_{ABC} = (0, 0, -1, 0) \begin{pmatrix} 0 \\ 0 \\ -1 \\ 0 \end{pmatrix} = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$K_{ABD} = (0, -1, 0, 0) \begin{pmatrix} 0 \\ -1 \\ 0 \\ 0 \end{pmatrix} = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$K_{ACD} = (-1, 0, 0, 0) \begin{pmatrix} -1 \\ 0 \\ 0 \\ 0 \end{pmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$K_{BCD} = \frac{1}{3}(1, 1, 1, 1) \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} = \frac{1}{3} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \end{bmatrix}$$

$$\therefore K_{sum} = \frac{1}{3} \begin{bmatrix} 4 & 1 & 1 & 1 \\ 1 & 4 & 1 & 1 \\ 1 & 1 & 4 & 1 \\ 1 & 1 & 1 & 4 \end{bmatrix}$$

$$K_A = K_{sum} - K_{BCD} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$K_B = K_{sum} - K_{ACD} = \frac{1}{3} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 4 & 1 & 1 \\ 1 & 1 & 4 & 1 \\ 1 & 1 & 1 & 4 \end{bmatrix}$$

$$K_C = K_{sum} - K_{ABD} = \frac{1}{3} \begin{bmatrix} 4 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 4 & 1 \\ 1 & 1 & 1 & 4 \end{bmatrix}$$

$$K_D = K_{sum} - K_{ABC} = \frac{1}{3} \begin{bmatrix} 4 & 1 & 1 & 1 \\ 1 & 4 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 4 \end{bmatrix}$$