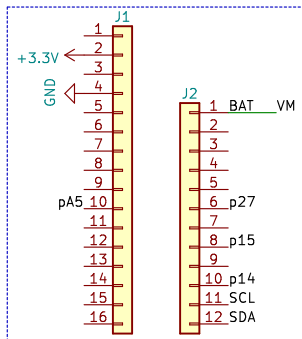
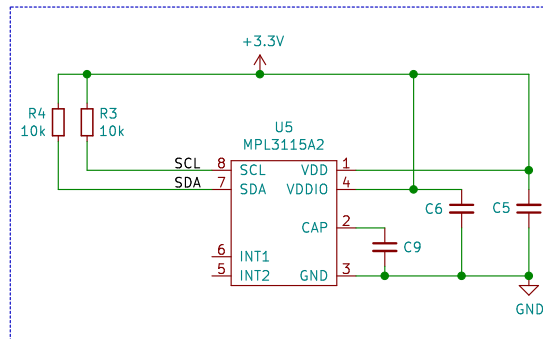


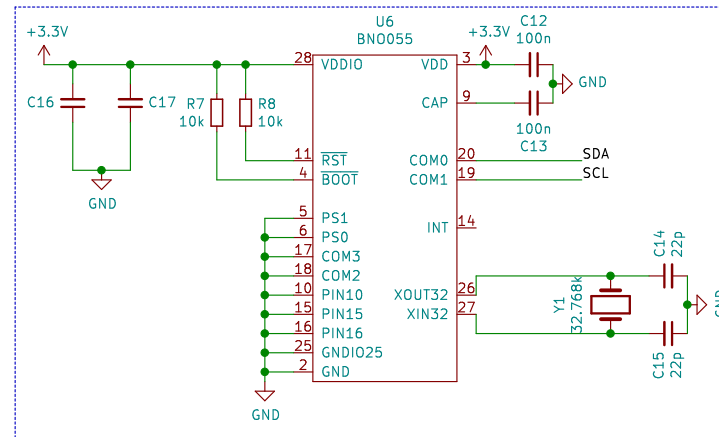
Feather board connector



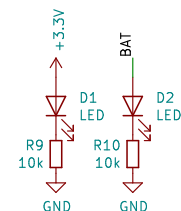
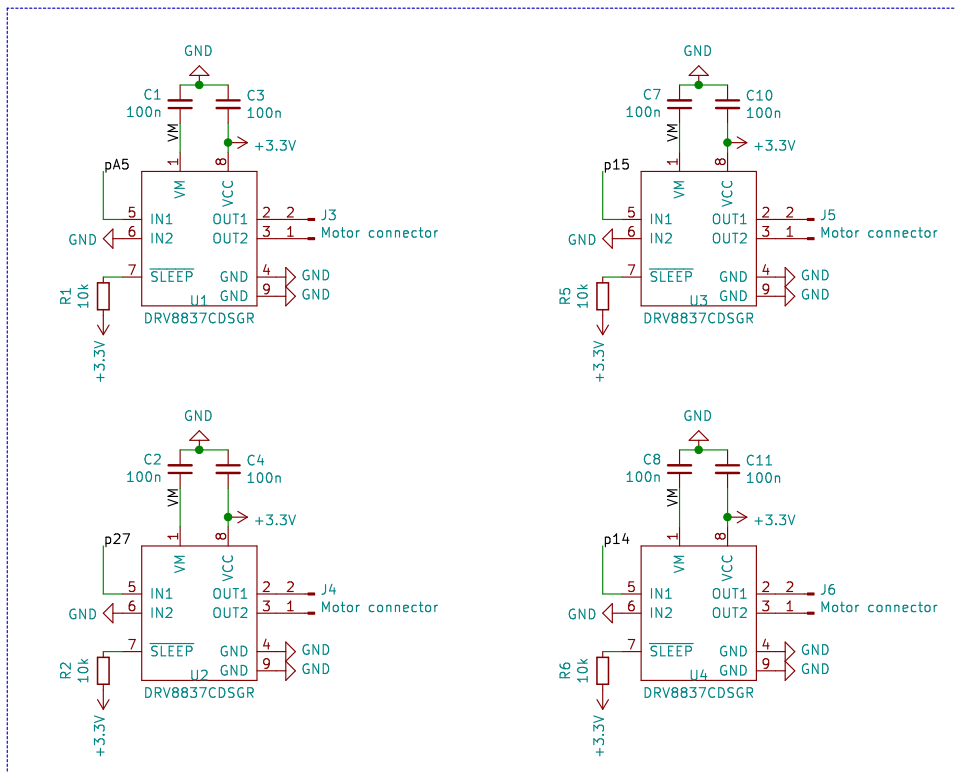
Altimeter: MPL3115A2



IMU: BNO055



Motor drivers: DRV8837C



## Notes

i2c address:  
BNO055 = 0x28  
MPL3115A2 = 0x60

Logs:  
28-Dec-2019: connected VDDIO to 3.3V  
26-Dec-2019: created

Iman

Sheet: /  
File: featherwing\_qcopter.sch

Title: Featherwing Quadcopter

Size: A4 Date: 2019-12-30

KiCad E.D.A. kicad (5.1.5)-3

Rev: 20191230

Id: 1/1