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Practical work: IPSA_SCHED

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Introduction

In this final assignment the objective is to design an RTOS with four periodic tasks that are :

Task 1:

Print a status message such as "Working !"

Task 2:

Convert a fixed Fahrenheit temperature value to degree Celsius

Task 3:

Multiply two long integer numbers and print the result

Task 4:

Perform binary search on a predefined list of 50 elements for a specific value

We will also be trying to find a WCET for all of these tasks

Part I: WCET

In this part we will be working toward calculating the WCET of each of the tasks we will be working in a C++ to code the tasks and measure them

```

int run_and_measure() {
    vector<long long> elapsedTimes;

    for (int i = 0; i < iterations; ++i) {
        //START MEASURE
        auto start = high_resolution_clock::now();

        // Convert F° to C°
        double fahrenheit = 100;
        double celsius = (5 / 9) * (fahrenheit-32);

        //END MEASURE
        auto elapsed = high_resolution_clock::now() - start;

        elapsedTimes.push_back(duration_cast<microseconds>(elapsed).count());
    }

    // Find the maximum time
    long long maxTime = *max_element(elapsedTimes.begin(), elapsedTimes.end());

    cout << "Maximum time taken by a single run: " << maxTime << " microseconds" << endl;

    return 0;
}

int main() {
    run_and_measure();
    return 0;
}

```

How we did that is that we first defined a function run and measure that will measure our task here the task 2 how many times we want (here 100 000 times). And then we store the value into a vector and use a premade command to find the maximum and conclude the WCET of that:

	Task 1	Task 2	Task 3	Task 4
WCET (in μ s)	981	66	659	129
Measures taken	100,000	1,000,000	100,000	1,000,000

WCET of the 4 tasks measured on my Machine

Part II: RTOS

```

/* Priorities at which the tasks are created. */
#define YOUR_TASK1_PRIORITY          ( tskIDLE_PRIORITY + 1 )
#define YOUR_TASK2_PRIORITY          ( tskIDLE_PRIORITY + 2 )
#define YOUR_TASK3_PRIORITY          ( tskIDLE_PRIORITY + 3 )
#define YOUR_TASK4_PRIORITY          ( tskIDLE_PRIORITY + 4 )
/* The rate at which data is sent to the queue. The times are converted
 * milliseconds to ticks using the pdMS_TO_TICKS() macro. */

#define TASK1_FREQUENCY              pdMS_TO_TICKS( 4000UL )
#define TASK2_FREQUENCY              pdMS_TO_TICKS( 200UL )
#define TASK3_FREQUENCY              pdMS_TO_TICKS( 3000UL )
#define TASK4_FREQUENCY              pdMS_TO_TICKS( 800UL )

```

I chose to make it so the priority of each Task is the same as their index (i.e. Task1 = Highest priority etc ...) and the frequency is higher as their WCET is higher

On my machine I have 1000000 clocks per seconds so with a quick conversion I can get C in ticks which is the same

	Task 1	Task 2	Task 3	Task 4
C (WCET in μ s)	981	66	659	129
C (WCET in ticks)	981	66	659	129
TI (in ticks)	4000	200	3000	800
p	0	1	2	3

Task 1: $U_1 = 981/4000 \approx 0.245$

Task 2: $U_2 = 66/200 \approx 0.33$

Task 3: $U_3 = 659/3000 \approx 0.2197$

Task 4: $U_4 = 129/800 \approx 0.16125$

Now lets sum up to get U_{total} and see if it's schedulable:

$U_{total} = U_1 + U_2 + U_3 + U_4$

$U_{total} \approx 0.245 + 0.33 + 0.2197 + 0.16125$

$U_{total} \approx 0.95595$

So our tasks are schedulable (on my machine at least).