

Designing Precoders to mitigate Inter-User Interference in MIMO FBMC Channels

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Overview

1. OFDM vs FBMC
2. MIMO
3. Multiuser MIMO
4. Zero-Forcing Precoder
5. Block Diagonalization Algorithm
6. Successive Optimization Algorithm

Orthogonal Frequency Division Multiplexing[1]

- Transmit Signal: $x(t) = \sum_n \sum_{k \in \mathcal{K}} s_k[n] p_T(t - nT) e^{j2\pi(t-nT)f_k} = \sum_n \sum_{k \in \mathcal{K}} s_k[n] p_{T,k}(t - nT)$
- \mathcal{K} denotes the set of active symbol indices
- $s_k[n]$ denote the data symbols, k is the subcarrier index
- $p_T(t)$ is the transmitting prototype filter, a **rectangular** pulse here
- T is the symbol time
- $p_{T,k}(t) = p_T(t) e^{j2\pi t f_k}$
- The receiving prototype filter $p_R(t)$ is also a rectangular pulse with duration $\tau \leq T$ to maintain the orthogonality condition
- **Bad spectral containment per subcarrier leading to inefficient bandwidth utilization**

Filter Bank Multi Carrier[2], [3]

- Transmit Signal: $x(t) = \sum_{k \in \mathcal{K}} \sum_{l=1}^L g_{l,k}(t) s_{l,k}$
- $s_{l,k}$ is the data symbol at the time frequency location (l, k)
- $g_{l,k}(t) = p(t - kT) e^{j2\pi l F(t - kT)} e^{j\theta_{l,k}}$ denotes the basis pulse which is a time and frequency shifted prototype filter $p(t)$
- T is the symbol time and F is the subcarrier spacing
- The receiving prototype filter is matched to the symmetric transmitting prototype filter, and hence both are the same and satisfy **orthogonality in real domain**

MIMO FBMC[3]

- Consider $N_r \times N_t$ MIMO system
- The transmit signal at a single transmit antenna in vector form: $\mathbf{s} = \mathbf{G}\mathbf{x}$
- $\mathbf{G} \in \mathbb{C}^{LK \times LK}$, $\mathbf{s}, \mathbf{x} \in \mathbb{C}^{LK \times 1}$
- Received signal at a single receiver antenna: $\mathbf{r} = \tilde{\mathbf{h}}\mathbf{G}\mathbf{x} + \tilde{\mathbf{n}}$
- Received symbols at a single receiver antenna: $\mathbf{y} = \mathbf{G}^* \tilde{\mathbf{h}}\mathbf{G}\mathbf{x} + \mathbf{n} = \mathbf{h}\mathbf{x} + \mathbf{n}$
- As there are $N_r \times N_t$ possible channels,

- Considering a single active symbol, we then have

$$\bar{\mathbf{y}} = \mathbf{H}\bar{\mathbf{x}} + \mathbf{n}$$

- $\bar{\mathbf{y}} \in \mathbb{C}^{LN_r \times 1}$
- $\mathbf{H} \in \mathbb{C}^{LN_r \times LN_t}$
- $\bar{\mathbf{x}} \in \mathbb{C}^{LN_t \times 1}$

Multiuser MIMO FBMC

- Considering there are K users with N_r antennas each and a base station downlink with N_t antennas and repeating the above procedure for every user

$$\bar{\mathbf{y}} = \mathbf{H}\bar{\mathbf{x}} + \mathbf{n}$$

- $\bar{\mathbf{y}} \in \mathbb{C}^{KLN_r \times 1}$
- $\mathbf{H} \in \mathbb{C}^{KLN_r \times LN_t}$
- $\bar{\mathbf{x}} \in \mathbb{C}^{LN_t \times 1}$

Zero Forcing (ZF) Precoder

- Consider a precoding matrix \mathbf{P} such that $\bar{\mathbf{x}} = \mathbf{P}\hat{\mathbf{x}}$
- $\hat{\mathbf{x}} = [\mathbf{x}_1, \dots, \mathbf{x}_K]^\top$, $\mathbf{x}_i \in \mathbb{C}^{L_K \times 1}$ is the message symbol vector corresponding to user i
- $\bar{\mathbf{y}} = \mathbf{H}\mathbf{P}\hat{\mathbf{x}} + \mathbf{n}$
- If $\mathbf{H}\mathbf{P} = \mathbf{D}$ where \mathbf{D} is a diagonal matrix, then there is no inter-user interference.
- In that case $\mathbf{P} = \mathbf{H}^\dagger \mathbf{D}$ which exists only when $\mathbf{H} \in \mathbb{C}^{KLN_r \times LN_t}$ has a full row rank -
Suboptimal solution since each user is able to coordinate the processing of its own receiver outputs[4]

Inter-User Interference[4]

Consider a precoder \mathbf{P}_i for each user i such that

$$\bar{\mathbf{x}} = \sum_{i=1}^K \mathbf{P}_i \hat{\mathbf{x}}_i$$

then for user j ,

$$\begin{aligned} \bar{\mathbf{y}}_j &= \mathbf{H}_j \left(\sum_{i=1}^K \mathbf{P}_i \hat{\mathbf{x}}_i \right) + \mathbf{n}_j \\ &= \mathbf{H}_j \mathbf{P}_j \hat{\mathbf{x}}_j + \underbrace{\mathbf{H}_j \tilde{\mathbf{P}}_j \tilde{\mathbf{x}}_j}_{\text{IUI}} + \mathbf{n}_j \end{aligned}$$

where

$$\begin{aligned} \tilde{\mathbf{P}}_j &= [\mathbf{P}_1 \dots \mathbf{P}_{j-1} \mathbf{P}_{j+1} \dots \mathbf{P}_K] \\ \tilde{\mathbf{x}}_j^T &= [\hat{\mathbf{x}}_1^T \dots \hat{\mathbf{x}}_{j-1}^T \hat{\mathbf{x}}_{j+1}^T \dots \hat{\mathbf{x}}_K^T] \end{aligned}$$

Block Diagonalization (BD) Algorithm[4]

- Denote

$$\mathbf{H}_S = [\mathbf{H}_1^T \mathbf{H}_2^T \dots \mathbf{H}_K^T]^T$$





$$\mathbf{P}_S = [\mathbf{P}_1 \mathbf{P}_2 \dots \mathbf{P}_K]$$

- For zero IUI, we want $\mathbf{H}_S \mathbf{P}_S$ to be a block diagonal matrix
- This can be done either for **Throughput Maximization** or **Power Control**
- Null space, SVD, Shanon's channel capacity theorem and waterfilling algorithm
- This is a **non-iterative** algorithm so that the closed form solution can be directly implemented
- *Implementation and simulation results for MIMO FBMC will be provided in the Activity 2 report later, if interested, the general algorithm can be studied in [4]*

Successive Optimization (SO) Algorithm[4]

- Another non-iterative algorithm for Power Control to get closed-form solution
- Remove IUI for one user at a time, with the condition that the precoder of the current user j is optimized such that it does not interfere with the previous $j - 1$ users' data
- Uses only the statistics of the interfering signals from previous steps and hence it is valid as long as this transmission procedure is a **Stationary Random Process**
- Here too the concepts of Null space, SVD, Shanon's channel capacity theorem and waterfilling algorithm are used
- *Implementation and simulation results for MIMO FBMC will be provided in the Activity 2 report later, if interested, the general algorithm can be studied in [4]*

References

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