# SANDESH G. BHAT, PH.D.

### **Post-Doctoral Research Fellow**

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## **EXPERIENCE**

## **Post-Doctoral Research Fellow**

### **Department of Orthopedics, Mayo Clinic**

May 2021 - Ongoing

Rochester, MN, USA

 Post-Doctoral Research Fellow in the Orthopedics Department under Dr. Kenton Kaufman.

### **Graduate Teaching Assistant**

### **Arizona State University**

Marg 2018 - Dec 2019

▼ Tempe, AZ, USA

- Teaching Assistant for EGR 217 and EGR 343. Both courses revolved around Mechanics and Strength of Materials.
- Instructed and guided undergraduate students in Matlab, C and other computational programming languages for EGR 219: Computational Modelling of Engineering Systems.

### **Graduate Research Assistant**

### **Arizona State University**

**Aug 2017 - Dec 2018** 

▼ Tempe, AZ, USA

- Worked in the Robotics, Dynamical Systems and Controls Group as a Ph.D. student under Dr. Sangram Redkar and Dr. Thomas Sugar.
- Designed and Developed a Passive Prosthetic Ankle under a Small Business Innovation Research grant.
- Worked on Universal Robots 5 and Baxter platforms and guided undergraduate students on the same.
- Worked on multiple proposals with Dr. Redkar.

### **PROJECTS**

- Upper Extremity Orthosis (Mayo Clinic) in 2021.
- Invariant Manifolds in Human Walking Gait (Arizona State University) in 2019.
- Mechanical Design of an Elbow Exoskeleton (Arizona State University) in 2019.
- Periodic Force Applied to the Hip During Normal Human Gait (Arizona State University) in 2018.
- Topology Optimization of Automotive Lower Control Arm (Arizona State University) in 2018.
- Application of Genetic Algorithm and Various Optimization Routines (Arizona State University) in 2018.
- Development of an IMU Based Motion Capture System (Arizona State University) from 2017 to 2018.
- Design/Development of a Passive Prosthetic Ankle (Arizona State University) in 2017.
- Hyper-loop Control System modelling and Simulations (Arizona State University) in 2017.
- Hyper-loop Control System modelling and Simulations (Arizona State University) in 2017.
- 3D printed bionic arm (University of Mumbai) in 2016.

# **EDUCATION**

### **Doctor of Philosophy**

Ira A. Fulton Schools of Engineering, Arizona State University, USA

🛗 January 2018 - May 2021

 Specialization in Gait Dynamics and Prosthetics/ Orthotics control.

### Master of Science

Ira A. Fulton Schools of Engineering, **Arizona State University, USA** 

August 2016 - December 2017

 Specialization in Mechanical Engineering, Controls and Robotics.

# **Bachelor of Engineering**

University of Mumbai, India

max August 2012 - May 2016

Specialization in Mechanical Engineering.

# ORGANIZATIONS

### Director of Outreach

**Graduate and Professional Student Association** 

math August 2020 - April 2021

### Assembly member

**Graduate and Professional Student Association** 

May 2020 - May 2020

### **Student President**

**Mechanical Engineering Students Association** 

math August 2020 - April 2021

### **Treasurer**

**Mechanical Engineering Students Association** 

Margust 2020 - April 2021

# STRENGTHS

Matlab and Simulink | Python |

Biomechanics toolkit

C\C++

Motion Capture and Data Analysis

Open-Sim

**Embedded Systems** 

Operation of various Manipulator Arms

CAD CAM