

# Chapter 4

# Later

**Definition 4.0.1.** A continuous bijective map  $f : X \rightarrow Y$  is called a homeomorphism if  $f^{-1}$  is also continuous.

**Remark** "homeomorphism" is not the same as "homomorphism".

**Definition 4.0.2.**  $X \simeq Y$  are homeomorphic or topological equivalent if there exists a homeomorphism  $f : X \rightarrow Y$

**Definition 4.0.3.** Two metric spaces  $(X, d_X)$  and  $(Y, d_Y)$  are called isometric if there exists a bijective map  $f : X \rightarrow Y$  such that for all  $x_1, x_2 \in X$ ,  $d_Y(f(x_1), f(x_2)) = d_X(x_1, x_2)$ . ( $f$  is called an isometry)

**Exercise** Prove that every isometry is a homeomorphism, but some homeomorphisms are not isometries.

**Example 4.0.1.** Let  $D = \{(x, y) \in \mathbb{R}^2 | x^2 + y^2 \leq 1\}$  be the unit disk in  $\mathbb{R}^2$  with the Euclidean metric. Let  $S^1 = \{(x, y) \in \mathbb{R}^2 | \max |x|, |y| = 1\}$  be the unit square in  $\mathbb{R}^2$  with the Euclidean metric. Then  $D$  and  $S^1$  are homeomorphic but not isometric.

**Proof**

The idea of prove homeomorphism is to map every radius of the disk to the corresponding line segment of the square.

Assume there exists an isometry  $f : D \rightarrow S^1$ . Note that the diameter of  $D$  is 2, while the diameter of  $S^1$  is  $2\sqrt{2}$ . This contradicts the definition of isometry. Thus, no such isometry exists.

**Example 4.0.2.** Another example of homeomorphism is the linear map from the interval  $(0, 1)$  to  $(a, b)$  (by stretching and compressing).

**Example 4.0.3.**  $(0, 1) \simeq (-\frac{\pi}{2}, \frac{\pi}{2}) \simeq \mathbb{R}$  by the tangent function.

The above example can be described graphically by a bowl (a circle centered at  $(0, \frac{1}{2})$  with radius  $\frac{1}{2}$  without the upper half) with radius  $\frac{1}{2}$  on the real line.

**Property 4.0.1.** If  $f : X \rightarrow Y$  and  $g : Y \rightarrow Z$  are continuous, then  $g \circ f : X \rightarrow Z$  is continuous.

**Corollary 4.0.1.** If  $f : X \rightarrow Y$  and  $g : Y \rightarrow Z$  are homeomorphisms, then  $g \circ f : X \rightarrow Z$  is a homeomorphism.

**Property 4.0.2.** Homeomorphism  $\simeq$  is an equivalence relation.

**Definition 4.0.4.**  $X$  is said to be path-connected if any two points  $x, y \in X$  can be joined by a path: there exists a continuous map  $f : [0, 1] \rightarrow X$  such that  $f(0) = x$  and  $f(1) = y$ .

**Definition 4.0.5.** Let  $X$  be a metric space.  $X$  is said to be connected if one of the following equivalent conditions holds:

1.  $X$  cannot be represented as  $X = U_1 \sqcup U_2$  where  $U_1, U_2$  are non-empty open subsets of  $X$ .
2.  $X$  cannot be represented as  $X = V_1 \sqcup V_2$  where  $V_1, V_2$  are non-empty closed subsets of  $X$ .
3. There is no proper non-empty subset  $U \subseteq X$  which is both open and closed in  $X$ .

**Property 4.0.3.** If  $X$  is path-connected and  $f : X \rightarrow Y$  is a homeomorphism, then  $Y$  is also path-connected.

**Proof** Let  $y_1, y_2 \in Y$ . Since  $f$  is bijective, there exist  $x_1, x_2 \in X$  such that  $f(x_1) = y_1$  and  $f(x_2) = y_2$ . Since  $X$  is path-connected, there exists a continuous map  $g : [0, 1] \rightarrow X$  such that  $g(0) = x_1$  and  $g(1) = x_2$ . Consider the map  $h = f \circ g : [0, 1] \rightarrow Y$ . Since both  $f$  and  $g$  are continuous,  $h$  is continuous. Moreover,  $h(0) = f(g(0)) = f(x_1) = y_1$  and  $h(1) = f(g(1)) = f(x_2) = y_2$ . Thus, there exists a continuous path in  $Y$  connecting  $y_1$  and  $y_2$ , proving that  $Y$  is path-connected. ■

**Theorem 4.0.1** (Intermediate Value Theorem). *Let  $f : [a, b] \rightarrow \mathbb{R}$  be continuous. For any  $c$  between  $f(a)$  and  $f(b)$ , there exists some  $x \in [a, b]$  such that  $f(x) = c$ .*

**Example 4.0.4.**  $\mathbb{R} \setminus \{0\}$  is not path-connected.

**Proof** By IVT.

**Theorem 4.0.2** (Intermediate Value Theorem for Path-Connectedness). *Let  $X$  be a path-connected space and  $f : X \rightarrow \mathbb{R}$  be continuous. Suppose there exist  $x_1, x_2 \in X$  such that  $f(x_1) = c_1$  and  $f(x_2) = c_2$ . Then for any  $c$  between  $c_1$  and  $c_2$ , there exists some  $x \in X$  such that  $f(x) = c$ .*

**Proof** Since  $X$  is path-connected, there exists a continuous map  $g : [0, 1] \rightarrow X$  such that  $g(0) = x_1$  and  $g(1) = x_2$ . Consider the map  $h = f \circ g : [0, 1] \rightarrow \mathbb{R}$ . Since both  $f$  and  $g$  are continuous,  $h$  is continuous. Moreover,  $h(0) = f(g(0)) = f(x_1) = c_1$  and  $h(1) = f(g(1)) = f(x_2) = c_2$ . By the Intermediate Value Theorem, for any  $c$  between  $c_1$  and  $c_2$ , there exists some  $t \in [0, 1]$  such that  $h(t) = c$ . Let  $x = g(t)$ . Then  $f(x) = f(g(t)) = h(t) = c$ . Thus, there exists some  $x \in X$  such that  $f(x) = c$ . ■

**Property 4.0.4.** *Let  $X$  be a metric space. Then IVT for  $X$  holds if and only if there is no continuous and surjective map  $f : X \rightarrow \{0, 1\}$ .*

**Proof**

We assume that  $X$  contains more than one point.

One direction is trivial.

Let's assume that the IVT doesn't hold for  $X$ .

Since the IVT does not hold for  $X$ , there exists  $y_1, y_2 \in \mathbb{R}$  such that there exists  $y_3$  between  $y_1$  and  $y_2$  which is not in the range of  $f$ . Then  $f : X \rightarrow \mathbb{R} \setminus \{y_3\}$ . Now we can easily define a continuous and surjective map  $\tilde{f} : X \rightarrow \{0, 1\}$ . ■

**Property 4.0.5.** *Let  $X$  be a metric space.  $X$  is connected if and only if IVT for  $X$  holds.*

**Proof**

The statement is equivalent to:  $X$  is connected if and only if there is no continuous and surjective map  $f : X \rightarrow \{0, 1\}$ .

Suppose there is a continuous and surjective map  $f : X \rightarrow \{0, 1\}$ . Then  $f^{-1}(\{0\})$  and  $f^{-1}(\{1\})$  are non-empty, disjoint, open subsets of  $X$  whose union is  $X$ . Thus,  $X$  is not connected.

Suppose that there is no continuous and surjective map  $f : X \rightarrow \{0, 1\}$ . If  $X$  is not connected, then there exist non-empty, disjoint, open subsets  $U_1, U_2$  of  $X$  such that  $X = U_1 \sqcup U_2$ . We can define a map  $f : X \rightarrow \{0, 1\}$  by setting  $f(x) = 0$  if  $x \in U_1$  and  $f(x) = 1$  if  $x \in U_2$ . This map is continuous and surjective, contradicting our assumption. Therefore,  $X$  must be connected. ■

**Corollary 4.0.2.** *Let  $X$  be a metric space. If  $X$  is path-connected, then  $X$  is connected.*

**Proof** Since  $X$  is path-connected, IVT for  $X$  holds. Thus,  $X$  is connected. ■

**Remark** IVT holds for  $X$  doesn't implies  $X$  is path-connected.

**Example 4.0.5.** *This is an example of a connected space but not path-connected:*

$$X = \{(x, \sin \frac{1}{x}) | x > 0\} \cup (\{0\} \times [-1, 1]) \quad (4.1)$$