

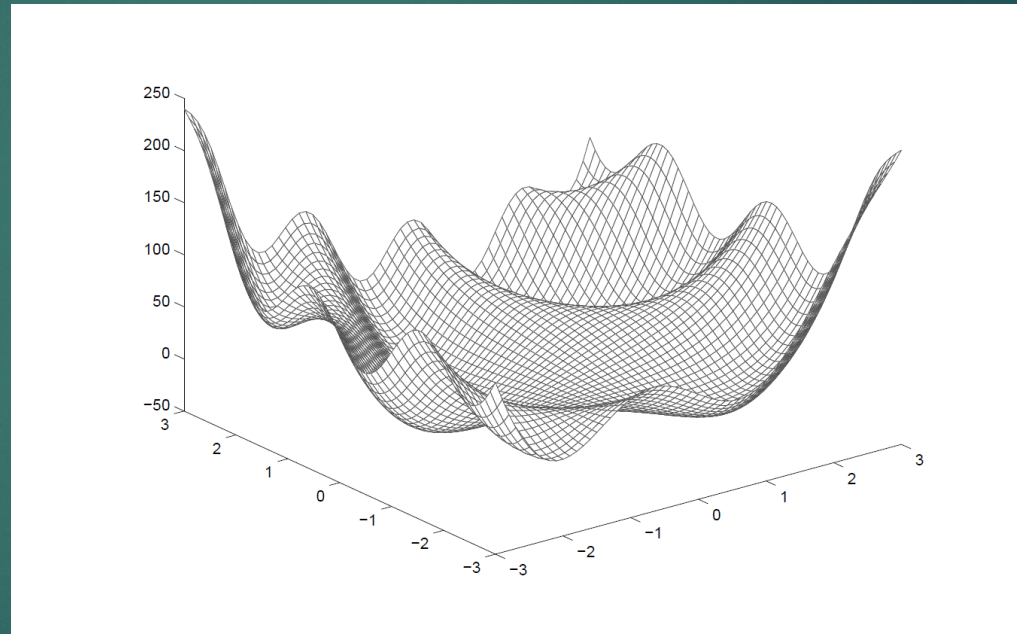
Optimization

Why Optimization?

- ▶ Example: Stock Market – “Minimize variance of return subject to getting at least \$50.”

Big Problem ...

- ▶ Local minima of f
- ▶ All kinds of constraints ...



- ▶ Answer: go for convex problems!

- ▶ Optimization is at the heart of many practical machine learning algorithms

- ▶ Linear regression

$$\text{minimize}_w \|Xw - y\|^2$$

- ▶ Logistic regression

$$\text{minimize}_w \|w\|^2 + C \sum_i \xi_i \text{ s.t. } \xi_i \geq 1 - y_i w_i^T w, \xi_i \geq 0$$

- ▶ Maximum likelihood estimation

$$\text{maximize} \sum_i \log p(x_i)$$

- ▶ k-means

$$\text{minimize } J = \sum_j \sum_{i \in C_j} \|x_i - \mu_j\|^2$$

- ▶ And more !

Gradient Descent

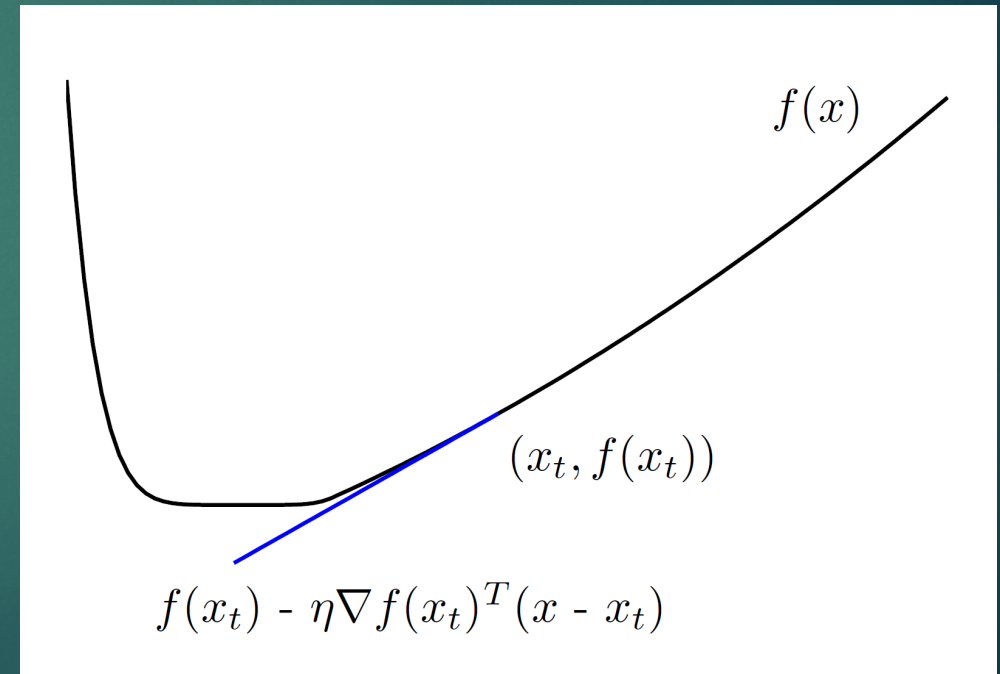
- ▶ Goal

$$\operatorname{argmin}_x f(x)$$

- ▶ Iterate

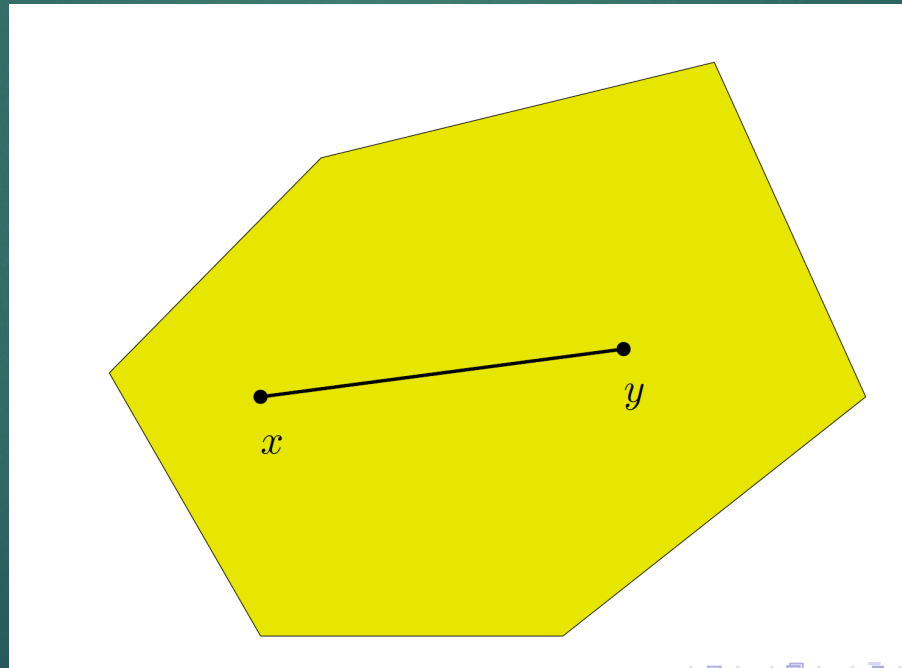
$$x_{t+1} = x_t - \eta \nabla f(x_t)$$

- ▶ η is the stepsize



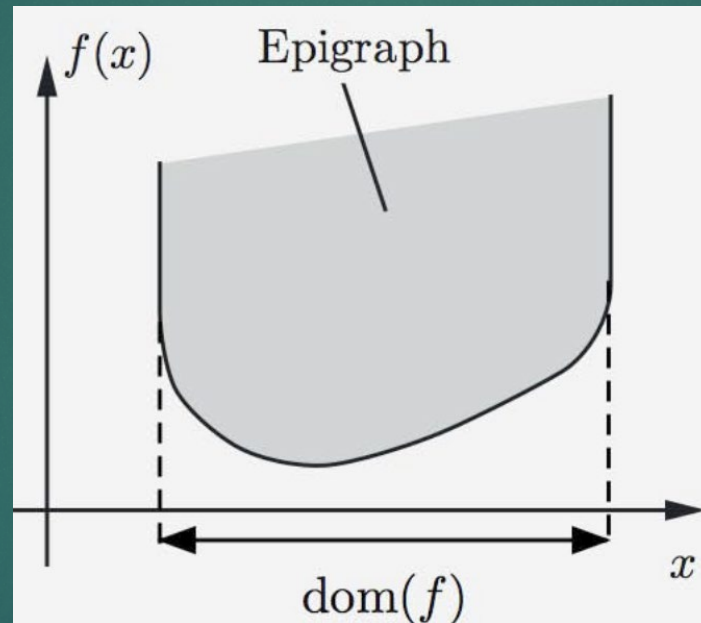
Convex Set

- ▶ A set $S \subseteq \mathbb{R}^n$ is convex if it contains the line segment joining any of its points.



Convex Function

- ▶ A function $f: \mathbb{R}^n \rightarrow \mathbb{R}$ is convex if $\text{epi}(f)$ is a convex set

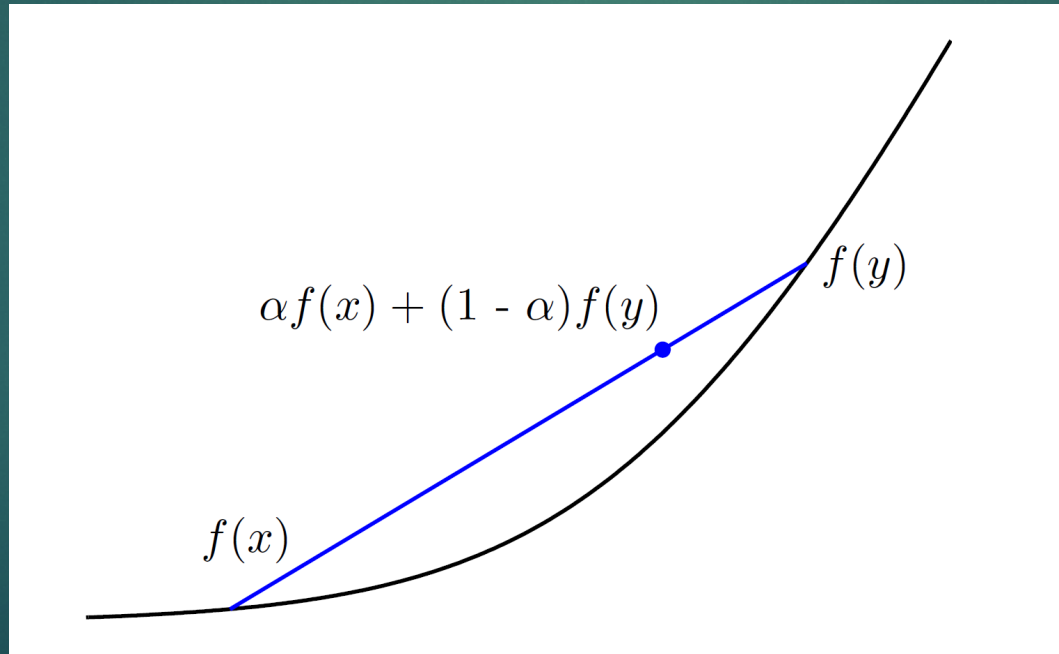


- ▶ Where $\text{dom}(f) = \{x \in X \mid f(x) < \infty\}$

Convex Function

- ▶ A function $f: \mathbb{R}^n \rightarrow \mathbb{R}$ is convex if for $x, y \in \mathbb{R}^n$ and any $\alpha \in [0,1]$

$$f(\alpha x + (1 - \alpha)y) \leq \alpha f(x) + (1 - \alpha)f(y)$$



Optimization Problem

- ▶ Many useful problems can be formulated as convex optimization problems
- ▶ Unconstrained optimization
- ▶ Constrained optimization

Unconstrained Optimization

- ▶ Recall how to find maxima and minima in calculus
- ▶ Given a function $y = f(x)$
- ▶ x^* is a critical point if $y' = \frac{df}{dx} = 0$
- ▶ x^* is maximum if $y'' = \frac{d^2f}{dx^2} < 0$
- ▶ x^* is minimum if $y'' = \frac{d^2f}{dx^2} > 0$
- ▶ x^* is neither maximum or minimum if $y'' = \frac{d^2f}{dx^2} = 0$



- ▶ For a multi-variable function $f(\mathbf{x})$
- ▶ Calculate $\nabla f(\mathbf{x})$ and $\nabla^2 f(\mathbf{x})$
 - ▶ $H(\mathbf{x}) = \nabla^2 f(\mathbf{x})$ is a matrix called the Hessian of $f(\mathbf{x})$
- ▶ Find the eigenvalues of $H(\mathbf{x})$ to determine the convexity of $f(\mathbf{x})$
 - ▶ $\lambda_1 > 0, \lambda_2 > 0 \rightarrow$ Positive Definite (PD) \rightarrow Strictly Convex
 - ▶ $\lambda_1 > 0, \lambda_2 = 0 \rightarrow$ Positive Semi Definite (PSD) \rightarrow Convex
 - ▶ $\lambda_1 < 0, \lambda_2 < 0 \rightarrow$ Negative Definite (ND) \rightarrow Strictly Concave
 - ▶ $\lambda_1 < 0, \lambda_2 = 0 \rightarrow$ Negative Semi Definite (NSD) \rightarrow Concave
 - ▶ $\lambda_1 > 0, \lambda_2 < 0 \rightarrow$ Indefinite

Eigenvalues of the Hessian matrix

- ▶ Let H be a square matrix then

$$H\mathbf{v} = \lambda\mathbf{v}$$

- ▶ Where

- ▶ λ is an eigenvalue of H
- ▶ \mathbf{v} is an eigenvector associated with λ

Example: $f(x, y) = x^2 + y^2$

► Compute $\nabla f(x, y)$

► $\frac{\partial f}{\partial x} = 2x$

► $\frac{\partial f}{\partial y} = 2y$

► Compute $\nabla^2 f(x, y)$

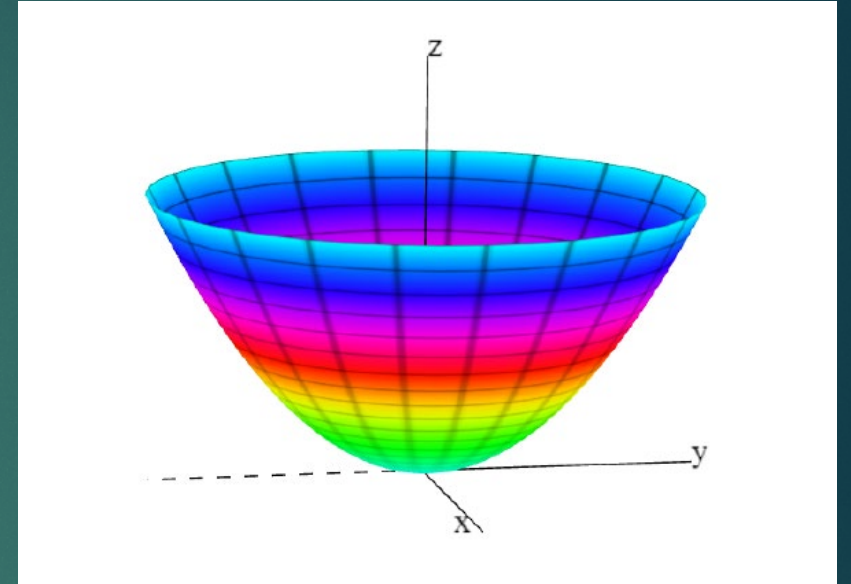
► $\frac{\partial^2 f}{\partial x^2} = 2$

► $\frac{\partial^2 f}{\partial y^2} = 2$

► $\frac{\partial f}{\partial x \partial y} = 0$

► $\frac{\partial f}{\partial y \partial x} = 0$

$$H = \begin{bmatrix} \frac{\partial^2 f}{\partial x^2} & \frac{\partial f}{\partial x \partial y} \\ \frac{\partial f}{\partial y \partial x} & \frac{\partial^2 f}{\partial y^2} \end{bmatrix} = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix}$$



Example: $f(x, y) = x^2 + y^2$

- ▶ Find the eigenvalues of the Hessian matrix
 - ▶ $\begin{vmatrix} 2-\lambda & 0 \\ 0 & 2-\lambda \end{vmatrix} = 0 \rightarrow (2-\lambda)(2-\lambda) - 0 = 0$ then solve for λ 's
 - ▶ $\lambda_1 = 2 > 0, \lambda_2 = 2 > 0 \rightarrow$ Positive Definite \rightarrow **Strictly Convex**

Constrained Optimization

- ▶ A large number of engineering problems can be formulated as constrained optimization problems.

- ▶ General form:

minimize $f(x)$

subject to $g_i(x) \leq 0, i = 1, \dots, m$

$h_i(x) = 0, i = 1, \dots, p$


$x \in \mathbb{R}^n$: optimization variable

$f: \mathbb{R}^n \rightarrow \mathbb{R}$: objective or cost function

$g_i(x) \leq 0$: inequality constraints

$h_i(x) = 0$: equality constraints

- ▶ Objective is to find optimal point x^* such that there are no other feasible points (points satisfies all constraints) where $f(x) < f(x^*)$

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- ▶ Solving general optimization problem is difficult
 - ▶ Local optima
 - ▶ Feasible set may be empty
 - ▶ Poor convergence rates
 - ▶ If f and g are convex and h is affine, then any local optimum is the global optimum

Lagrangian Function

- ▶ Recall the standard form:

minimize $f(x)$

subject to $g_i(x) \leq 0, i = 1, \dots, m$

$h_i(x) = 0, i = 1, \dots, p$

- ▶ Lagrangian

- ▶ $L(x, \alpha, \beta) = f(x) + \sum_{i=1}^m \alpha_i g_i(x) + \sum_{i=1}^p \beta_i h_i(x)$

- ▶ Scalars α_i, β_i are called Lagrange multipliers

- ▶ Lagrange Dual Function

- ▶ $\theta_D(\alpha, \beta) = \min_x L(x, \alpha, \beta) = \min_x [f(x) + \sum_{i=1}^m \alpha_i g_i(x) + \sum_{i=1}^p \beta_i h_i(x)]$

Example:

- ▶ Given a constraint optimization problem

$$\begin{aligned} &\text{minimize } -2x + y + x^2 - 2xy + y^2 \\ &\text{subject to } x + y = 0 \end{aligned}$$

- ▶ A). Find the optimal solution (x^*, y^*)

- ▶ $L = f(x, y) + \lambda h(x, y) = -2x + y + x^2 - 2xy + y^2 + \lambda(x + y)$

- ▶ $\frac{\partial L}{\partial x} = -2 + 2x - 2y + \lambda = 0$

- ▶ $\frac{\partial L}{\partial y} = 1 - 2x + 2y + \lambda = 0$

- ▶ $\frac{\partial L}{\partial \lambda} = x + y = 0$

- ▶ $\lambda = \frac{1}{2}, x^* = \frac{3}{8}, y^* = -\frac{3}{8}$

- ▶ No other point (x, y) yields $f(x, y) \leq f(x^*, y^*)$

Example:

- ▶ B). Determine the convexity of the function

- ▶ Find the Hessian matrix

- ▶ $\frac{\partial f}{\partial x} = -2 + 2x - 2y \rightarrow \frac{\partial^2 f}{\partial x^2} = 2, \frac{\partial^2 f}{\partial x \partial y} = -2$

- ▶ $\frac{\partial f}{\partial y} = 1 - 2x + 2y \rightarrow \frac{\partial^2 f}{\partial y^2} = 2, \frac{\partial^2 f}{\partial y \partial x} = -2$

- ▶ $H = \begin{bmatrix} \frac{\partial^2 f}{\partial x^2} & \frac{\partial^2 f}{\partial x \partial y} \\ \frac{\partial^2 f}{\partial y \partial x} & \frac{\partial^2 f}{\partial y^2} \end{bmatrix} = \begin{bmatrix} 2 & -2 \\ -2 & 2 \end{bmatrix}$

- ▶ Compute the eigenvalues

- ▶ $\begin{vmatrix} 2 - \lambda & -2 \\ -2 & 2 - \lambda \end{vmatrix} = 0 \rightarrow \lambda_1 = 0, \lambda_2 = 4 \rightarrow \text{PSD} \rightarrow \text{the function is convex}$

References

- ▶ Introduction to Convex Optimization for Machine Learning by J. Duchi
- ▶ Convex Optimization by S. Boyd and L. Vandenberghe