

# VECTOR SPACE

---

REFERENCE: INTRODUCTION TO LINEAR ALGEBRA (GILBERT STRANG)

# VECTOR SPACE

---

Any subset  $E \subseteq \mathbb{C}^N$  coupled with addition and multiplication operations that satisfies:

- Commutation:  $\mathbf{x} + \mathbf{y} = \mathbf{y} + \mathbf{x}$
- Association:  $(\mathbf{x} + \mathbf{y}) + \mathbf{z} = \mathbf{x} + (\mathbf{y} + \mathbf{z})$   $(\alpha\beta)\mathbf{x} = \alpha(\beta\mathbf{x})$
- Distribution:  $\alpha(\mathbf{x} + \mathbf{y}) = \alpha\mathbf{x} + \alpha\mathbf{y}$   $(\alpha + \beta)\mathbf{x} = \alpha\mathbf{x} + \beta\mathbf{x}$
- Additive identity:  $\mathbf{x} + \mathbf{0} = \mathbf{x}$
- Additive inverse:  $\mathbf{x} + (-\mathbf{x}) = \mathbf{0}$
- Multiplicative identity:  $\mathbf{1} \cdot \mathbf{x} = \mathbf{x}$

where  $\mathbf{x}, \mathbf{y}, \mathbf{z} \in E$  and  $\alpha, \beta \in \mathbb{C}$

# SUBSPACE

---

- Any set  $M \subseteq E$  for which the following properties hold:
  - Closure under addition:  $\mathbf{x}, \mathbf{y} \in M \rightarrow \mathbf{x} + \mathbf{y} \in M$
  - Closure under scalar multiplication:  $\mathbf{x} \in M, \alpha \in \mathbb{C} \rightarrow \alpha \mathbf{x} \in M$

# LINEAR INDEPENDENCE

---

- Given  $S = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$  in vector space  $V$
- $S$  is a linearly independent set if  $\sum_i \alpha_i \mathbf{v}_i = 0$  is true only when  $\alpha_i = 0 \forall i$

# SPAN

---

- Given  $S = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$  in vector space  $V$
- $S$  spans  $V$  if every vector in  $V$  can be written as a linear combination of  $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n$



# BASIS

---

- $S = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$  is a basis for subspace  $V$  iff
  - $S$  spans  $V$
  - $S$  is linearly independent
- Orthogonal basis:  $\langle \mathbf{v}_i, \mathbf{v}_j \rangle = \begin{cases} \neq 0 & \text{if } i = j \\ 0 & \text{otherwise} \end{cases}$
- Orthonormal basis is an orthogonal basis where  $\|\mathbf{v}_i\| = 1 \ \forall i$ 
  - Hence,  $\langle \mathbf{v}_i, \mathbf{v}_j \rangle = \begin{cases} 1 & \text{if } i = j \\ 0 & \text{otherwise} \end{cases}$
  - Good for coordinate systems