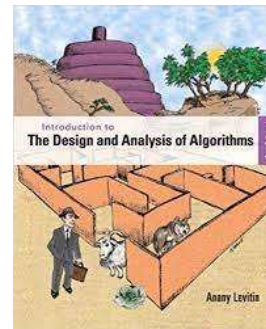


5-Divide-and-Conquer

A. Levitin "Introduction to the Design & Analysis of Algorithms," 3rd ed., Ch. 1 ©2012
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Divide-and-Conquer

The most-well known algorithm design strategy:

1. Divide instance of problem into two or more smaller instances
2. Solve smaller instances recursively
3. Obtain solution to original (larger) instance by combining these solutions

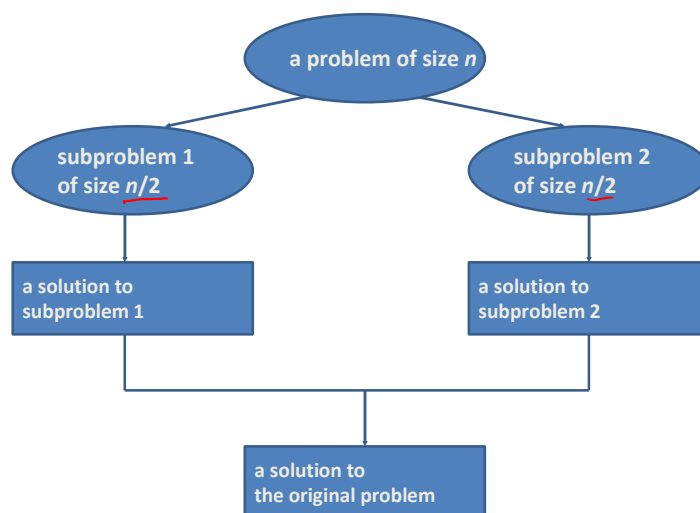
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Divide-and-Conquer Technique (cont.)



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Divide-and-Conquer Examples

- Sorting: mergesort and quicksort
- Binary tree traversals
- Multiplication of large integers
- Matrix multiplication: Strassen's algorithm
- Closest-pair and convex-hull algorithms
- *Binary search: decrease-by-half (or degenerate divide&conq.)*

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General Divide-and-Conquer Recurrence

$$T(n) = aT(n/b) + f(n) \text{ where } f(n) \in \Theta(n^d), d \geq 0$$

Master Theorem:

- If $a < b^d$, $T(n) \in \Theta(n^d)$
- If $a = b^d$, $T(n) \in \Theta(n^d \log n)$
- If $a > b^d$, $T(n) \in \Theta(n^{\log_b a})$

Note: The same results hold with \underline{O} instead of $\underline{\Theta}$.

Examples: $T(n) = 4T\left(\frac{n}{2}\right) + n \rightarrow T(n) \in ?$

$$T(n) = 4T\left(\frac{n}{2}\right) + n^2 \rightarrow T(n) \in ?$$

$$T(n) = 4T\left(\frac{n}{2}\right) + n^3 \rightarrow T(n) \in ?$$

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If $a < b^d$, $T(n) \in \Theta(n^d)$
 If $a = b^d$, $T(n) \in \Theta(n^d \log n)$
 If $a > b^d$, $T(n) \in \Theta(n^{\log_b a})$

1) $T(n) = 4T(n/2) + n$
 $a=4$ $b=2$ $d=1$ $b^d=2 \rightarrow \log_2 2 = 1$
 $a > b^d \Rightarrow T(n) \in \Theta(n^{\log_2 4}) = \Theta(n^2)$

2) $T(n) = 4T(n/2) + n^2$
 $a=4$ $b=2$ $d=2$ $b^d=4$
 $a = b^d \Rightarrow T(n) \in \Theta(n^2 \log n)$

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If $a < b^d$, $T(n) \in \Theta(n^d)$
 If $a = b^d$, $T(n) \in \Theta(n^d \log n)$
 If $a > b^d$, $T(n) \in \Theta(n^{\log_b a})$

$$\begin{aligned}
 3) \quad T(n) &= 4T(n/2) + n^3 \\
 a &= 4 \quad b = 2 \quad d = 3 \\
 a &< b^d \Rightarrow T(n) \in \Theta(n^3)
 \end{aligned}$$

$$\begin{aligned}
 4) \quad T(n) &= 3T\left(\frac{2n}{3}\right) + n^{1/2} \\
 a &= 3 \quad b = \frac{3}{2} \quad d = 1 \\
 a &> b^d \Rightarrow T(n) \in \Theta(n^{\log_{3/2} 3})
 \end{aligned}$$

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Mergesort

- Split array $A[0..n-1]$ in two about equal halves and make copies of each half in arrays B and C
- Sort arrays B and C recursively
- Merge sorted arrays B and C into array A as follows:
 - Repeat the following until no elements remain in one of the arrays:
 - compare the first elements in the remaining unprocessed portions of the arrays
 - copy the smaller of the two into A, while incrementing the index indicating the unprocessed portion of that array
 - Once all elements in one of the arrays are processed, copy the remaining unprocessed elements from the other array into A.

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Pseudocode of Mergesort

ALGORITHM *Mergesort*($A[0..n-1]$)

$T(n) = 2T(n/2) + f(n)$
 $f(n) \in \Theta(n)$

//Sorts array $A[0..n-1]$ by recursive mergesort
 //Input: An array $A[0..n-1]$ of orderable elements *in all cases*
 //Output: Array $A[0..n-1]$ sorted in nondecreasing order
if $n > 1$
 copy $A[0..\lfloor n/2 \rfloor - 1]$ to $B[0..\lfloor n/2 \rfloor - 1]$
 copy $A[\lfloor n/2 \rfloor..n-1]$ to $C[0..\lfloor n/2 \rfloor - 1]$
 → *Mergesort*($B[0..\lfloor n/2 \rfloor - 1]$)
 → *Mergesort*($C[0..\lfloor n/2 \rfloor - 1]$)
 Merge(B, C, A) //see below → $\Theta(n)$

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Pseudocode of Mergesort

ALGORITHM *Merge*($B[0..p-1], C[0..q-1], A[0..p+q-1]$)

//Merges two sorted arrays into one sorted array
 //Input: Arrays $B[0..p-1]$ and $C[0..q-1]$ both sorted
 //Output: Sorted array $A[0..p+q-1]$ of the elements of B and C
 $i \leftarrow 0; j \leftarrow 0; k \leftarrow 0$
while $i < p$ **and** $j < q$ **do**
 if $B[i] \leq C[j]$
 $A[k] \leftarrow B[i]; i \leftarrow i + 1$
 else $A[k] \leftarrow C[j]; j \leftarrow j + 1$
 $k \leftarrow k + 1$
if $i = p$
 copy $C[j..q-1]$ to $A[k..p+q-1]$
else copy $B[i..p-1]$ to $A[k..p+q-1]$

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Merge:

B → 1 3 5 7 9 11
C → 2 4 6 8 10 12

1 2 3

for $n \rightarrow n-1$ comparisons.
worst case $\Theta(n)$

best case

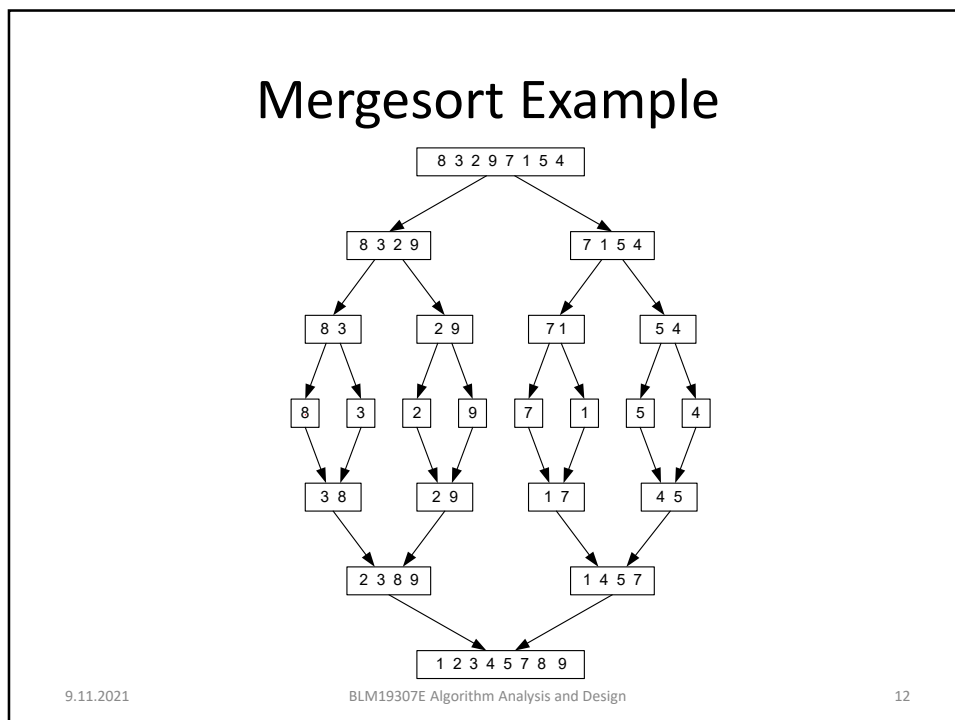
1 2 3 4 5 6
7 8 9 10 11 12

$n/2$ comparisons
 $\Theta(n)$

Merge

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Analysis of Mergesort

- All cases have same efficiency: $\Theta(n \log n)$
- Number of comparisons in the worst case is close to theoretical minimum for comparison-based sorting:

$$\lceil \log_2 n! \rceil \approx n \log_2 n - 1.44n$$
- Space requirement: $\Theta(n)$ (not in-place)
- Can be implemented without recursion (bottom-up)

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$$T(n) = 2T(n/2) + f(n) \quad f(n) \in \Theta(n)$$

Master theorem

$$a=2 \quad b=2 \quad d=1$$

$$a=b^d \Rightarrow \Theta(n^d \log n)$$

$$\Rightarrow \boxed{T(n) \in \Theta(n \log n)}$$

in all cases.

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3-way mergesort

Pseudocode:

```

mergesort3(A[0...n-1])
if n > 1
  copy A[0...L(n/3)-1] to B
  copy A[L(n/3)...2L(n/3)-1] to C
  copy A[2L(n/3)...n-1] to D
  - mergesort3(B)
  - mergesort3(C)
  - mergesort3(D)
  - merge(B, C, E)
  - merge(E, D, A)

```

Recurrence Relation

$$T(n) = 3T(n/3) + f(n)$$

$$T(n) = 3T(n/3) + \frac{5n}{3} - 2$$

Worst case:

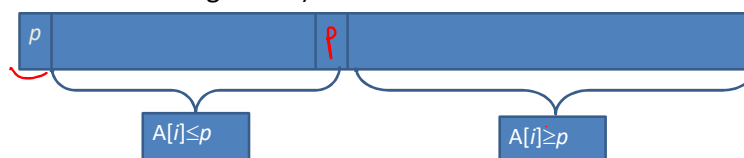
m.i.t. $a=3, b=3, c=1$
 $a=b^c \Rightarrow T(n) \in (n \log n)$

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Quicksort

- Select a pivot (partitioning element) – here, the first element
- Rearrange the list so that all the elements in the first s positions are smaller than or equal to the pivot and all the elements in the remaining n-s positions are larger than or equal to the pivot (see next slide for an algorithm)



- Exchange the pivot with the last element in the first (i.e., \leq) subarray — the pivot is now in its final position
- Sort the two subarrays recursively

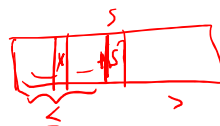
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Pseudocode of Quicksort



ALGORITHM *Quicksort*($A[l..r]$)

//Sorts a subarray by quicksort

//Input: Subarray of array $A[0..n - 1]$, defined by its left and right
// indices l and r

//Output: Subarray $A[l..r]$ sorted in nondecreasing order

if $l < r$

$s \leftarrow \text{Partition}(A[l..r])$ // s is a split position

↪ *Quicksort*($A[l..s - 1]$)

↪ *Quicksort*($A[s + 1..r]$)

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Hoare's Partitioning Algorithm

ALGORITHM *HoarePartition*($A[l..r]$)

//Partitions a subarray by Hoare's algorithm, using the first element
// as a pivot

//Input: Subarray of array $A[0..n - 1]$, defined by its left and right
// indices l and r ($l < r$)

//Output: Partition of $A[l..r]$, with the split position returned as
// this function's value

$p \leftarrow A[l]$

$i \leftarrow l; j \leftarrow r + 1$

repeat

repeat $i \leftarrow i + 1$ **until** $A[i] \geq p$

repeat $j \leftarrow j - 1$ **until** $A[j] \leq p$

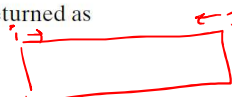
swap($A[i], A[j]$)

until $i \geq j$

swap($A[i], A[j]$) //undo last swap when $i \geq j$

swap($A[l], A[j]$)

return j



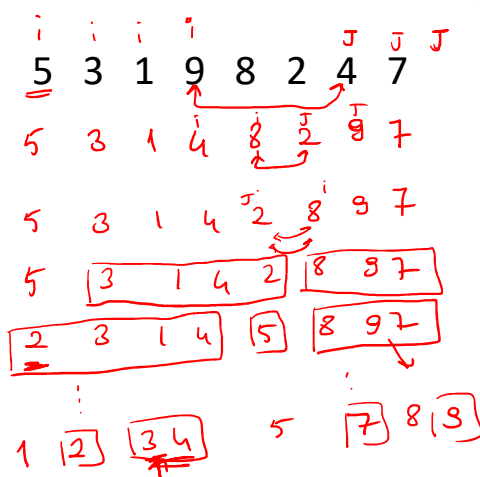
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Quicksort Example



ALGORITHM *HoarePartition*($A[l..r]$)

```
//Partitions a subarray by Hoare's algorithm, using the first element
// as a pivot
//Input: Subarray of array  $A[0..n-1]$ , defined by its left and right
// indices  $l$  and  $r$  ( $l < r$ )
//Output: Partition of  $A[l..r]$ , with the split position returned as
// this function's value
 $p \leftarrow A[l]$ 
 $i \leftarrow l; j \leftarrow r + 1$ 
repeat
  repeat  $i \leftarrow i + 1$  until  $A[i] \geq p$ 
  repeat  $j \leftarrow j - 1$  until  $A[j] \leq p$ 
  swap( $A[i], A[j]$ )
until  $i \geq j$ 
 $\text{swap}(A[i], A[j])$  //undo last swap when  $i \geq j$ 
 $\text{swap}(A[l], A[j])$ 
return  $j$ 
```

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Analysis of Quicksort

- Best case: split in the middle — $\Theta(n \log n)$
- Worst case: sorted array! — $\Theta(n^2)$ $\Rightarrow C_w(n) = C_w(n-1) + n$
- Average case: random arrays — $\Theta(n \log n)$ $\Rightarrow \Theta(n^2)$

Improvements:

- better pivot selection: median of three partitioning
- switch to insertion sort on small subfiles
- elimination of recursion

These combine to 20-25% improvement

- Considered the method of choice for internal sorting of large files ($n \geq 10000$)

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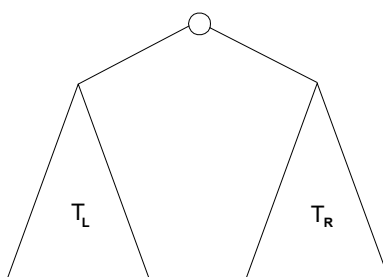
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Binary Tree Algorithms

Binary tree is a divide-and-conquer ready structure!



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Binary Tree Algorithms

Ex. 1: Classic traversals (preorder, inorder, postorder)

- In the **preorder** traversal, the root is visited before the left and right subtrees are visited (in that order).
- In the **inorder** traversal, the root is visited after visiting its left subtree but before visiting the right subtree.
- In the **postorder** traversal, the root is visited after visiting the left and right subtrees (in that order).

- Efficiency: $\Theta(n)$

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Binary Tree Algorithms (cont.)

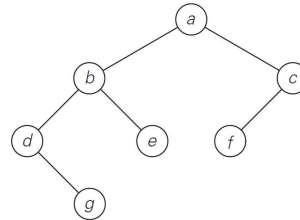
Algorithm *Inorder*(*T*)

if $T \neq \emptyset$

Inorder(T_{left})

print(root of *T*)

Inorder(T_{right})



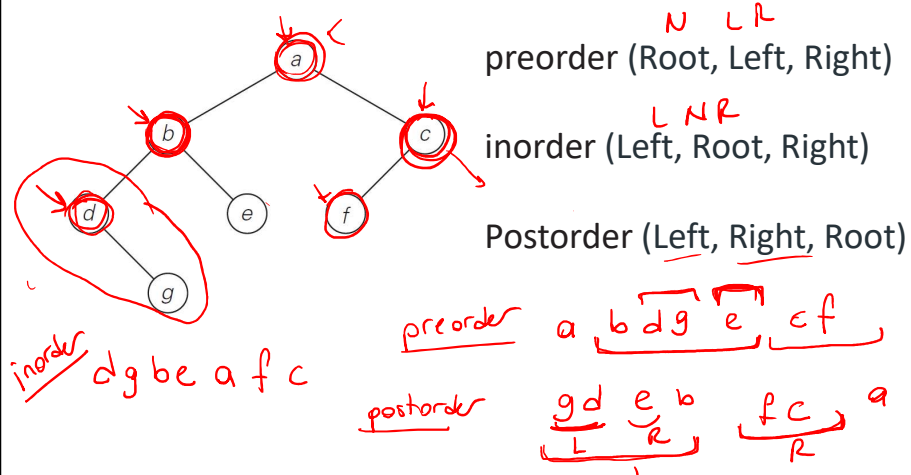
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Binary Tree Algorithms (cont.)



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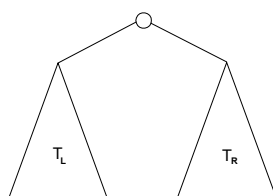
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Binary Tree Algorithms (cont.)

Ex. 2: Computing the height of a binary tree



$$h(T) = \max\{h(T_L), h(T_R)\} + 1 \text{ if } T \neq \emptyset \text{ and } h(\emptyset) = -1$$

Efficiency: $\theta(n)$

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Binary Tree Algorithms (cont.)

ALGORITHM *Height*(*T*)

//Computes recursively the height of a binary tree

//Input: A binary tree *T*

//Output: The height of *T*

if *T* = \emptyset **return** -1

else return $\max\{\text{Height}(T_{\text{left}}), \text{Height}(T_{\text{right}})\} + 1$

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Multiplication of Large Integers

Consider the problem of multiplying two (large) n -digit integers represented by arrays of their digits such as:

$A = 12345678901357986429$ $B = 87654321284820912836$

The grade-school algorithm:

$$\begin{array}{r}
 a_1 \ a_2 \ \dots \ a_n \\
 b_1 \ b_2 \ \dots \ b_n \\
 \hline
 (d_{10}) \ d_{11} \ d_{12} \ \dots \ d_{1n} \\
 (d_{20}) \ d_{21} \ d_{22} \ \dots \ d_{2n} \\
 \dots \dots \dots \dots \dots \dots \dots \\
 (d_{n0}) \ d_{n1} \ d_{n2} \ \dots \ d_{nn}
 \end{array}$$

Efficiency: n^2 one-digit multiplications

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First Divide-and-Conquer Algorithm

A small example: $A * B$ where $A = 2135$ and $B = 4014$ $n=4$
 $n/2=2$

$A = (21 \cdot 10^2 + 35)$, $B = (40 \cdot 10^2 + 14)$

So, $A * B = (21 \cdot 10^2 + 35) * (40 \cdot 10^2 + 14)$

$$= 21 * 40 \cdot 10^4 + (21 * 14 + 35 * 40) \cdot 10^2 + 35 * 14$$

In general, if $A = A_1A_2$ and $B = B_1B_2$ (where A and B are n -digit, A_1, A_2, B_1, B_2 are $n/2$ -digit numbers),

$$A * B = A_1 * B_1 \cdot 10^n + (A_1 * B_2 + A_2 * B_1) \cdot 10^{n/2} + A_2 * B_2$$

Recurrence for the number of one-digit multiplications $M(n)$:

$$M(n) = 4M(n/2), \quad M(1) = 1$$

Solution: $M(n) = n^2$ master theorem $\Rightarrow \Theta(n^2)$

as $k=2$ $\downarrow = 3$

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Second Divide-and-Conquer Algorithm

$$A * B = A_1 * B_1 \cdot 10^n + (A_1 * B_2 + A_2 * B_1) \cdot 10^{n/2} + A_2 * B_2$$

$$A = A_1 A_2 \\ B = B_1 B_2$$

The idea is to decrease the number of multiplications from 4 to 3:

$$(A_1 + A_2) * (B_1 + B_2) = A_1 * B_1 + (A_1 * B_2 + A_2 * B_1) + A_2 * B_2$$

i.e. $(A_1 * B_2 + A_2 * B_1) = (A_1 + A_2) * (B_1 + B_2) - A_1 * B_1 - A_2 * B_2$
which requires only 3 multiplications at the expense of (4-1) extra
add/sub.

$$A * B = (A_1 * B_1) \cdot 10^n + [(A_1 + A_2) * (B_1 + B_2) - A_1 * B_1 - A_2 * B_2] \cdot 10^{n/2} + A_2 * B_2$$

Recurrence for the number of multiplications $M(n)$:

$$M(n) = 3M(n/2), \quad M(1) = 1$$

$$\text{Solution: } M(n) = 3^{\log_2 n} = n^{\log_2 3} \approx n^{1.585}$$

Master theorem

$$< \mathcal{O}(n^2)$$

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Example of Large-Integer Multiplication

$$2135 * 4014$$

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Strassen's Matrix Multiplication

Strassen observed [1969] that the product of two matrices can be computed as follows:

$$\begin{pmatrix} C_{00} & C_{01} \\ C_{10} & C_{11} \end{pmatrix} = \begin{pmatrix} A_{00} & A_{01} \\ A_{10} & A_{11} \end{pmatrix} * \begin{pmatrix} B_{00} & B_{01} \\ B_{10} & B_{11} \end{pmatrix}$$

$A_{n \times n}$ $A_{n/2 \times n/2}$
 $B_{n \times n}$ $B_{n/2 \times n/2}$

$$= \begin{pmatrix} M_1 + M_4 - M_5 + M_7 & M_3 + M_5 \\ M_2 + M_4 & M_1 + M_3 - M_2 + M_6 \end{pmatrix}$$

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Formulas for Strassen's Algorithm

$$M_1 = (A_{00} + A_{11}) * (B_{00} + B_{11})$$

$$M_2 = (A_{10} + A_{11}) * B_{00}$$

$$M_3 = A_{00} * (B_{01} - B_{11})$$

$$M_4 = A_{11} * (B_{10} - B_{00})$$

$$M_5 = (A_{00} + A_{01}) * B_{11}$$

$$M_6 = (A_{10} - A_{00}) * (B_{00} + B_{01})$$

$$M_7 = (A_{01} - A_{11}) * (B_{10} + B_{11})$$

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Analysis of Strassen's Algorithm

If n is not a power of 2, matrices can be padded with zeros.

$$\begin{bmatrix} 1 & 2 & 3 & 0 \\ 4 & 5 & 6 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Number of multiplications:

$$M(n) = 7M(n/2), \quad M(1) = 1$$

Solution: $M(n) = 7^{\log_2 n} = n^{\log_2 7} \approx n^{2.807}$ vs. n^3 of brute-force alg.

master theorem. $a=7 \quad b=2 \quad d=0$
 $\Theta(n^{2.807}) < \Theta(n^3)$

Algorithms with better asymptotic efficiency are known but they are even more complex.

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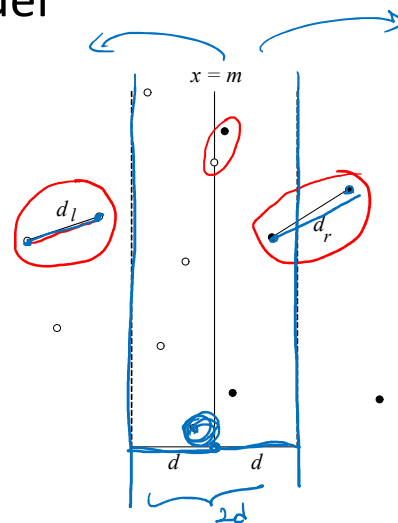
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Closest-Pair Problem by Divide-and-Conquer

Step 1 Divide the points given into two subsets P_l and P_r by a vertical line $x = m$ so that half the points lie to the left or on the line and half the points lie to the right or on the line.

$$d = \min\{d_l, d_r\}$$



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Closest Pair by Divide-and-Conquer (cont.)

Step 2 Find recursively the closest pairs for the left and right subsets.

Step 3 Set $d = \min\{d_l, d_r\}$

We can limit our attention to the points in the symmetric vertical strip S of width $2d$ as possible closest pair. (The points are stored and processed in increasing order of their y coordinates.)

Step 4 Scan the points in the vertical strip S from the lowest up. For every point $p(x, y)$ in the strip, inspect points in the strip that may be closer to p than d . There can be no more than 5 such points following p on the strip list!

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Efficiency of the Closest-Pair Algorithm

Running time of the algorithm is described by

$$T(n) = \underline{2T(n/2)} + \overset{5n}{\underline{M(n)}}, \text{ where } M(n) \in \underline{O(n)}$$

By the Master Theorem (with $a = 2$, $b = 2$, $d = 1$)

$$\boxed{T(n) \in O(n \log n)}$$

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Quickhull Algorithm

Convex hull: smallest convex set that includes given points

- Assume points are sorted by x -coordinate values
- Identify *extreme points* P_1 and P_2 (leftmost and rightmost)
- Compute *upper hull* recursively:
 - find point P_{\max} that is farthest away from line P_1P_2
 - compute the upper hull of the points to the left of line P_1P_{\max}
 - compute the upper hull of the points to the left of line $P_{\max}P_2$
- Compute *lower hull* in a similar manner

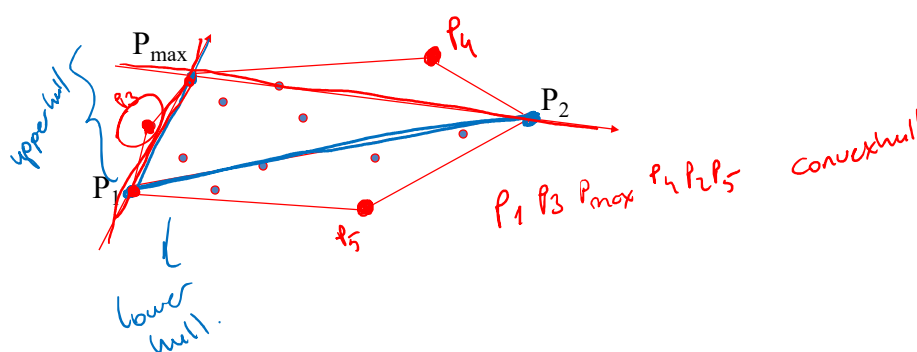
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Quickhull Algorithm



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Efficiency of Quickhull Algorithm

- Finding point farthest away from line P_1P_2 can be done in linear time
- Time efficiency:
 - worst case: $\Theta(n^2)$ (as quicksort) *→ all the points are lower hull*
 - average case: $\Theta(n)$ (under reasonable assumptions about distribution of points given)
- If points are not initially sorted by x-coordinate value, this can be accomplished in $O(n \log n)$ time
- Several $O(n \log n)$ algorithms for convex hull are known

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Example

LCPr = Berna
LCPL = Zehi

Berna
Berila

Divide and Conquer Example – Longest Common Prefix

Given n strings, the problem is to find the longest common prefix of these strings. As an example, if the input is {"abdullah", "abdi", "abdal", "abdulkerim"}, output would be "abd". If the input is {"kelam", "kelime", "kema", "kemik"}, output would be "ke".

(a) Design a divide-and-conquer algorithm for this problem. Please provide a step by step description of your algorithm.

(b) What is the time complexity of your algorithm? Write a recurrence relation and solve it. Provide an answer in terms of n and m , where n is the number of strings and m is the length of the largest string.

$T(n) = 2T(n/2) + m$ *in the worst case* *worst case.*
 $T(1) = 0$

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$S_1 \ S_2 \ \dots \ S_{n/2} \mid S_{n/2+1} \ \dots \ S_n$ n strings.
 $\underbrace{\hspace{1.5cm}}_{LCP_L} \quad \underbrace{\hspace{1.5cm}}_{LCP_R}$ 'berno'

How can combine this?

$LCP(LCP_L, LCP_R)$

if $n=1$, return whole string
 else Divide n strings into two parts.
 find LCP from the left part recursively.
 find LCP " " right " "
 ⊕ find LCP of these two prefixes
 and return this.

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$$\begin{aligned}
 T(n) &= 2T(n/2) + m & n=2^k \quad T(1) &= 0 \\
 &= 2 \cdot T(2^{k-1}) + m \\
 &= 2 \cdot [2T(2^{k-2}) + m] + m = 2^2 \cdot T(2^{k-2}) + 2m + m \\
 &= 2 \cdot [2 \cdot [2T(2^{k-3}) + m] + m] + m \\
 &= 2^3 \cdot T(2^{k-3}) + 2^2 m + 2m + m \\
 &\vdots \\
 &= 2^k T(2^{k-k}) + 2^{k-1} m + 2^{k-2} m + \dots + 2m + m \\
 &= m(2^{k-1} + 2^{k-2} + \dots + 2^1 + 1) = m(2^k - 1) \\
 &= m(n - 1) \\
 &\Rightarrow \Theta(mn)
 \end{aligned}$$

worst case.

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Example

$A[1] = 50$
 $A[2] = 55$
 Brute force. $\Theta(n^2)$



You are given an array A of n numbers. $A[i]$ is the price of a specific stock on day i . Your goal is to figure out the best days to buy and sell that stock in order to maximize profit. That is, you must find two days i, j such that $i < j$, and $A[j] - A[i]$ is maximized. Brute-force algorithm for this problem has a complexity of $O(n^2)$, but we are seeking for a more efficient algorithm.

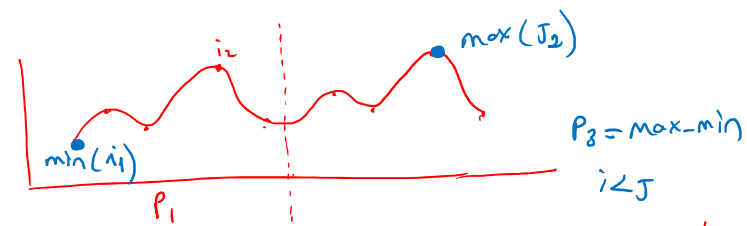
(a) Here is a divide and conquer algorithm for this problem:

1. If array has at most 2 elements, solve the problem trivially, return.
2. Solve the problem in first $n/2$ elements (recursively). Let p_1 be the maximum profit. *left*
3. Solve the problem in last $n/2$ elements (recursively). Let p_2 be the maximum profit. *right*
4.
5. Return the maximum of p_1, p_2 and p_3 .

Fill the fourth step of the above algorithm.

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p_1 : max profit when I buy in the first part and sell it in the first part.

p_2 : max profit when I buy in the second part and sell it in the second part.

p_3 : max profit when I buy in the first part and sell it in the second part.

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4) find min element in the left part $\frac{n}{2}$ (first)
 find max element in the right part $\frac{n}{2}$ (second)

$i < j$

$p_3 = \max - \min$



recursive

time complexity

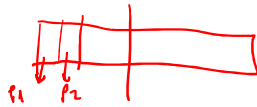
$$T(n) = 2T\left(\frac{n}{2}\right) + \frac{n}{2} + \frac{n}{2}$$

find min find max

$$T(n) = 2T\left(\frac{n}{2}\right) + n$$

$a=2$
 $b=2$
 $d=1$

Master theorem:
 $T(n) \in \Theta(n \log n)$
 Brute force $\Theta(n^2)$



$$T(n) = aT\left(\frac{n}{b}\right) + f(n)$$

$f(n) \in \Theta(n^d)$

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