

Analysis Of An airfoil Using Vortex Panel Method (S1223)

```
data      = load('s1223.txt');
XB        = flip(data(:,1));
YB        = flip(data(:,2));
YB(1,1)   = 0;
YB(end,1) = 0;

M = size(XB,1);

z = 1;
alp=0; % > array of various Angle of Attacks
cavg_arr=0; % > array of Avg(coefficent of pressure)
cavg=0; % > Avg(coefficent of pressure)
coeff=0; % > coefficent of lift
c_arr=0; % > array of coefficent of lift
p=0;
cp_arr=0;
X=0;
Y=0;
Gama=0;
V=0;
CP1=0;
V_inf=2; % > represent v infinity
CT1=0;CT2=0;CPu=0;CP=0;CN1=0;CN2=0;AT=0;AN=0;RHS=0;
theta=0;% > array of coefficent of pressure
```

Calculation of control points and other geometric parameters

```
alpha1 = 0; % > Angle of Attack used for making array of various angles v
alpha = 0; % > Angle of Attack (used in inner loop for finding various p
for p = 1:40

    alpha1=alpha1+0.5;
    alp(p)=alpha1; %alp is the alpha array
    alpha = (alpha1) * (pi/180);

    for i = 1:M-1
        X(i,1) = 0.5*( XB(i) + XB(i+1) );
        Y(i,1) = 0.5*( YB(i) + YB(i+1) );
        S(i,1) = sqrt( (XB(i+1)-XB(i))^2 + (YB(i+1)-YB(i))^2 );
        theta(i,1) = atan2( (YB(i+1)-YB(i)) , (XB(i+1)-XB(i)) );
        RHS(i,1) = sin(theta(i) - alpha);
    end
```

Calculation of Coefficients

```
for i = 1:M-1
    for j = 1:M-1
        if (i == j)
```

```

        CN1(i,j) = -1;
        CN2(i,j) = 1 ;
        CT1(i,j) = 0.5*pi;
        CT2(i,j) = 0.5*pi;
    else
        A = - (X(i) - XB(j))*(cos(theta(j))) - (Y(i) - YB(j))*(sin(theta(j)));
        B = (X(i) - XB(j))^2 + (Y(i) - YB(j))^2;
        C = sin(theta(i) - theta(j));
        D = cos(theta(i) - theta(j));
        E = (X(i) - XB(j))*sin(theta(j)) - (Y(i) - YB(j))*cos(theta(j));
        F = log(1 + ((S(j))^2 + (2*A*S(j))) / B);
        G = atan2((E*S(j)) , (B + A*S(j)));
        P = ((X(i) - XB(j)) * sin(theta(i) - 2*theta(j))) + ((Y(i) - YB(j)) * cos(theta(i) - 2*theta(j)));
        Q = ((X(i) - XB(j)) * cos(theta(i) - 2*theta(j))) - ((Y(i) - YB(j)) * sin(theta(i) - 2*theta(j)));

        CN2(i,j) = D + ((0.5*Q*F)/S(j)) - ((A*C + D*E)*(G/S(j)));
        CN1(i,j) = 0.5*D*F + C*G - CN2(i,j);
        CT2(i,j) = C + ((0.5*P*F)/S(j)) + ((A*D - C*E)*(G/S(j)));
        CT1(i,j) = 0.5*C*F - D*G - CT2(i,j);
    end
end
end

```

Computation of Influence Coefficients

```

for i = 1:M-1
    AN(i,1) = CN1(i,1);
    AN(i,M) = CN2(1,M-1);
    AT(i,1) = CT1(i,1);
    AT(i,M) = CT2(i,M-1);
    for j = 2:M-1
        AN(i,j) = CN1(i,j) + CN2(i,j-1);
        AT(i,j) = CT1(i,j) + CT2(i,j-1);
    end
end
AN(M,1) = 1;
AN(M,M) = 1;
for j = 2:M-1
    AN(M,j) = 0;
end
RHS(M) = 0;

```

Solve for Gamma and velocity/pressure

```

Gama = AN\RHS; % Solving for a syetem of linear equations

for i = 1:M-1
    V(i) = cos(theta(i)-alpha);
    for j = 1:M
        V(i) = V(i) + AT(i,j)*Gama(j);
        CP(i) = 1 - (V(i))^2;
    end
end
end

```

Calculation of Lift Coefficient

```
CP1 = CP(1:((M-1)/2));
CP1 = flip(CP1);
CPu = CP(((M-1)/2)+1:end);

dCP = CP1 - CPu;
dx = X(((M-1)/2)+1:end);
ds = 0;
j=0;

coeff = trapz(dx,dCP);
c_arr(p)=coeff; % > For making array of coefficient of lift

% > For making array of Avg(coefficient of pressure)

cavg_arr(p)=cavg;
cavg=0;
for j = 1:80
    cavg=cavg+CP(j);
end

cavg=cavg/160; % > Calculating average value of CP
cp_arr(p)=cavg; % > array of Avg(CP)
end

% > Plot of CP vs. X
figure(1)
plot(X,CP);
set(gca,'Ydir','reverse');
xlabel('x/c');
ylabel('Coefficient of Pressure (CP)');
grid on;
grid minor;
title('Fig. 1 CP vs. x/c (Chambered Airfoil)');

% > Plot of CL vs. Alpha
figure (2)
plot(alp,c_arr);
xlabel('Angle of Attack (Alpha)');
ylabel('Coefficient of Lift (CL)');
grid on;
grid minor;
title('Fig. 2 CL vs. Alpha (Chambered Airfoil)');

% > Plot of CL vs. CP
figure (3)
plot(cp_arr,c_arr);
xlabel('Average Coefficient of Pressure');
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ylabel('Coefficient of Lift (CL)');
grid on;
grid minor;
title('Fig. 3 CL vs. CP (Chambered Airfoil)');

% > Plot of Avg(CP) vs. Alpha
figure (4)
plot(alp,cp_arr);
xlabel('Angle of Attack (Alpha)');
ylabel('Average Coefficient of Pressure');
grid on;
grid minor;
title('Fig. 4 Avg(CP) vs. Alpha (Chambered Airfoil)');

% > Plot of Airfoil
figure(5)
plot(XB,YB,'b',X,Y,'g^');
axis equal; legend('Panel approximation','Control points')
xlabel('x, m'); ylabel('y, m');
grid on;
grid minor;

% > this code is used to plot velocity over the airfoil

for l=1:80
    ds(l)=XB(l+1)-XB(l);    %-> Represents the elemental length
end
n=80;                        %-> number of panels

thet=0;                      %-> Defining the angle between control points and point where
scale = 0.01;

Q = zeros(101,101);

for i=0:100                  %-> This loop is used to find the potential over the surface
    for j=-50:50
        potential = 0;
        if 0 == inpolygon(scale*i,scale*j,X,Y)
            for k = 1:n
                thet=atan((j*scale-Y(k))/(i*scale-X(k)));
                potential=potential-(1/(2*pi)).*Gama(k).*ds(k).*thet;    %-> Formula for potential
            end
        end
        Q(i+1,j+51) = potential;
    end
end
U = zeros(100, 100);        %-> defining the horizontal velocity
V = zeros(100, 100);

for i = 1:100
    for j = -49:50
        if 0 == inpolygon(scale*i,scale*j,X,Y)    %-> condition to obtain velocity

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```

        U(i,j+50) = V_inf + (Q(i+1, j+50) - Q(i, j+50))/scale;
        V(i,j+50) = (Q(i, j+51) - Q(i, j+50))/scale;
    else
        U(i,j+50) = 0; %-> cancelling the velocity
        V(i,j+50) = 0;
    end
end
end

figure(6)
hold on;
for i = 1:100
    for j = -49:50
        if 0 == inpolygon(scale*i,scale*j,X,Y) %-> plotting velocity vectors
            v = [U(i,j+50),V(i,j+50)];
            M = 50*norm(v); %-> making the velocity vectors uniform
            quiver(i*scale, j*scale, (U(i,j+50)/M), (V(i,j+50)/M));
        end
    end
end
end

```

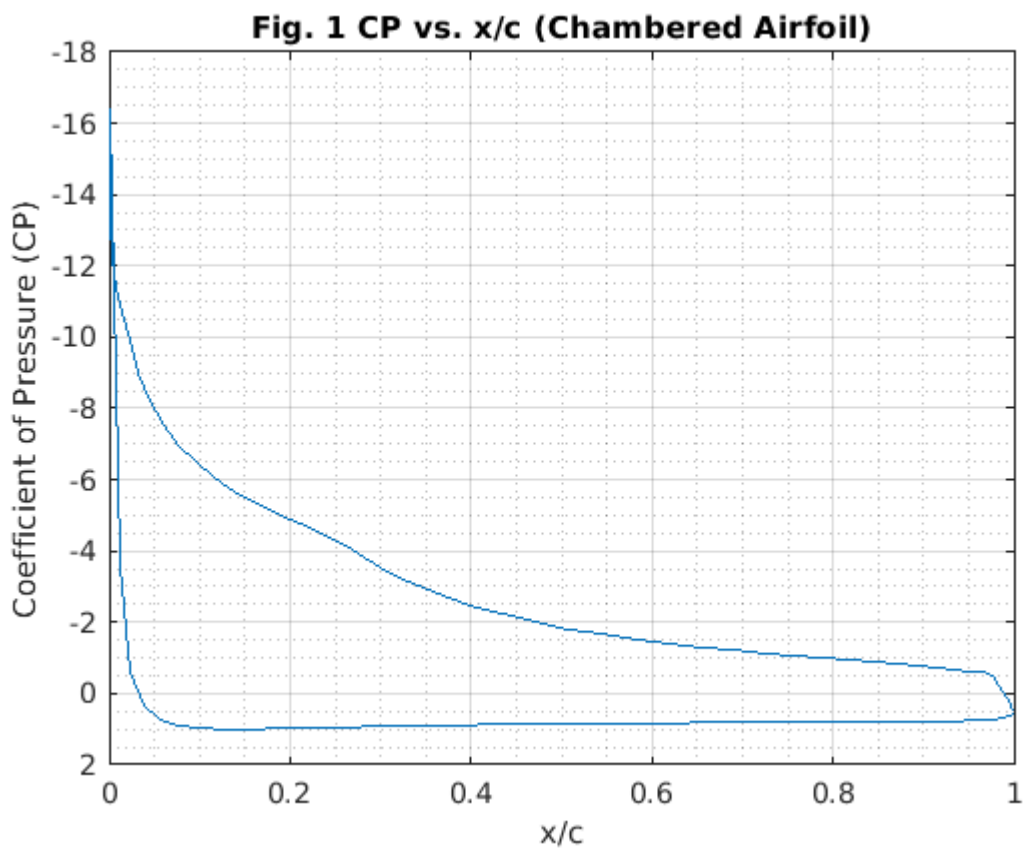


Fig. 2 CL vs. Alpha (Chambered Airfoil)

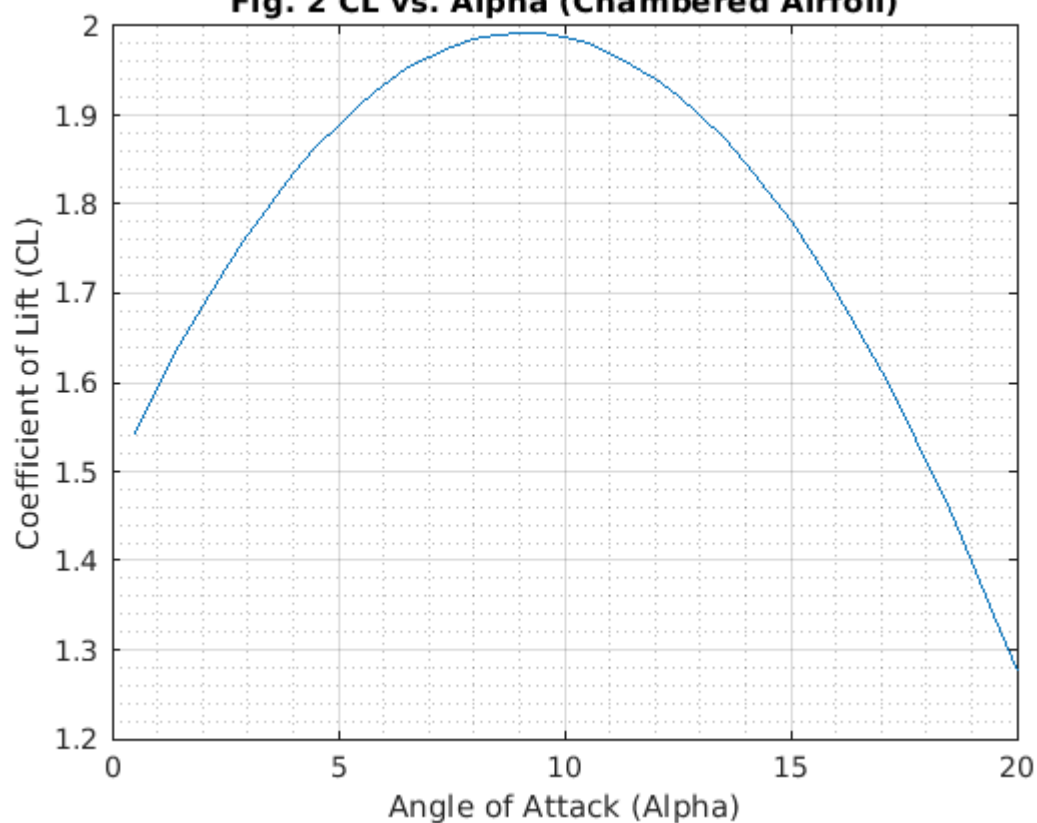


Fig. 3 CL vs. CP (Chambered Airfoil)

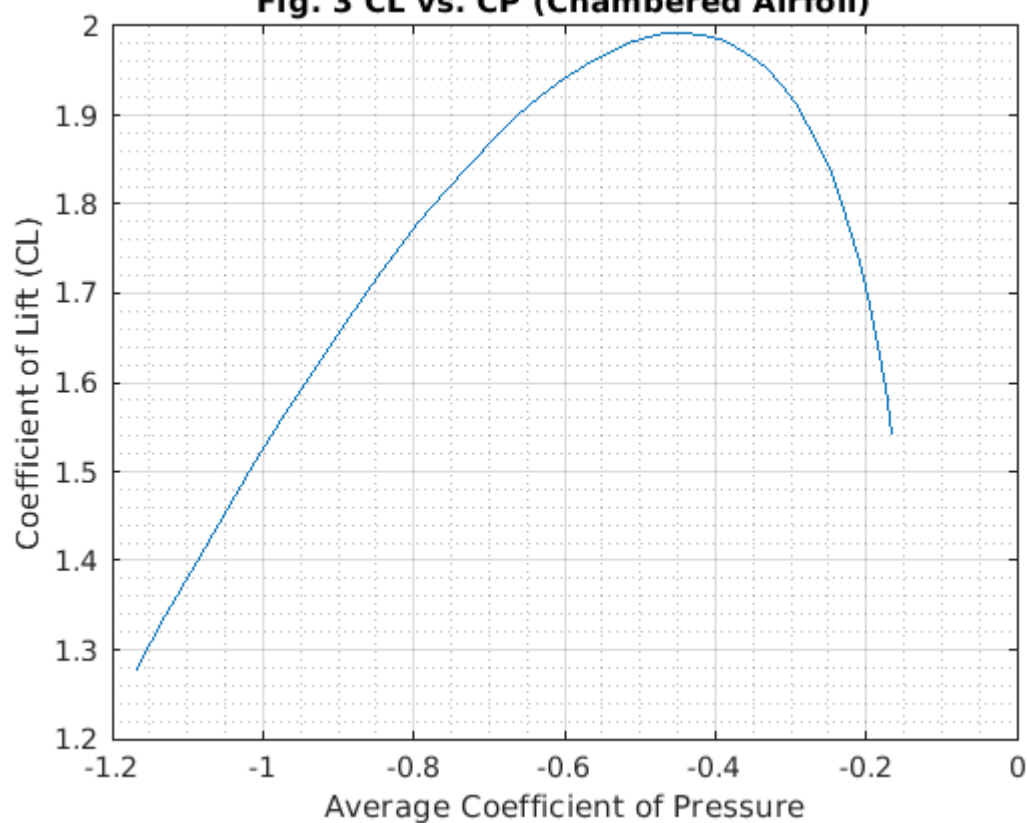


Fig. 4 Avg(CP) vs. Alpha (Chambered Airfoil)

