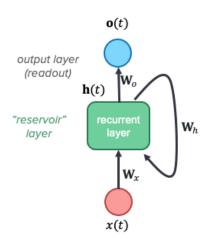
# Additional Material (Lab3-2):

# **Echo State Networks**



- Input  $\mathbf{x}(t)$ : column vector of size  $N_x$
- Reservoir state  $\mathbf{h}(t)$ : column vector of size  $N_h$
- Output  $\mathbf{o}(t)$ : column vector of size  $N_o$

When both input and output are 1-dimensional (e.g., as in the assignments), we use  $N_{\rm Y}=N_{\rm Y}=1$ .

#### Reservoir

- It is a recurrent, non-linear layer with (typically) sparse connectivity among units.
- It computes the state transition function: how the state at time step *t* is obtained from the input at time step *t* and from the state at time step *t-1*:

$$\mathbf{h}(t) = \tanh \left( \mathbf{W_h} \mathbf{h}(t-1) + \mathbf{W_x} \mathbf{x}(t) + \mathbf{b} \right)$$

• Note that the bias vector can be included in the input-weight matrix  $\mathbf{W}_{\mathbf{x}}$  for simplicity, in this case the input at each time-step should be augmented by a fixed input bias term equal to 1. In this case, the reservoir equation reads as follows:

$$\mathbf{h}(t) = \tanh \left( \mathbf{W_h} \mathbf{h}(t-1) + \mathbf{W_x} [\mathbf{x}(t); 1] \right),$$

where [;] denotes vector concatenation

- Input bias for the reservoir: concatenate the input at each time step with a constant input bias equal to 1;
- Use a null state as initial state of the ESN:  $\mathbf{h}(0) = \mathbf{0}$

#### Readout

It computes the output function: how the output of the network at time step *t* is obtained from the state at time step *t*. In the simplest form, it is implemented as a feed-forward, linear dense layer, as follows:

$$\mathbf{o}(t) = \mathbf{W}_{v}[\mathbf{o}(t); 1]$$

where the readout bias vector is already included in the output weight matrix  $\mathbf{W}_{\nu}$ .

#### **Reservoir Initialization**

Initialize the reservoir according to the necessary condition for the Echo State Property (ESP), i.e.,  $\rho(\mathbf{W}_h) < 1$ . Recall that  $\rho(\cdot)$  denotes the *spectral radius* (i.e., the maximum length of an eigenvalue) of its argument, namely  $\rho(\mathbf{W}_h) = \max{(abs(eig(\mathbf{W}_h)))}$ .

To properly initialize the reservoir weights, proceed as follows:

- 1. Initialization of the input weight matrix: Choose the values of  $\mathbf{W}_{x}$  from a random distribution scaled by a hyperparameter  $\omega_{x}$ . A typical choice is a uniform distribution on  $(-\omega_{x}, \omega_{x})$ .
- 2. Initialization of the bias vector: Choose the values of **b** from a random distribution scaled by a hyperparameter  $\omega_b$ . A typical choice is a uniform distribution on  $(-\omega_b, \omega_b)$ .
- 3. Initialization of the recurrent weight matrix:
  - a. Initialize randomly the values of  $\mathbf{W}_h$  from a random distribution (e.g., from a uniform distribution in (-1, 1)).
  - b. Re-scale  $\mathbf{W}_h$  to a unitary spectral radius, i.e.,  $\mathbf{W}_h \leftarrow \frac{\mathbf{W}_h}{\rho(\mathbf{W}_h)}$
  - c. Finally, re-scale  $\mathbf{W}_h$  to the desired spectral radius  $\rho$ , i.e.,  $\mathbf{W}_h \leftarrow \rho \ \mathbf{W}_h$

## **Readout Training**

Only the readout needs to be trained.

1. Discard an initial transient (run the network for some steps before starting collecting the states)

2. Collect all reservoir <u>states</u> and <u>target</u> values for each time step into matrices (after the initial transient)

$$\mathbf{H} = [\mathbf{h}(1), ..., \mathbf{h}(T)]$$
  $\mathbf{Y} = [\mathbf{y}(1), ..., \mathbf{y}(T)]$ 

where  $\mathbf{y}(t)$  here denotes the target output at time-step t.

- 3. After having collected all the states, train the linear readout
  - Pseudo-inverse

$$\mathbf{W}_o = \mathbf{Y} \, \mathbf{H}^+$$

- Ridge regression (  $\lambda_r$  is a regularization coefficient)  $\mathbf{W}_o = \mathbf{Y} \mathbf{H}^T (\mathbf{H} \mathbf{H}^T + \lambda_r \mathbf{I})^{-1}$ 

note: the readout should not be trained after each time step, but only once after the collection of all the states

## **Implementation notes**

- In NumPy, you can use the linear algebra functions in the numpy.linalg library (<a href="https://numpy.org/doc/stable/reference/routines.linalg.html">https://numpy.org/doc/stable/reference/routines.linalg.html</a>) for computing the spectral radius and for training the readout (e.g., for inverse, pseudo inverse, etc)
- In Matlab, you can use the functions eig(.), pinv(.), and inv(.)

### **Reservoir Guesses**

For every reservoir hyper-parametrization the performance (e.g. accuracy for classification task, MSE for regression task) should be averaged over a number of reservoir guesses (different random instantiations of networks with the same values of the hyper-parameters).

### **Model Selection!**

To properly setup the network you need to use a proper model selection (e.g, by grid or random search), considering suitable values of the hyper-parameters. Relevant hyper-parameters include: number of reservoir units, spectral radius, input scaling, bias scaling, readout regularization