

Irfan Ahmed

ICP 11

Due Date: 11/21/2020

### **Parameters changed and reasoning.**

Optimizer was changed to ‘Adagrad’, validation split was increased to 0.25, the batch size was changed to 32, and epochs to 25. Also, added additional layers to model and compared to the unchanged model.

I ended up changing the optimizer along with adding additional layers to see if the val\_dice\_acc would improve or not. First, I ran the model unchanged to see what the accuracy would be. Then after adding additional sections the model was compiled and executed. The accuracy was best for the model that was provided by the instructor, and when I added additional layers and changed the optimizer and validation split the val\_dice\_acc was 0.7207 compared to 0.8683. The changes made were for comparative purpose to better understand how to best tune any model. Few things to note is I was unsure if my model setup was even correct and that must be taken into consideration when looking at the results. Other thing to note is that optimizer ‘adam’ is the best choice to use when validating the model. Adding additional layers saw zero improvements in the overall val\_dice\_acc.

#### **a. What you learned in the ICP**

The goal of this ICP was to understand the U-Net architecture. The architecture is composed of three sections. The contraction, bottleneck, and expansion section/layers. The contraction layer has many contraction blocks, where each block takes an input 3X3 convolution layer followed by 2X2 max pooling. The kernels double after each block, and the bottom layer mediates between the contraction layer and expansion layer. From this contraction and expansion layer we can see a semi u-shape, where the name is derived from.

#### **b. ICP description what was the task you were performing**

- Imported the required libraries/packages
- Installed Kaggle and used my token to get access to the dataset
- Extracted the dataset from data-science-bowl-2018 and obtained the train data
- Initialized my img width, height and channels and then trained the x and y
- Two models were built and the first was unchanged from what was given in class. The second model added more sections to compare the results.
- Compiled my model and looked at the results
- Used visualizing to look at the results.

#### **c. Challenges you faced**

One thing that was difficult for me was how to add more layers/sections. Still bit confused on some of the topic but I ended up just adding 9 additional layers to keep the pattern consistent and was able to run the model.

**d. Screen shots that shows the successful execution of each required step of your code**

Make 4 changes(for example changing number of layers, changing hyper parameters, adding architecture given in the source code and train it on the same (or different) data set. Justify report for each of the change you made. Visualize model performance and compare any diff

## ▼ model performance.

Things I changed.

- The epochs was changed to 25
- The Max pooling layer was added
- Covolution layer was added c6
- optimizer Adagrad was applied to the compiler

Importing the required libraries and packages

```
[1] import tensorflow as tf
    import os
    import sys
    import cv2
    import random
    import numpy as np
    from tqdm import tqdm
    from itertools import chain
    from skimage.io import imread, imshow
    from keras import backend as K
    import matplotlib.pyplot as plt
```

Installing kaggle pacakge. This will allow me to download the needed data to run the model

```
[2] !pip install -q kaggle
```

Uploading my token

2)

kaggle.json

- **kaggle.json**(application/json) - 63 bytes, last modified: 11/21/2020 - 100% done

Saving kaggle.json to kaggle.json

```
{'kaggle.json': b'{"username":"irfanac","key":"f2743e6080e6edcffb6a841299eb3dce"}
```



```
!mkdir ~/.kaggle  
! cp kaggle.json ~/.kaggle
```



```
[6] ! chmod 600 ~/.kaggle/kaggle.json
```

```
[7] ! kaggle datasets list
```

Warning: Looks like you're using an outdated API Version, please consider updating ref title

unanimad/us-election-2020	US Election 2020
antgoldbloom/covid19-data-from-john-hopkins-university	COVID-19 data from John
manchunhui/us-election-2020-tweets	US Election 2020 Tweets
headsortails/us-election-2020-presidential-debates	US Election 2020 - Presi
etsc9287/2020-general-election-polls	Election, COVID, and Dem
radustoicescu/2020-united-states-presidential-election	2020 United States presi
shivamb/netflix-shows	Netflix Movies and TV Sh
terenceshin/covid19s-impact-on-airport-traffic	COVID-19's Impact on Air
sootersaalu/amazon-top-50-bestselling-books-2009-2019	Amazon Top 50 Bestsellin
nehaprabhavalkar/indian-food-101	Indian Food 101
karangadiya/fifa19	FIFA 19 complete player
heeraldedhia/groceries-dataset	Groceries dataset
andrewmvd/trip-advisor-hotel-reviews	Trip Advisor Hotel Revie
docstein/brics-world-bank-indicators	BRICS World Bank Indicat
omarhanyy/500-greatest-songs-of-all-time	500 Greatest Songs of Al
google/tinyquickdraw	QuickDraw Sketches
datasnaek/youtube-new	Trending YouTube Video S
uciml/mushroom-classification	Mushroom Classification
anikannal/solar-power-generation-data	Solar Power Generation D
zynicide/wine-reviews	Wine Reviews

```
▶ !pip install --upgrade kaggle
```

```
↳ Requirement already up-to-date: kaggle in /usr/local/lib/python3.6/dist-packages
Requirement already satisfied, skipping upgrade: python-dateutil in /usr/local/lib/python3.6/dist-packages
Requirement already satisfied, skipping upgrade: certifi in /usr/local/lib/python3.6/dist-packages
Requirement already satisfied, skipping upgrade: urllib3 in /usr/local/lib/python3.6/dist-packages
Requirement already satisfied, skipping upgrade: slugify in /usr/local/lib/python3.6/dist-packages
Requirement already satisfied, skipping upgrade: requests in /usr/local/lib/python3.6/dist-packages
Requirement already satisfied, skipping upgrade: python-slugify in /usr/local/lib/python3.6/dist-packages
Requirement already satisfied, skipping upgrade: six>=1.10 in /usr/local/lib/python3.6/dist-packages
Requirement already satisfied, skipping upgrade: tqdm in /usr/local/lib/python3.6/dist-packages
Requirement already satisfied, skipping upgrade: chardet<4,>=3.0.2 in /usr/local/lib/python3.6/dist-packages
Requirement already satisfied, skipping upgrade: idna<3,>=2.5 in /usr/local/lib/python3.6/dist-packages
Requirement already satisfied, skipping upgrade: text-unidecode>=1.3 in /usr/local/lib/python3.6/dist-packages
```

```
[9] !kaggle competitions download -c data-science-bowl-2018
```

```
Warning: Looks like you're using an outdated API Version, please consider updating.
Downloading stage2_test_final.zip to /content
100% 276M/276M [00:03<00:00, 52.8MB/s]
100% 276M/276M [00:03<00:00, 78.9MB/s]
Downloading stage1_test.zip to /content
  55% 5.00M/9.10M [00:00<00:00, 7.25MB/s]
100% 9.10M/9.10M [00:00<00:00, 12.5MB/s]
Downloading stage1_sample_submission.csv.zip to /content
    0% 0.00/2.62k [00:00<?, ?B/s]
100% 2.62k/2.62k [00:00<00:00, 2.41MB/s]
Downloading stage2_sample_submission_final.csv.zip to /content
    0% 0.00/112k [00:00<?, ?B/s]
100% 112k/112k [00:00<00:00, 115MB/s]
Downloading stage1_solution.csv.zip to /content
    0% 0.00/386k [00:00<?, ?B/s]
100% 386k/386k [00:00<00:00, 55.0MB/s]
Downloading stage1_train_labels.csv.zip to /content
    0% 0.00/2.67M [00:00<?, ?B/s]
100% 2.67M/2.67M [00:00<00:00, 88.1MB/s]
Downloading stage1_train.zip to /content
  94% 74.0M/79.1M [00:02<00:00, 20.7MB/s]
100% 79.1M/79.1M [00:02<00:00, 33.6MB/s]
```

```
[10] ! mkdir train
```

```
! unzip /content/stage1_train.zip -d train
```

## Setting up my model

```
▶  IMG_WIDTH = 128
    IMG_HEIGHT = 128
    IMG_CHANNELS = 3

    DATA_PATH = '/content/train/'

    seed = 42
    random.seed = seed
    np.random.seed = seed

    image_ids = next(os.walk(DATA_PATH))[1]

    X = np.zeros((len(image_ids), IMG_HEIGHT, IMG_WIDTH, IMG_CHANNELS), dtype=np.uint8)
    Y = np.zeros((len(image_ids), IMG_HEIGHT, IMG_WIDTH, 1), dtype=np.bool)

    for n, id_ in tqdm(enumerate(image_ids), total=len(image_ids)):
        path = DATA_PATH + id_
        img = imread(path + '/images/' + id_ + '.png')[ :, :, :IMG_CHANNELS]
        img = cv2.resize(img, (IMG_HEIGHT, IMG_WIDTH), )
        X[n] = img
        mask = np.zeros((IMG_HEIGHT, IMG_WIDTH, 1), dtype=np.bool)
        for mask_file in next(os.walk(path + '/masks/'))[2]:
            mask_ = imread(path + '/masks/' + mask_file)
            mask_ = np.expand_dims(cv2.resize(mask_, (IMG_HEIGHT, IMG_WIDTH)), interpolation=cv2.INTER_NEAREST)
            mask = np.maximum(mask, mask_)
        Y[n] = mask

    x_train=X

    y_train=Y
```

⌚ 100% |██████████| 670/670 [01:04<00:00, 10.36it/s]

This is the first run without

```

# Build U-Net model
inputs = tf.keras.layers.Input((IMG_HEIGHT, IMG_WIDTH, IMG_CHANNELS))
s = tf.keras.layers.Lambda(lambda x: x / 255)(inputs)

c1 = tf.keras.layers.Conv2D(16, (3, 3), activation=tf.keras.activations.elu, kernel_initializer='he_normal',
                         padding='same')(s)
c1 = tf.keras.layers.Dropout(0.1)(c1)
c1 = tf.keras.layers.Conv2D(16, (3, 3), activation=tf.keras.activations.elu, kernel_initializer='he_normal',
                         padding='same')(c1)
p1 = tf.keras.layers.MaxPooling2D((2, 2))(c1)

c2 = tf.keras.layers.Conv2D(32, (3, 3), activation=tf.keras.activations.elu, kernel_initializer='he_normal',
                         padding='same')(p1)
c2 = tf.keras.layers.Dropout(0.1)(c2)
c2 = tf.keras.layers.Conv2D(32, (3, 3), activation=tf.keras.activations.elu, kernel_initializer='he_normal',
                         padding='same')(c2)
p2 = tf.keras.layers.MaxPooling2D((2, 2))(c2)

c3 = tf.keras.layers.Conv2D(64, (3, 3), activation=tf.keras.activations.elu, kernel_initializer='he_normal',
                         padding='same')(p2)
c3 = tf.keras.layers.Dropout(0.2)(c3)
c3 = tf.keras.layers.Conv2D(64, (3, 3), activation=tf.keras.activations.elu, kernel_initializer='he_normal',
                         padding='same')(c3)
p3 = tf.keras.layers.MaxPooling2D((2, 2))(c3)

c4 = tf.keras.layers.Conv2D(128, (3, 3), activation=tf.keras.activations.elu, kernel_initializer='he_normal',
                         padding='same')(p3)
c4 = tf.keras.layers.Dropout(0.2)(c4)
c4 = tf.keras.layers.Conv2D(128, (3, 3), activation=tf.keras.activations.elu, kernel_initializer='he_normal',
                         padding='same')(c4)
p4 = tf.keras.layers.MaxPooling2D(pool_size=(2, 2))(c4)

c5 = tf.keras.layers.Conv2D(256, (3, 3), activation=tf.keras.activations.elu, kernel_initializer='he_normal',
                         padding='same')(p4)
c5 = tf.keras.layers.Dropout(0.3)(c5)
c5 = tf.keras.layers.Conv2D(256, (3, 3), activation=tf.keras.activations.elu, kernel_initializer='he_normal',
                         padding='same')(c5)

u6 = tf.keras.layers.Conv2DTranspose(128, (2, 2), strides=(2, 2), padding='same')(c5)
u6 = tf.keras.layers.concatenate([u6, c4])
c6 = tf.keras.layers.Conv2D(128, (3, 3), activation=tf.keras.activations.elu, kernel_initializer='he_normal',
                         padding='same')(u6)
c6 = tf.keras.layers.Dropout(0.2)(c6)
c6 = tf.keras.layers.Conv2D(128, (3, 3), activation=tf.keras.activations.elu, kernel_initializer='he_normal',
                         padding='same')(c6)

u7 = tf.keras.layers.Conv2DTranspose(64, (2, 2), strides=(2, 2), padding='same')(c6)
u7 = tf.keras.layers.concatenate([u7, c3])
c7 = tf.keras.layers.Conv2D(64, (3, 3), activation=tf.keras.activations.elu, kernel_initializer='he_normal',
                         padding='same')(u7)
c7 = tf.keras.layers.Dropout(0.2)(c7)
c7 = tf.keras.layers.Conv2D(64, (3, 3), activation=tf.keras.activations.elu, kernel_initializer='he_normal',
                         padding='same')(c7)

u8 = tf.keras.layers.Conv2DTranspose(32, (2, 2), strides=(2, 2), padding='same')(c7)
u8 = tf.keras.layers.concatenate([u8, c2])
c8 = tf.keras.layers.Conv2D(32, (3, 3), activation=tf.keras.activations.elu, kernel_initializer='he_normal',
                         padding='same')(u8)
c8 = tf.keras.layers.Dropout(0.1)(c8)
c8 = tf.keras.layers.Conv2D(32, (3, 3), activation=tf.keras.activations.elu, kernel_initializer='he_normal',
                         padding='same')(c8)

u9 = tf.keras.layers.Conv2DTranspose(16, (2, 2), strides=(2, 2), padding='same')(c8)
u9 = tf.keras.layers.concatenate([u9, c1], axis=3)
c9 = tf.keras.layers.Conv2D(16, (3, 3), activation=tf.keras.activations.elu, kernel_initializer='he_normal',
                         padding='same')(u9)
c9 = tf.keras.layers.Dropout(0.1)(c9)
c9 = tf.keras.layers.Conv2D(16, (3, 3), activation=tf.keras.activations.elu, kernel_initializer='he_normal',
                         padding='same')(c9)

outputs = tf.keras.layers.Conv2D(1, (1, 1), activation='sigmoid')(c9)

```

```
[15] def dice_acc(y_true, y_pred):
    smooth = 1.
    y_true_f = K.flatten(y_true)
    y_pred_f = K.flatten(y_pred)
    intersection = K.sum(y_true_f * y_pred_f)
    return (2. * intersection + smooth) / (K.sum(y_true_f) + K.sum(y_pred_f) + smooth)
```

```
[17] model = tf.keras.Model(inputs=[inputs], outputs=[outputs])
model.compile(optimizer='adam', loss='binary_crossentropy', metrics=[dice_acc])
model.summary()
```

↳ Model: "functional\_3"

Layer (type)	Output Shape	Param #	Connected to
<hr/>			
input_2 (InputLayer)	(None, 128, 128, 3)	0	
lambda_1 (Lambda)	(None, 128, 128, 3)	0	input_2[0][0]
conv2d_23 (Conv2D)	(None, 128, 128, 16)	448	lambda_1[0][0]
dropout_11 (Dropout)	(None, 128, 128, 16)	0	conv2d_23[0][0]
conv2d_24 (Conv2D)	(None, 128, 128, 16)	2320	dropout_11[0][0]
max_pooling2d_5 (MaxPooling2D)	(None, 64, 64, 16)	0	conv2d_24[0][0]
conv2d_25 (Conv2D)	(None, 64, 64, 32)	4640	max_pooling2d_5[0][0]
dropout_12 (Dropout)	(None, 64, 64, 32)	0	conv2d_25[0][0]
conv2d_26 (Conv2D)	(None, 64, 64, 32)	9248	dropout_12[0][0]
max_pooling2d_6 (MaxPooling2D)	(None, 32, 32, 32)	0	conv2d_26[0][0]
conv2d_27 (Conv2D)	(None, 32, 32, 64)	18496	max_pooling2d_6[0][0]
dropout_13 (Dropout)	(None, 32, 32, 64)	0	conv2d_27[0][0]
conv2d_28 (Conv2D)	(None, 32, 32, 64)	36928	dropout_13[0][0]
max_pooling2d_7 (MaxPooling2D)	(None, 16, 16, 64)	0	conv2d_28[0][0]
conv2d_29 (Conv2D)	(None, 16, 16, 128)	73856	max_pooling2d_7[0][0]
dropout_14 (Dropout)	(None, 16, 16, 128)	0	conv2d_29[0][0]
conv2d_30 (Conv2D)	(None, 16, 16, 128)	147584	dropout_14[0][0]

conv2d\_20[0][0]

conv2d_37 (Conv2D)	(None, 64, 64, 32)	18464	concatenate_7[0][0]
dropout_18 (Dropout)	(None, 64, 64, 32)	0	conv2d_37[0][0]
conv2d_38 (Conv2D)	(None, 64, 64, 32)	9248	dropout_18[0][0]
conv2d_transpose_8 (Conv2DTranspose)	(None, 128, 128, 16)	2064	conv2d_38[0][0]
concatenate_8 (Concatenate)	(None, 128, 128, 32)	0	conv2d_transpose_8[0][0]
conv2d_39 (Conv2D)	(None, 128, 128, 16)	4624	concatenate_8[0][0]
dropout_19 (Dropout)	(None, 128, 128, 16)	0	conv2d_39[0][0]
conv2d_40 (Conv2D)	(None, 128, 128, 16)	2320	dropout_19[0][0]
conv2d_41 (Conv2D)	(None, 128, 128, 1)	17	conv2d_40[0][0]
=====			
Total params: 1,941,105			
Trainable params: 1,941,105			
Non-trainable params: 0			

```
checkpoint_path = "training_1/cp.ckpt"
checkpoint_dir = os.path.dirname(checkpoint_path)

# Create checkpoint callback
cp_callback = tf.keras.callbacks.ModelCheckpoint(checkpoint_path,
                                                 save_weights_only=True,
                                                 verbose=1)

callbacks = [
    tf.keras.callbacks.EarlyStopping(patience=50, monitor='val_loss', verbose=1), #pati
    tf.keras.callbacks.TensorBoard(log_dir='./logs'),
    cp_callback
]

results_1 = model.fit(x_train, y_train, validation_split=0.01, batch_size=16, epochs=
#results_2 = model.fit(x_train, y_train, validation_split=0.25, batch_size=32, epochs
```

▶ 41/42 [=====>.] - ETA: 0s - loss: 0.0827 - dice\_acc: 0.8550  
Epoch 00014: saving model to training\_1/cp.ckpt  
↳ 42/42 [=====] - 2s 44ms/step - loss: 0.0828 - dice\_acc: 0.8549  
Epoch 15/25  
41/42 [=====>.] - ETA: 0s - loss: 0.0793 - dice\_acc: 0.8610  
Epoch 00015: saving model to training\_1/cp.ckpt  
42/42 [=====] - 2s 44ms/step - loss: 0.0792 - dice\_acc: 0.8600  
Epoch 16/25  
41/42 [=====>.] - ETA: 0s - loss: 0.0769 - dice\_acc: 0.8647  
Epoch 00016: saving model to training\_1/cp.ckpt  
42/42 [=====] - 2s 44ms/step - loss: 0.0774 - dice\_acc: 0.8645  
Epoch 17/25  
41/42 [=====>.] - ETA: 0s - loss: 0.0772 - dice\_acc: 0.8653  
Epoch 00017: saving model to training\_1/cp.ckpt  
42/42 [=====] - 2s 44ms/step - loss: 0.0771 - dice\_acc: 0.8652  
Epoch 18/25  
41/42 [=====>.] - ETA: 0s - loss: 0.0767 - dice\_acc: 0.8678  
Epoch 00018: saving model to training\_1/cp.ckpt  
42/42 [=====] - 2s 44ms/step - loss: 0.0770 - dice\_acc: 0.8673  
Epoch 19/25  
41/42 [=====>.] - ETA: 0s - loss: 0.0765 - dice\_acc: 0.8650  
Epoch 00019: saving model to training\_1/cp.ckpt  
42/42 [=====] - 2s 44ms/step - loss: 0.0763 - dice\_acc: 0.8657  
Epoch 20/25  
41/42 [=====>.] - ETA: 0s - loss: 0.0758 - dice\_acc: 0.8677  
Epoch 00020: saving model to training\_1/cp.ckpt  
42/42 [=====] - 2s 45ms/step - loss: 0.0755 - dice\_acc: 0.8688  
Epoch 21/25  
41/42 [=====>.] - ETA: 0s - loss: 0.0743 - dice\_acc: 0.8718  
Epoch 00021: saving model to training\_1/cp.ckpt  
42/42 [=====] - 2s 44ms/step - loss: 0.0742 - dice\_acc: 0.8723  
Epoch 22/25  
41/42 [=====>.] - ETA: 0s - loss: 0.0745 - dice\_acc: 0.8698  
Epoch 00022: saving model to training\_1/cp.ckpt  
42/42 [=====] - 2s 45ms/step - loss: 0.0745 - dice\_acc: 0.8698  
Epoch 23/25  
41/42 [=====>.] - ETA: 0s - loss: 0.0752 - dice\_acc: 0.8690  
Epoch 00023: saving model to training\_1/cp.ckpt  
42/42 [=====] - 2s 46ms/step - loss: 0.0752 - dice\_acc: 0.8689  
Epoch 24/25  
42/42 [=====] - ETA: 0s - loss: 0.0742 - dice\_acc: 0.8692  
Epoch 00024: saving model to training\_1/cp.ckpt  
42/42 [=====] - 2s 45ms/step - loss: 0.0742 - dice\_acc: 0.8692  
Epoch 25/25  
41/42 [=====>.] - ETA: 0s - loss: 0.0762 - dice\_acc: 0.8685  
Epoch 00025: saving model to training\_1/cp.ckpt  
42/42 [=====] - 2s 45ms/step - loss: 0.0761 - dice\_acc: 0.8683

```
idx = random.randint(0, len(x_train))
x=np.array(x_train[idx])
x=np.expand_dims(x, axis=0)
predict = model.predict(x, verbose=1)

predict = (predict > 0.5).astype(np.uint8)

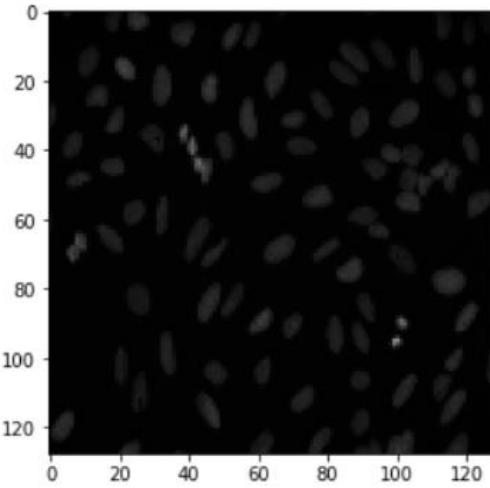
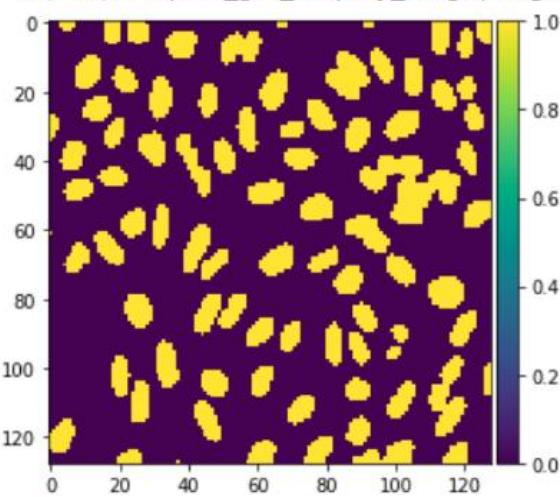
imshow(np.squeeze(predict[0]))
plt.show()

imshow(x_train[idx])

plt.show()
```

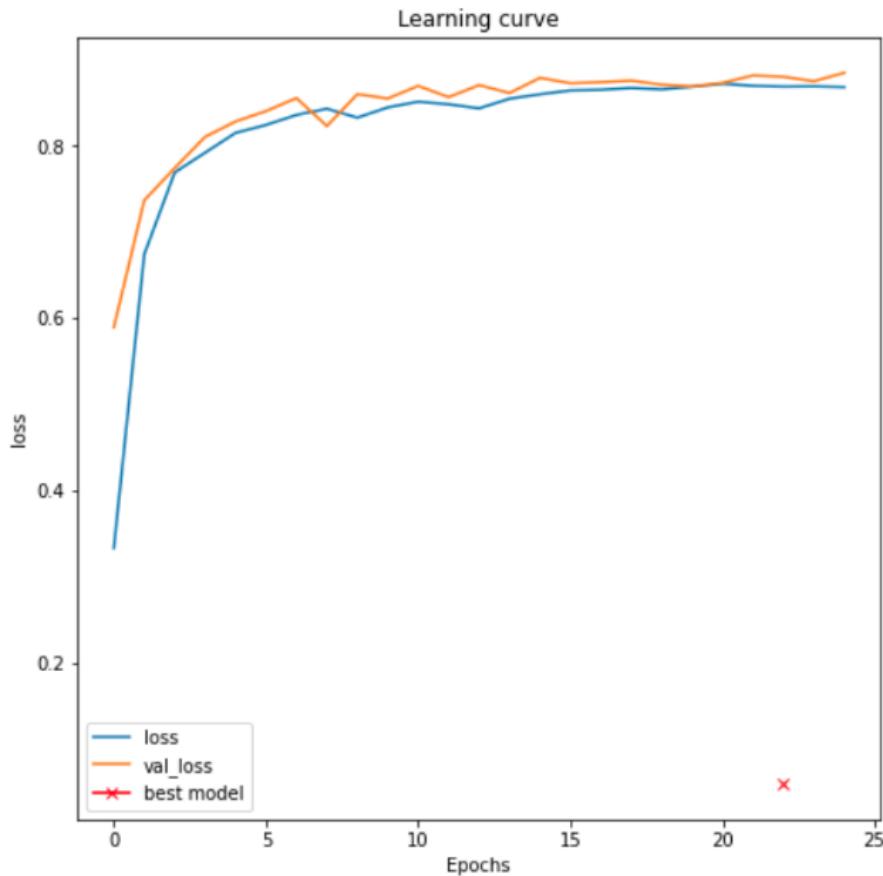
1/1 [=====] - 0s 3ms/step

/usr/local/lib/python3.6/dist-packages/skimage/io/\_plugins/matplotlib\_plugin.py:150: UserWarning:



```
[1]: plt.figure(figsize=(8, 8))
plt.title("Learning curve")
plt.plot(results_1.history["dice_acc"], label="loss")
plt.plot(results_1.history["val_dice_acc"], label="val_loss")
plt.plot(np.argmin(results_1.history["val_loss"]), np.min(results_1.history["val_loss"]),
        marker="x", label="best model")
plt.xlabel("Epochs")
plt.ylabel("loss")
plt.legend()
```

```
[2]: <matplotlib.legend.Legend at 0x7ff142bb7f28>
```



The images below are for result 2 where changes were made, and the results compared using visualization.

```
▶ checkpoint_path = "training_1/cp.ckpt"
checkpoint_dir = os.path.dirname(checkpoint_path)

# Create checkpoint callback
cp_callback = tf.keras.callbacks.ModelCheckpoint(checkpoint_path,
                                                 save_weights_only=True,
                                                 verbose=1)

callbacks = [
    tf.keras.callbacks.EarlyStopping(patience=50, monitor='val_loss', verbose=1), #patience was ch
    tf.keras.callbacks.TensorBoard(log_dir='./logs'),
    cp_callback
]

#results_1 = model.fit(x_train, y_train, validation_split=0.01, batch_size=16, epochs=25,callbacks=callbacks)
results_2 = model.fit(x_train, y_train, validation_split=0.25, batch_size=32, epochs=25,callbacks=callbacks)

10/10 [=====] - ETA: 0s - loss: 0.1727 - dice_acc: 0.6930
Epoch 00011: saving model to training_1/cp.ckpt
16/16 [=====] - 2s 128ms/step - loss: 0.1729 - dice_acc: 0.6930 - val_l
Epoch 12/25
16/16 [=====] - ETA: 0s - loss: 0.1720 - dice_acc: 0.6948
Epoch 00012: saving model to training_1/cp.ckpt
16/16 [=====] - 2s 129ms/step - loss: 0.1720 - dice_acc: 0.6948 - val_l
Epoch 13/25
16/16 [=====] - ETA: 0s - loss: 0.1711 - dice_acc: 0.6953
Epoch 00013: saving model to training_1/cp.ckpt
16/16 [=====] - 2s 129ms/step - loss: 0.1711 - dice_acc: 0.6953 - val_l
Epoch 14/25
16/16 [=====] - ETA: 0s - loss: 0.1713 - dice_acc: 0.6944
Epoch 00014: saving model to training_1/cp.ckpt
16/16 [=====] - 2s 130ms/step - loss: 0.1713 - dice_acc: 0.6944 - val_l
Epoch 15/25
16/16 [=====] - ETA: 0s - loss: 0.1698 - dice_acc: 0.7000
Epoch 00015: saving model to training_1/cp.ckpt
16/16 [=====] - 2s 130ms/step - loss: 0.1698 - dice_acc: 0.7000 - val_l
Epoch 16/25
16/16 [=====] - ETA: 0s - loss: 0.1698 - dice_acc: 0.6984
Epoch 00016: saving model to training_1/cp.ckpt
16/16 [=====] - 2s 129ms/step - loss: 0.1698 - dice_acc: 0.6984 - val_l
Epoch 17/25
16/16 [=====] - ETA: 0s - loss: 0.1692 - dice_acc: 0.7009
Epoch 00017: saving model to training_1/cp.ckpt
16/16 [=====] - 2s 130ms/step - loss: 0.1692 - dice_acc: 0.7009 - val_l
Epoch 18/25
16/16 [=====] - ETA: 0s - loss: 0.1686 - dice_acc: 0.7020
Epoch 00018: saving model to training_1/cp.ckpt
16/16 [=====] - 2s 130ms/step - loss: 0.1686 - dice_acc: 0.7020 - val_l
Epoch 19/25
16/16 [=====] - ETA: 0s - loss: 0.1680 - dice_acc: 0.7028
Epoch 00019: saving model to training_1/cp.ckpt
```

▶ 16/16 [=====] - 2s 129ms/step - loss: 0.1711 - dice\_acc: 0.6953 - val\_1  
Epoch 14/25  
⌚ 16/16 [=====] - ETA: 0s - loss: 0.1713 - dice\_acc: 0.6944  
Epoch 00014: saving model to training\_1/cp.ckpt  
16/16 [=====] - 2s 130ms/step - loss: 0.1713 - dice\_acc: 0.6944 - val\_1  
Epoch 15/25  
16/16 [=====] - ETA: 0s - loss: 0.1698 - dice\_acc: 0.7000  
Epoch 00015: saving model to training\_1/cp.ckpt  
16/16 [=====] - 2s 130ms/step - loss: 0.1698 - dice\_acc: 0.7000 - val\_1  
Epoch 16/25  
16/16 [=====] - ETA: 0s - loss: 0.1698 - dice\_acc: 0.6984  
Epoch 00016: saving model to training\_1/cp.ckpt  
16/16 [=====] - 2s 129ms/step - loss: 0.1698 - dice\_acc: 0.6984 - val\_1  
Epoch 17/25  
16/16 [=====] - ETA: 0s - loss: 0.1692 - dice\_acc: 0.7009  
Epoch 00017: saving model to training\_1/cp.ckpt  
16/16 [=====] - 2s 130ms/step - loss: 0.1692 - dice\_acc: 0.7009 - val\_1  
Epoch 18/25  
16/16 [=====] - ETA: 0s - loss: 0.1686 - dice\_acc: 0.7020  
Epoch 00018: saving model to training\_1/cp.ckpt  
16/16 [=====] - 2s 130ms/step - loss: 0.1686 - dice\_acc: 0.7020 - val\_1  
Epoch 19/25  
16/16 [=====] - ETA: 0s - loss: 0.1680 - dice\_acc: 0.7028  
Epoch 00019: saving model to training\_1/cp.ckpt  
16/16 [=====] - 2s 128ms/step - loss: 0.1680 - dice\_acc: 0.7028 - val\_1  
Epoch 20/25  
16/16 [=====] - ETA: 0s - loss: 0.1676 - dice\_acc: 0.7025  
Epoch 00020: saving model to training\_1/cp.ckpt  
16/16 [=====] - 2s 128ms/step - loss: 0.1676 - dice\_acc: 0.7025 - val\_1  
Epoch 21/25  
16/16 [=====] - ETA: 0s - loss: 0.1671 - dice\_acc: 0.7064  
Epoch 00021: saving model to training\_1/cp.ckpt  
16/16 [=====] - 2s 128ms/step - loss: 0.1671 - dice\_acc: 0.7064 - val\_1  
Epoch 22/25  
16/16 [=====] - ETA: 0s - loss: 0.1662 - dice\_acc: 0.7061  
Epoch 00022: saving model to training\_1/cp.ckpt  
16/16 [=====] - 2s 128ms/step - loss: 0.1662 - dice\_acc: 0.7061 - val\_1  
Epoch 23/25  
16/16 [=====] - ETA: 0s - loss: 0.1658 - dice\_acc: 0.7082  
Epoch 00023: saving model to training\_1/cp.ckpt  
16/16 [=====] - 2s 128ms/step - loss: 0.1658 - dice\_acc: 0.7082 - val\_1  
Epoch 24/25  
16/16 [=====] - ETA: 0s - loss: 0.1655 - dice\_acc: 0.7081  
Epoch 00024: saving model to training\_1/cp.ckpt  
16/16 [=====] - 2s 127ms/step - loss: 0.1655 - dice\_acc: 0.7081 - val\_1  
Epoch 25/25  
16/16 [=====] - ETA: 0s - loss: 0.1642 - dice\_acc: 0.7093  
Epoch 00025: saving model to training\_1/cp.ckpt  
16/16 [=====] - 2s 126ms/step - loss: 0.1642 - dice\_acc: 0.7093 - val\_1

```
▶ idx = random.randint(0, len(x_train))
x=np.array(x_train[idx])
x=np.expand_dims(x, axis=0)
predict = model.predict(x, verbose=1)

predict = (predict > 0.5).astype(np.uint8)

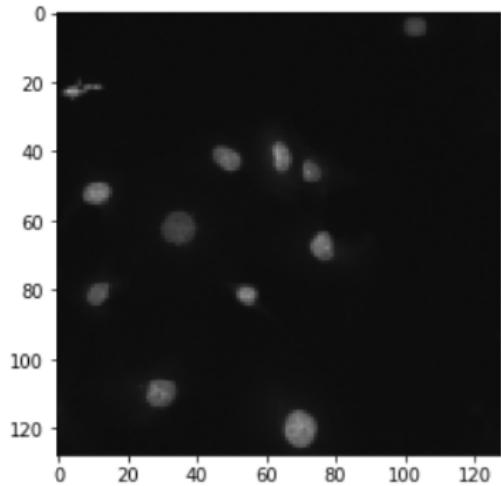
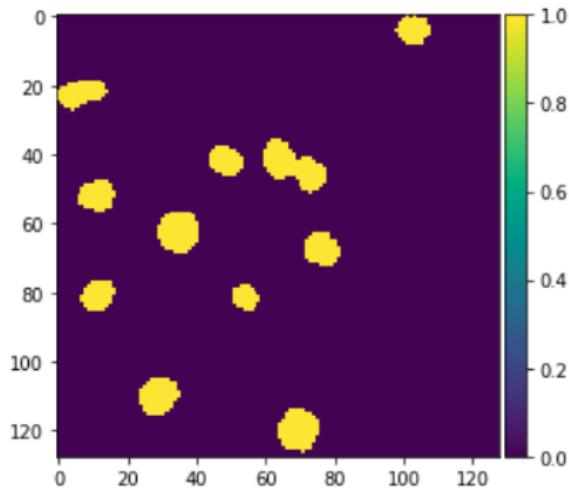
imshow(np.squeeze(predict[0]))
plt.show()

imshow(x_train[idx])

plt.show()
```

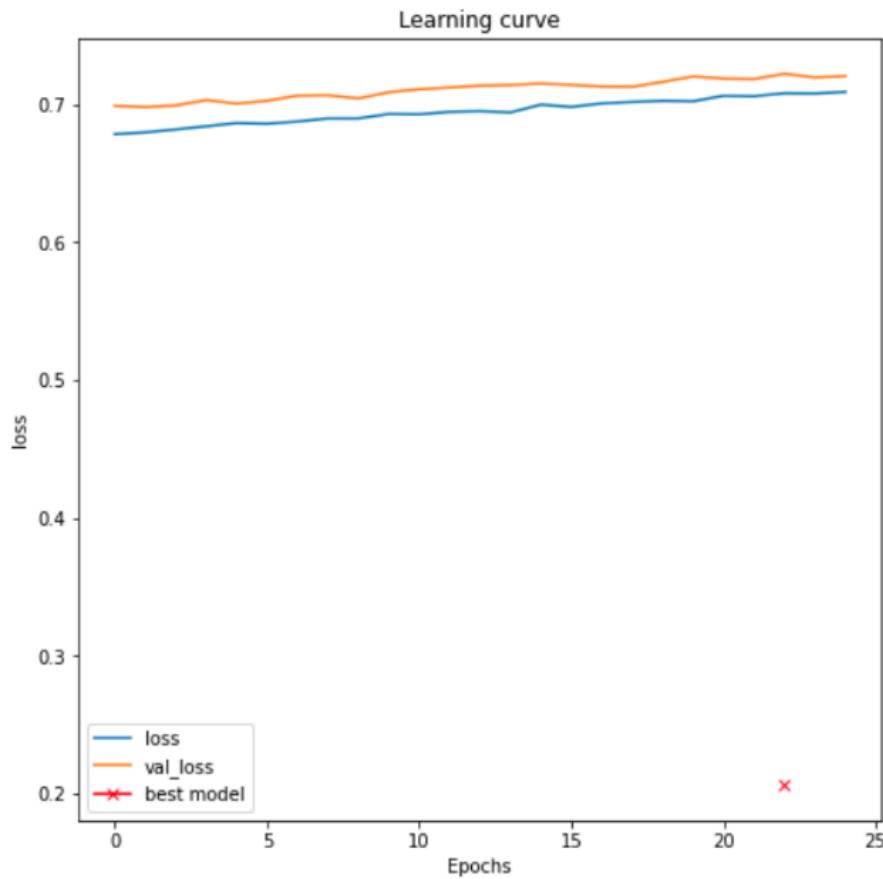
↳ 1/1 [=====] - 0s 3ms/step

/usr/local/lib/python3.6/dist-packages/skimage/io/\_plugins/matplotlib\_plugin.py:150: UserWarning:  
lo, hi, cmap = \_get\_display\_range(image)



```
▶ plt.figure(figsize=(8, 8))
plt.title("Learning curve")
plt.plot(results_2.history["dice_acc"], label="loss")
plt.plot(results_2.history["val_dice_acc"], label="val_loss")
plt.plot(np.argmin(results_1.history["val_loss"]), np.min(results_1.history["val_loss"]), marker="x")
plt.xlabel("Epochs")
plt.ylabel("loss")
plt.legend()
```

```
<matplotlib.legend.Legend at 0x7ff1421b44a8>
```



e. Output file link if applicable

<https://github.com/UMKC-APL-BigDataAnalytics/icp-11-irfancheemaa>

f. Video link (YouTube or any other publicly available video platform)

<https://umkc.hosted.panopto.com/Panopto/Pages/Viewer.aspx?id=f8816e88-b9fb-4150-b3e4-ac7c0158c0fd>

**g. Any inside about the data or the ICP in general**

None at the moment.