

# **FSM 1 : Intro to Finite State Machines**

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# Ask Week 8 Questions here...

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You can ask questions during the week using slido here :

<https://app.sli.do/event/3Xrj339dhu9a2XXbT4Hxg6>

Or at [slido.com](https://www.slido.com) + #2026 008

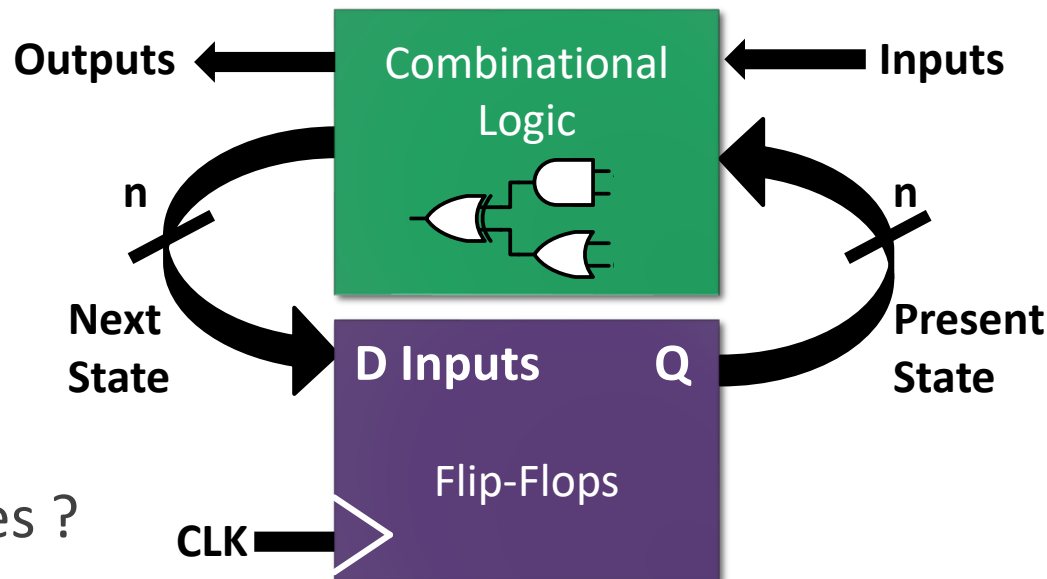
Or the tiny little QR :



# What is a FSM?

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- FSM : Finite State Machine
- Synchronous Machine with “states” of operation
- At each *active clock edge*, combinational logic computes **outputs and next state**,  
as a function of **inputs and present state**



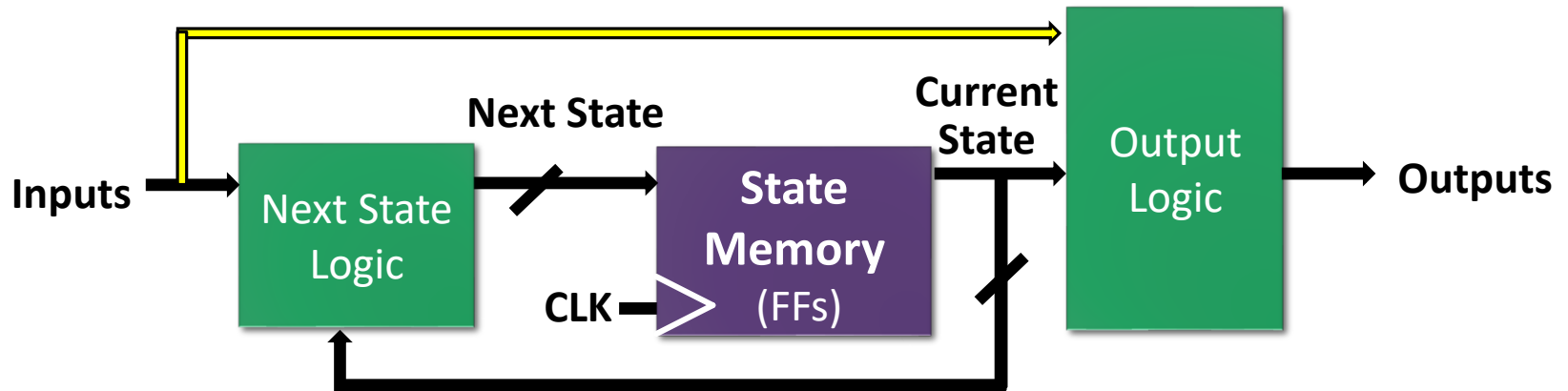
○ Examples ?



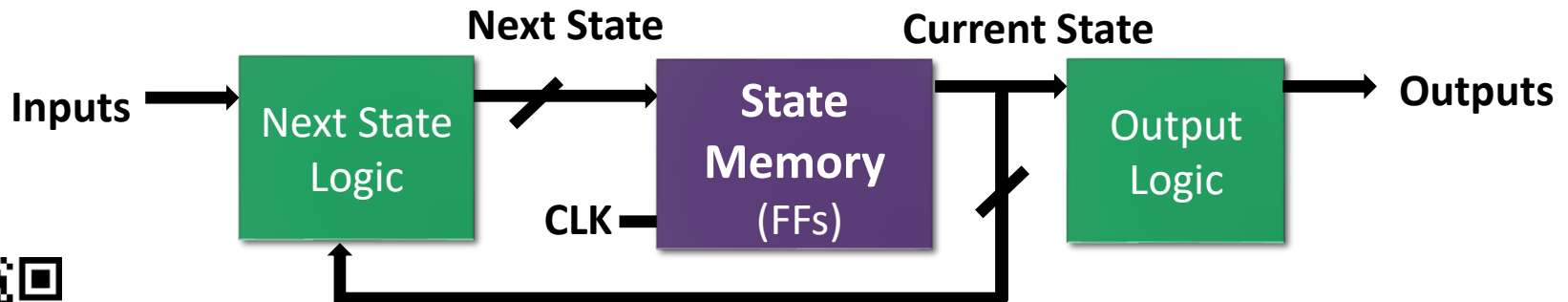
# Mealy and Moore

## Moore vs Mealy FSMs : Different Output Generation

- Mealy machine: *output is a function of a present state & inputs.*



- Moore machine: *output is a function of a present state only.*



# Structure

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## State Memory

- set of  $n$  FFs store current state of machine; up to  $2^n$  states.
- FFs can be J-K or D, but D FFs simpler (1 input vs. 2 inputs for J-K FFs)

## Next State Logic

- combinational circuit which decides the next state of the machine based on current state and inputs:

$$\text{Next state} = f(\text{inputs}, \text{current state})$$

## Output logic

- combinational circuit which creates the output

Moore : outputs depend on current state

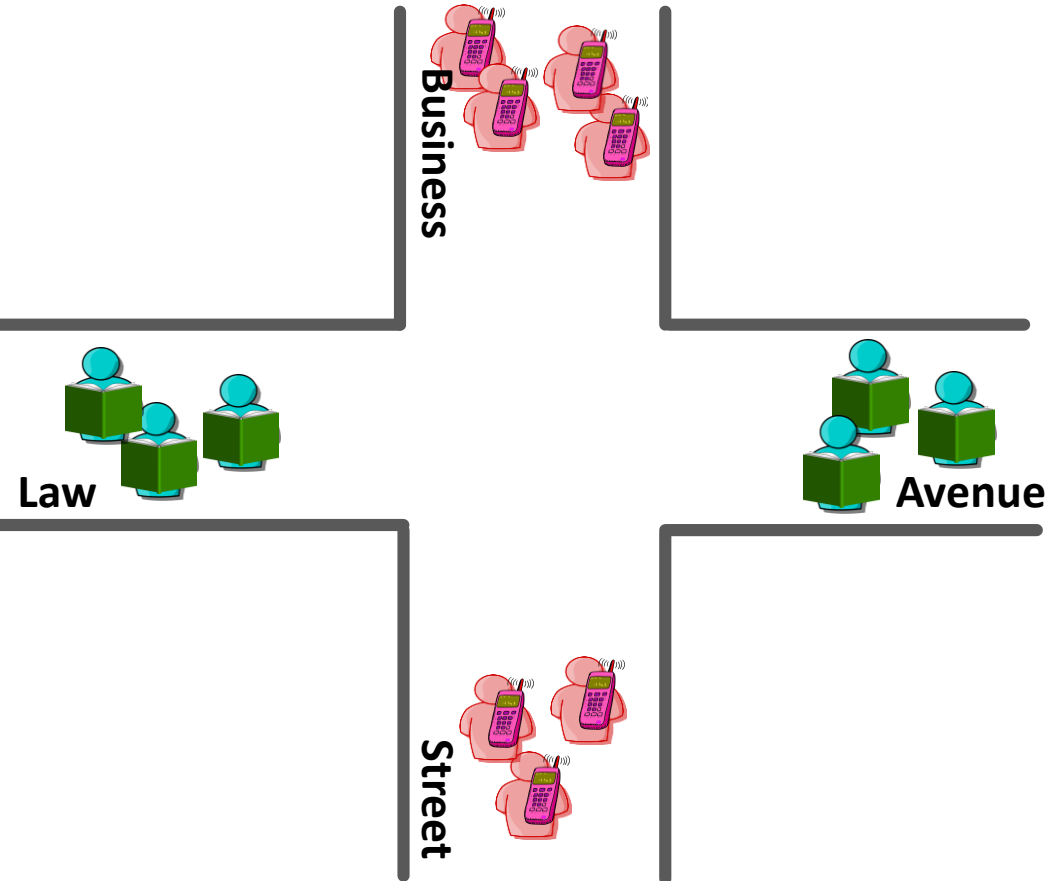
$$\text{outputs} = g(\text{current state})$$

Mealy : outputs depend on the current state & inputs

$$\text{outputs} = g(\text{inputs}, \text{current state})$$



# Traffic Problem...



**At a busy intersection on campus...**

Students from the Law faculty are burying their heads in their books and are not looking where they are going.

Students from the Business faculty are occupied on their phones and aren't looking at where they're going either....



# Traffic Problem...

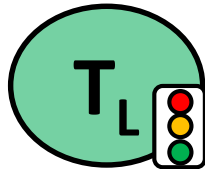


$L_B$

Business



$T_B$



$T_L$



$L_B$

Street



$T_B$



$L_L$



Avenue

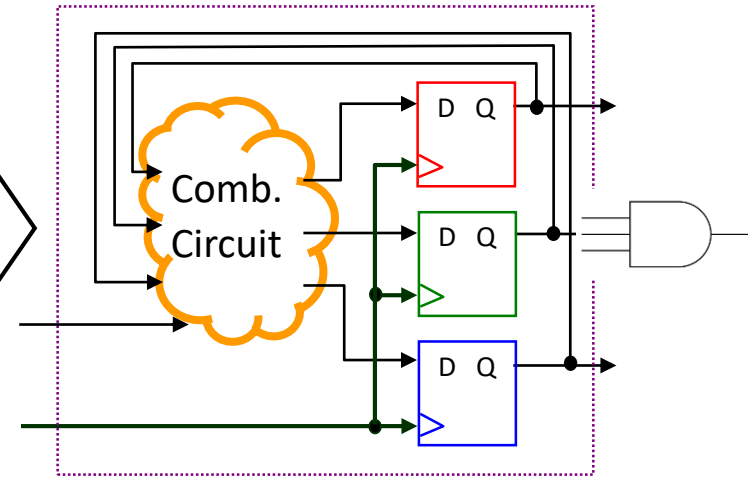
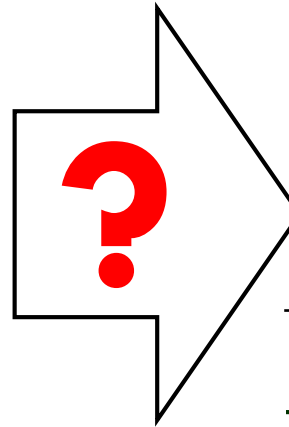
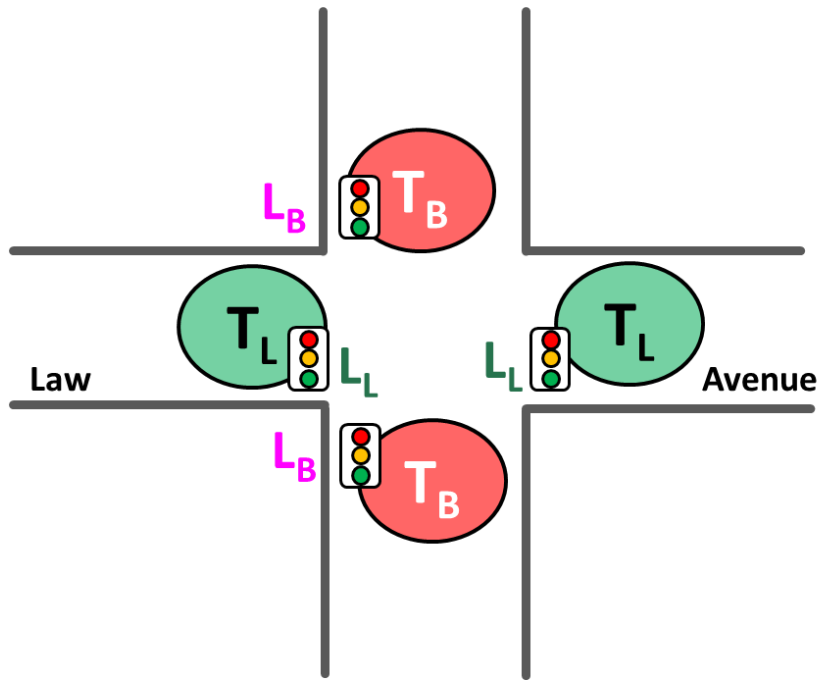
## Design a FSM to control the traffic lights!

- 1) Sensors  $T_B$  and  $T_L$  are TRUE when students are present. False otherwise.
- 2) Control traffic lights  $L_L$ ,  $L_B$  to be green, yellow, red.
- 3) Reset to Green on Law Ave and Red on Business St.

## Every 5 sec, check the traffic and decide what to do!

- If the lights on Business St. are green and there's no traffic, the lights turn yellow for 5 secs. After that, they turn red and Law Ave. lights turn green.
- So on, so forth.
- If there is traffic, lights do not change.





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A SYSTEMATIC PROCEDURE TO GO FROM

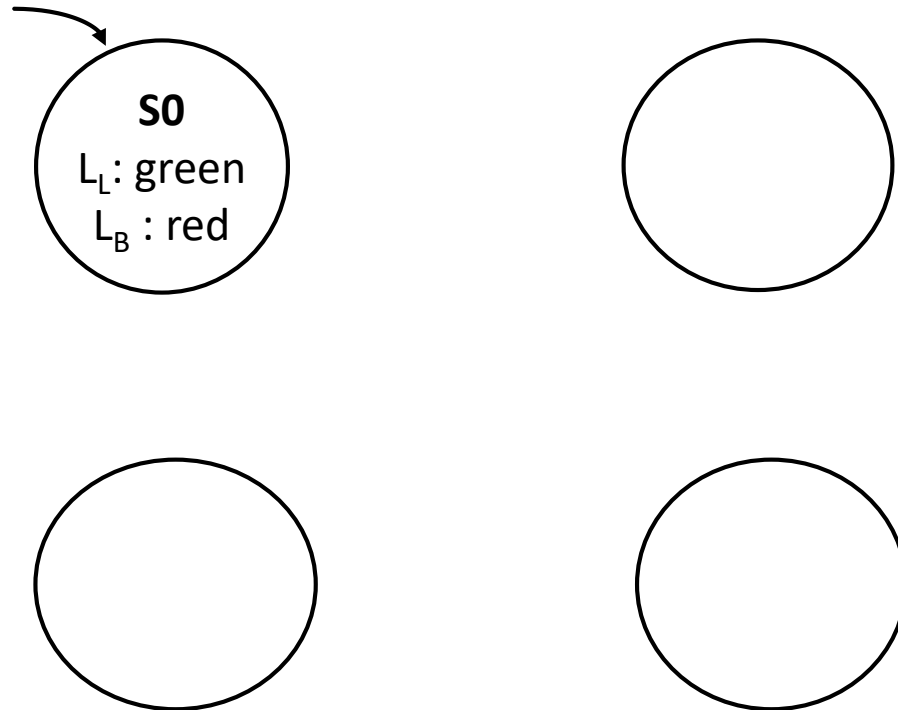
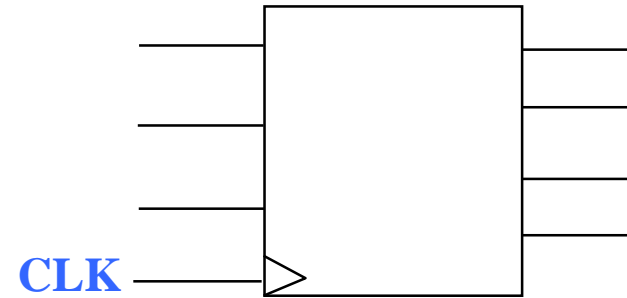
IDEA → IMPLEMENTATION



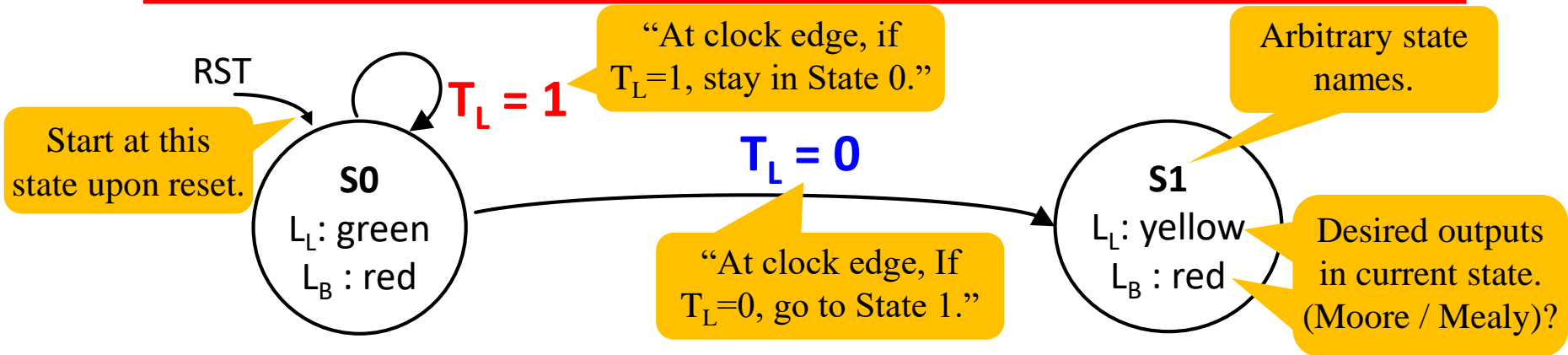
# Step 1 : State Transition Diagram

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- Block Diagram of Desired System
- Design **State Transition Diagram** to represent FSM



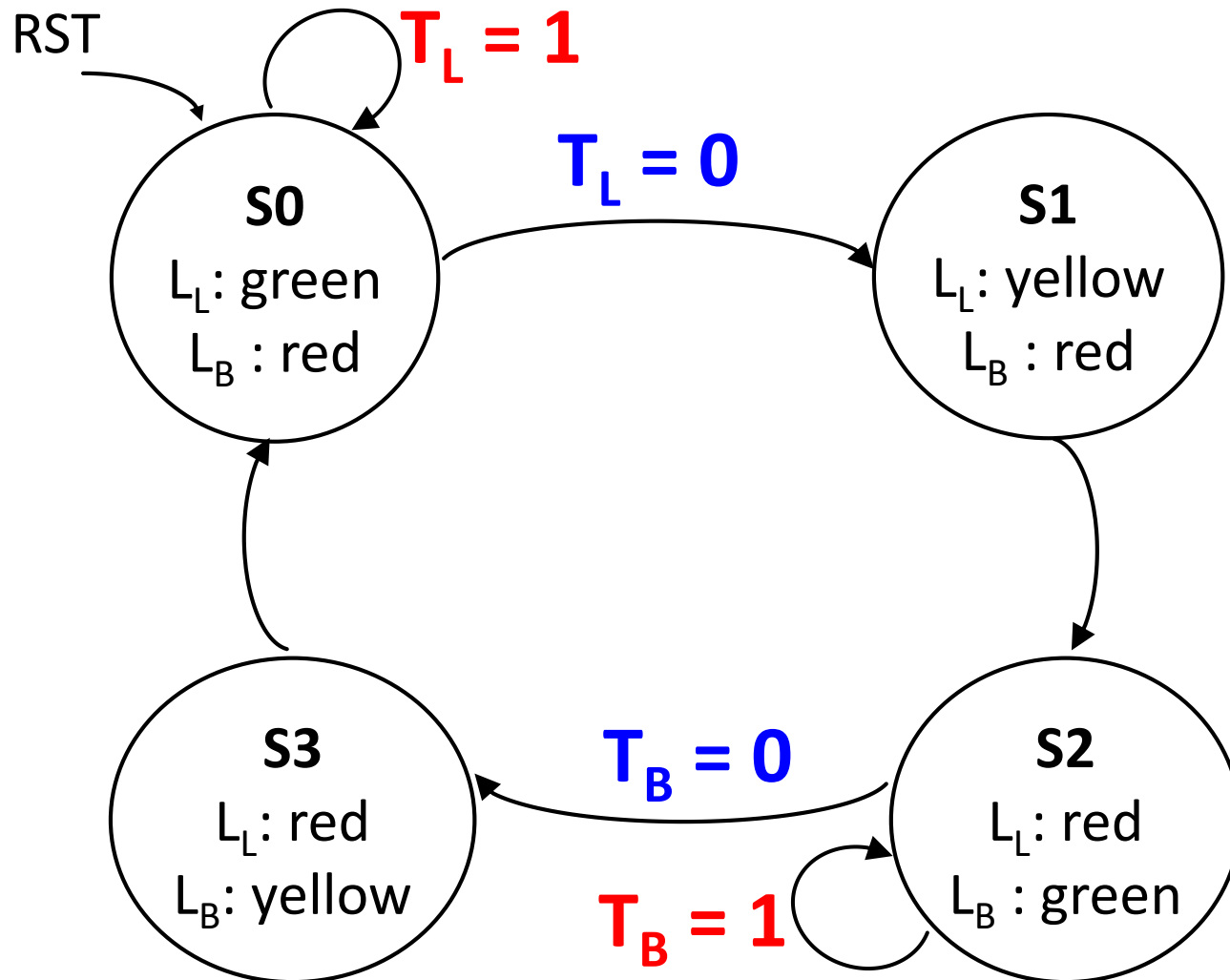
# Moore State Transition Diagrams



- Circles represent **states**.
  - \* Each state specifies values for all outputs (Moore)
- Arcs represents **transitions** between states.
  - \* Labels → input that triggers the transition.
  - \* Transitions take place on the **active edge** of the clock.
- Arc from outer space (eg reset) applies globally from all states
- Within each state, for any combination of input values, there's exactly one applicable arc.



# State Transition Diagram



# Step 2 : Next State Table

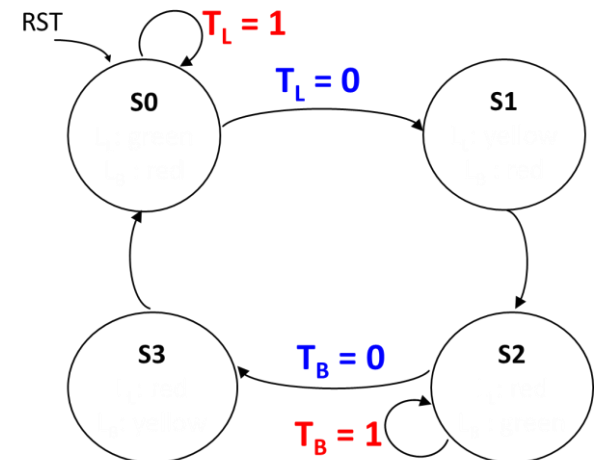
1. From STD, find the number of states
2. Number of bits / FFs required = ? to go through these states

3. State Assignment

State	$S_1S_0$
S0	00
S1	01
S2	10
S3	11

4. Next State Table

Current State		Inputs		Next State
S		$T_L$	$T_B$	S+
S0	0	X		S1
S0	1	X		S0
S1	X	X		S2
S2	X	0		S3
S2	X	1		S2
S3	X	X		S0



# Step 2 : Next State Table

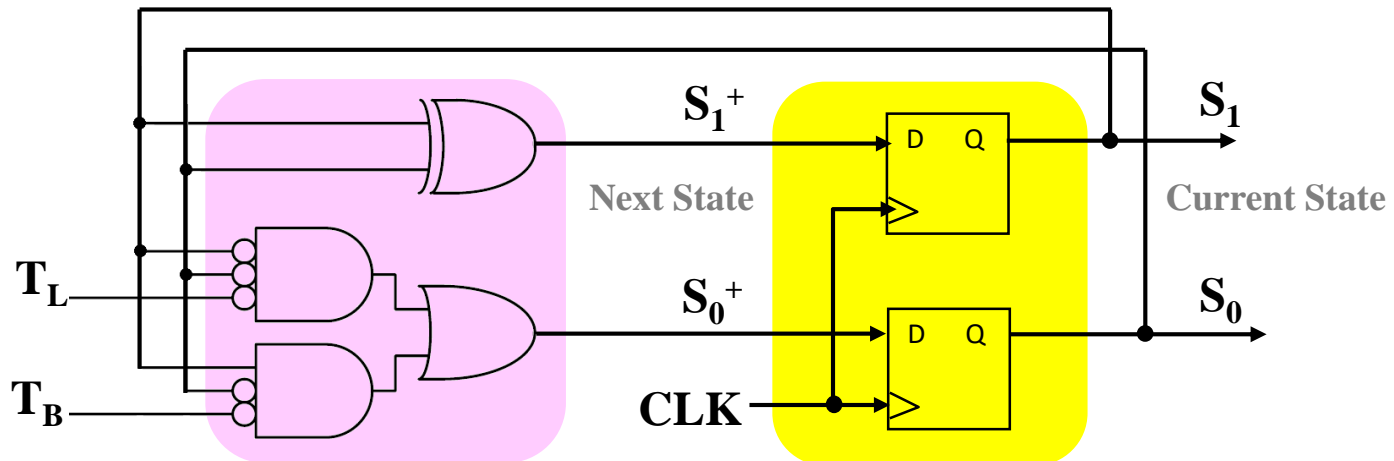
## 5. State Generator Circuit

Current State		Inputs		Next State	
$S_1$	$S_0$	$T_L$	$T_B$	$S_1^+$	$S_0^+$
0	0	0	X	0	1
0	0	1	X	0	0
0	1	X	X	1	0
1	0	X	0	1	1
1	0	X	1	1	0
1	1	X	X	0	0

$$S_1^+ = \overline{S_1}S_0 + S_1\overline{S_0}\overline{T_B} + S_1\overline{S_0}T_B$$

$$= S_1 \oplus S_0$$

$$S_0^+ = \overline{S_1}\overline{S_0}\overline{T_L} + S_1\overline{S_0}\overline{T_B}$$



# Step 3 : Output Logic

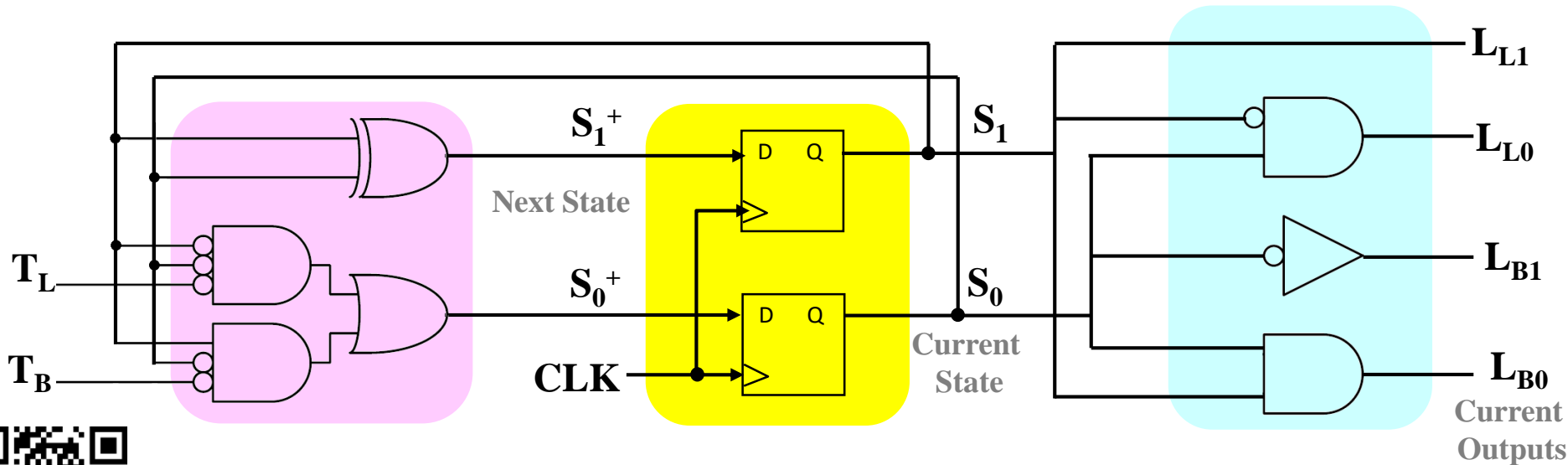
## 1. Output Truth Table

Current State		Outputs			
$S_1$	$S_0$	$L_{L1}$	$L_{L0}$	$L_{B1}$	$L_{B0}$
0	0	0	0	1	0
0	1	0	1	1	0
1	0	1	0	0	0
1	1	1	0	0	1

Output	$L_1L_0$
Green	00
Yellow	01
Red	10

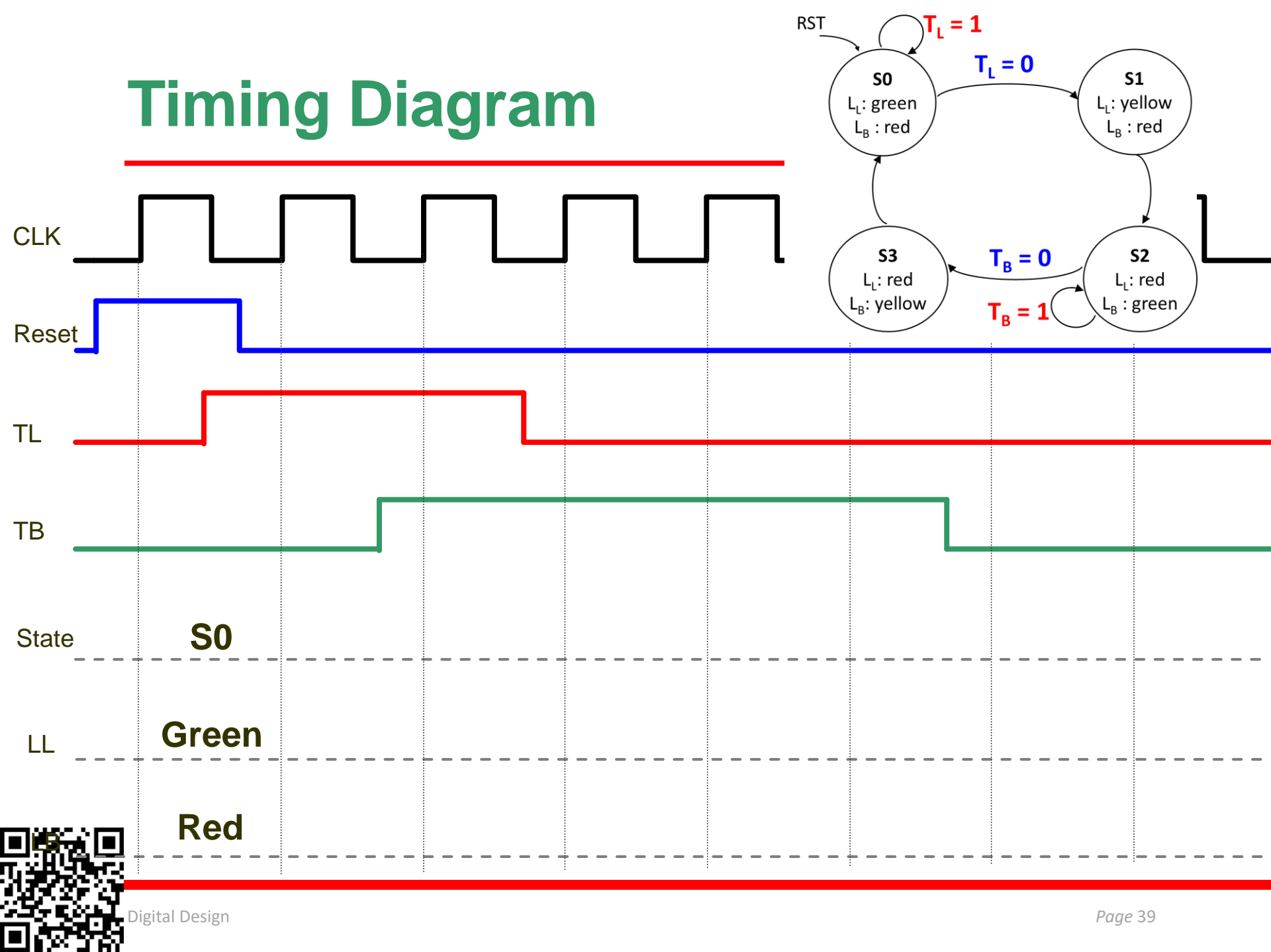
$$L_{L1} = S_1 \quad L_{L0} = \overline{S_1}S_0$$

$$L_{B1} = \overline{S_1} \quad L_{B0} = S_1S_0$$



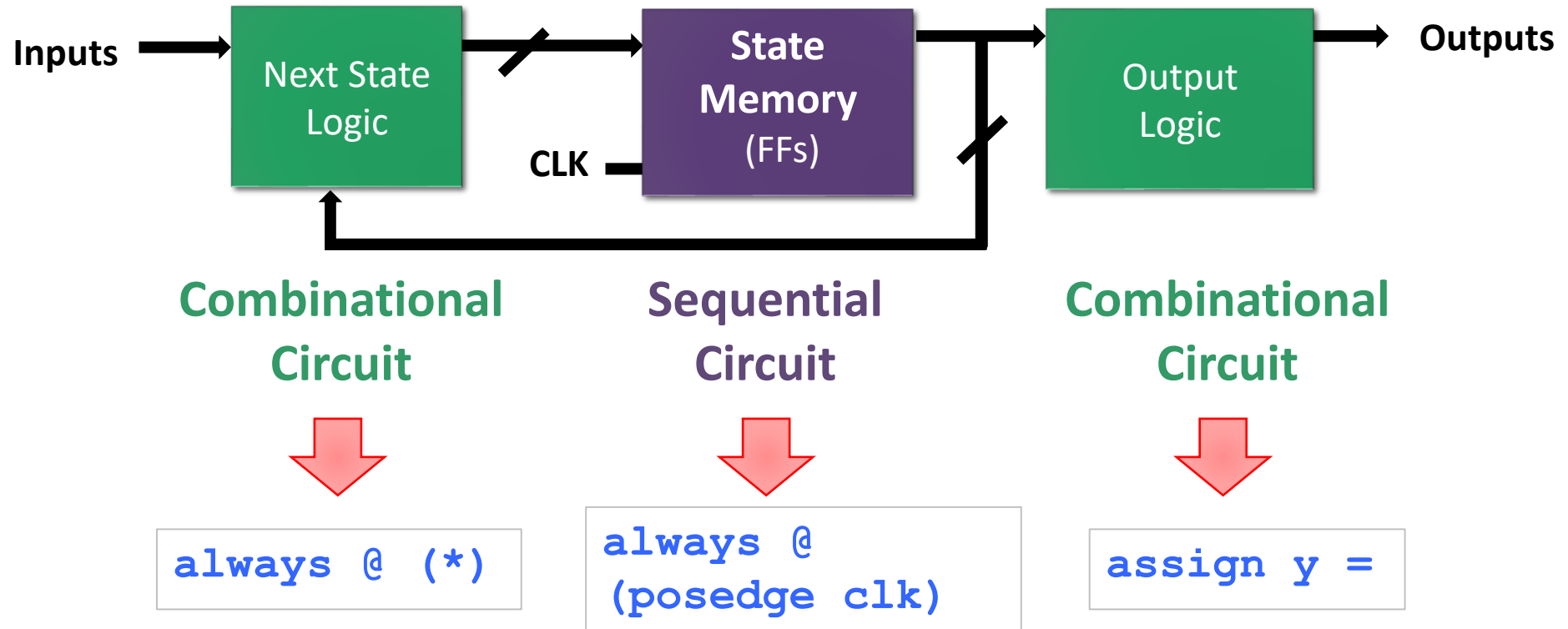
Did we miss out anything?

# Timing Diagram



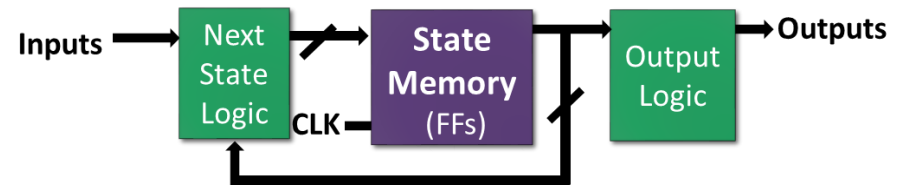
# Verilog~! – Code Structure

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# FSM in Verilog



```
module fsm(input clk, ... , output ... );
    reg __ state, nextstate;
```

```
parameter S0 = 2'b00;
parameter S1 = 2'b01;
```

**parameter** is used to define constants within a module, improving code readability.

```
always @ (*)
    case (state)
        S0 : nextstate = S1;
        S1 : nextstate = S0;
    endcase
```

**Next State Combinational Logic :**

(\*) code is triggered whenever any input changes → combinational logic.  
**case** represents next state table.

```
always @ (posedge clk, posedge reset)
    if (reset) state <= S0;
    else state <= nextstate;
```

**Sequential Logic :**

Use <= to infer flip-flops.  
*Is this Sync or Async reset?*

```
assign y = ( state == S0 );
```

**Output Logic :** Use **assign** to infer combinational logic.

```
endmodule
```

Equality Comparison :  
a == b evaluates to 1 if a equals b.



# FSM Traffic Controller in Verilog

```
module traffic (input clk, reset,
TL, TB, output [1:0] LL, LB);

reg [1:0] state, nextstate;

parameter S0 = 2'b00, S1 = 2'b01,
S2 = 2'b10, S3 = 2'b11;

parameter green = 2'b00,
yellow= 2'b01, red= 2'b10;

always @ (*) begin
    case (state)
        S0: nextstate = TL ? S0 : S1;
        S1: nextstate = S2;
        S2: nextstate = TB ? S2 : S3;
        S3: nextstate = S0;
    endcase
end
```

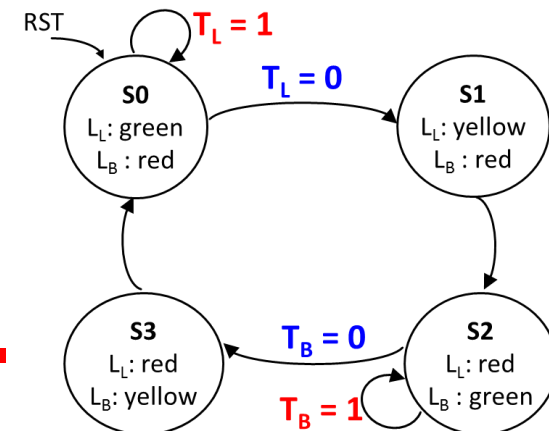
```
always@(posedge clk, posedge reset)
begin
    if (reset) state <= S0;
    else state <= nextstate;
end
```

//What's the diff between these  
//2 ways of coding output logic ?

```
assign LL
= {state[1], ~state[1] & state[0]};
```

```
assign LB =
(state== S0 || state== S1) ? red :
( (state == S2) ? green : yellow );
```

```
endmodule
```



# Traffic Controller

- Check the waveforms in the timing diagram below...

Are they correct?

