

Irfan Mohammad Al Hasib Machine Learning Engineer



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About me —

I am a passionate engineer, always seeking to learn something new.

Skills — Deep Learning

Deep Neural Network, CNN
Transformers, Diffusion Models, LLMs
Reinforcement Learning
Proficient in TensorFlow, PyTorch, Keras
Proficient in Python, Numpy, Pandas, Sklearn

Machine Learning

Regression, SVM,Naive Bias, k-NN, Decision Tree, CART, Random Forest, AdaBoost, GBoosting, XGboost, Bagging, Boosting, Stacking, Ensemble, K Means Clustering etc.

Computer Vision

CNN: YOLO, SSD, U-Net, DeepLab, R-CNN, ResNet, MobileNet, EfficientNet. CV: HOG, Haar, SURF, SIFT, ORB, Opt. Flow, Segmentation, Detection, Tracking etc.

Reinforcement Learning

Value Iteration, Policy Gradient, MDP, TD/MC Learning, DQN, DDPG, PPO, A2C, A3C etc.

Experience

Vision AI Engineer
Digital Media Professionals Inc., Tokyo, Japan (February, 2024- Till Present)
www.jiw.co.jp

- » Working on precise object pose estimation robotic ARM based factory automation.
- » Colaborating research work on Vision Language Model for safe driving.

Artificial Intelligence Engineer

Japan Infrastructure Waymark, Tokyo, Japan (August, 2021 - February, 2024) www.jiw.co.jp

- » Leading multiple client AI projects from requirement analysis to deployment.
- » Leading research on infrastrusture inspection using **anomaly detection**, **visual change detection** from image data.
- » Research and Development of **structural component and defect detection** system from drone video for severel top companies in Japan using SOTA AI models.
- » Development and maintainance the **Machine Learning Pipeline** for production environment. Frequently work with **Python, AWS, CI/CD , Linux systems, Docker** etc.

Artificial Intelligence Engineer
Hiperdyne Corporation, Japan (July, 2019- August 2021)
www.hiperdyne.com

- » Development of **AI based automation of an industrial process control system** with optimal control parameter estimation. *detail link*
- » Product shipment optimization utilizing **AI based optimization techniques**. An AI driven tool for shipment planning for oil supplier company. *detail link*
- \gg Development of **Deep Learning based system for Production KPI estimation**, from real time **sensor data** in a industry. *detail link*
- » A system for **Production dynamics visualization using Machine Learning.** The system generated 2D/3D dimensional visual output from high dimensional data stream to assists a human operator at industry. *detail link*

Artificial Intelligence and Japanese Language Training
Hiperdyne Corporation, Japan (November, 2018- April, 2019)
www.hiperdyne.com

Jr. Research Engineer (Product development and Research Dept.)
Pi Labs Bangladesh Ltd. (August, 2017- September, 2018)
www.pilabsbd.com

- » IoT based Security and Monitoring System Development utilizing **ESP8266** based sensor nodes and **Raspberry Pi** based server. *detail link*
- » Programmable Syringe Infusion Pump Development. Platforms : **AVR micro controller**; **FreeRTOS**. *detail link*
- » Box **tracking system** based on utilization of **GPRS signal** transmitted from the box at regular interval with location information. *detail link*
- » Online weight measuring machine in supply shop. detail link

Achievements

2016

Participated along with my team, Interplaneter in University Rover challenge, 2016 at Utah, USA. Our team attained 5th position in Phobos final. I was in charge of **Robotic Manipulator Design and deployment**. The Competition is organized by Mars Society, USA annually for college students world wide. URC 2016 Result, video link YouTube

Publications (Lead Author)

2023 My work as main author - "Boosting auxiliary task guidance: a probabilistic approach" has been published in IAES International Journal of Artificial Intelligence, *Volume 12PDF*



Python: Advanced Level (4 year +) C++: Intermediate Level (1.5 year)

Web Development, React JS: Basic (few months)

Data Analysis:

Standard Data Preprocessing Pipeline, SMOTE, Correlation & Feature Importance Analysis, Confusion Matrix, AUC & ROC, Data Visualization Tools, VAE, PCA, t-SNE, SVD, FFT, Wavelet Transform etc.

Development Platform

Linux : Intermediate Level (2 year +)
GitHub : Intermediate Level (3 year +)
DBMS (SQL) : Developing (1 year)
Docker : Developing (1 Year)

AWS: EC2, S3, ECS, Lambda Developing (

1 Year)

Web Development: Flask, Django (6 months) Spark & Hadoop: Basic (Roughly a month)

Kubernetes: (Learning)

Embedded System & IoT

AVR Micro-controller (C++), Basic ARM ESP 8266, Raspberry Pi (Python, C++)

Engineering Mathematics:

Linear Algebra, Vector & Matrix, Transformations, Eigen-decomposition, Differential Calculus, Engineering Mathematics

Probability and Statistics:

Data Distributions, Bayes Theorem, Entropy, Cross Entropy, KL-divergence, Information Gain, Relevant theorems of Probability, Statistics and Information Theory.

Robotics:

IoT & Embedded System Design

Path Planning Algorithms
Robot Vision Algorithms
Robot Operating System (ROS)
Visual Odometry and SLAM

Data Structure and Algorithms

Data Structures and Sorting Algorithms Graph and Tree based Algorithms Recursion & Dynamic Programming

Project Management

Agile Project Management Requirement Analysis PM Tools : Trello, Asana

Machine Learning Project

2022	My Deep Learning and Computer Vision Blogs on FasterRCNN, YOLO,
2020	CNN Networks etc. https://irfanhasib0.github.io/blogs/ Machine Learning Algorithms implementation from scratch (ANN,
2020	SVM, Descision Tree, Logistic Regression, Naive Bias, kNN) GitHub Implementation of Deep Learning based Computer Vision Algo-
	rithms - YOLO-V1-3, UNet, Flow-Net(optical flow), Disparity estima-
	tor. GitHub link

Reinforcement Learning Algorithms from Scratch (DQN, DDPG, A2C,

PPO) using Python and Tensorflow. GitHub link

2019 **Kaggle Competition**: House Price Prediction using state of the art data preprocessing methods and hyperparameter tuning. GitHub link

Robotics Project

Implementing optimal steering angle estimator from road coordinates using **Model Predictive Controller (MPC)** and Iterative Linear Quadratic Regulator (ILQR) algorithms from scratch. Tested the on AirSim environment and OpenAI car racing environment.GitHub

Designed a simple two link Robot using URDF and written driver codes for **ROS in Python**. YouTube link

Built a programmable (G- code) **Desktop CNC Machine** using AVR Platform, for G-code parsing I have used an open source called GRBL.

YouTube link

Visually instructed **Robotic arm on AVR Platform**. I have build a simple object tracker using IR sensor array YouTube link 1 I also built a GUI software in python for controlling, link 2

Education

2017 B.Sc. in Mechanical Engineering

Bangladesh University of Engineering and Technology (BUET)

CGPA: 3.23 out of 4.00

2011 HSC (Science)

Rajuk Uttara Model College, Uttara, Dhaka 1207

GPA: 5.00 out of 5.00

2009 SSC (Science)

Rajuk Uttara Model College, Uttara, Dhaka 1207

GPA: 5.00 out of 5.00

Language

English: Business level proficiency in English

Japanese: Passed NAT-N5

Academic Project

A Remote control Surveillance robot. The robot was able to pick up small objects from hole. It could also send temperature, pressure and video feed from an remote place using Bluetooth signal for surveil-

lance support.(link)

For undergrad thesis we developed a precision velocity measurement system. We used Kalman filtering for **Sensor Fusion** and combined

GPS (Ublox-NEO 6) and IMU Sensor(MPU6050) data. (link)

Co-Curricular activities

2016 Founding President at BUET ROBOTICS SOCIETY (BRS) (page)

2016 Co-organized Annual Robotics Competition for BRS

Other Publications

Development of a two wheeled self balancing robot with speech recognition and navigation algorithm, Journal: AIP

2019 Integrating data mining and microsimulation modelling to reduce

traffic congestion. Journal: Urban Science