

Geometrie și algebră liniară

① a)

② b)

③ b)

④ a)

⑤ $\Gamma: f(x) = x_1^2 - 8x_1x_2 + 7x_2^2 - 12x_1 - 6x_2 - 9 = 0$

a) $A = \begin{pmatrix} 1 & -4 \\ -4 & 7 \end{pmatrix} \quad B = \begin{pmatrix} -6 \\ -3 \end{pmatrix} \quad \tilde{A} = \begin{pmatrix} 1 & -4 & -6 \\ -4 & 7 & -3 \\ -6 & -3 & -9 \end{pmatrix}$

$\delta = \det A = \begin{vmatrix} 1 & -4 \\ -4 & 7 \end{vmatrix} = 7 - 16 = -9 \neq 0 \Rightarrow$ conică cu centru unic

$\Delta = \det \tilde{A} = \begin{vmatrix} 1 & -4 & -6 \\ -4 & 7 & -3 \\ -6 & -3 & -9 \end{vmatrix} = -324 \neq 0 \Rightarrow$ conică nedegenerată

Fie P_0 centrul conicei.

$P_0: \begin{cases} \frac{\partial f}{\partial x_1} = 0 \\ \frac{\partial f}{\partial x_2} = 0 \end{cases} \Rightarrow \begin{cases} 2x_1 - 8x_2 - 12 = 0 \\ -8x_1 + 14x_2 - 6 = 0 \end{cases} \Rightarrow \begin{cases} x_1 - 4x_2 = 6 \\ -4x_2 + 7x_2 = 3 \end{cases} \Rightarrow \begin{cases} x_1 - 4x_2 = 6 \\ -9x_2 = 27 \end{cases} \quad (+)$

$\Rightarrow x_2 = -3, x_1 = -6 \Rightarrow \boxed{P_0(-6, -3)}$

$R = \{O; e_1, e_2\} \xrightarrow[\text{translație}]{\Theta} R' = \{P_0; e_1, e_2\} \xrightarrow[\text{rotatie}]{\gamma} R'' = \{P_0; e'_1, e'_2\}$

$\Theta: x = x' + x_0, x_0 = \begin{pmatrix} -6 \\ -3 \end{pmatrix}$

$\Theta(\Gamma): X'^T A X' + \frac{\Delta}{\delta} = 0$

$$Q: \mathbb{R}^2 \rightarrow \mathbb{R}, Q(x) = x'^T A x' \rightarrow Q(x) = x_1'^2 - 8x_1'x_2' + 7x_2'^2$$

Aducem Q la forma canonică, folosind metoda valorilor proprii.

$$\lambda^2 - \text{Tr}(A)\lambda + \det A = 0$$

$$\lambda^2 - 8\lambda - 9 = 0$$

$$(\lambda - 9)(\lambda + 1) = 0 \begin{cases} \lambda_1 = 9 \\ \lambda_2 = -1 \end{cases}$$

$$\begin{aligned} \bullet V_{\lambda_1} &= \{x \in \mathbb{R}^2 \mid Ax = 9x\} \\ &\quad (A - 9I_2)x = 0 \end{aligned} \quad \begin{cases} -8x_1 - 4x_2 = 0 \\ -4x_1 - 2x_2 = 0 \end{cases} \Rightarrow \begin{aligned} -2x_1 - x_2 &= 0 \Rightarrow \\ x_2 &= -2x_1 \end{aligned}$$

$$V_{\lambda_1} = \{(x_1, -2x_1) \mid x_1 \in \mathbb{R}\} = \langle \{(1, -2)\} \rangle \Rightarrow \boxed{e_1' = \frac{1}{\sqrt{5}} (1, -2)}$$

$$\begin{aligned} \bullet V_{\lambda_2} &= \{x \in \mathbb{R}^2 \mid Ax = -x\} \\ &\quad (A + I_2)x = 0 \end{aligned} \quad \begin{cases} 2x_1 - 4x_2 = 0 \\ -4x_1 + 8x_2 = 0 \end{cases} \Rightarrow \begin{aligned} x_1 - 2x_2 &= 0 \Rightarrow \\ x_1 &= 2x_2 \end{aligned}$$

$$V_{\lambda_2} = \{(2x_2, x_2) \mid x_2 \in \mathbb{R}\} = \langle \{(2, 1)\} \rangle \Rightarrow \boxed{e_2' = \frac{1}{\sqrt{5}} (2, 1)}$$

$$\mathcal{L}: x' = R x'', R = \frac{1}{\sqrt{5}} \begin{pmatrix} 1 & 2 \\ -2 & 1 \end{pmatrix}$$

$$\mathcal{L} \circ \Theta(\Gamma): x = R x'' + x_0$$

$$\lambda_1 x_1''^2 + \lambda_2 x_2''^2 + \frac{\Delta}{\delta} = 0 \Rightarrow$$

$$\Rightarrow \mathcal{L} \circ \Theta(\Gamma): 9x_1''^2 - x_2''^2 + 36 = 0$$

$$\frac{x_1''^2}{4} - \frac{x_2''^2}{36} + 1 = 0$$

$$-\frac{x_2''^2}{4} + \frac{x_2''^4}{36} = 1 \Rightarrow \Gamma \text{ hiperbolă.}$$

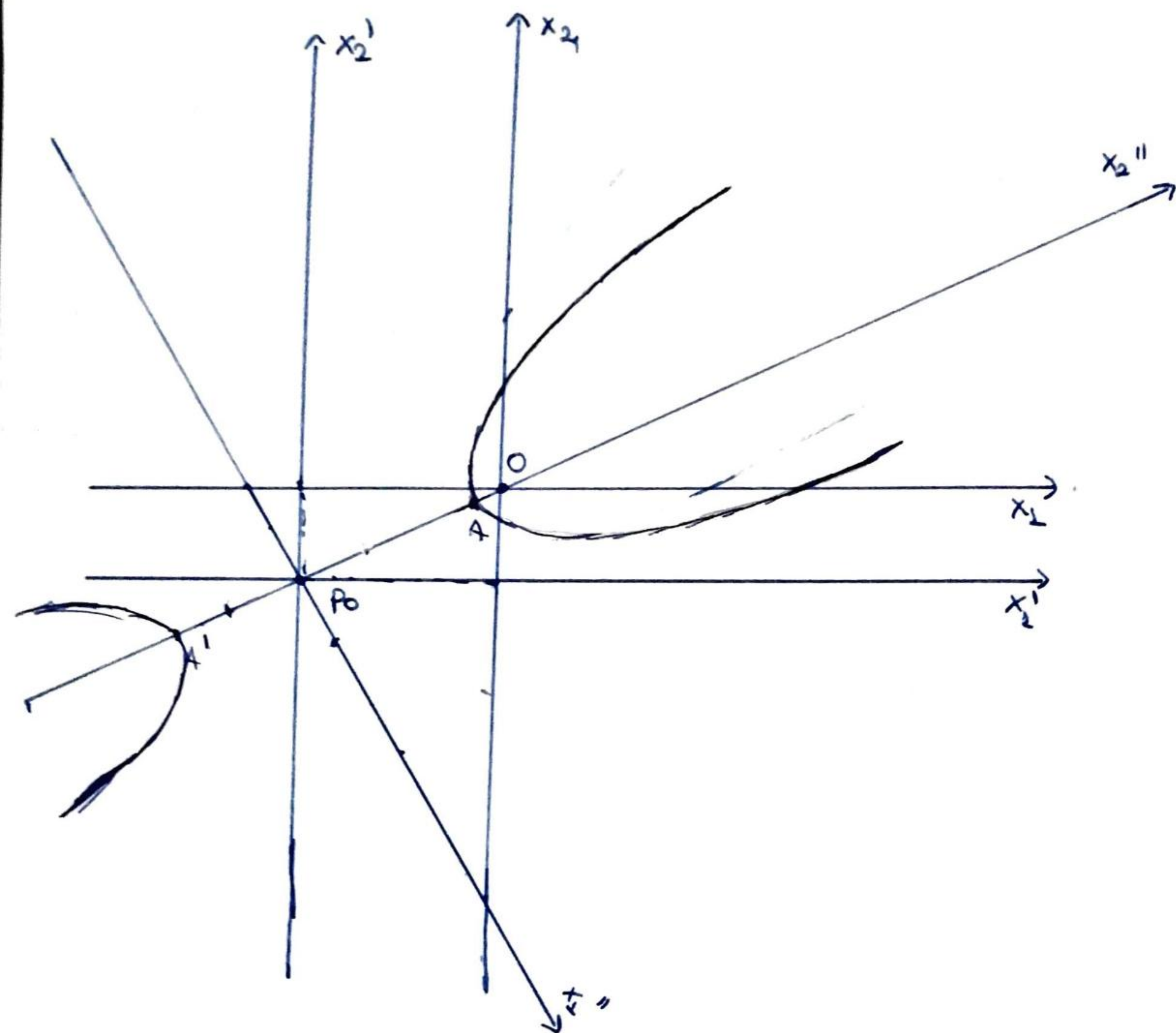
$$\mathcal{H}: -\frac{x_1''^2}{4} + \frac{x_2''^4}{36} = 1$$

$$e_1' = \frac{1}{\sqrt{5}} (1, -2)$$

$$e_2' = \frac{1}{\sqrt{5}} (2, 1)$$

$$a = 2$$

$$b = 6$$



⑥ a) $A = [f]_{\mathcal{R}_0, \mathcal{R}_0} = \begin{pmatrix} 3 & -1 & 1 \\ 2 & 0 & 1 \\ 2 & -2 & 3 \end{pmatrix}$

• $U_1 = e_1 + e_2$

$f(U_1) = f(e_1 + e_2) = f(e_1) + f(e_2) = (3, 2, 2) + (-1, 0, -2) =$

$=(2, 2, 0) = 2(1, 1, 0) = 2U_1 \Rightarrow U_1 \text{ e vector proprie}$

$\boxed{\lambda_1 = 2}$ val proprie coresp. lui U_1

• $U_2 = e_2 + e_3$

$f(U_2) = f(e_2 + e_3) = f(e_2) + f(e_3) = (-1, 0, -2) + (1, 1, 3) = (0, 1, 1) = U_2$

$\Rightarrow U_2 \text{ e vector proprie}$

$\boxed{\lambda_2 = 1}$ val. proprie coresp. lui U_2

$$v_3 = e_1 + e_2 + e_3$$

$$f(v_3) = f(e_1 + e_2 + e_3) = f(e_1) + f(e_2) + f(e_3) = (3, 2, 2) + (-1, 0, -2) + (4, 3) \\ = (3+1-1, 2+1, 2-2+3) = (3, 3, 3) = 3v_3 \Rightarrow v_3 \text{ e vector propriu} \\ \boxed{\lambda_3 = 3} \text{ val. proprie coresp. lui } v_3.$$

e) $\lambda_1 \neq \lambda_2 \neq \lambda_3 \Rightarrow v_1, v_2, v_3$ vectori proprii coresp. la val proprii distincte $\Rightarrow K = \{v_1, v_2, v_3\}$ formează un SLI $\Rightarrow K$ reper al lui \mathbb{R}^3 .
 $|K| = 3 = \dim_{\mathbb{R}} \mathbb{R}^3$

• Fie $a, b, c \in \mathbb{R}$. ai $v = av_1 + bv_2 + cv_3$

$$v = e_1 + 2e_2 + e_3 = a(e_1 + e_2) + b(e_2 + e_3) + c(e_1 + e_2 + e_3) \\ = ae_1 + ae_2 + be_2 + be_3 + ce_1 + ce_2 + ce_3 \\ = e_1(a+c) + e_2(a+b+c) + e_3(b+c)$$

$$\Rightarrow \begin{cases} a+c=1 \\ a+b+c=2 \\ b+c=1 \end{cases} \Rightarrow \begin{matrix} a=1 \\ b=1 \\ c=0 \end{matrix} \rightarrow (1, 1, 0) \text{ coord. lui } v \text{ în raport cu } K.$$

$$f(v) = f(v_1 + v_2) = f(v_1) + f(v_2) \xrightarrow{\text{cf. a)}} 2v_1 + v_2 \Rightarrow (2, 1, 0) \text{ coord lui } f(v) \text{ în raport cu } K.$$

$$(7) a) A = [f]_{K_0, K_0} = \frac{1}{3} \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix}$$

f proiecție $\Leftrightarrow f \circ f = f$

Fie $x \in \mathbb{R}^3$

$$f \circ f(x) = f(f(x)) = f\left(\frac{1}{3}(x_1 + x_2 + x_3, x_1 + x_2 + x_3, x_1 + x_2 + x_3)\right) =$$

$$= f\left(\frac{x_1 + x_2 + x_3}{3}, \frac{x_1 + x_2 + x_3}{3}, \frac{x_1 + x_2 + x_3}{3}\right) =$$

$$= \frac{1}{3} \left(\frac{x_1 + x_2 + x_3}{3}, \frac{x_1 + x_2 + x_3}{3}, \frac{x_1 + x_2 + x_3}{3} \right) =$$

$$= \frac{1}{3}(x_1+x_2+x_3, x_1+x_2+x_3, x_1+x_2+x_3) = f(x) \rightarrow$$

$$\Rightarrow f \circ f = f \Rightarrow \underline{f \text{ projective}}$$

$$f \in \text{Sim}(\mathbb{R}^3) \Leftrightarrow A^T = A$$

$$A^T = \frac{1}{3} \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix} = A \Rightarrow A^T = A \Rightarrow f \in \text{Sim}(\mathbb{R}^3)$$

$$a) P(\lambda) = \det(A - \lambda I_3) = 0$$

$$\lambda^3 - \sigma_1 \lambda^2 + \sigma_2 \lambda - \sigma_3 = 0$$

$$\sigma_1 = \frac{1}{3}(1+1+1) = 1$$

$$\sigma_2 = \frac{1}{9} \begin{vmatrix} 1 & 1 \\ 1 & 1 \end{vmatrix} + \frac{1}{9} \begin{vmatrix} 1 & 1 \\ 1 & 1 \end{vmatrix} + \frac{1}{9} \begin{vmatrix} 1 & 1 \\ 1 & 1 \end{vmatrix} = 0$$

$$\sigma_3 = \det A = 0$$

$$\lambda^3 - \lambda^2 = 0 \Rightarrow \lambda^2(\lambda - 1) = 0 \rightarrow \begin{cases} \lambda_1 = 0, m_1 = 2 \\ \lambda_2 = 1, m_2 = 1 \end{cases}$$

$$\bullet V_{\lambda_1} = \{x \in \mathbb{R}^3 \mid Ax = 0\} \begin{cases} \frac{1}{3}(x_1 + x_2 + x_3) = 0 \\ \frac{1}{3}(x_1 + x_2 + x_3) = 0 \Rightarrow x_1 + x_2 + x_3 = 0 \\ \frac{1}{3}(x_1 + x_2 + x_3) = 0 \Rightarrow x_3 = -x_1 - x_2 \end{cases}$$

$$V_{\lambda_1} = \{(x_1, x_2, -x_1 - x_2) \mid x_1, x_2 \in \mathbb{R}\} = \langle \{(1, 0, -1), (0, 1, -1)\} \rangle$$

$$\bullet V_{\lambda_2} = \{x \in \mathbb{R}^3 \mid Ax = x\} \quad (A - I_3)x = 0 \quad \begin{cases} -\frac{2}{3}x_1 + \frac{1}{3}x_2 + \frac{1}{3}x_3 = 0 \\ \frac{1}{3}x_1 - \frac{2}{3}x_2 + \frac{1}{3}x_3 = 0 \quad \text{or} \\ \frac{1}{3}x_1 + \frac{1}{3}x_2 - \frac{2}{3}x_3 = 0 \end{cases}$$

$$\Leftrightarrow \begin{cases} -2x_1 + x_2 + x_3 = 0 \\ x_1 - 2x_2 + x_3 = 0 \\ x_1 + x_2 - 2x_3 = 0 \end{cases} \Rightarrow x_2 = x_1, x_3 = x_1$$

$$V_{\lambda_2} = \{(x_1, x_1, x_1) \mid x_1 \in \mathbb{R}\} = \langle \{(1, 1, 1)\} \rangle$$

$$R_2 = \{(1, 1, 1)\} \text{ reper in } V_{\lambda_2}$$

Există un reper $R = R_1 \cup R_2$, R reper în \mathbb{R}^3 cu matricea asociată
 lui f în raport cu R este diagonală

$$R = \{(1, 0, -1), (0, 1, -1)\} \cup \{(1, 1, 1)\} = \{(1, 0, -1), (0, 1, -1), (1, 1, 1)\}$$

$$A' = [f]_{R,R} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

⑧ a) $d_1: x_2 = x_3 = 0$

$$d_1: \frac{x_1}{1} = \frac{x_2}{0} = \frac{x_3}{0} \Rightarrow \begin{cases} x_1 = t \\ x_2 = 0 \\ x_3 = 0 \end{cases} \quad \begin{matrix} A_1(0, 0, 0) \\ U = (1, 0, 0) \end{matrix}$$

$$d_2: \begin{cases} x_2 - 1 = 0 \\ x_1 = x_3 \end{cases} \Rightarrow \begin{cases} x_1 = s \\ x_2 = 1 \\ x_3 = s \end{cases} \quad \begin{matrix} A_2(0, 1, 0) \\ V = (1, 0, 1) \end{matrix}$$

$$\begin{vmatrix} u_1 & v_1 & u_1 - v_1 \\ u_2 & v_2 & u_2 - v_2 \\ u_3 & v_3 & u_3 - v_3 \end{vmatrix} = \begin{vmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{vmatrix} = -1 \neq 0 \Rightarrow d_1, d_2 \text{ necoplanare.}$$

Fie d perpendiculara comună

Fie $P_1 = d \cap d_1$, $P_2 = d \cap d_2$

$$P_1(t, 0, 0)$$

$$P_2(s, 1, s)$$

$$\overrightarrow{P_1 P_2} = (s - t, 1, s), \quad U = (1, 0, 0), \quad V = (1, 0, 1)$$

$$\begin{cases} \langle \overrightarrow{P_1 P_2}, U \rangle = 0 \\ \langle \overrightarrow{P_1 P_2}, V \rangle = 0 \end{cases} \Rightarrow \begin{cases} s - t = 0 \\ s - t + s = 0 \end{cases} \Rightarrow \begin{matrix} t = 0 \\ s = 0 \end{matrix}$$

$$P_1(0, 0, 0), P_2(0, 1, 0), \overrightarrow{P_1 P_2} = (0, 1, 0)$$

$$d: \frac{x_1}{0} = \frac{x_2}{1} = \frac{x_3}{0}$$

b) $\text{dist}(d_1, d_2) = \text{dist}(P_1, P_2) = \sqrt{1^2} = 1$

$$(9) a) A = \frac{1}{7} \begin{pmatrix} -3 & -2 & 6 \\ 6 & -3 & 2 \\ 2 & 6 & 3 \end{pmatrix}$$

$$A^T A = \frac{1}{49} \begin{pmatrix} -3 & 6 & 2 \\ -2 & -3 & 6 \\ 6 & 2 & 3 \end{pmatrix} \begin{pmatrix} -3 & -2 & 6 \\ 6 & -3 & 2 \\ 2 & 6 & 3 \end{pmatrix} = I_3 \quad (1)$$

$$\det A = \frac{1}{343} \begin{vmatrix} -3 & -2 & 6 \\ 6 & -3 & 2 \\ 2 & 6 & 3 \end{vmatrix} = \frac{1}{343} (27 + 216 - 8 + 36 + 36 + 36) = 1 \quad (2)$$

$$(1), (2) \Rightarrow A \in SO(3) \Rightarrow \varphi = R_\varphi$$

$$e) \operatorname{Tr} A = \frac{1}{7} (-3 - 3 + 3) = -\frac{3}{7} = 1 + 2 \cos \varphi \Rightarrow$$

$$\Rightarrow 2 \cos \varphi = -\frac{3}{7} - 1 = -\frac{10}{7}$$

$$\cos \varphi = -\frac{5}{7} \Rightarrow \boxed{\varphi = \arccos\left(-\frac{5}{7}\right)}$$

$$\text{axa: } \varphi(x) = x \Rightarrow \begin{cases} -3x_1 - 2x_2 + 6x_3 = 7x_1 \\ 6x_1 - 3x_2 + 2x_3 = 7x_2 \\ 2x_1 + 6x_2 + 3x_3 = 7x_3 \end{cases} \Leftrightarrow$$

$$\Leftrightarrow \begin{cases} -10x_1 - 2x_2 + 6x_3 = 0 \\ 6x_1 - 10x_2 + 2x_3 = 0 \\ 2x_1 + 6x_2 - 4x_3 = 0 \end{cases} \Rightarrow \begin{cases} 10x_1 - 2x_2 = -6x_3 \\ 6x_1 - 10x_2 = -2x_3 \end{cases} \Rightarrow$$

$$\Rightarrow \begin{cases} -5x_1 - x_2 = -3x_3 \quad | \cdot (-5) \\ 3x_1 - 5x_2 = -x_3 \end{cases} \Rightarrow \begin{cases} 25x_1 + 5x_2 = 15x_3 \\ 3x_1 - 5x_2 = -x_3 \end{cases} \quad (A)$$

$$28x_1 = 14x_3 \Rightarrow x_1 = \frac{1}{2} x_3$$

$$x_2 = 3x_3 - 5x_1 = 3x_3 - \frac{5}{2}x_3 = \frac{1}{2}x_3$$

$$\langle \left\{ \left(\frac{1}{2}, \frac{1}{2}, 1 \right) \right\} \rangle = \langle \{ (1, 1, 2) \} \rangle \quad \underline{\text{axa de rotație}}$$