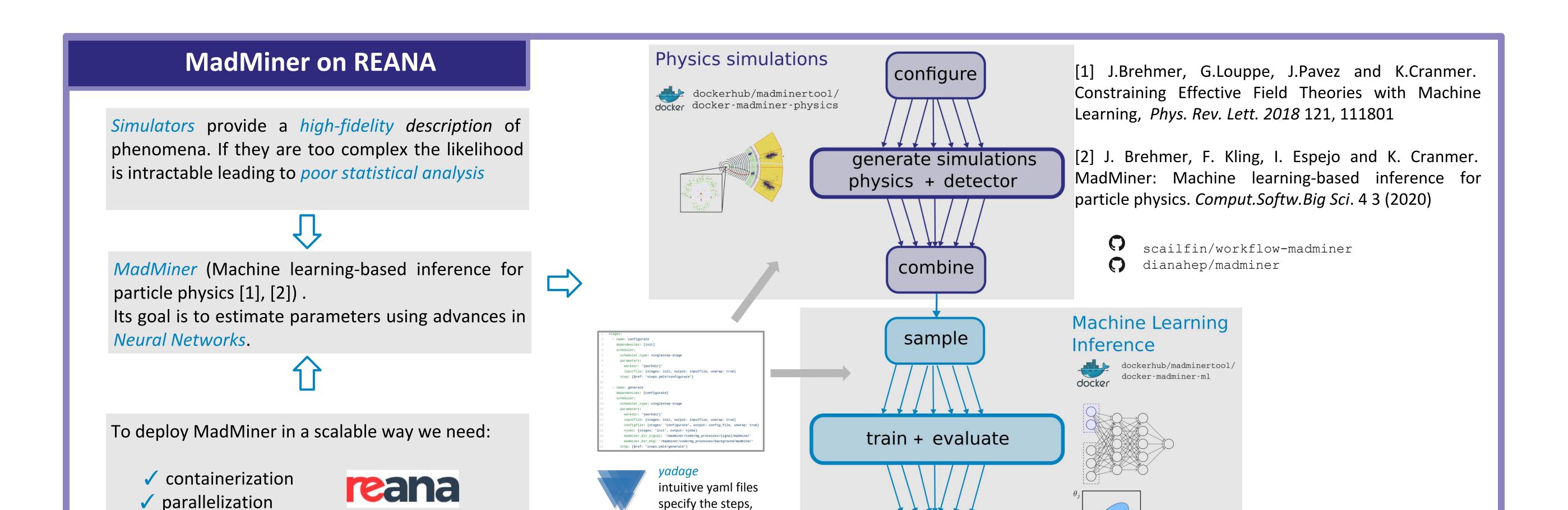


## Scalable cyberinfrastructure applications

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Institutions: <sup>1</sup> Center for Data Science, New York University <sup>2</sup> Department of Physics, New York University





plot + results

## **Excursion**

✓ reusability

- Goal is to find *level sets of black-box functions* that are expensive to evaluate. Examples: test statistics from complex simulations.
- Evaluate the black box function at *interesting points only* instead of evaluating at whole regular grid. We use a *Gaussian process* to: interpolate between samples and model uncertainty in the knowledge of the black box function.

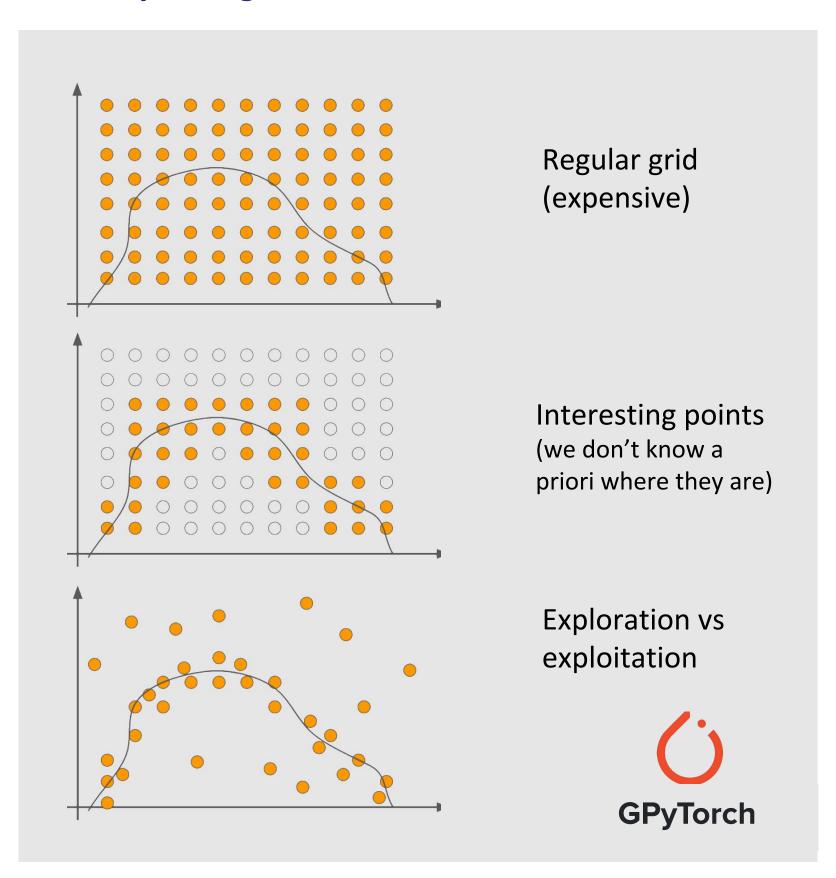
The *acquisition function* regulates the exploration vs exploitation tradeoff. Select one that *minimizes global uncertainty* of the location of the excursion set.

• Future: efforts will focus on *scalability* wrt the dimensionality of the function domain space. Example, likelihood ratio as function of mass, charge, spin,...

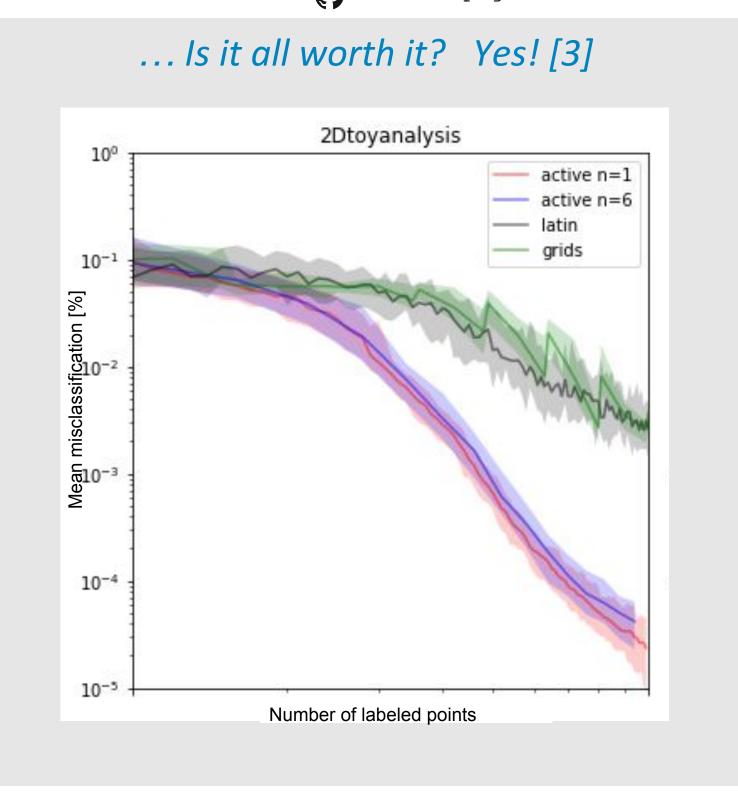
## in collaboration with G. Louppe<sup>2</sup> and L. Heinrich<sup>3</sup> <sup>2</sup>University of Liège, <sup>3</sup>CERN

then builds the

workflow



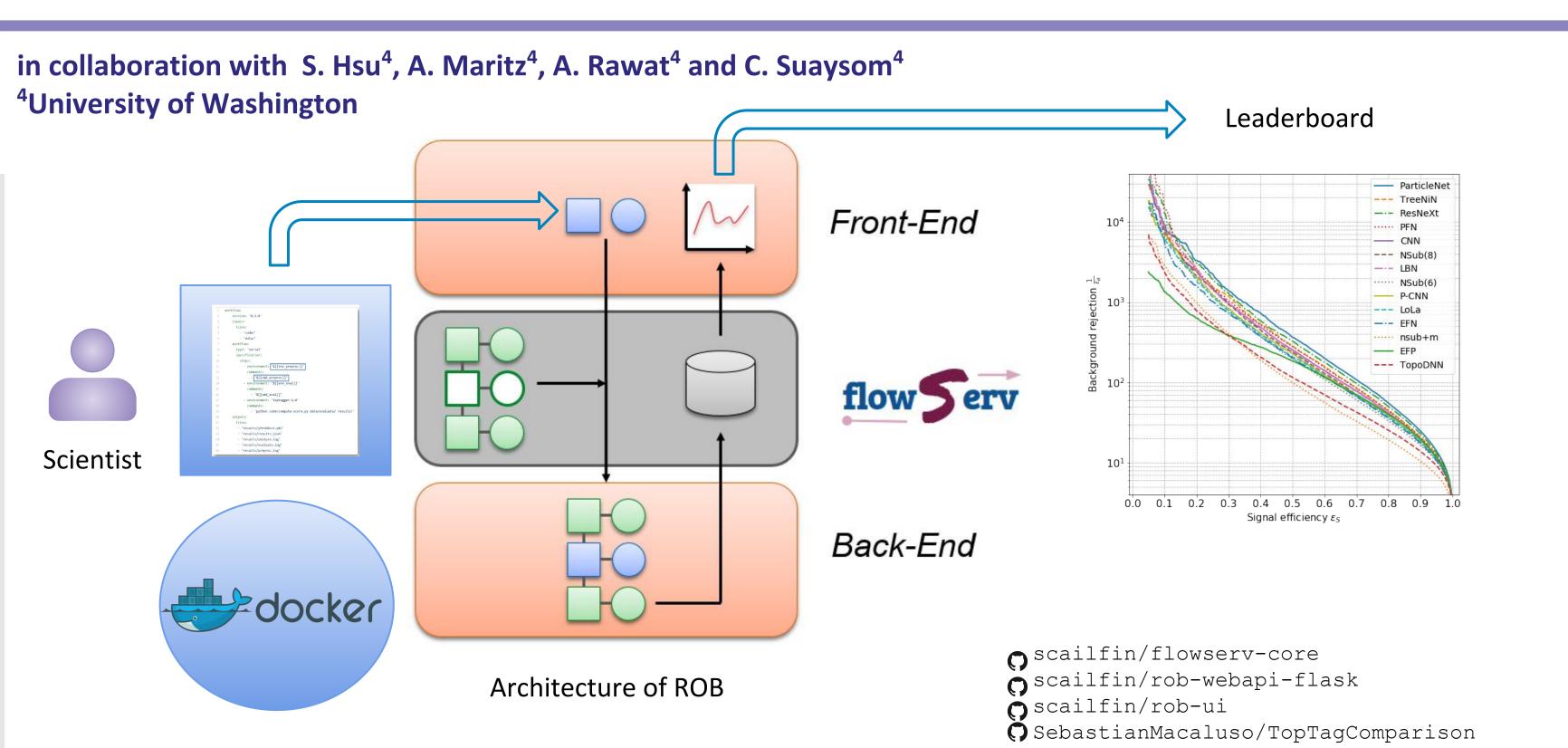
diana-hep/excursion irinaespejo/excursion



[3] L. Heinrich, G. Louppe, K. Cranmer, Excursion Set Estimation using Sequential Entropy Reduction for Efficient Searches for New Physics at the LHC, ACAT 2019

## ROB Reproducible Open Benchmark Platform

- ROB is an experimental prototype for enabling community benchmarks of data analysis algorithms. The goal of ROB is to allow user communities to evaluate the performance of their different data analysis algorithms in a reproducible competition-style format.
- The workflow template and input data are defined by a coordinator. The template contains placeholders for workflow steps that are implemented by the participants (e.g., with Docker containers). The backend processes the submission workflows. The user interface allows participants to submit new runs and to view the results.



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