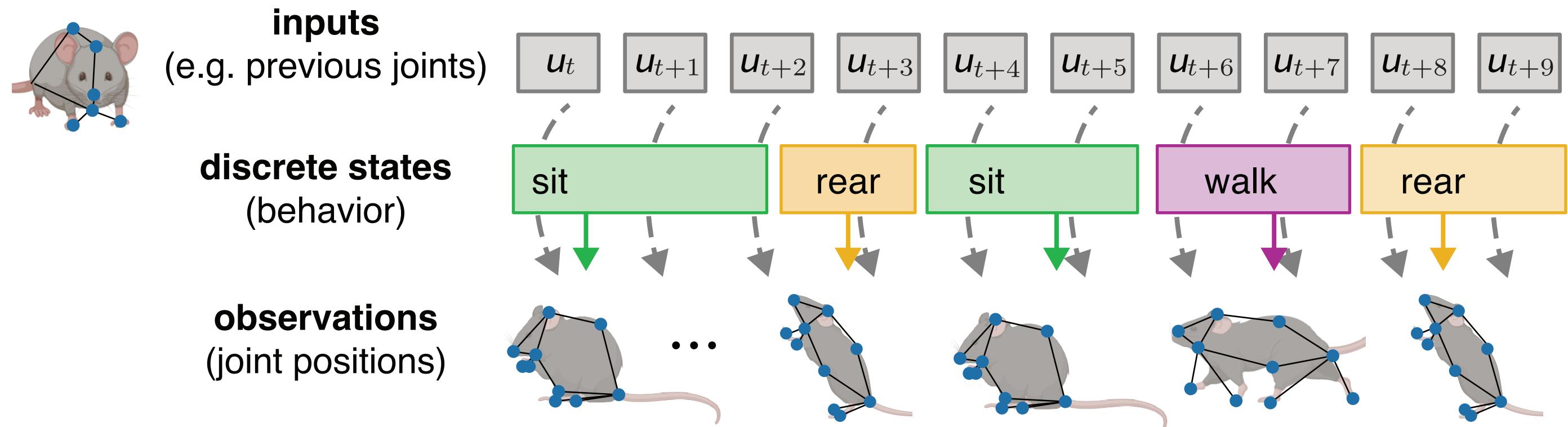
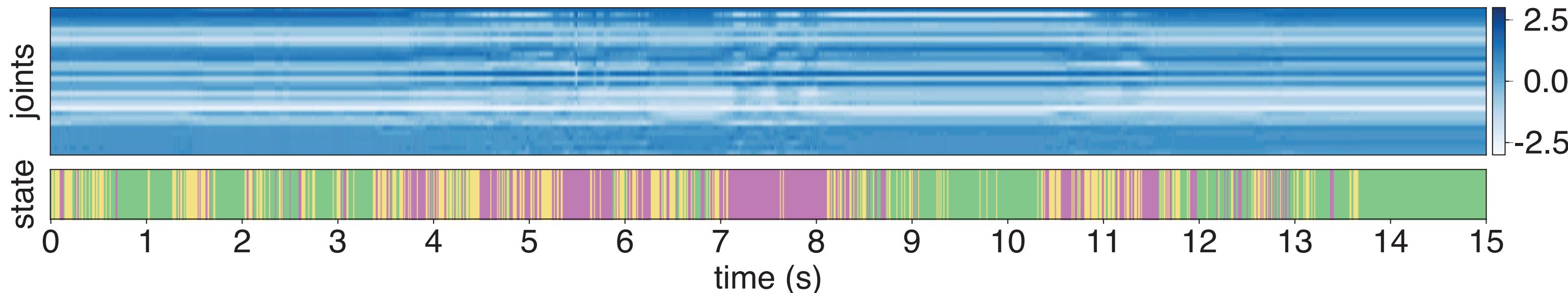
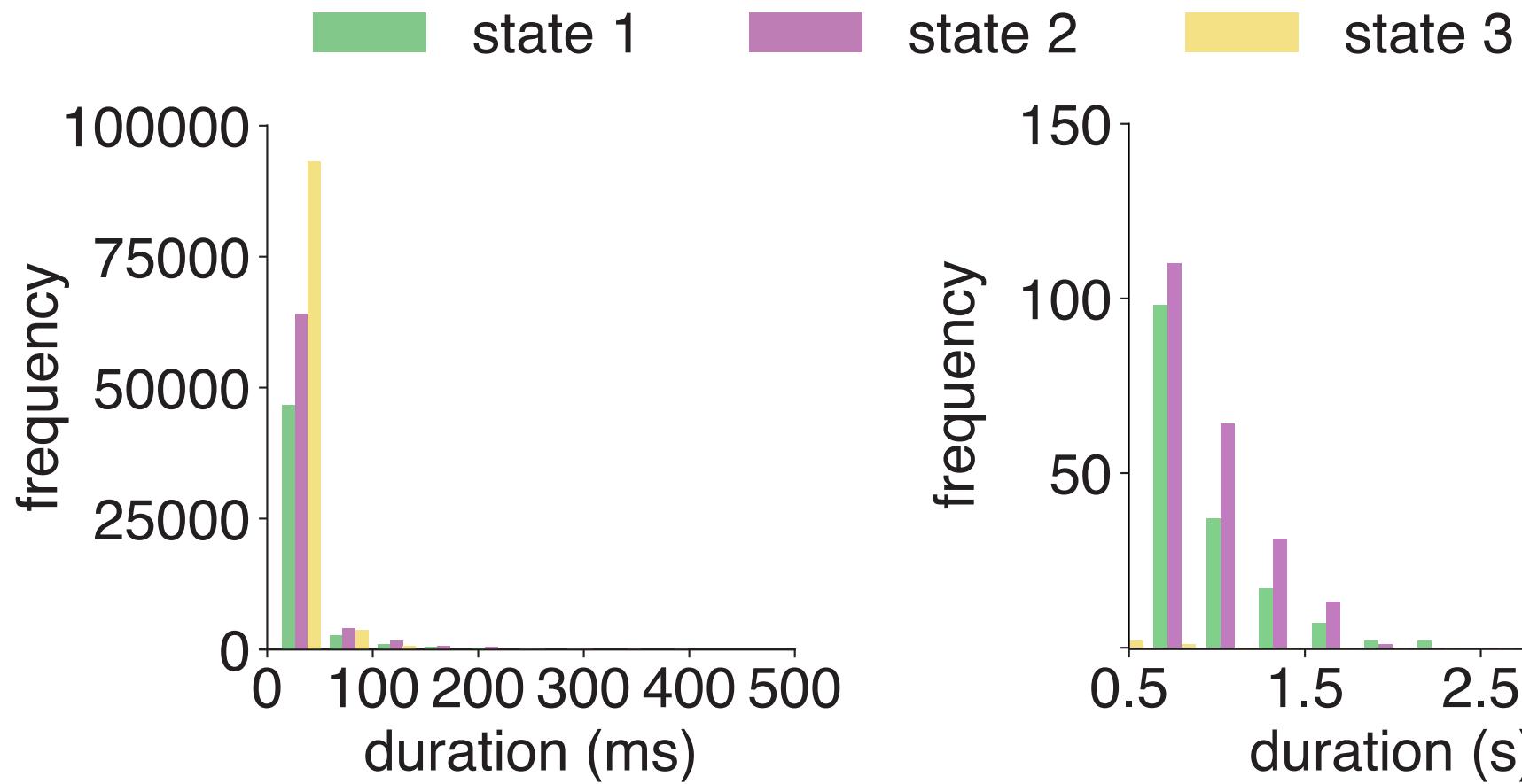
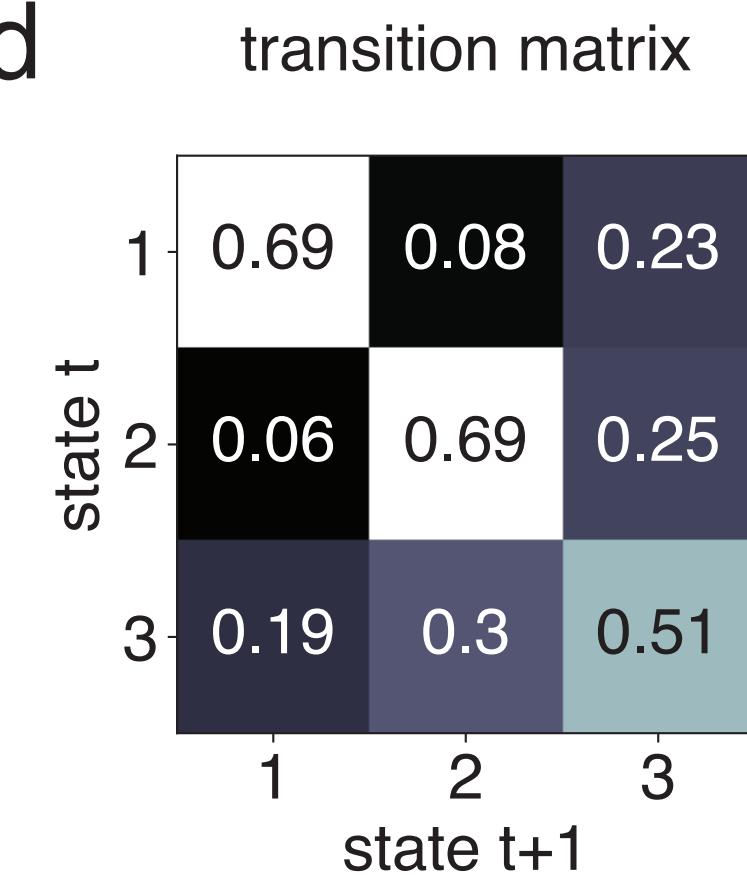
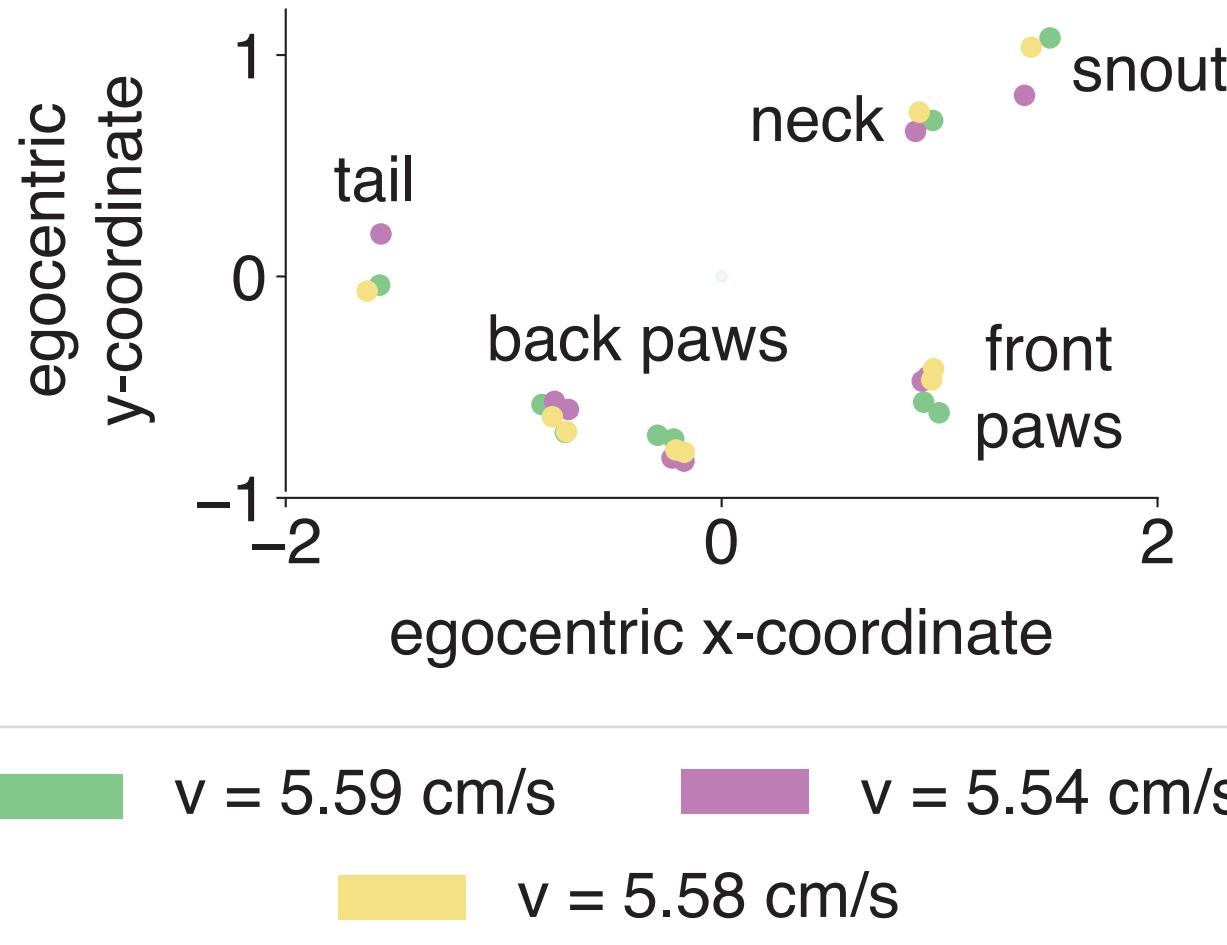


a

autoregressive hidden markov model for natural behavior

**b****c****d****e** average position and velocity per state**f** example video frames of behaviors in each state