

# Irmak Guzey

irmakguzey@nyu.edu · [irmakguzey.github.io/](https://github.com/irmakguzey)

## Education

### P.h.D in Computer Science

09/2024 –

Courant Institute of the Mathematical Sciences, New York University · GPA: N/A

CILVR Lab (Computational Intelligence, Learning, Vision, and Robotics)

*Advised by: Lerrel Pinto, Interested in Imitation Learning for Embodied Agents*

### M.S. in Computer Science

09/2021 – 05/2023

Courant Institute of the Mathematical Sciences, New York University · GPA: 3.9/4.0

*Research Interests:* Robot Learning, Imitation Learning, Representation Learning, Reinforcement Learning

### B.E. in Computer Engineering

09/2016 – 05/2020

Bogazici University, Istanbul · GPA: 3.7/4.0

*Relevant Coursework:* Machine Learning, Robot Learning, Artificial Intelligence, Operating Systems

## Honors and Awards

NYU Henry M. MacCracken Doctoral Fellowship

2024 – 2029

Fulbright Scholarship, Recipient of \$150,000.00.

2021 – 2023

NYU Graduate School of Arts and Sciences Best Master's Thesis Award

2023

NYU Graduate School of Arts and Sciences Tuition Scholarship, Recipient of \$70,000.00.

2021 – 2023

Higher Education Quality Council of Turkey, Student Evaluator

2018

## Publications

1. **I. Guzey**, Y. Dai, G. Savva, R. Bhirangi, L. Pinto. “*HuDOR: Bridging the Human to Robot Dexterity Gap through Object-Oriented Rewards*”. Project Website. (Under Review)
2. **I. Guzey**, Y. Dai, B. Evans, S. Chintala, L. Pinto. “*See to Touch: Learning Tactile Dexterity through Visual Incentives*”. International Conference on Robotics and Automation (ICRA) 2024. (Accepted)
3. **I. Guzey**, B. Evans, S. Chintala, L. Pinto. “*Dexterity from Touch: Self-Supervised Pre-Training of Tactile Representations with Robotic Play*”. Conference on Robot Learning (CoRL) 2023. (Accepted)
4. S. P. Arunachalam, **I. Guzey**, S. Chintala, L. Pinto. “*Holo-Dex: Teaching Dexterity with Immersive Mixed Reality*”. International Conference on Robotics and Automation (ICRA) 2023. (Accepted)
5. **I. Guzey**, A. E. Tekden, E. Samur, E. Ugur. “*Human Motion Prediction with Graph Neural Networks*”. Long Term Human Prediction Workshop(LHMP) of ICRA, 2020. (Accepted)

## Employment

Computer Engineer, DOF Robotics

11/2020 – 08/2021

Machine Learning Engineering Intern, Google (Youtube)

06/2020 – 11/2020

Software Engineering Intern, X

06/2019 – 09/2019

Software Engineering Intern, Google

06/2018 – 09/2018

## Teaching

Grader, Introduction to Machine Learning (CSCI-UA 473), New York University

2023

Teaching Assistant, Introduction to Computer Vision (DS-GA 3001), New York University

2022

## Advising

Georgy Savva (M.S. Student in CILVR)

2024 –

Yinlong Dai (B.S. Student in CILVR)

2022 – 2024

## Professional Service

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### *Voluntary Endeavours*

Trainer & Organizer, *Women's Advocacy*, Turkey

2019 – 2021

English Theatre Club, President & Director, *Kadikoy Anadolu Highschool*

2012 – 2015

## Skills

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Training and Deploying Robot Policies on Dexterous Robot Hands (*Pytorch, ROS, Hydra, Numpy*)

Tactile Sensor Integration for Learning (*Linux, ROS, Pytorch*)

Distributed Self-supervised Visual Encoder Training (*Pytorch*)

Visual Calibration for Robots (*Sci-kit, OpenCV, Pandas, Numpy*)

General Machine Learning Workflows (*Pytorch, Tensorflow, Keras, Pandas, Sci-kit Learn*)

## Spoken & Written Languages

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Turkish

Native Proficiency

English

Working Proficiency

German

Beginner