1. Description

1.1. Project

Project Name	Drone
Board Name	Drone
Generated with:	STM32CubeMX 4.21.0
Date	06/28/2017

1.2. MCU

MCU Series	STM32F1
MCU Line	STM32F103
MCU name	STM32F103CBTx
MCU Package	LQFP48
MCU Pin number	48

2. Pinout Configuration
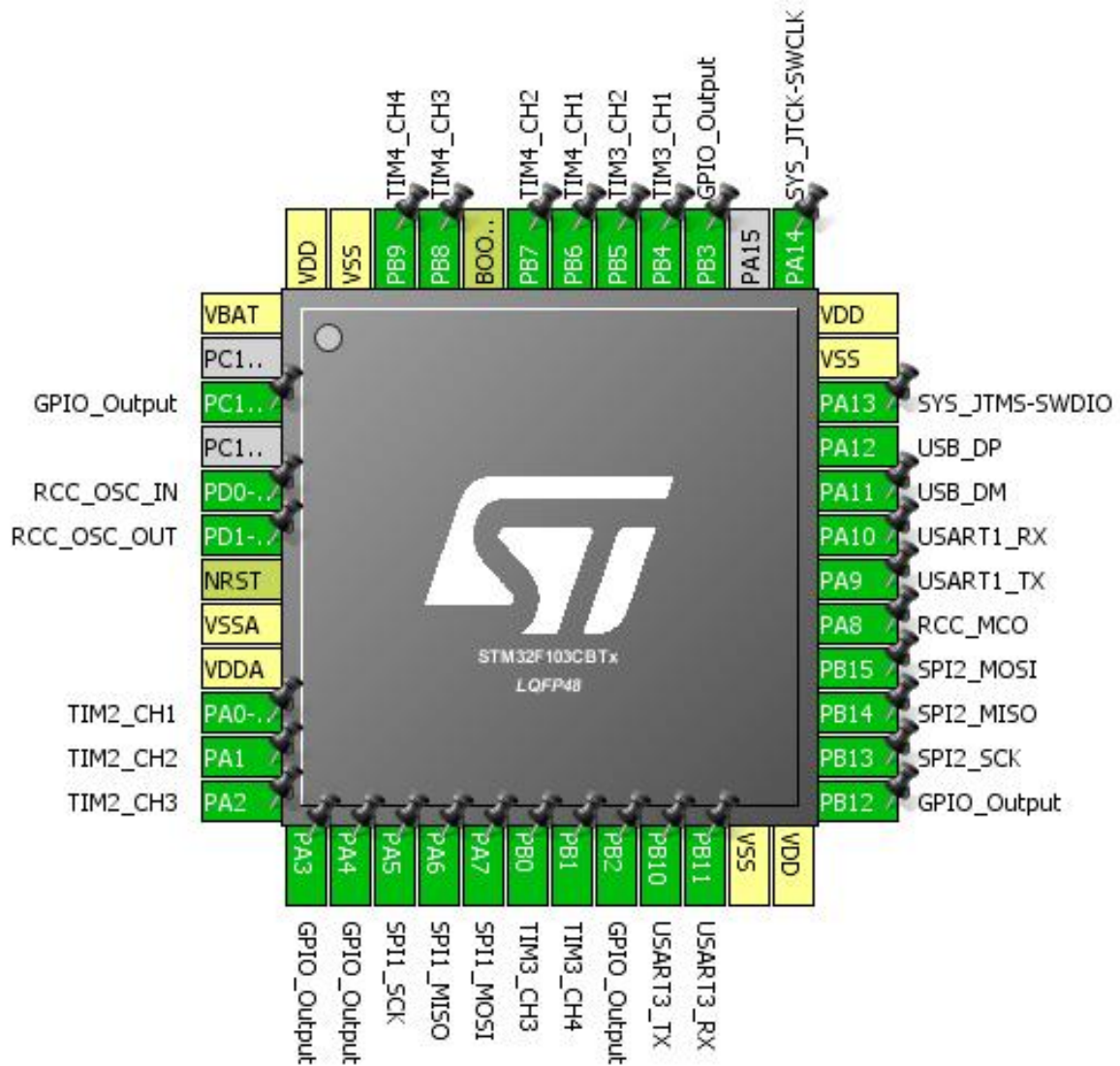
3. Pins Configuration

Pin Number LQFP48	Pin Name (function after reset)	Pin Type	Alternate Function(s)	Label
1	VBAT	Power		
3	PC14-OSC32_IN *	I/O	GPIO_Output	
5	PD0-OSC_IN	I/O	RCC_OSC_IN	
6	PD1-OSC_OUT	I/O	RCC_OSC_OUT	
7	NRST	Reset		
8	VSSA	Power		
9	VDDA	Power		
10	PA0-WKUP	I/O	TIM2_CH1	
11	PA1	I/O	TIM2_CH2	
12	PA2	I/O	TIM2_CH3	
13	PA3 *	I/O	GPIO_Output	
14	PA4 *	I/O	GPIO_Output	
15	PA5	I/O	SPI1_SCK	
16	PA6	I/O	SPI1_MISO	
17	PA7	I/O	SPI1_MOSI	
18	PB0	I/O	TIM3_CH3	
19	PB1	I/O	TIM3_CH4	
20	PB2 *	I/O	GPIO_Output	
21	PB10	I/O	USART3_TX	
22	PB11	I/O	USART3_RX	
23	VSS	Power		
24	VDD	Power		
25	PB12 *	I/O	GPIO_Output	
26	PB13	I/O	SPI2_SCK	
27	PB14	I/O	SPI2_MISO	
28	PB15	I/O	SPI2_MOSI	
29	PA8	I/O	RCC_MCO	
30	PA9	I/O	USART1_TX	
31	PA10	I/O	USART1_RX	
32	PA11	I/O	USB_DM	
33	PA12	I/O	USB_DP	
34	PA13	I/O	SYS_JTMS-SWDIO	
35	VSS	Power		
36	VDD	Power		
37	PA14	I/O	SYS_JTCK-SWCLK	
39	PB3 *	I/O	GPIO_Output	

Pin Number LQFP48	Pin Name (function after reset)	Pin Type	Alternate Function(s)	Label
40	PB4	I/O	TIM3_CH1	
41	PB5	I/O	TIM3_CH2	
42	PB6	I/O	TIM4_CH1	
43	PB7	I/O	TIM4_CH2	
44	BOOT0	Boot		
45	PB8	I/O	TIM4_CH3	
46	PB9	I/O	TIM4_CH4	
47	VSS	Power		
48	VDD	Power		

* The pin is affected with an I/O function

4. Clock Tree Configuration
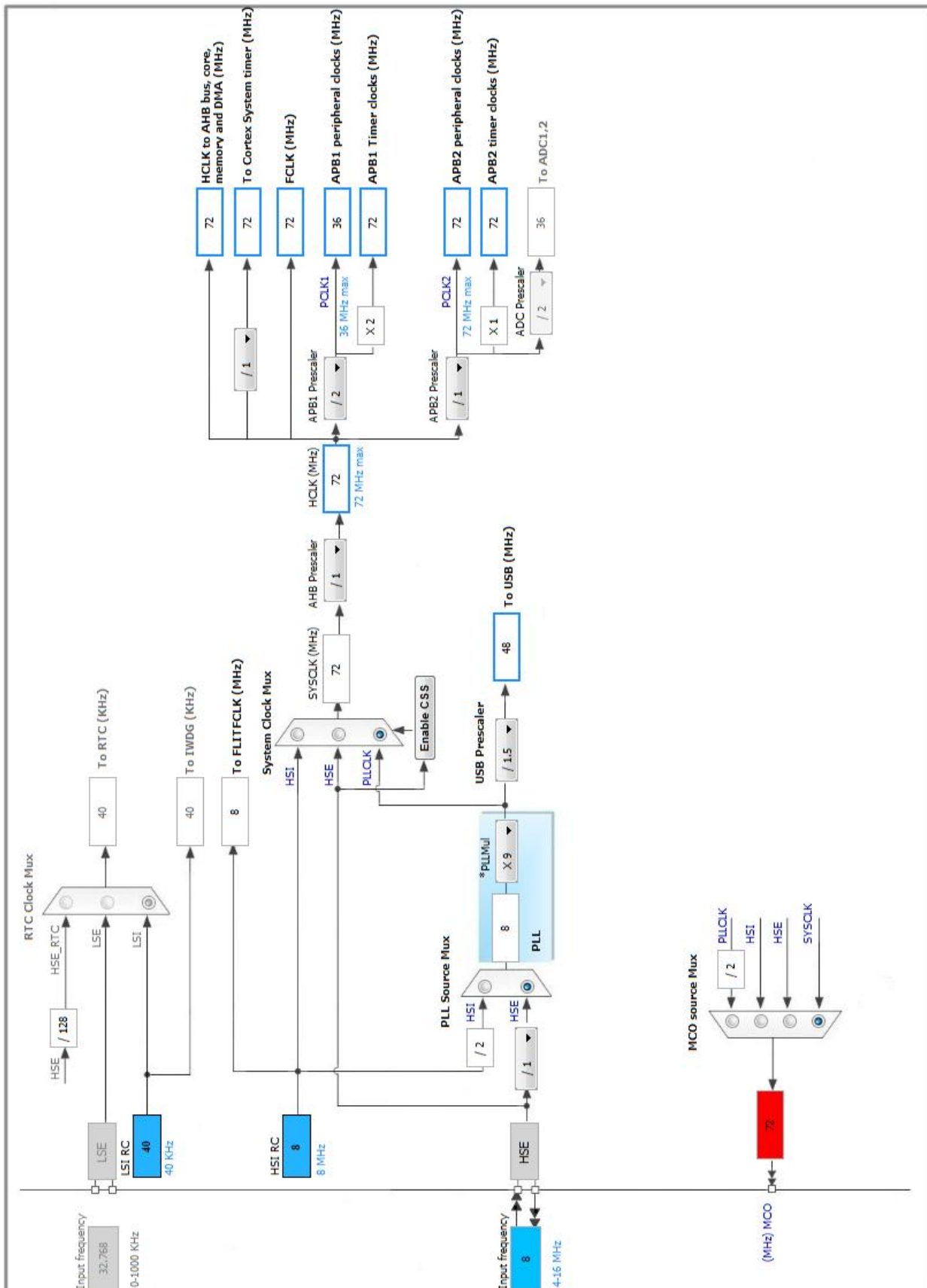
5. IPs and Middleware Configuration

5.1. RCC

High Speed Clock (HSE): Crystal/Ceramic Resonator mode: Master Clock Output

5.1.1. Parameter Settings:

System Parameters:

VDD voltage (V)	3.3
Prefetch Buffer	Enabled
Flash Latency(WS)	2 WS (3 CPU cycle)

RCC Parameters:

HSI Calibration Value	16
HSE Startup Timout Value (ms)	100
LSE Startup Timout Value (ms)	5000

5.2. SPI1

Mode: Full-Duplex Master

5.2.1. Parameter Settings:

Basic Parameters:

Frame Format	Motorola
Data Size	8 Bits
First Bit	MSB First

Clock Parameters:

Prescaler (for Baud Rate)	**4 ***
Baud Rate	**18.0 MBits/s ***
Clock Polarity (CPOL)	Low
Clock Phase (CPHA)	1 Edge

Advanced Parameters:

CRC Calculation	Disabled
NSS Signal Type	Software

5.3. SPI2

Mode: Full-Duplex Master

5.3.1. Parameter Settings:

Basic Parameters:

Frame Format	Motorola
Data Size	8 Bits
First Bit	MSB First

Clock Parameters:

Prescaler (for Baud Rate)	2
Baud Rate	**18.0 MBits/s ***
Clock Polarity (CPOL)	Low
Clock Phase (CPHA)	1 Edge

Advanced Parameters:

CRC Calculation	Disabled
NSS Signal Type	Software

5.4. SYS

Debug: Serial Wire

Timebase Source: SysTick

5.5. TIM1

Clock Source   : Internal Clock

5.5.1. Parameter Settings:

Counter Settings:

Prescaler (PSC - 16 bits value)	0
Counter Mode	Up
Counter Period (AutoReload Register - 16 bits value)	0
Internal Clock Division (CKD)	No Division
Repetition Counter (RCR - 8 bits value)	0

Trigger Output (TRGO) Parameters:

Master/Slave Mode	Disable (no sync between this TIM (Master) and its Slaves
Trigger Event Selection	Reset (UG bit from TIMx_EGR)

5.6. TIM2

Channel1: Input Capture direct mode
Channel2: Input Capture direct mode
Channel3: PWM Generation CH3

5.6.1. Parameter Settings:

Counter Settings:

Prescaler (PSC - 16 bits value)	0
Counter Mode	Up
Counter Period (AutoReload Register - 16 bits value)	0
Internal Clock Division (CKD)	No Division

Trigger Output (TRGO) Parameters:

Master/Slave Mode	Disable (no sync between this TIM (Master) and its Slaves
Trigger Event Selection	Reset (UG bit from TIMx_EGR)

Input Capture Channel 1:

Polarity Selection	Rising Edge
IC Selection	Direct
Prescaler Division Ratio	No division
Input Filter (4 bits value)	0

Input Capture Channel 2:

Polarity Selection	Rising Edge
IC Selection	Direct
Prescaler Division Ratio	No division
Input Filter (4 bits value)	0

PWM Generation Channel 3:

Mode	PWM mode 1
Pulse (16 bits value)	0
Fast Mode	Disable
CH Polarity	High

5.7. TIM3

Channel1: PWM Generation CH1
Channel2: Input Capture direct mode

Channel3: Input Capture direct mode
Channel4: Input Capture direct mode

5.7.1. Parameter Settings:

Counter Settings:

Prescaler (PSC - 16 bits value)	0
Counter Mode	Up
Counter Period (AutoReload Register - 16 bits value)	0
Internal Clock Division (CKD)	No Division

Trigger Output (TRGO) Parameters:

Master/Slave Mode	Disable (no sync between this TIM (Master) and its Slaves
Trigger Event Selection	Reset (UG bit from TIMx_EGR)

PWM Generation Channel 1:

Mode	PWM mode 1
Pulse (16 bits value)	0
Fast Mode	Disable
CH Polarity	High

Input Capture Channel 2:

Polarity Selection	Rising Edge
IC Selection	Direct
Prescaler Division Ratio	No division
Input Filter (4 bits value)	0

Input Capture Channel 3:

Polarity Selection	Rising Edge
IC Selection	Direct
Prescaler Division Ratio	No division
Input Filter (4 bits value)	0

Input Capture Channel 4:

Polarity Selection	Rising Edge
IC Selection	Direct
Prescaler Division Ratio	No division
Input Filter (4 bits value)	0

5.8. TIM4

Channel1: Input Capture direct mode
Channel2: PWM Generation CH2

Channel3: PWM Generation CH3
Channel4: PWM Generation CH4

5.8.1. Parameter Settings:

Counter Settings:

Prescaler (PSC - 16 bits value)	0
Counter Mode	Up
Counter Period (AutoReload Register - 16 bits value)	0
Internal Clock Division (CKD)	No Division

Trigger Output (TRGO) Parameters:

Master/Slave Mode	Disable (no sync between this TIM (Master) and its Slaves
Trigger Event Selection	Reset (UG bit from TIMx_EGR)

Input Capture Channel 1:

Polarity Selection	Rising Edge
IC Selection	Direct
Prescaler Division Ratio	No division
Input Filter (4 bits value)	0

PWM Generation Channel 2:

Mode	PWM mode 1
Pulse (16 bits value)	0
Fast Mode	Disable
CH Polarity	High

PWM Generation Channel 3:

Mode	PWM mode 1
Pulse (16 bits value)	0
Fast Mode	Disable
CH Polarity	High

PWM Generation Channel 4:

Mode	PWM mode 1
Pulse (16 bits value)	0
Fast Mode	Disable
CH Polarity	High

5.9. USART1

Mode: Asynchronous

5.9.1. Parameter Settings:

Basic Parameters:

Baud Rate	115200
Word Length	8 Bits (including Parity)
Parity	None
Stop Bits	1

Advanced Parameters:

Data Direction	Receive and Transmit
Over Sampling	16 Samples

5.10. USART3
Mode: Asynchronous

5.10.1. Parameter Settings:

Basic Parameters:

Baud Rate	115200
Word Length	8 Bits (including Parity)
Parity	None
Stop Bits	1

Advanced Parameters:

Data Direction	Receive and Transmit
Over Sampling	16 Samples

5.11. USB
mode: Device (FS)

5.11.1. Parameter Settings:

Basic Parameters:

Speed	Full Speed 12MBit/s
Endpoint 0 Max Packet size	8 Bytes

Power Parameters:

Low Power	Disabled
Link Power Management	Disabled

Battery Charging   Disabled

* User modified value

6. System Configuration

6.1. GPIO configuration

IP	Pin	Signal	GPIO mode	GPIO pull/up pull down	Max Speed	User Label
RCC	PD0-OSC_IN	RCC_OSC_IN	n/a	n/a	n/a	
	PD1-OSC_OUT	RCC_OSC_OUT	n/a	n/a	n/a	
	PA8	RCC_MCO	Alternate Function Push Pull	n/a	Low	
SPI1	PA5	SPI1_SCK	Alternate Function Push Pull	n/a	**High ***	
	PA6	SPI1_MISO	Input mode	No pull-up and no pull-down	**n/a**	
	PA7	SPI1_MOSI	Alternate Function Push Pull	n/a	**High ***	
SPI2	PB13	SPI2_SCK	Alternate Function Push Pull	n/a	**High ***	
	PB14	SPI2_MISO	Input mode	No pull-up and no pull-down	**n/a**	
	PB15	SPI2_MOSI	Alternate Function Push Pull	n/a	**High ***	
SYS	PA13	SYS_JTMS-SWDIO	n/a	n/a	n/a	
	PA14	SYS_JTCK-SWCLK	n/a	n/a	n/a	
TIM2	PA0-WKUP	TIM2_CH1	Input mode	No pull-up and no pull-down	n/a	
	PA1	TIM2_CH2	Input mode	No pull-up and no pull-down	n/a	
	PA2	TIM2_CH3	Alternate Function Push Pull	n/a	Low	
TIM3	PB0	TIM3_CH3	Input mode	No pull-up and no pull-down	n/a	
	PB1	TIM3_CH4	Input mode	No pull-up and no pull-down	n/a	
	PB4	TIM3_CH1	Alternate Function Push Pull	n/a	Low	
	PB5	TIM3_CH2	Input mode	No pull-up and no pull-down	n/a	
TIM4	PB6	TIM4_CH1	Input mode	No pull-up and no pull-down	n/a	
	PB7	TIM4_CH2	Alternate Function Push Pull	n/a	Low	
	PB8	TIM4_CH3	Alternate Function Push Pull	n/a	Low	
	PB9	TIM4_CH4	Alternate Function Push Pull	n/a	Low	
USART1	PA9	USART1_TX	Alternate Function Push Pull	n/a	**High ***	
	PA10	USART1_RX	Input mode	No pull-up and no pull-down	**n/a**	
USART3	PB10	USART3_TX	Alternate Function Push Pull	n/a	**High ***	
	PB11	USART3_RX	Input mode	No pull-up and no pull-down	**n/a**	
USB	PA11	USB_DM	n/a	n/a	n/a	
	PA12	USB_DP	n/a	n/a	n/a	
GPIO	PC14-	GPIO_Output	Output Push Pull	n/a	Low	

IP	Pin	Signal	GPIO mode	GPIO pull/up pull down	Max Speed	User Label
	OSC32_IN					
	PA3	GPIO_Output	Output Push Pull	n/a	Low	
	PA4	GPIO_Output	Output Push Pull	n/a	Low	
	PB2	GPIO_Output	Output Push Pull	n/a	Low	
	PB12	GPIO_Output	Output Push Pull	n/a	Low	
	PB3	GPIO_Output	Output Push Pull	n/a	Low	

6.2. DMA configuration

nothing configured in DMA service

6.3. NVIC configuration

Interrupt Table	Enable	Preenmption Priority	SubPriority
Non maskable interrupt	true	0	0
Hard fault interrupt	true	0	0
Memory management fault	true	0	0
Prefetch fault, memory access fault	true	0	0
Undefined instruction or illegal state	true	0	0
System service call via SWI instruction	true	0	0
Debug monitor	true	0	0
Pendable request for system service	true	0	0
System tick timer	true	0	0
PVD interrupt through EXTI line 16	unused		
Flash global interrupt	unused		
RCC global interrupt	unused		
USB high priority or CAN TX interrupts	unused		
USB low priority or CAN RX0 interrupts	unused		
TIM1 break interrupt	unused		
TIM1 update interrupt	unused		
TIM1 trigger and commutation interrupts	unused		
TIM1 capture compare interrupt	unused		
TIM2 global interrupt	unused		
TIM3 global interrupt	unused		
TIM4 global interrupt	unused		
SPI1 global interrupt	unused		
SPI2 global interrupt	unused		
USART1 global interrupt	unused		
USART3 global interrupt	unused		

* User modified value

7. Power Consumption Calculator report

7.1. Microcontroller Selection

Series	STM32F1
Line	STM32F103
MCU	STM32F103CBTx
Datasheet	13587_Rev17

7.2. Parameter Selection

Temperature	25
Vdd	3.3

8. Software Project

8.1. Project Settings

Name	Value
Project Name	Drone
Project Folder	D:\Work\UAV\Drone\Drone-MDK
Toolchain / IDE	MDK-ARM V5
Firmware Package Name and Version	STM32Cube FW_F1 V1.4.0

8.2. Code Generation Settings

Name	Value
STM32Cube Firmware Library Package	Copy all used libraries into the project folder
Generate peripheral initialization as a pair of '.c/.h' files	No
Backup previously generated files when re-generating	No
Delete previously generated files when not re-generated	Yes
Set all free pins as analog (to optimize the power consumption)	No