

МИНИСТЕРСТВО ОБРАЗОВАНИЯ И НАУКИ РОССИЙСКОЙ ФЕДЕРАЦИИ

МОСКОВСКИЙ АВИАЦИОННЫЙ ИНСТИТУТ
(НАЦИОНАЛЬНЫЙ ИССЛЕДОВАТЕЛЬСКИЙ УНИВЕРСИТЕТ)

ЛАБОРАТОРНАЯ РАБОТА №6

по курсу “Объектно-ориентированное программирование”

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Задание:

Дополнить класс-контейнер из лабораторной работы №5 шаблоном типа данных.

Вариант №12:

- Фигура: Трапеция (Trapezoid)
- Контейнер: Очередь (TQueue)

Описание программы:

Исходный код разделён на 10 файлов:

- figure.h – описание класса фигуры
- point.h – описание класса точки
- point.cpp – реализация класса точки
- trapezoid.h – описание класса трапеции
- trapezoid.cpp – реализация класса трапеции
- Tqueue_item.h – описание элемента очереди
- Tqueue_item.cpp – реализация элемента очереди
- tqueue.h – описание очереди
- tqueue.cpp – реализация очереди
- main.cpp – основная программа

Дневник отладки:

Ошибок не возникло.

Вывод:

В данной лабораторной работе я познакомился с шаблонами. Шаблоны позволяют определить операции класса или функции и предоставить пользователю указание конкретных типов, с которыми должны работать эти операции. Шаблоны играют огромную роль в языке C++. Очень многое в программировании на C++ держится на шаблонах.

Исходный код:

point.h:

```
#ifndef POINT_H
#define POINT_H

#include <iostream>

class Point {
public:
    Point();
```

```

Point(std::istream &is);
Point(double x, double y);

double dist(Point& other);

void SetX(double x);
void SetY(double y);

double GetX();
double GetY();

friend std::istream& operator>>(std::istream& is, Point& p);
friend std::ostream& operator<<(std::ostream& os, Point& p);
friend std::ostream& operator<<(std::ostream& os, const Point& p);

public:
    double x_;
    double y_;
};

#endif // POINT_H

```

point.cpp:

```

#include "point.h"
#include <iostream>
#include <cmath>

Point::Point() : x_(0.0), y_(0.0) {}

Point::Point(double x, double y) : x_(x), y_(y) {}

Point::Point(std::istream &is) {
    is >> x_ >> y_;
}

void Point::SetX(double x) {
    this->x_ = x;
}

void Point::SetY(double y) {
    this->y_ = y;
}

double Point::GetX() {
    return this->x_;
}

double Point::GetY() {
    return this->y_;
}

double Point::dist(Point& other) {
    double dx = (other.x_ - x_);
    double dy = (other.y_ - y_);
    return std::sqrt(dx*dx + dy*dy);
}

std::istream& operator>>(std::istream& is, Point& p) {
    is >> p.x_ >> p.y_;
}

```

```

        return is;
    }

    std::ostream& operator<<(std::ostream& os, Point& p) {
        os << "(" << p.x_ << ", " << p.y_ << ")";
        return os;
    }

    std::ostream& operator<<(std::ostream& os, const Point& p) {
        os << "(" << p.x_ << ", " << p.y_ << ")";
        return os;
    }
}

```

figure.h:

```

#ifndef FIGURE_H
#define FIGURE_H

#include <iostream>

class Figure {
public:
    virtual size_t VertexesNumber() = 0;
    virtual double Area() = 0;
    virtual ~Figure() {};
};

#endif // FIGURE_H

```

trapezoid.h:

```

#ifndef TRAPEZOID_H
#define TRAPEZOID_H

#include "figure.h"
#include <iostream>
#include "point.h"
#include <memory>

class Trapezoid : public Figure {
public:
    Trapezoid();
    Trapezoid(double a, double b, double c, double d);
    Trapezoid(std::shared_ptr<Trapezoid>& other);

    friend std::istream& operator>>(std::istream& is, Trapezoid& obj);
    friend std::ostream& operator<<(std::ostream& os, const Trapezoid& obj);

    Trapezoid& operator=(const Trapezoid& right);
    bool operator==(const Trapezoid& right);

    virtual ~Trapezoid();

    size_t VertexesNumber();
    double Area();
public:
    double len_ab, len_bc, len_cd, len_da;
    Point a_, b_, c_, d_;
};

```

```
#endif // TRAPEZOID_H
```

trapezoid.cpp:

```
#include "trapezoid.h"
```

```
#include <cmath>
```

```
Trapezoid::Trapezoid()
```

```
: len_ab(0.0),  
   len_bc(0.0),  
   len_cd(0.0),  
   len_da(0.0) {  
}
```

```
Trapezoid::Trapezoid(double ab, double bc, double cd, double da)
```

```
: len_ab(ab),  
   len_bc(bc),  
   len_cd(cd),  
   len_da(da) {  
}
```

```
Trapezoid::Trapezoid(std::shared_ptr<Trapezoid>& other)
```

```
: Trapezoid(other->len_ab, other->len_bc, other->len_cd, other->len_da) {  
}
```

```
std::istream& operator>>(std::istream& is, Trapezoid& obj) {
```

```
    std::cout << "Enter points: ";
```

```
    is >> obj.a_;
```

```
    is >> obj.b_;
```

```
    is >> obj.c_;
```

```
    is >> obj.d_;
```

```
    obj.len_ab = obj.a_.dist(obj.b_);
```

```
    obj.len_bc = obj.b_.dist(obj.c_);
```

```
    obj.len_cd = obj.c_.dist(obj.d_);
```

```
    obj.len_da = obj.d_.dist(obj.a_);
```

```
    return is;
```

```
}
```

```
std::ostream& operator<<(std::ostream& os, const Trapezoid& obj) {
```

```
    std::cout << "Trapezoid: ";
```

```
    os << obj.a_; std::cout << " ";
```

```
    os << obj.b_; std::cout << " ";
```

```
    os << obj.c_; std::cout << " ";
```

```
    os << obj.d_; std::cout << std::endl;
```

```
    return os;
```

```
}
```

```
Trapezoid& Trapezoid::operator=(const Trapezoid& other) {
```

```
    if (this == &other)
```

```
        return *this;
```

```
    len_ab = other.len_ab;
```

```
    len_bc = other.len_bc;
```

```
    len_cd = other.len_cd;
```

```
    len_da = other.len_da;
```

```

    a_.x_ = other.a_.x_;
    a_.y_ = other.a_.y_;
    b_.x_ = other.b_.x_;
    b_.y_ = other.b_.y_;
    c_.x_ = other.c_.x_;
    c_.y_ = other.c_.y_;
    d_.x_ = other.d_.x_;
    d_.x_ = other.d_.x_;

    std::cout << "Trapezoid copied" << std::endl;

    return *this;
}

bool Trapezoid::operator==(const Trapezoid& other) {
    if (this->len_ab == other.len_ab &&
        this->len_bc == other.len_bc &&
        this->len_cd == other.len_cd &&
        this->len_da == other.len_da) {
        std::cout << "Trapezoids are equal" << std::endl;
        return 1;
    } else {
        std::cout << "Trapezoids are not equal" << std::endl;
        return 0;
    }
}

size_t Trapezoid::VertexesNumber() {
    return 4;
}

double Trapezoid::Area() {
    double p = (len_ab + len_bc + len_cd + len_da) / 2;
    return (len_bc + len_da) *
        std::sqrt((p - len_bc) *
            (p - len_da) *
            (p - len_da - len_ab) *
            (p - len_da - len_cd)) /
        std::abs(len_bc - len_da);
}

Trapezoid::~Trapezoid() {
    std::cout << "Trapezoid deleted" << std::endl;
}

```

tqueue_item.h:

```

#ifndef TQUEUE_ITEM_H
#define TQUEUE_ITEM_H

#include <memory>
#include "trapezoid.h"

template<typename T> class TQueueItem {
public:
    TQueueItem(const std::shared_ptr<T>& trapezoid);
    TQueueItem(const TQueueItem& other);

    std::shared_ptr<TQueueItem<T>> SetNext(std::shared_ptr<TQueueItem> &next);
    std::shared_ptr<TQueueItem<T>> GetNext();

```

```

std::shared_ptr<T> GetTrapezoid() const;

template<typename A> friend std::ostream& operator<<(std::ostream& os, const TQueueItem<A>& obj);

virtual ~TQueueItem();

public:
    std::shared_ptr<T> item;
    std::shared_ptr<TQueueItem<T>> next;
};

#endif // TQUEUE_ITEM_H

```

Tqueue_item.cpp:

```

#include "tqueue_item.h"
#include <iostream>

template <class T>
TQueueItem<T>::TQueueItem(const std::shared_ptr<T>& item) {
    this->item = item;
    this->next = nullptr;
    std::cout << "Queue item: created" << std::endl;
}

template <class T>
TQueueItem<T>::TQueueItem(const TQueueItem& other) {
    this->item = other.item;
    this->next = other.next;
    std::cout << "Queue item: copied" << std::endl;
}

template <class T>
std::shared_ptr<TQueueItem<T>> TQueueItem<T>::SetNext(std::shared_ptr<TQueueItem<T>> &next) {
    std::shared_ptr<TQueueItem<T>> old = this->next;
    this->next = next;
    return old;
}

template <class T>
std::shared_ptr<T> TQueueItem<T>::GetTrapezoid() const {
    return this->item;
}

template <class T>
std::shared_ptr<TQueueItem<T>> TQueueItem<T>::GetNext() {
    return this->next;
}

template <class T>
TQueueItem<T>::~~TQueueItem() {
    std::cout << "Queue item: deleted" << std::endl;
}

template <class A>
std::ostream& operator<<(std::ostream& os, const TQueueItem<A>& obj) {
    os << obj.item->Area();
    return os;
}

template class TQueueItem<Trapezoid>;

```

```
template std::ostream& operator<<(std::ostream& os, const TQueueItem<Trapezoid>& obj);
```

TBinaryTree.h:

```
#ifndef TQUEUE_H
#define TQUEUE_H

#include "tqueue_item.h"
#include <memory>

template <typename T> class TQueue {
public:

    TQueue();
    TQueue(const TQueue& other);
    void Push(std::shared_ptr<T> &&trapezoid);
    void Pop();
    std::shared_ptr<T>& Top();
    bool Empty();
    size_t Length();
    template <class A> friend std::ostream& operator<<(std::ostream& os, const TQueue<A>& queue);
    void Clear();
    virtual ~TQueue();
private:
    std::shared_ptr<TQueueItem<T>> head, tail;
};

#endif // TQUEUE_H
```

tqueue.cpp:

```
#include "tqueue.h"
#include <vector>

template <class T>
TQueue<T>::TQueue() : head(nullptr), tail(nullptr) {
    std::cout << "Default queue created" << std::endl;
}

template <class T>
TQueue<T>::TQueue(const TQueue<T>& other) {
    head = other.head;
    tail = other.tail;
    std::cout << "Queue copied" << std::endl;
}

template <class T>
void TQueue<T>::Push(std::shared_ptr<T> &&trapezoid) {
    std::shared_ptr<TQueueItem<T>> other(new TQueueItem<T>(trapezoid));

    if (tail == nullptr) {
        head = tail = other;
        std::cout << "Added one trapezoid to tail. " << "Coordinates: " << *other->item << ". Area = " << other->item->Area() <<
std::endl;
        return;
    }
    tail->SetNext(other);
    tail = other;
    tail->next = nullptr;
    std::cout << "Added one trapezoid to tail. " << "Coordinates: " << *other->item << ". Area = " << other->item->Area() <<
std::endl;
```



```

}

template <class T>
void TQueue<T>::Pop() {
    if (head == nullptr)
        return;

    std::cout << "Removed one trapezoid from head." << "Coordinates: " << *head->item << ". Area = " << head->item->Area() <<
std::endl;

    head = head->GetNext();

    if (head == nullptr)
        tail = nullptr;
}

template <class T>
std::shared_ptr<T>& TQueue<T>::Top() {
    return head->item;
}

template <class T>
bool TQueue<T>::Empty() {
    return (head == nullptr) && (tail == nullptr);
}

template <class T>
size_t TQueue<T>::Length() {
    if (head == nullptr && tail == nullptr)
        return 0;
    std::shared_ptr<TQueueItem<T>> temp = head;
    int counter = 0;
    while (temp != tail->GetNext()) {
        temp = temp->GetNext();
        counter++;
    }
    return counter;
}

template <class T>
std::ostream& operator<<(std::ostream& os, const TQueue<T>& queue) {
    std::shared_ptr<TQueueItem<T>> temp = queue.head;
    std::vector<std::shared_ptr<TQueueItem<T>>> v;

    os << "Queue: ";
    os << "=> ";
    while (temp != nullptr) {
        v.push_back(temp);
        temp = temp->GetNext();
    }
    for (int i = v.size() - 1; i >= 0; --i)
        os << *v[i] << " ";
    os << "=>";
    return os;
}

template <class T>
void TQueue<T>::Clear() {
    for (int i = 0; i < this->Length(); i++) {
        this->Pop();
    }
}

```

```

    }
    std::cout << "Queue was cleared but still exist" << std::endl;
}

template <class T>
TQueue<T>::~~TQueue() {
    std::cout << "Queue was deleted" << std::endl;
}

template class TQueue<Trapezoid>;
template std::ostream& operator<<(std::ostream& os, const TQueue<Trapezoid>& queue);

```

main.cpp:

```

#include <iostream>
#include "tqueue.h"

int main(int argc, char** argv) {
    TQueue<Trapezoid> queue;
    std::shared_ptr<Trapezoid> tr(new Trapezoid(1, 2, 3, 4));

    std::cout << queue << std::endl;

    std::shared_ptr<Trapezoid> t;

    std::cout << "Enter n: ";
    int n; std::cin >> n;

    for (int i = 0; i < n; i++) {
        std::cin >> *tr;
        std::cout << *tr << std::endl;
        queue.Push(std::shared_ptr<Trapezoid>(new Trapezoid(*tr)));
        std::cout << queue;
        std::cout << std::endl;
        std::cout << "Length: " << queue.Length() << std::endl;
    }

    TQueue<Trapezoid> queue2 = queue;

    std::cout << "Queue: " << queue << std::endl;

    std::cout << "Queue2: " << queue2 << std::endl;

    return 0;
}

```