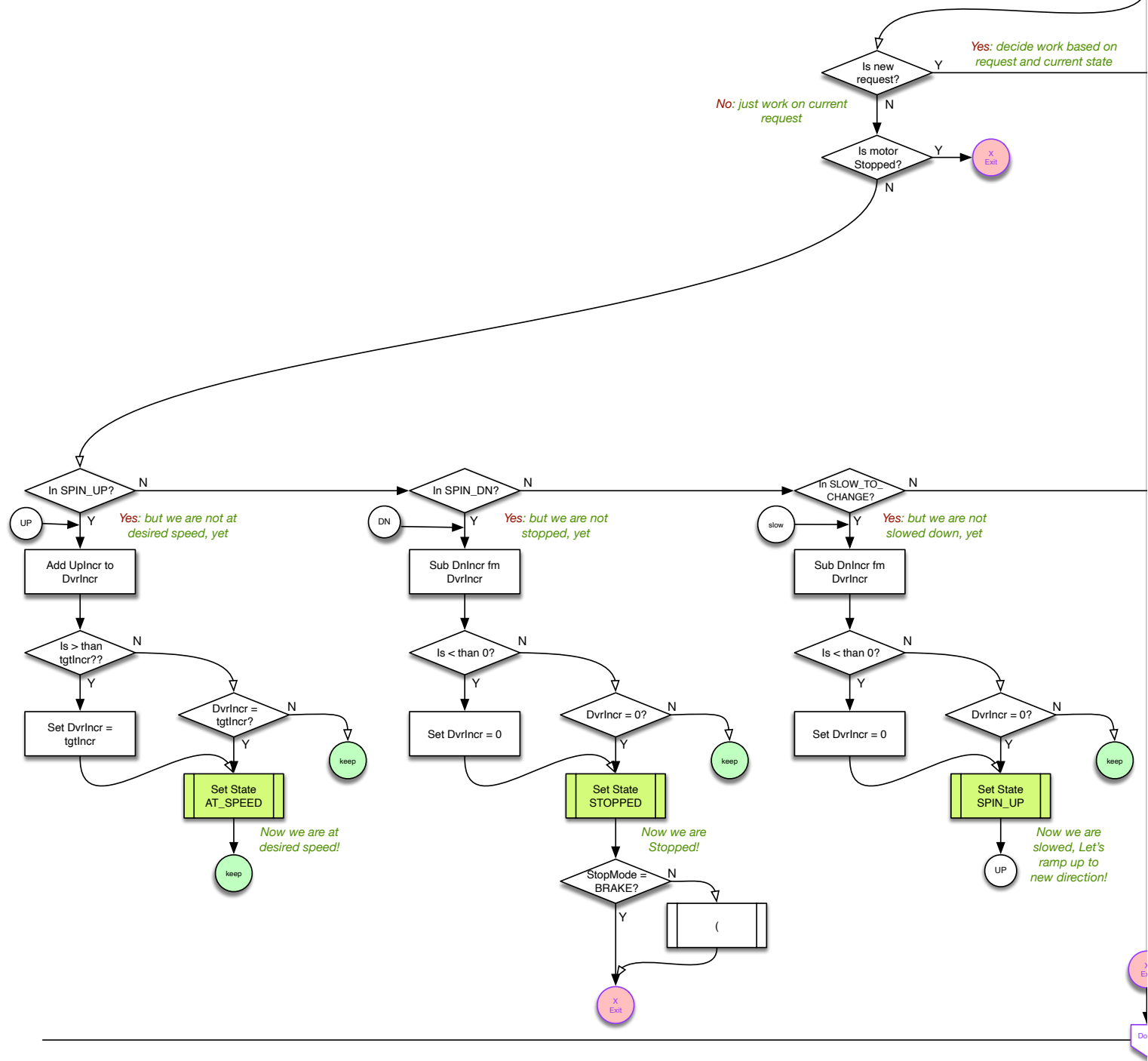


Motor Drive Control Algorithm

Fwd: +Angle
Rev: -Angle
(input variable)



(output variable)

hm - Runs every 500 uSec

