

Functional Analysis Reading Group

The Euler-Lagrange Equations

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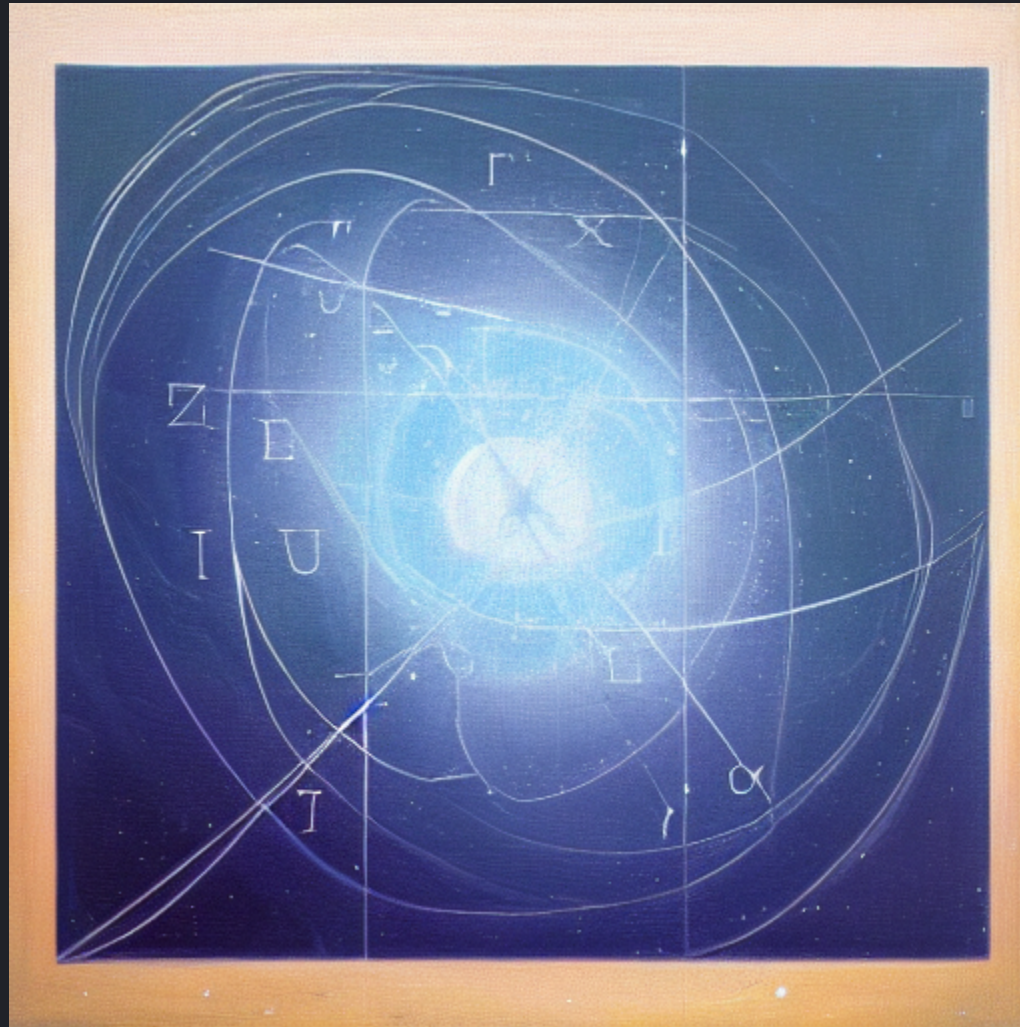
Last meeting

- Generalized derivative of maps $f : X \rightarrow Y$
- Optimality conditions (stationary point + convexity)

Finding stationary points is generally not easy, though

Today

- A way to turn a broad class of functional minimization problems into differential equations
- Secret sauce behind modern physics



"The Euler-Lagrange Equations, oil painting, trending on artstation HQ" generated with Stable Diffusion

Euler-Lagrange Equations

Given a functional of the form

$$f(x) = \int_a^b F(x(t), x'(t), t) dt$$

Stationary points x_* of f satisfy the *Euler-Lagrange equation*

$$\frac{\partial F}{\partial x}(x_*(t), x'_*(t), t) - \frac{d}{dt} \frac{\partial F}{\partial x'}(x_*(t), x'_*(t), t) = 0$$

Link with the functional derivative

Given a candidate stationary point x_* , consider the Banach space of perturbations

$$X = \{h \in C^1[a, b] : h(a) = h(b) = 0\}$$

and the modified functional $\tilde{f} : X \rightarrow \mathbb{R}$

$$\tilde{f}(h) = f(x_* + h)$$

Then x_* is a stationary point of f iff $D\tilde{f}(0) = 0$

Example: Shortest path (euclidian norm)

Let $S = \{\gamma \in C^1([0, 1], \mathbb{R}^n) \mid \gamma(0) = x_a, \gamma(1) = x_b\}$

$$L_1(\gamma) = \int_0^1 \|\gamma'(t)\|_2 dt$$

The E-L equations yield

$$\frac{d}{dt} \frac{\gamma'_i(t)}{\|\gamma'(t)\|_2} = 0$$

which admits the solution

$$\gamma(t) = (1 - t)x_a + tx_b$$

Newtonian mechanics

Given a point mass particle of mass m , subject to some force F , Newton's law describes the motion of the particle:

$$mq''(t) = F(q(t))$$

This can be reformulated using the Euler-Lagrange equations

Lagrangian mechanics

Given some (1D) trajectory q , define its potential energy V by

$$V(x) = - \int_{x_0}^x F(d\xi) d\xi$$

equivalently

$$\frac{dV}{dx} = F(x)$$

and its kinetic energy as

$$K = \frac{m}{2} (q'(t))^2$$

Principle of stationary action

Define the *Action* of the system as

$$A(q) = \int_{t_i}^{t_f} L(q(t), q'(t)) dt$$

where $L(q(t), q'(t)) = \frac{m}{2} (q'(t))^2 - V(q(t))$ is the *Lagrangian* of the system

Principle of Stationary action: The motion $q(t)$ of the particle is a *stationary point* of the Action

From Euler-Lagrange to Newton

The Euler-Lagrange equations are

$$-\frac{dV}{dx}(q(t)) - \frac{d}{dt}\left(\frac{m}{2} \cdot dq'(t)\right) = 0$$

Injecting $\frac{dV}{dx}(x) = -F(x)$, we recover Newton's law

$$mq''(t) = F(q(t))$$

Example: 2-body problem

Given a body of mass m , orbiting around a body of mass M , with polar coordinates r, φ

$$f(r, \varphi) = \int_a^b \frac{m}{2} (r'(t))^2 + \frac{m}{2} (r(t)\varphi'(t))^2 + \frac{GMm}{r(t)} dt$$

yields the equations

$$r''(t) = r(t)(\varphi'(t))^2 - \frac{GMm}{(r(t))^2}$$


$$\frac{d}{dt} (m(r(t))^2 \varphi'(t)) = 0$$

Lagrangian mechanics

Beyond classical mechanics, most of modern physics can be framed in terms of the stationary action principle:


- Electromagnetism: $\mathcal{L} = -\frac{1}{4\mu_0} F_{\mu\nu} F^{\mu\nu} - J^\mu A_\mu$
- General Relativity $\mathcal{L} = \frac{1}{2\kappa} R + \mathcal{L}_M$
- Quantum mechanics*

Lagrangian mechanics provide a unifying language for physics!




PHASE 1 PHASE 2 PHASE 3

**WRITE
DOWN THE
LAGRANGIAN**



**SOLVE THE
EULER-LAGRANGE
EQUATIONS**

Profit



PHYSICISTS

$$\begin{aligned}
& \frac{1}{2}\partial_\nu g_\mu^a \partial_\nu g_\mu^a - g_s f^{abc} \partial_\mu g_\nu^a g_\mu^b g_\nu^c - \frac{1}{4}g_s^2 f^{abc} f^{ade} g_\mu^b g_\nu^c g_\mu^d g_\nu^e + \\
& \frac{1}{2}ig_s^2(\bar{q}_i^\sigma \gamma^\mu q_j^\sigma)g_\mu^a + \bar{G}^a \partial^2 G^a + g_s f^{abc} \partial_\mu \bar{G}^a G^b g_\mu^c - \partial_\nu W_\mu^+ \partial_\nu W_\mu^- - \\
& M^2 W_\mu^+ W_\mu^- - \frac{1}{2}\partial_\nu Z_\mu^0 \partial_\nu Z_\mu^0 - \frac{1}{2c_w^2}M^2 Z_\mu^0 Z_\mu^0 - \frac{1}{2}\partial_\mu A_\nu \partial_\mu A_\nu - \frac{1}{2}\partial_\mu H \partial_\mu H - \\
& \frac{1}{2}m_h^2 H^2 - \partial_\mu \phi^+ \partial_\mu \phi^- - M^2 \phi^+ \phi^- - \frac{1}{2}\partial_\mu \phi^0 \partial_\mu \phi^0 - \frac{1}{2c_w^2}M\phi^0 \phi^0 - \beta_h[\frac{2M^2}{g^2} + \\
& \frac{2M}{g}H + \frac{1}{2}(H^2 + \phi^0 \phi^0 + 2\phi^+ \phi^-)] + \frac{2M^4}{g^2}\alpha_h - igc_w[\partial_\nu Z_\mu^0(W_\mu^+ W_\nu^- - \\
& W_\nu^+ W_\mu^-) - Z_\nu^0(W_\mu^+ \partial_\nu W_\mu^- - W_\mu^- \partial_\nu W_\mu^+) + Z_\mu^0(W_\nu^+ \partial_\nu W_\mu^- - \\
& W_\nu^- \partial_\nu W_\mu^+)] - ig s_w[\partial_\nu A_\mu(W_\mu^+ W_\nu^- - W_\nu^+ W_\mu^-) - A_\nu(W_\mu^+ \partial_\nu W_\mu^- - \\
& W_\mu^- \partial_\nu W_\mu^+) + A_\mu(W_\nu^+ \partial_\nu W_\mu^- - W_\nu^- \partial_\nu W_\mu^+)] - \frac{1}{2}g^2 W_\mu^+ W_\mu^- W_\nu^+ W_\nu^- + \\
& \frac{1}{2}g^2 W_\mu^+ W_\nu^- W_\mu^+ W_\nu^- + g^2 c_w^2(Z_\mu^0 W_\mu^+ Z_\nu^0 W_\nu^- - Z_\mu^0 Z_\nu^0 W_\mu^+ W_\nu^-) + \\
& g^2 s_w^2(A_\mu W_\mu^+ A_\nu W_\nu^- - A_\mu A_\nu W_\mu^+ W_\nu^-) + g^2 s_w c_w[A_\mu Z_\nu^0(W_\mu^+ W_\nu^- - \\
& W_\nu^+ W_\mu^-) - 2A_\mu Z_\mu^0 W_\nu^+ W_\nu^-] - g\alpha[H^3 + H\phi^0 \phi^0 + 2H\phi^+ \phi^-] - \\
& \frac{1}{8}g^2 \alpha_h[H^4 + (\phi^0)^4 + 4(\phi^+ \phi^-)^2 + 4(\phi^0)^2 \phi^+ \phi^- + 4H^2 \phi^+ \phi^- + 2(\phi^0)^2 H^2] - \\
& gMW_\mu^+ W_\mu^- H - \frac{1}{2}g\frac{M}{c_w^2}Z_\mu^0 Z_\mu^0 H - \frac{1}{2}ig[W_\mu^+(\phi^0 \partial_\mu \phi^- - \phi^- \partial_\mu \phi^0) - \\
& W_\mu^-(\phi^0 \partial_\mu \phi^+ - \phi^+ \partial_\mu \phi^0)] + \frac{1}{2}g[W_\mu^+(H \partial_\mu \phi^- - \phi^- \partial_\mu H) - W_\mu^-(H \partial_\mu \phi^+ - \\
& \phi^+ \partial_\mu H)] + \frac{1}{2}g\frac{1}{c_w}(Z_\mu^0(H \partial_\mu \phi^0 - \phi^0 \partial_\mu H) - ig\frac{s_w^2}{c_w}MZ_\mu^0(W_\mu^+ \phi^- - W_\mu^- \phi^+) + \\
& ig s_w MA_\mu(W_\mu^+ \phi^- - W_\mu^- \phi^+) - ig\frac{1-2c_w^2}{2c_w}Z_\mu^0(\phi^+ \partial_\mu \phi^- - \phi^- \partial_\mu \phi^+) + \\
& ig s_w A_\mu(\phi^+ \partial_\mu \phi^- - \phi^- \partial_\mu \phi^+) - \frac{1}{4}g^2 W_\mu^+ W_\mu^- [H^2 + (\phi^0)^2 + 2\phi^+ \phi^-] - \\
& \frac{1}{4}g^2 \frac{1}{c_w^2}Z_\mu^0 Z_\mu^0 [H^2 + (\phi^0)^2 + 2(2s_w^2 - 1)^2 \phi^+ \phi^-] - \frac{1}{2}g^2 \frac{s_w^2}{c_w}Z_\mu^0 \phi^0(W_\mu^+ \phi^- + \\
& W_\mu^- \phi^+) - \frac{1}{2}ig^2 \frac{s_w^2}{c_w}Z_\mu^0 H(W_\mu^+ \phi^- - W_\mu^- \phi^+) + \frac{1}{2}g^2 s_w A_\mu \phi^0(W_\mu^+ \phi^- + \\
& W_\mu^- \phi^+) + \frac{1}{2}ig^2 s_w A_\mu H(W_\mu^+ \phi^- - W_\mu^- \phi^+) - g^2 \frac{s_w}{c_w}(2c_w^2 - 1)Z_\mu^0 A_\mu \phi^+ \phi^- - \\
& g^1 s_w^2 A_\mu A_\mu \phi^+ \phi^- - \bar{e}^\lambda(\gamma \partial + m_e^\lambda)e^\lambda - \bar{\nu}^\lambda \gamma \partial \nu^\lambda - \bar{u}_j^\lambda(\gamma \partial + m_u^\lambda)u_j^\lambda - \\
& \bar{d}_j^\lambda(\gamma \partial + m_d^\lambda)d_j^\lambda + ig s_w A_\mu [-(\bar{e}^\lambda \gamma^\mu e^\lambda) + \frac{2}{3}(\bar{u}_j^\lambda \gamma^\mu u_j^\lambda) - \frac{1}{3}(\bar{d}_j^\lambda \gamma^\mu d_j^\lambda)] + \\
& \frac{ig}{4c_w}Z_\mu^0[(\bar{\nu}^\lambda \gamma^\mu(1 + \gamma^5)\nu^\lambda) + (\bar{e}^\lambda \gamma^\mu(4s_w^2 - 1 - \gamma^5)e^\lambda) + (\bar{u}_j^\lambda \gamma^\mu(\frac{4}{3}s_w^2 - \\
& 1 - \gamma^5)u_j^\lambda) + (\bar{d}_j^\lambda \gamma^\mu(1 - \frac{8}{3}s_w^2 - \gamma^5)d_j^\lambda)] + \frac{ig}{2\sqrt{2}}W_\mu^+[(\bar{\nu}^\lambda \gamma^\mu(1 + \gamma^5)e^\lambda) + \\
& (\bar{u}_j^\lambda \gamma^\mu(1 + \gamma^5)C_{\lambda\kappa} d_j^\kappa)] + \frac{ig}{2\sqrt{2}}W_\mu^-[(\bar{e}^\lambda \gamma^\mu(1 + \gamma^5)\nu^\lambda) + (\bar{d}_j^\kappa C_{\lambda\kappa}^\dagger \gamma^\mu(1 + \\
& \gamma^5)u_j^\lambda)] + \frac{ig}{2\sqrt{2}}\frac{m_\lambda^2}{M}[-\phi^+(\bar{\nu}^\lambda(1 - \gamma^5)e^\lambda) + \phi^-(\bar{e}^\lambda(1 + \gamma^5)\nu^\lambda)] - \\
& \frac{g}{2}\frac{m_\lambda^2}{M}[H(\bar{e}^\lambda e^\lambda) + i\phi^0(\bar{e}^\lambda \gamma^5 e^\lambda)] + \frac{ig}{2M\sqrt{2}}\phi^+[-m_d^\kappa(\bar{u}_j^\lambda C_{\lambda\kappa}(1 - \gamma^5)d_j^\kappa) + \\
& m_u^\lambda(\bar{u}_j^\lambda C_{\lambda\kappa}(1 + \gamma^5)d_j^\kappa) + \frac{ig}{2M\sqrt{2}}\phi^-[m_d^\lambda(\bar{d}_j^\lambda C_{\lambda\kappa}^\dagger(1 + \gamma^5)u_j^\kappa) - m_u^\kappa(\bar{d}_j^\lambda C_{\lambda\kappa}^\dagger(1 - \\
& \gamma^5)u_j^\kappa) - \frac{g}{2}\frac{m_\lambda^2}{M}H(\bar{u}_j^\lambda u_j^\lambda) - \frac{g}{2}\frac{m_\lambda^2}{M}H(\bar{d}_j^\lambda d_j^\lambda) + \frac{ig}{2}\frac{m_\lambda^2}{M}\phi^0(\bar{u}_j^\lambda \gamma^5 u_j^\lambda) - \\
& \frac{ig}{2}\frac{m_\lambda^2}{M}\phi^0(\bar{d}_j^\lambda \gamma^5 d_j^\lambda)] + \bar{X}^+(\partial^2 - M^2)X^+ + \bar{X}^-(\partial^2 - M^2)X^- + \bar{X}^0(\partial^2 - \\
& \frac{M^2}{c_w^2})X^0 + \bar{Y}\partial^2 Y + igc_w W_\mu^+(\partial_\mu \bar{X}^0 X^- - \partial_\mu \bar{X}^+ X^0) + ig s_w W_\mu^+(\partial_\mu \bar{Y} X^- - \\
& \partial_\mu \bar{X}^+ Y) + igc_w W_\mu^-(\partial_\mu \bar{X}^- X^0 - \partial_\mu \bar{X}^0 X^+) + ig s_w W_\mu^-(\partial_\mu \bar{X}^- Y - \\
& \partial_\mu \bar{Y} X^+) + igc_w Z_\mu^0(\partial_\mu \bar{X}^+ X^+ - \partial_\mu \bar{X}^- X^-) + ig s_w A_\mu(\partial_\mu \bar{X}^+ X^+ - \\
& \partial_\mu \bar{X}^- X^-) - \frac{1}{2}gM[\bar{X}^+ X^+ H + \bar{X}^- X^- H + \frac{1}{c_w}\bar{X}^0 X^0 H] + \\
& \frac{1-2c_w^2}{2c_w}igM[\bar{X}^+ X^0 \phi^+ - \bar{X}^- X^0 \phi^-] + \frac{1}{2c_w}igM[\bar{X}^0 X^- \phi^+ - \bar{X}^0 X^+ \phi^-] + \\
& igMs_w[\bar{X}^0 X^- \phi^+ - \bar{X}^0 X^+ \phi^-] + \frac{1}{2}igM[\bar{X}^+ X^+ \phi^0 - \bar{X}^- X^- \phi^0]
\end{aligned}$$

Conservation laws

Symmetries of the Lagrangian give rise to conservation laws

- The Energy $E = K + V$ is conserved

$$E'(t) = (mq''(t) - F(q(t))) \cdot q'(t) = 0$$

- If $L = L(q')$, the momentum $p = mq'(t)$ is conserved

$$p'(t) = mq''(t) = -\frac{\partial L}{\partial x}(q(t), q'(t)) = 0$$

See also: Noether's theorem

Beyond Euler-Lagrange

Lagrangian mechanics can be further refined into *Hamiltonian mechanics*

(We won't get into it today, but they are fundamental in e.g. Quantum Mechanics)

