Paths in Graphs: Most Direct Route

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Higher School of Economics

Graph Algorithms Data Structures and Algorithms

Outline

- Paths and Distances
- 2 Breadth-first Search
- 3 Implementation and Analysis
- 4 Proof of Correctness
- 5 Shortest-path Tree

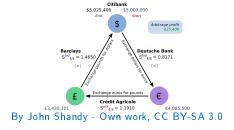












The most direct route

What is the minimum number of flight segments to get from Hamburg to Moscow?

The most direct route

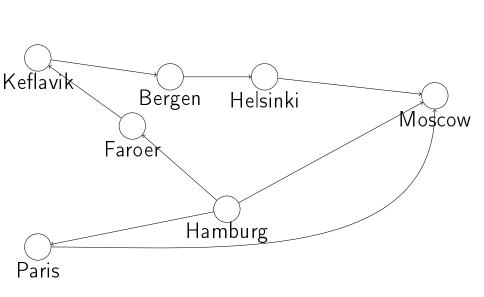
What is the minimum number of flight segments to get from Hamburg to Moscow?

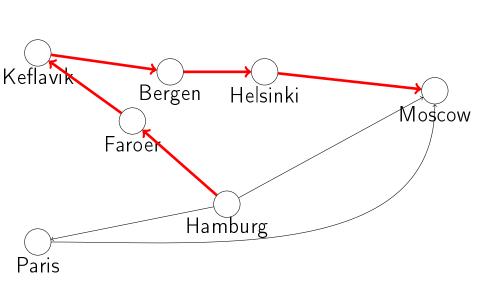


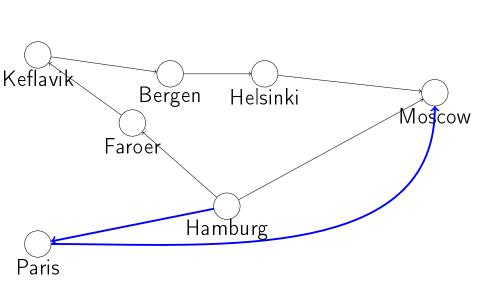
The most direct route

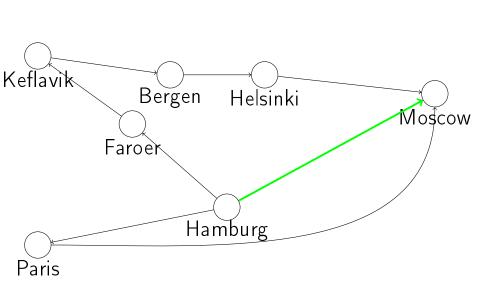
What is the minimum number of flight segments to get from Hamburg to Moscow?





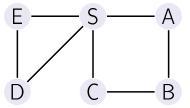






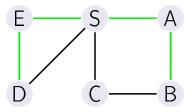
Paths and lengths

Length of the path L(P) is the number of edges in the path.



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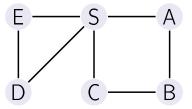
$$L(D-E-S-A-B)=4$$

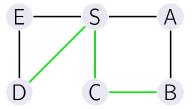
Paths and lengths

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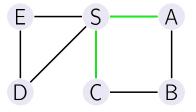
$$L(D - E - S - A - B) = 4$$

 $L(D - S - C - B) = 3$

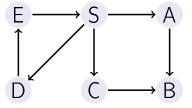


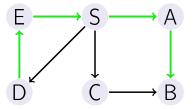


$$d(D, B) = 3$$

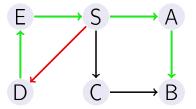


$$d(D,B) = 3$$
$$d(C,A) = 2$$

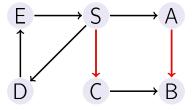




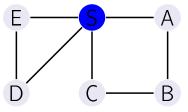
$$d(D,B)=4$$



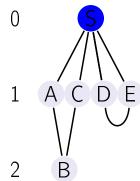
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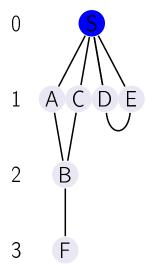


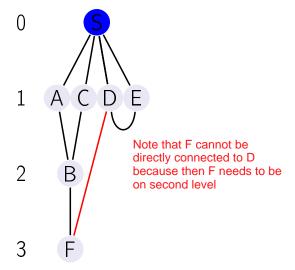
$$d(D,B) = 4$$
$$d(C,A) = \infty$$

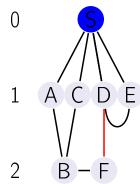


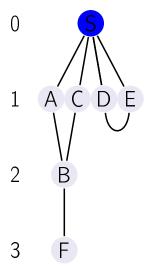


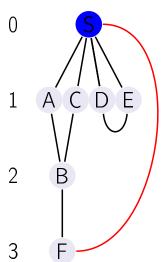


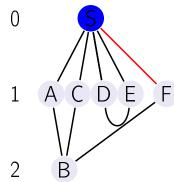


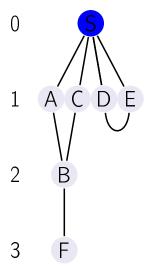


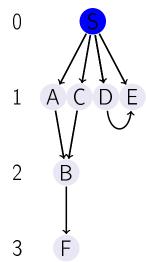


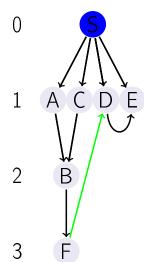


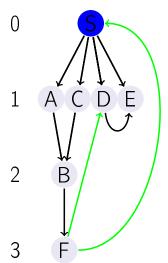




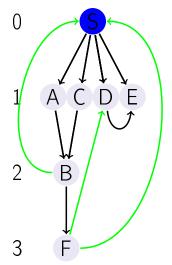




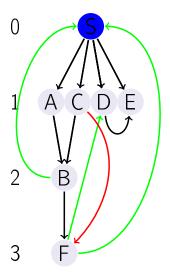




Distance layers



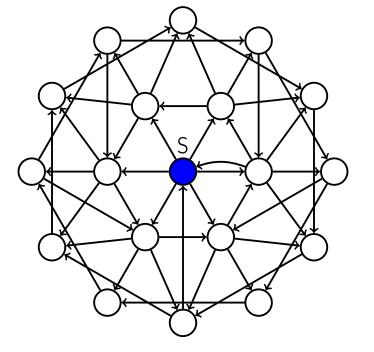
Distance layers

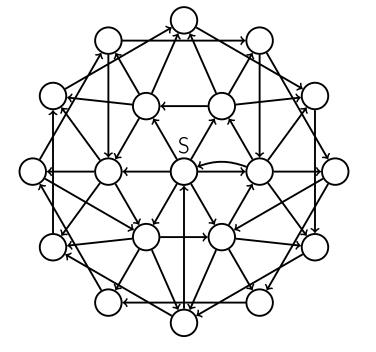


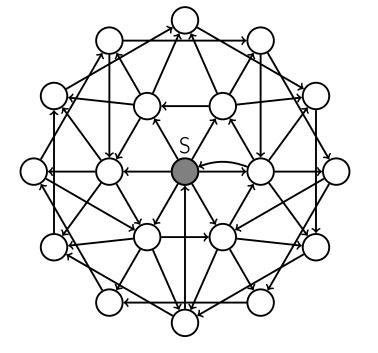
Note that we can have the connection in opposite direction as the shortest path from S does not change. However not in the same direction as then F needs to be brought to level 2

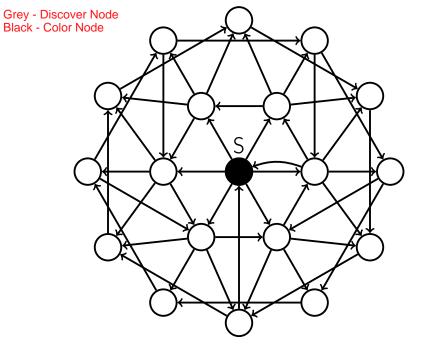
Outline

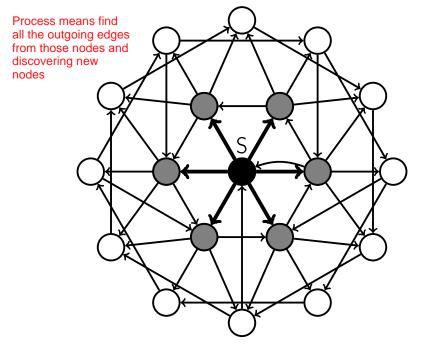
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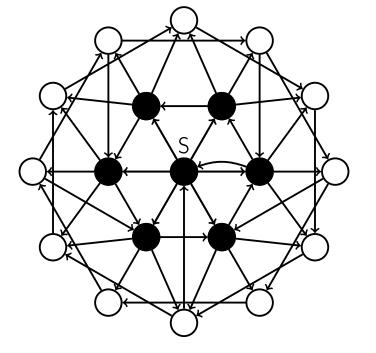






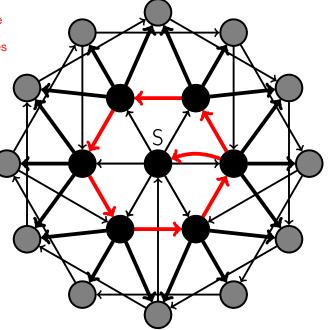


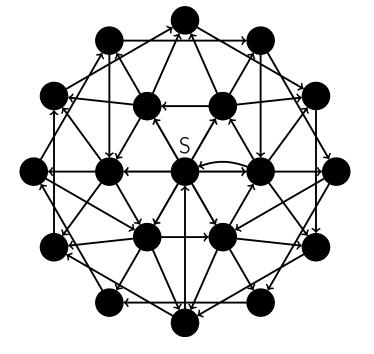


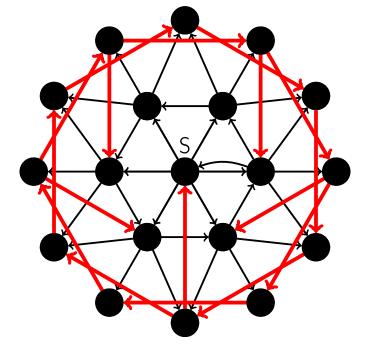


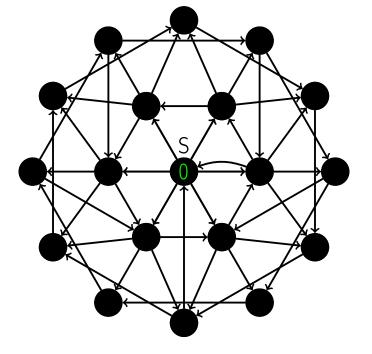
Notice that we don't need to discover edges we have already discovered

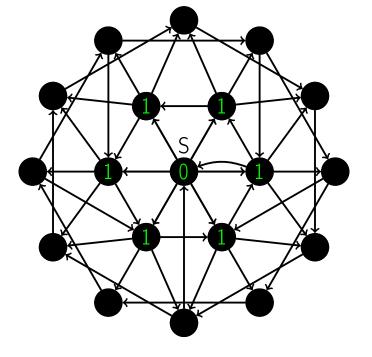
Red means nodes at the end are already discovered and we don't need to do anything

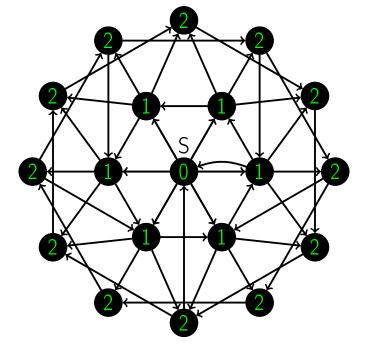


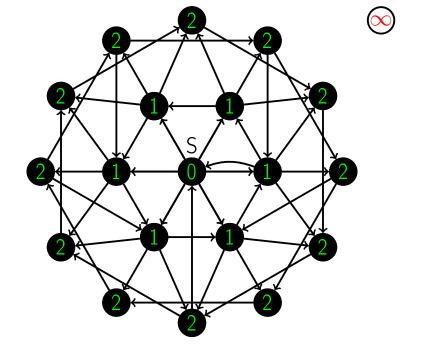


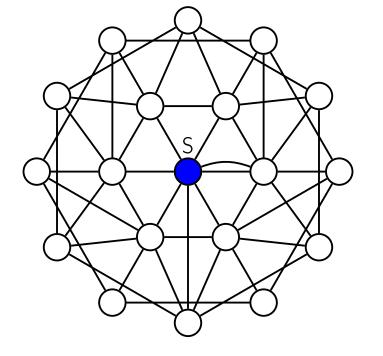


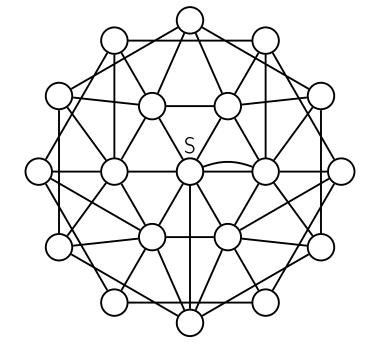


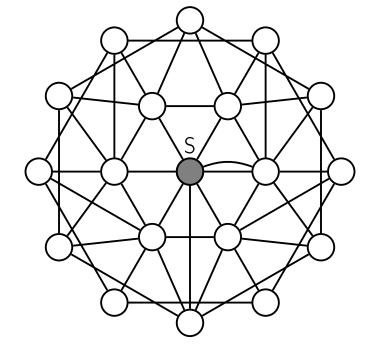


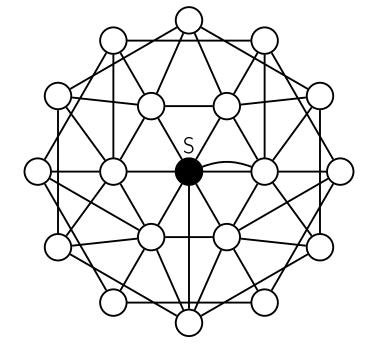


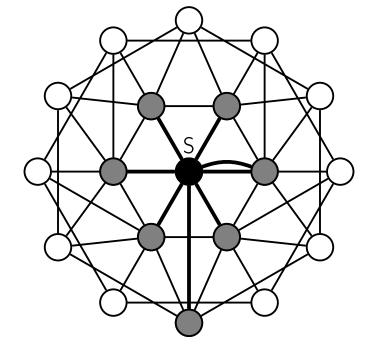


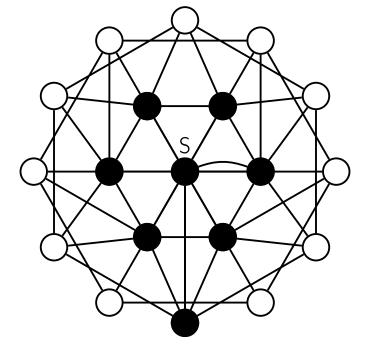


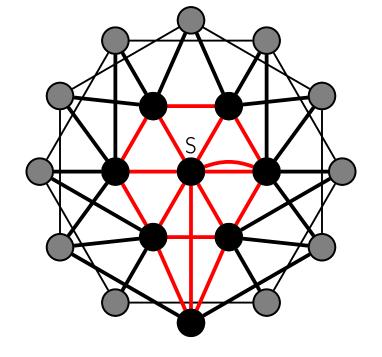


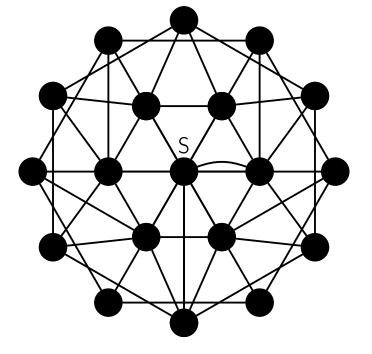


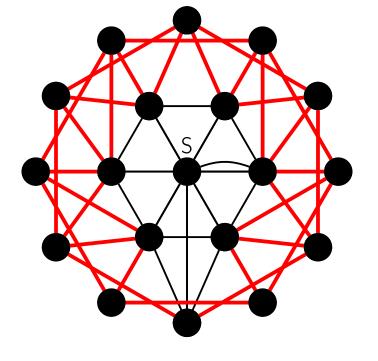


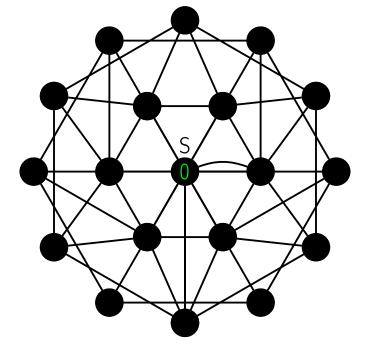


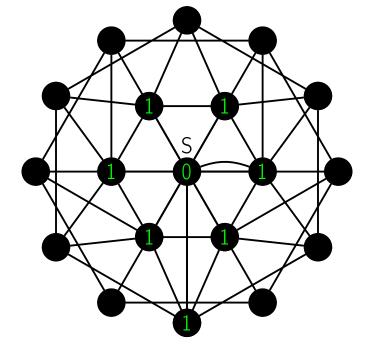


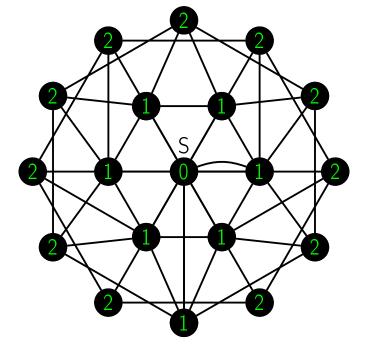


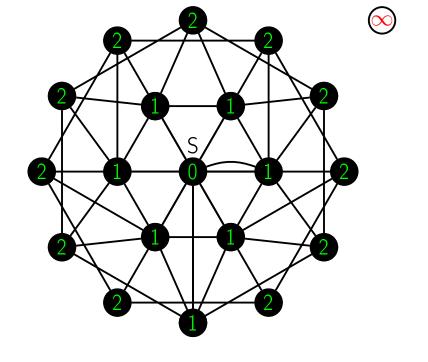


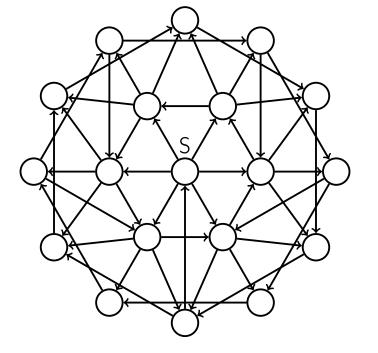


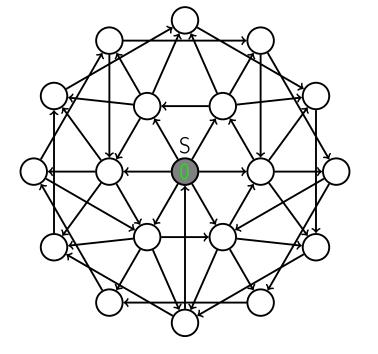


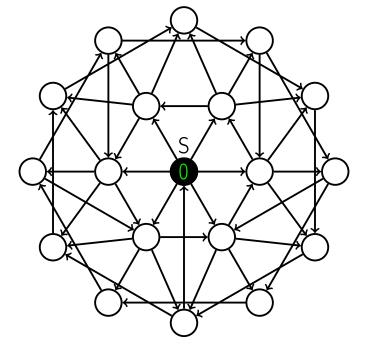






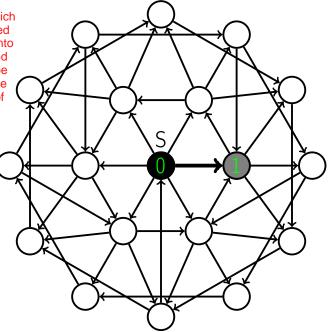


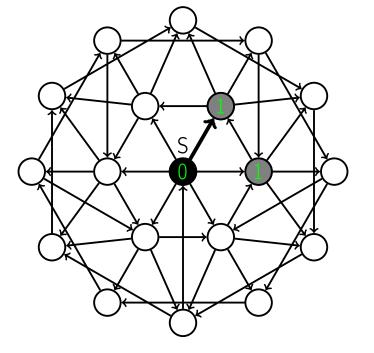


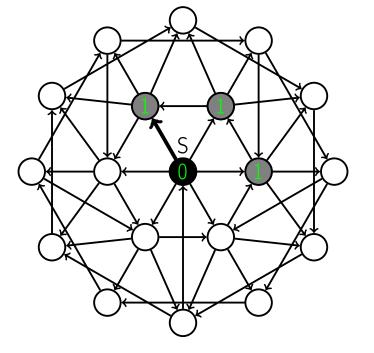


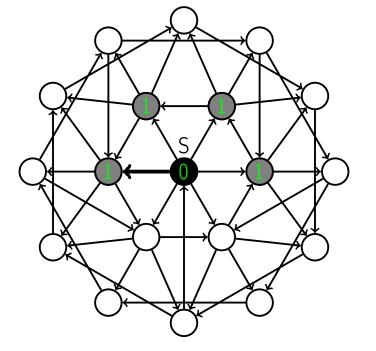
The node which are discovered are pushed into the queue and the node to be processed are popped out of

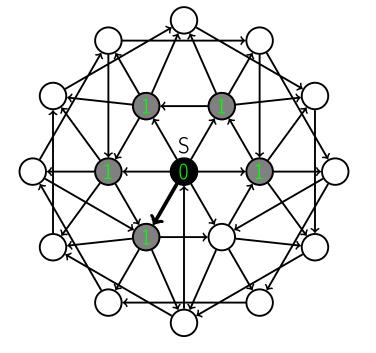
Hence the nodes discovered earlier will also be processed earlier

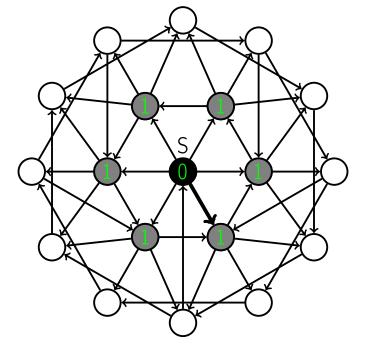


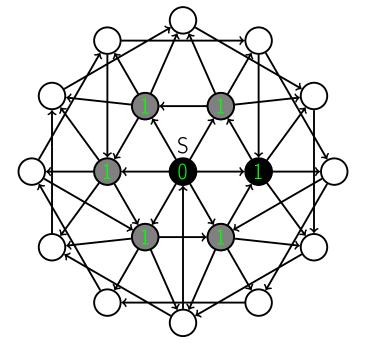


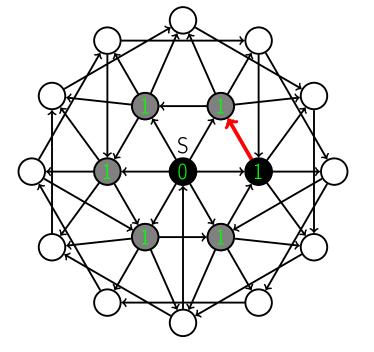


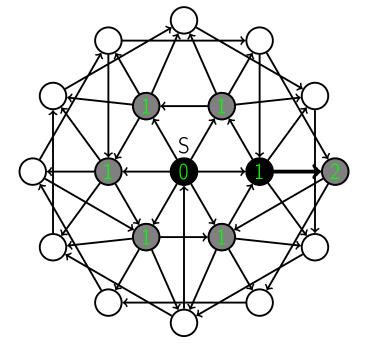


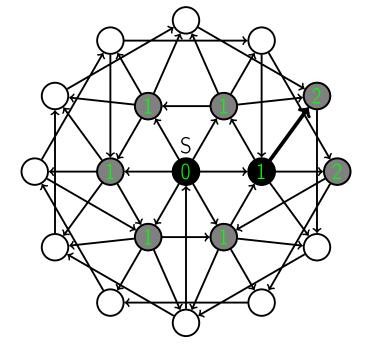


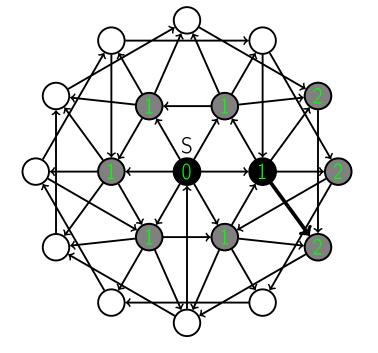


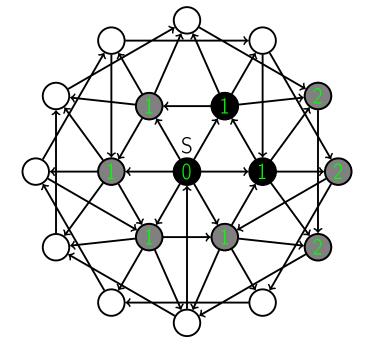


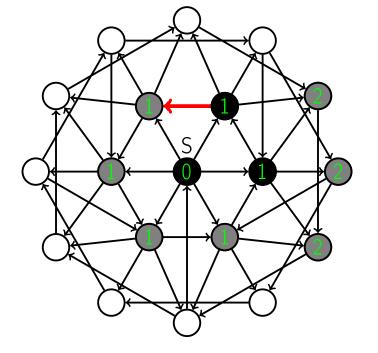


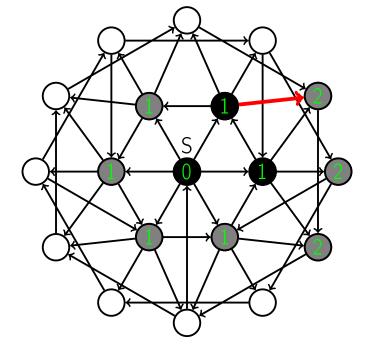


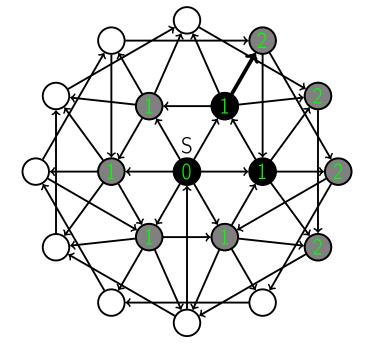


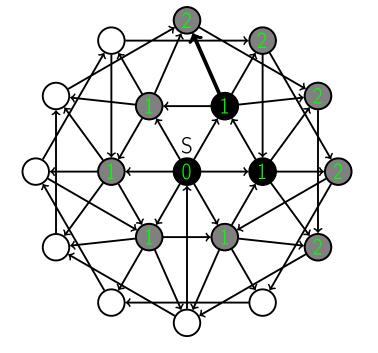


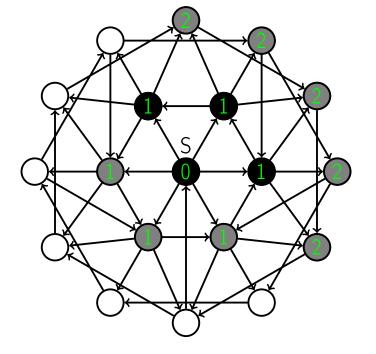


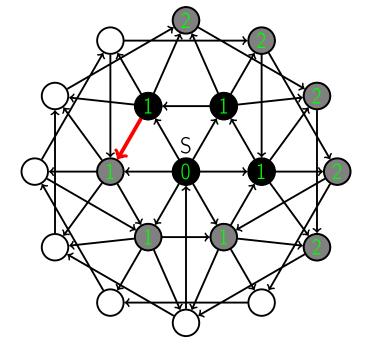


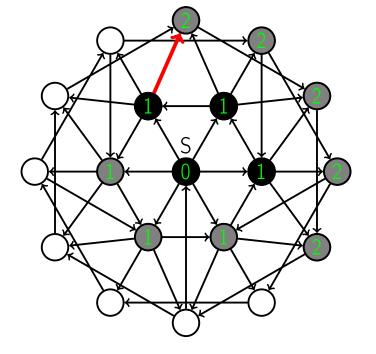


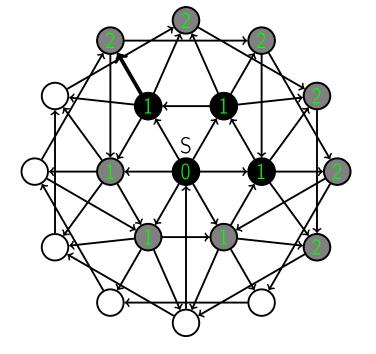


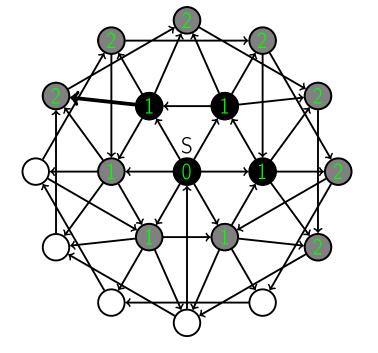


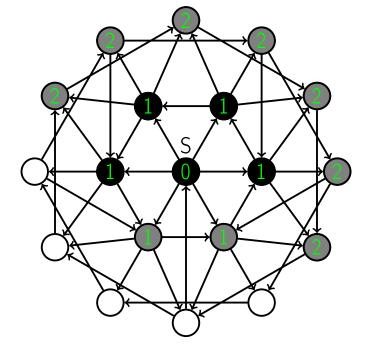


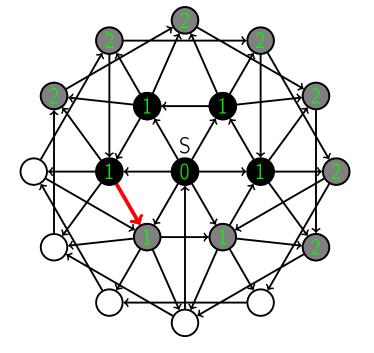


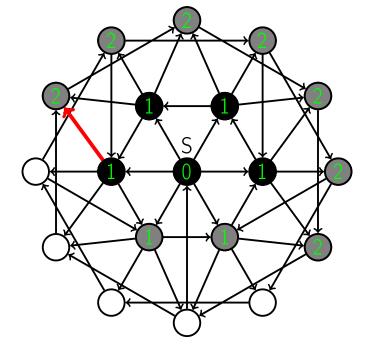


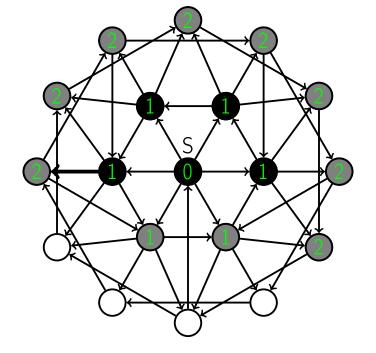


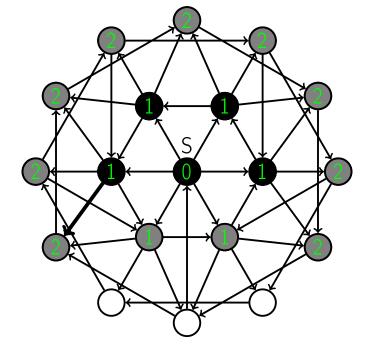


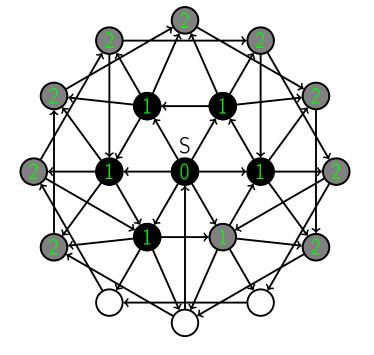


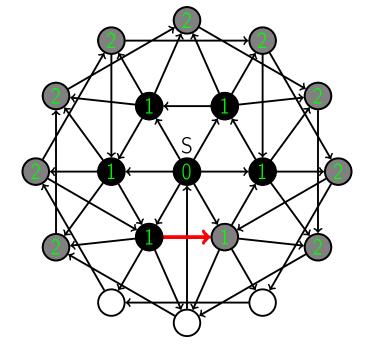


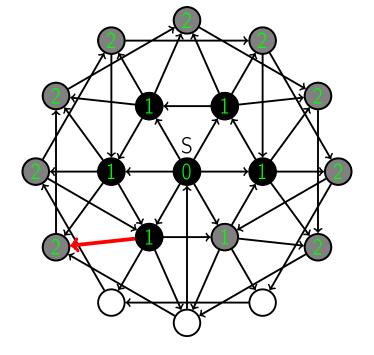


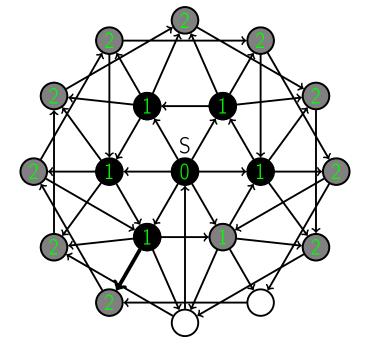


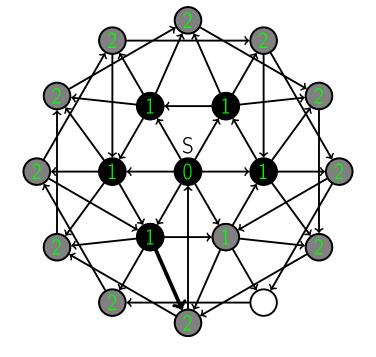


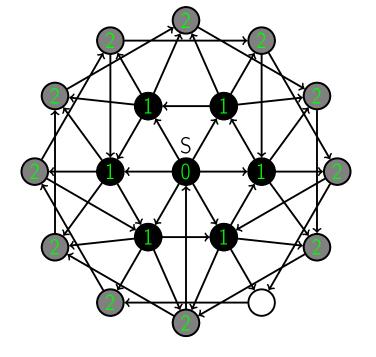


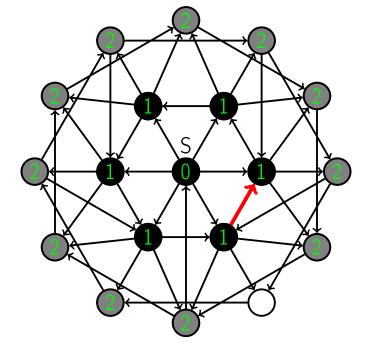


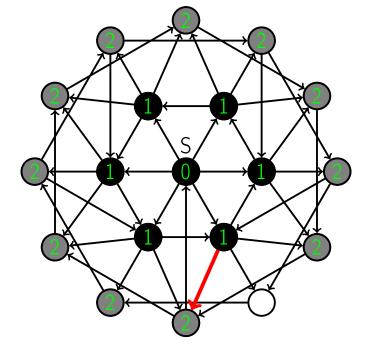


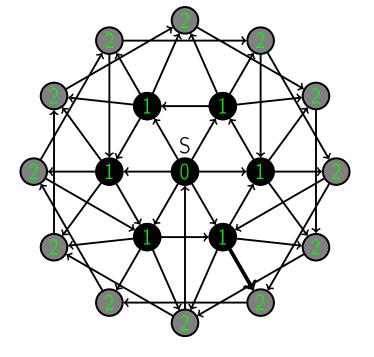


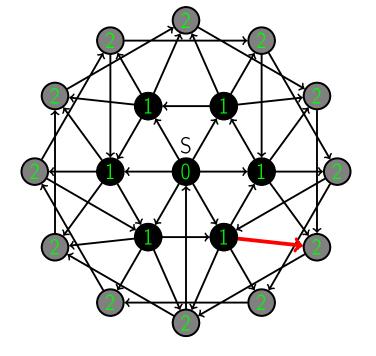


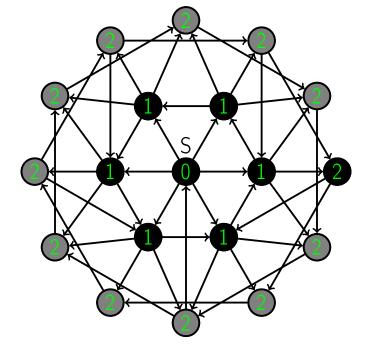


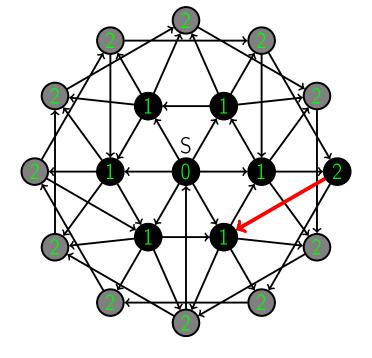


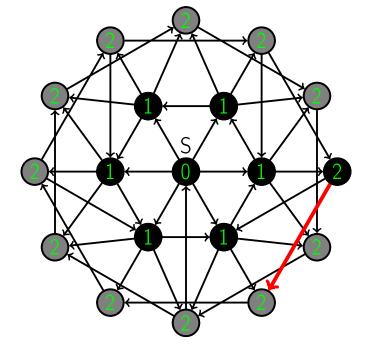


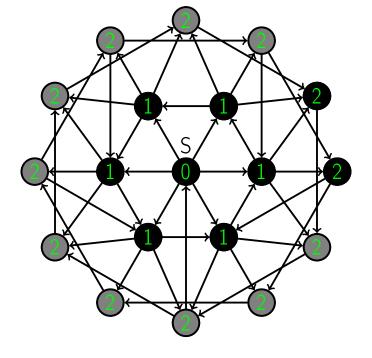


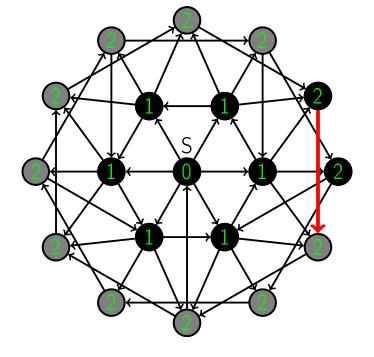


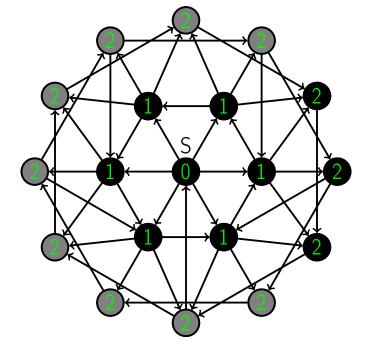


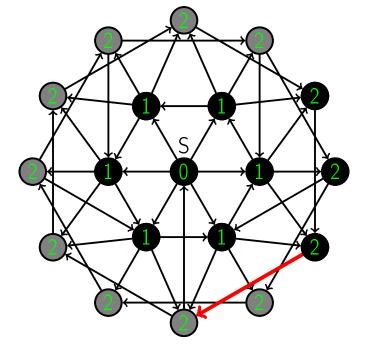


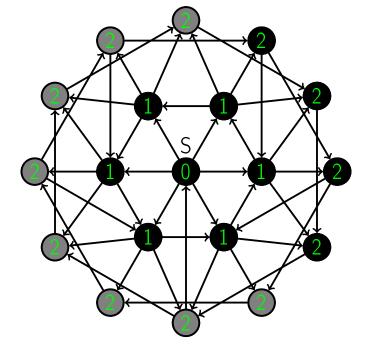


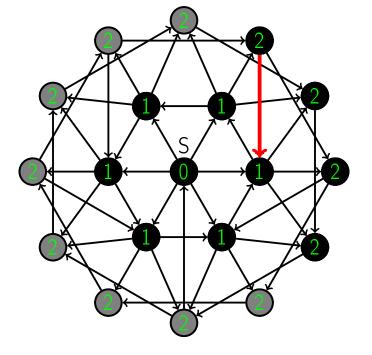


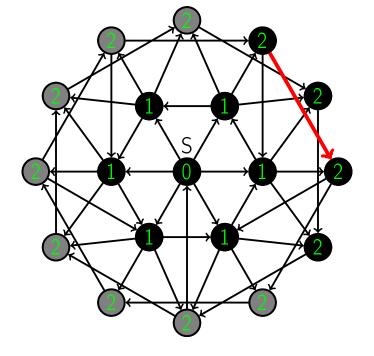


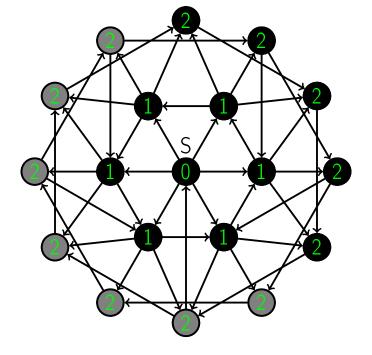


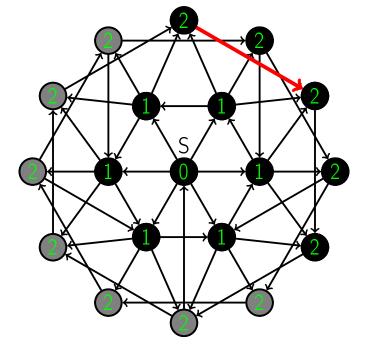


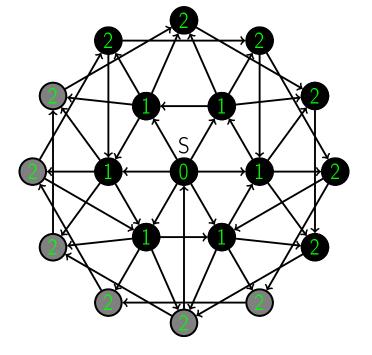


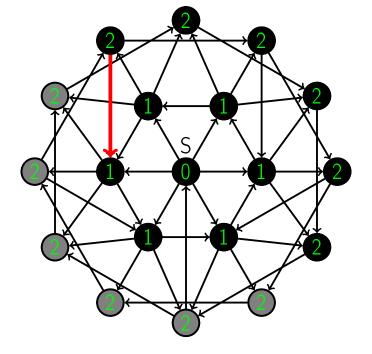


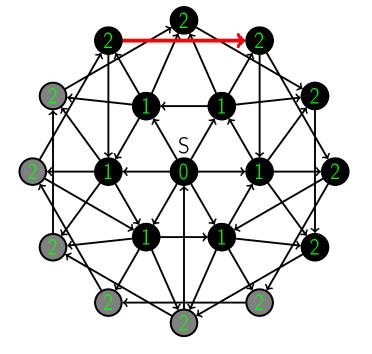


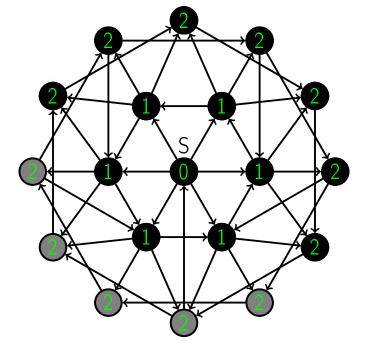


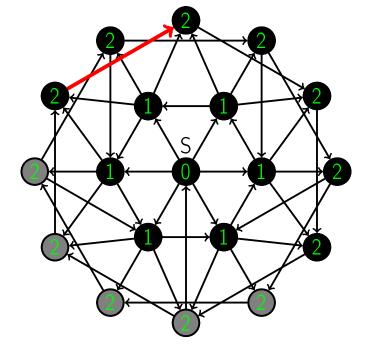


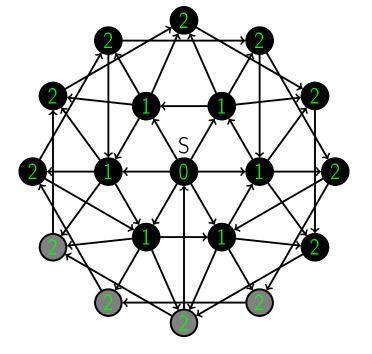


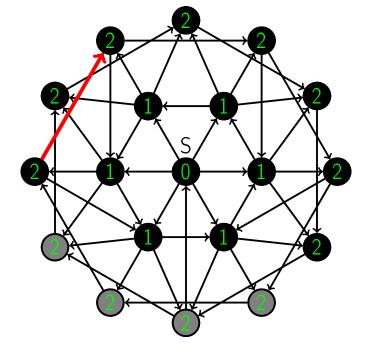


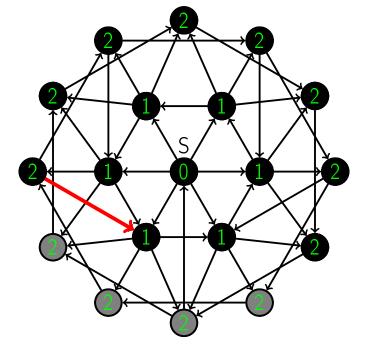


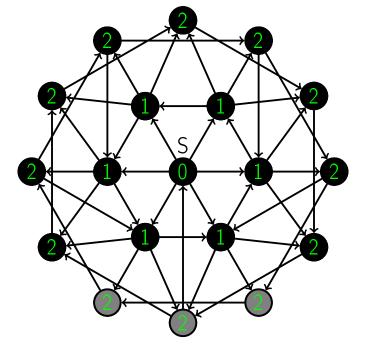


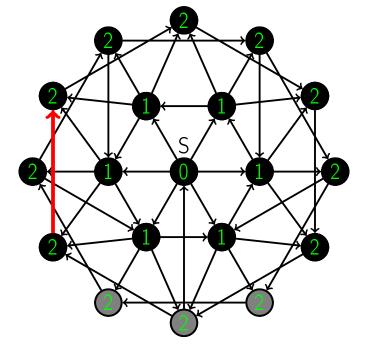


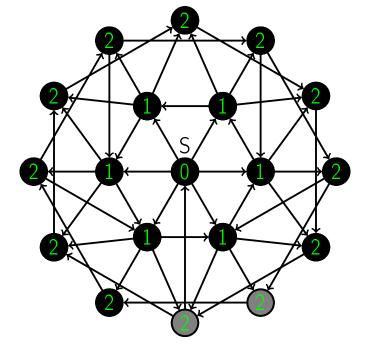


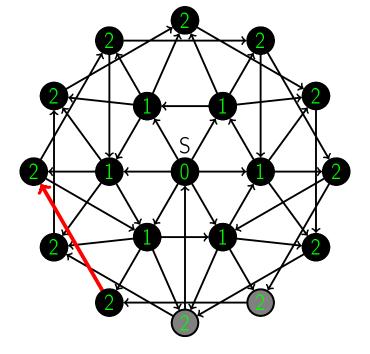


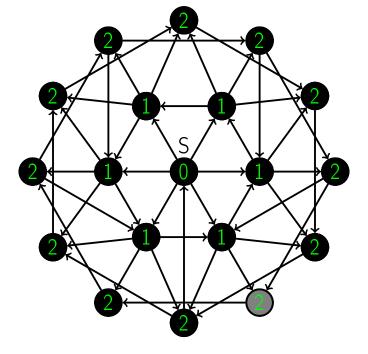


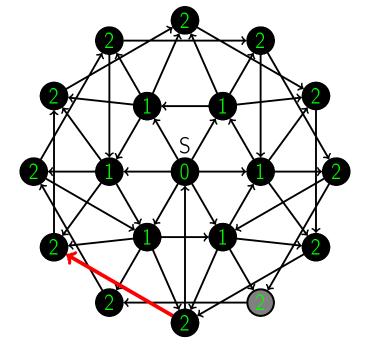


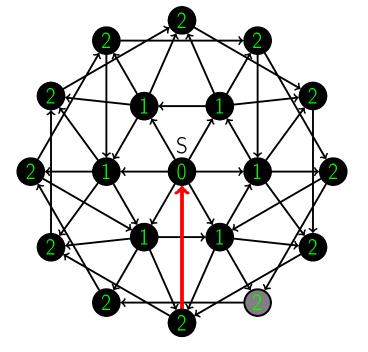


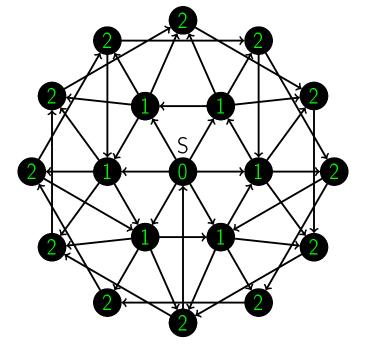


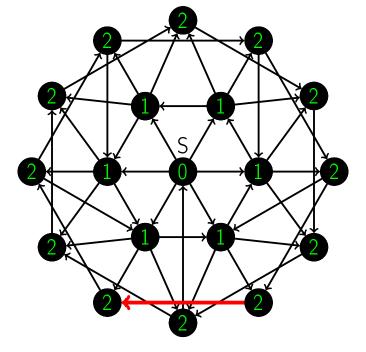


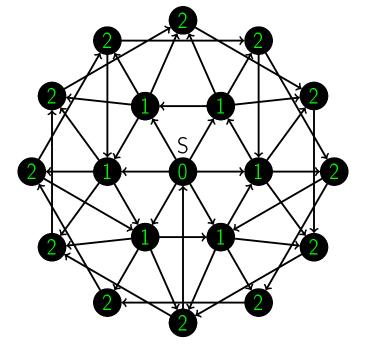


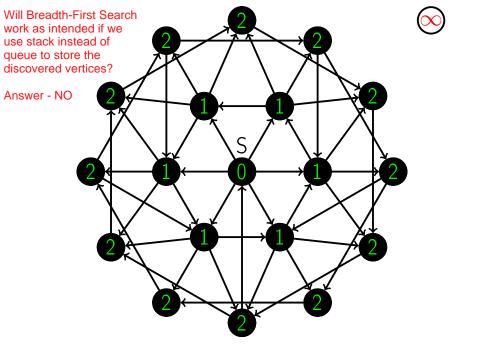












Outline

- Paths and Distances
- 2 Breadth-first Search
- 3 Implementation and Analysis
- 4 Proof of Correctness
- Shortest-path Tree

Breadth-first search

$\mathsf{BFS}(G,S)$ G as graph and S as input node

for all $u \in V$:

```
\operatorname{dist}[u] \leftarrow \infty All nodes has distance infinity
       \operatorname{dist}[S] \leftarrow 0 S set to distance 0
       Q \leftarrow \{S\} {queue containing just S} Push S to 0 hence discovered
       while Q is not empty:
          u \leftarrow \text{Dequeue}(Q) Now dequeue and process nodes one by one
          for all (u, v) \in E:
              if dist[v] = \infty:
                                              If distance is not infinity means the node has
                                              already been discovered and nothing needs
                  Enqueue(Q, v)
                                              to be done
                  \operatorname{dist}[v] \leftarrow \operatorname{dist}[u] + 1
                                                           distance equal to distance of
                                                           previous layer plus 1
very high number like a number greater then the max no of nodes or edges
```

Running time

Lemma

The running time of breadth-first search is O(|E| + |V|).

Proof

Running time

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Proof

Each vertex is enqueued at most once

Running time

Lemma

The running time of breadth-first search is O(|E| + |V|).

Proof

External While loop is at most

- Each vertex is enqueued at most once number of nodes |V|
- Each edge is examined either once (for directed graphs) or twice (for undirected graphs) total no of iterations of internal for loop is atmost |E|

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Reachability

Definition

Node u is reachable from node S if there is a path from S to u

Lemma

Reachable nodes are discovered at some point, so they get a finite distance estimate from the source. Unreachable nodes are not discovered at any point, and the distance to them stays infinite.

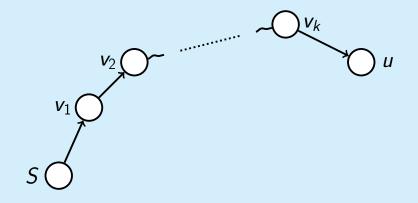
Proof

) u

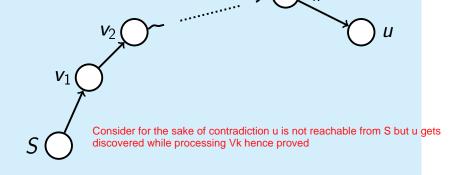
 $S \bigcirc$

lacksquare u — reachable undiscovered closest to S

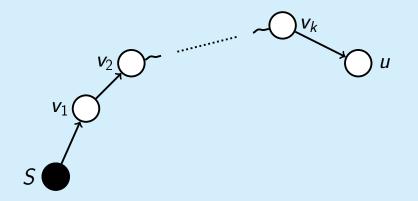
Proof



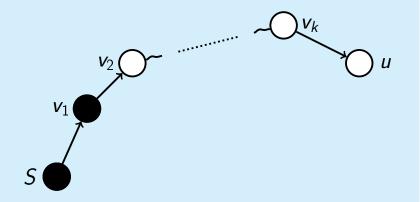
- lacktriangleq u reachable undiscovered closest to S
- lacksquare $S-v_1-\cdots-v_k-u$ shortest path



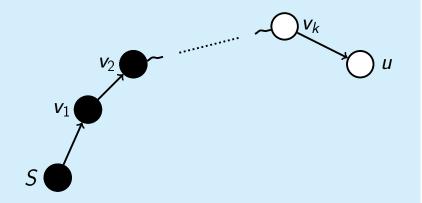
- lacktriangleq u reachable undiscovered closest to S
- $S v_1 \cdots v_k u$ shortest path
- \mathbf{u} is discovered while processing \mathbf{v}_k



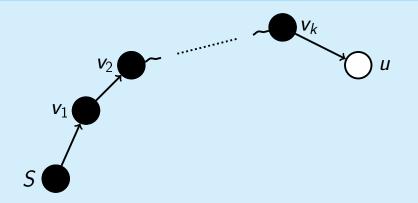
- u reachable undiscovered closest to S■ $S - v_1 - \cdots - v_k - u$ — shortest path
- \mathbf{u} is discovered while processing \mathbf{v}_k



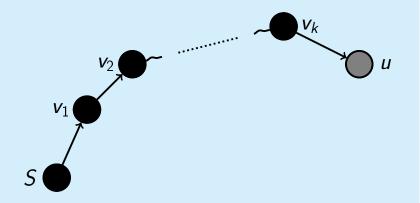
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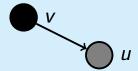


- u reachable undiscovered closest to S■ $S - v_1 - \cdots - v_k - u$ — shortest path
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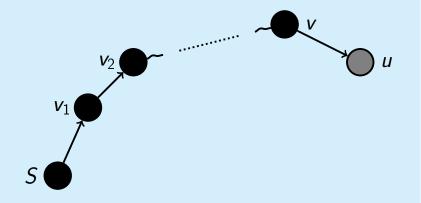


■ *u* — first unreachable discovered





- *u* first unreachable discovered
- *u* was discovered while processing *v*



- *u* first unreachable discovered
- u was discovered while processing v
- \mathbf{u} is reachable through \mathbf{v} Contradiction

Order Lemma

Lemma

By the time node u at distance d from S is dequeued, all the nodes at distance at most d have already been discovered (enqueued).

This is very understandable no need to break head with the proof



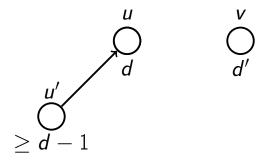
Consider the first time the order was broken

Lets consider by contradiction again that u is discovered and processed while v is not yet discovered

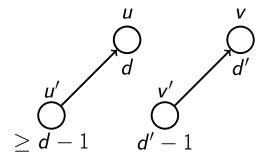




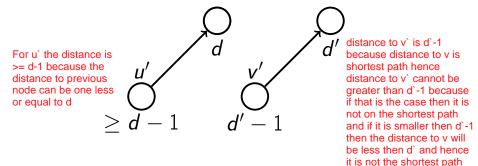
Consider the first time the order was broken $d' \leq d$

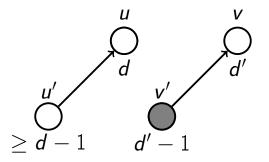


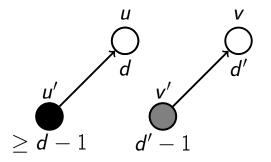
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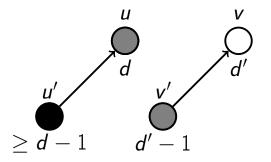


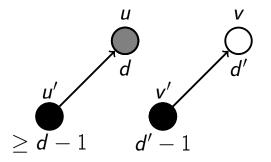
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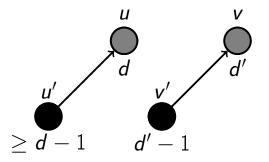


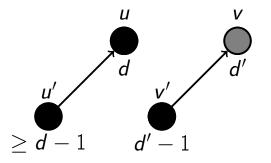












Lemma

When node u is discovered (enqueued), dist[u] is assigned exactly d(S, u).

Proof

Use mathematical induction

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- Base: when S is discovered, dist[S] is assigned 0 = d(S, S)

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- Base: when S is discovered, dist[S] is assigned 0 = d(S, S)
- Inductive step: suppose proved for all nodes at distance $\leq k$ from $S \rightarrow$ prove for nodes at distance k+1

Proof

■ Take a node \mathbf{v} at distance $\mathbf{k} + 1$ from \mathbf{S}

- Take a node v at distance k+1 from S
- v was discovered while processing u

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- ullet v is discovered after u is dequeued, so d(S,u) < d(S,v) = k+1
- So d(S, u) = k, and $dist[v] \leftarrow dist[u] + 1 = k + 1$

Queue: $d \mid d \mid d \mid \ldots \mid d \mid d \mid d + 1 \mid d + 1 \mid \ldots \mid d + 1 \mid$

Lemma

At any moment, if the first node in the queue is at distance d from S, then all the nodes in the queue are either at distance d from S or at distance d+1 from S. All the nodes in the queue at distance d go before (if any) all the nodes at distance d+1.

Proof

All nodes at distance d were enqueued before first such node is dequeued, so they go before nodes at distance d+1

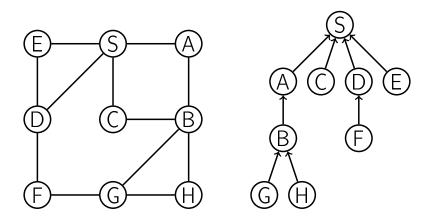
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- Nodes at distance d-1 were enqueued before nodes at d, so they are not in the queue anymore
- Nodes at distance > d + 1 will be discovered when all d are gone

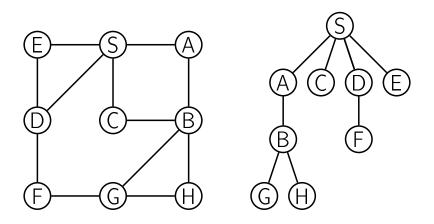
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Shortest-path tree

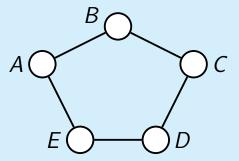


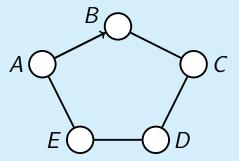
Shortest-path tree

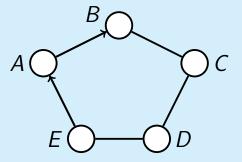


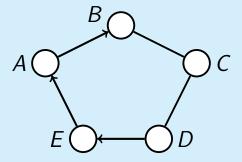
Lemma

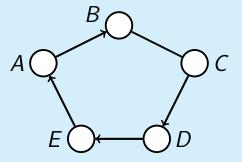
Shortest-path tree is indeed a tree, i.e. it doesn't contain cycles (it is a connected component by construction).

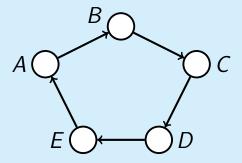


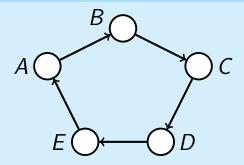




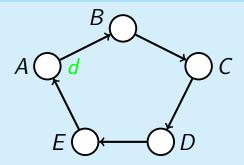




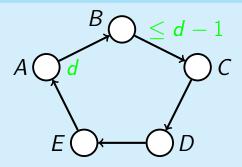




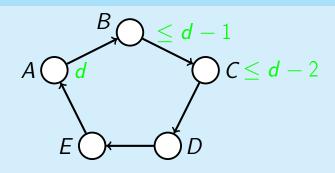
- Only one outgoing edge from each node
- Distance to S decreases after going by edge



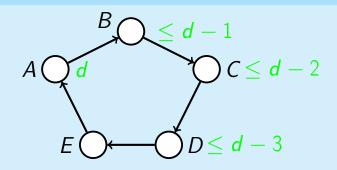
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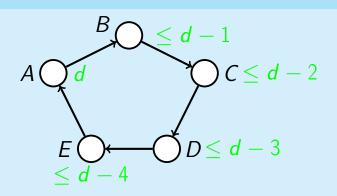
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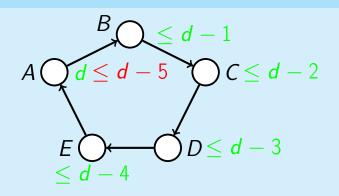
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- Only one outgoing edge from each node
- Distance to *S* decreases after going by edge



- Only one outgoing edge from each node
- Distance to S decreases after going by edge



- Only one outgoing edge from each node
- $lue{}$ Distance to S decreases after going by edge

Constructing shortest-path tree

BFS(G, S)

```
for all u \in V:
   dist[u] \leftarrow \infty, prev[u] \leftarrow nil
dist[S] \leftarrow 0
Q \leftarrow \{S\} {queue containing just S}
while Q is not empty:
   u \leftarrow \text{Dequeue}(Q)
   for all (u, v) \in E:
       if dist[v] = \infty:
          Enqueue(Q, v)
          \operatorname{dist}[v] \leftarrow \operatorname{dist}[u] + 1, \operatorname{prev}[v] \leftarrow u
```

Reconstructing Shortest Path

ReconstructPath(S, u, prev)

```
 \begin{array}{l} \text{result} \leftarrow \text{empty} \\ \text{while } u \neq S : \\ \text{result.append}(u) \\ u \leftarrow \text{prev}[u] \\ \text{return Reverse(result)} \end{array}
```

 Can find the minimum number of flight segments to get from one city to another

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- Can reconstruct the optimal path
- Can build the tree of shortest paths
 from one origin Meaning can find the shortest path from origin node to all nodes and not just target
- Works in O(|E| + |V|)