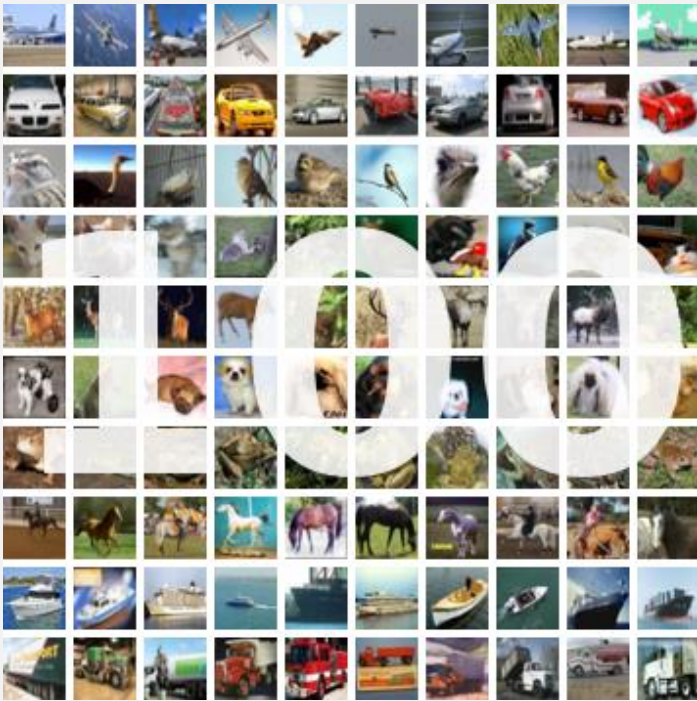


# The Comparison of Different Machine Learning Platforms and Models for CIFAR 100



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Group 2

4<sup>th</sup> Dec, 2018

# CONTENT

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- **1** Introduction of the dataset
- **2** Multilayer perceptron (PyTorch)
- **3** Convolution neural network (PyTorch)
- **4** Transfer learning (Tensorflow/Keras)
- **5** Conclusion



# Introduction to the dataset – CIFAR100

## Superclass

aquatic mammals  
fish  
flowers  
food containers  
fruit and vegetables  
household electrical devices  
household furniture  
insects  
large carnivores  
large man-made outdoor things  
large natural outdoor scenes  
large omnivores and herbivores  
medium-sized mammals  
non-insect invertebrates  
people  
reptiles  
small mammals  
trees  
vehicles 1  
vehicles 2

## Classes

beaver, dolphin, otter, seal, whale  
aquarium fish, flatfish, ray, shark, trout  
orchids, poppies, roses, sunflowers, tulips  
bottles, bowls, cans, cups, plates  
apples, mushrooms, oranges, pears, sweet peppers  
clock, computer keyboard, lamp, telephone, television  
bed, chair, couch, table, wardrobe  
bee, beetle, butterfly, caterpillar, cockroach  
bear, leopard, lion, tiger, wolf  
bridge, castle, house, road, skyscraper  
cloud, forest, mountain, plain, sea  
camel, cattle, chimpanzee, elephant, kangaroo  
fox, porcupine, possum, raccoon, skunk  
crab, lobster, snail, spider, worm  
baby, boy, girl, man, woman  
crocodile, dinosaur, lizard, snake, turtle  
hamster, mouse, rabbit, shrew, squirrel  
maple, oak, palm, pine, willow  
bicycle, bus, motorcycle, pickup truck, train  
lawn-mower, rocket, streetcar, tank, tractor

100 classes containing 600 images each.

500 training images and 100 testing images per class.

Total 50,000 training set and 10,000 test set

The 100 classes in the CIFAR-100 are grouped into 20 superclasses.

**02**

## **MLP in PyTorch**

# MLP in PyTorch – Initial Setup

```
input_size = 3 * 32 * 32
hidden_size = 200
num_classes = 100
num_epochs = 20
batch_size = 100
learning_rate = 0.0001
momentum = 0.9
```

```
class Net(nn.Module):
    def __init__(self, input_size, hidden_size, num_classes):
        super(Net, self).__init__()
        self.fc1 = nn.Linear(input_size, hidden_size)
        self.relu = nn.ReLU()
        self.fc2 = nn.Linear(hidden_size, num_classes)
        self.softmax = nn.LogSoftmax(dim=1)

    def forward(self, x):
        out = self.fc1(x)
        out = self.relu(out)
        out = self.fc2(out)
        out = self.softmax(out)
        return out
```

# MLP in PyTorch - Adjustment

	Layer	Total parameters	Accuracy
Test	2	317200	23 %
Test1	4	316856	21%; 22% (double epochs)
Test2	7	317400	10%

Table 1 Accuracy with different layers under same total parameters

Optimizer	SGD	Adam	<u>Adagrad</u>	<u>RMSprop</u>	<u>Adadelta</u>
Accuracy	22%	21%	18%	9%	9%

Table 2 Accuracy with different optimizers

## MLP in PyTorch - Adjustment

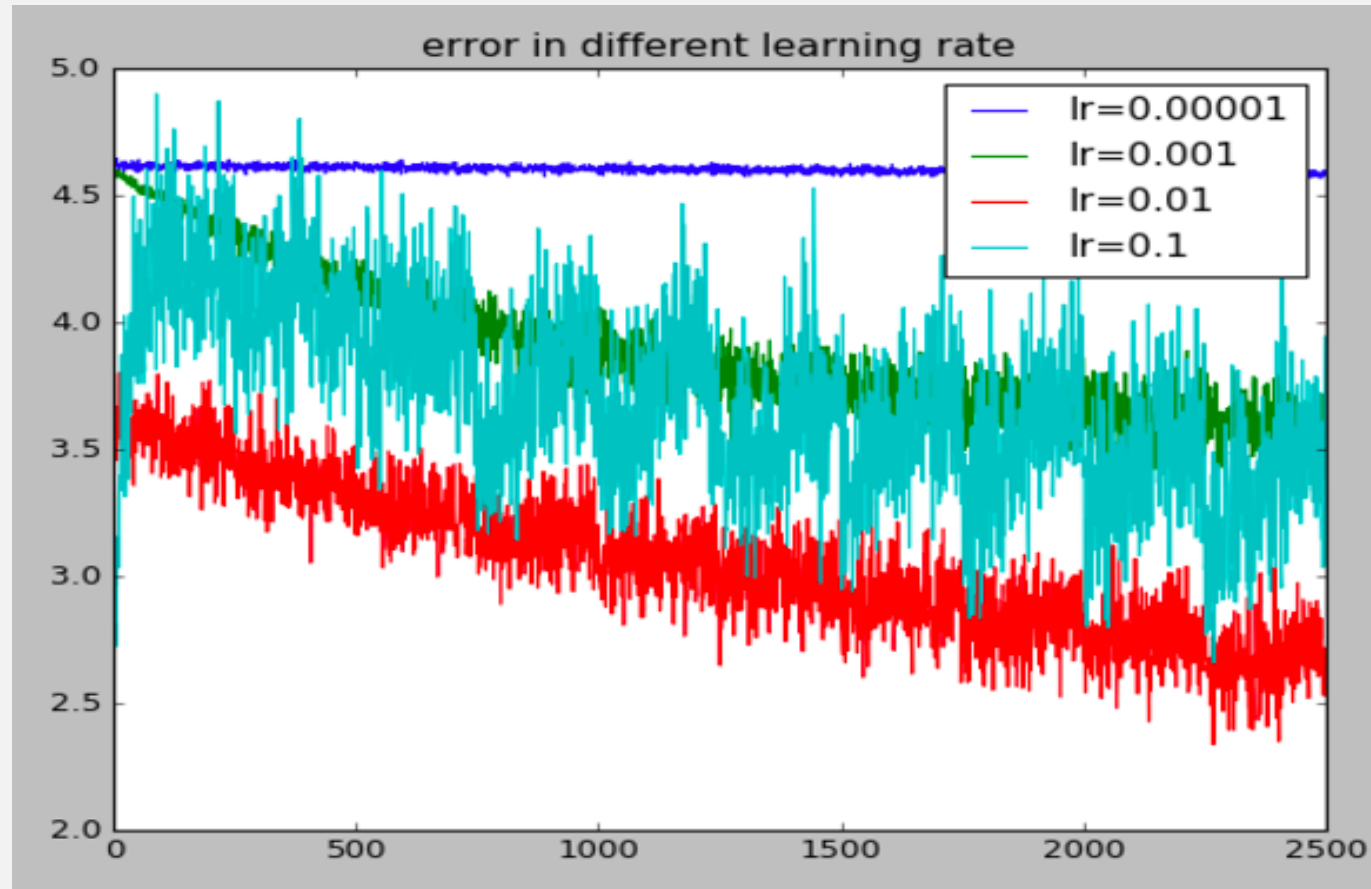
Batch size	50	100	200	500	1000	2000
Accuracy	23.84%	22.41	19%	15.73	12%	5%
Time	280	265	243	245	248	248

Table 3 Different batch size with accuracy and training time

Hidden size	100	200	500	800
Accuracy	19.45	20.2	21	21
Time	253	250	258	268

Table 4 Accuracy with different number of neurons

# MLP in PyTorch - Adjustment



Small learning rate will be hard to converge in the network.

If it is too big, the update will not be stable, also it will bypass the minimum point.



# MLP in PyTorch - Result

```
input_size = 3 * 32 * 32
hidden_size = 500
num_classes = 100
num_epochs = 50
batch_size = 50
learning_rate = 0.001
momentum = 0.9
```

```
('Accuracy of subclasses is', 27.363636363636363)
```

```
Accuracy of the network on the 10000 test images: 27 %
```

```
#
class_correct = list(0. for i in range(100))
class_total = list(0. for i in range(100))
subclass_correct=list(0. for i in range(20))
subclass_total=list(0. for i in range(20))
for data in test_loader:
    images, labels = data
    images = Variable(images.view(-1, 3 * 32 * 32)).cuda()
    outputs = net(images)
    _, predicted = torch.max(outputs.data, 1)
    labels = labels.cpu().numpy()
    c = (predicted.cpu().numpy() == labels)
    for i in range(batch_size):
        label = labels[i]
        if (label >= 0) and (label < 5):
            subclass_correct[0] += c[i]
            subclass_total[0] += 1

        elif (label >= 5) and (label < 10):
            subclass_correct[1] += c[i]
            subclass_total[1] += 1

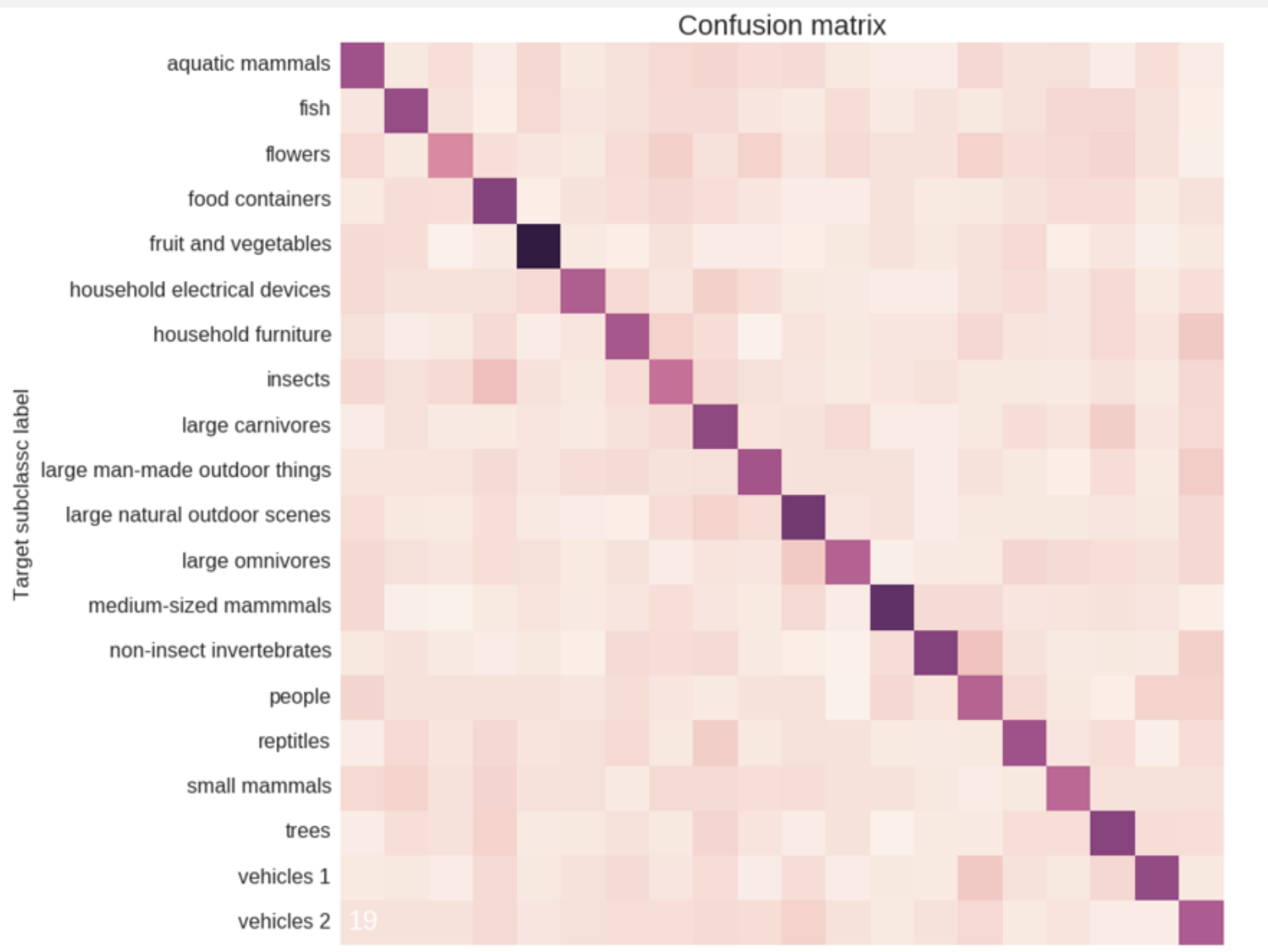
        elif (label >= 10) and (label < 15):
            subclass_correct[2] += c[i]
            subclass_total[2] += 1

        elif (label >= 15) and (label < 20):
            subclass_correct[3] += c[i]
            subclass_total[3] += 1

        elif (label >= 20) and (label < 25):
            subclass_correct[4] += c[i]
            subclass_total[4] += 1

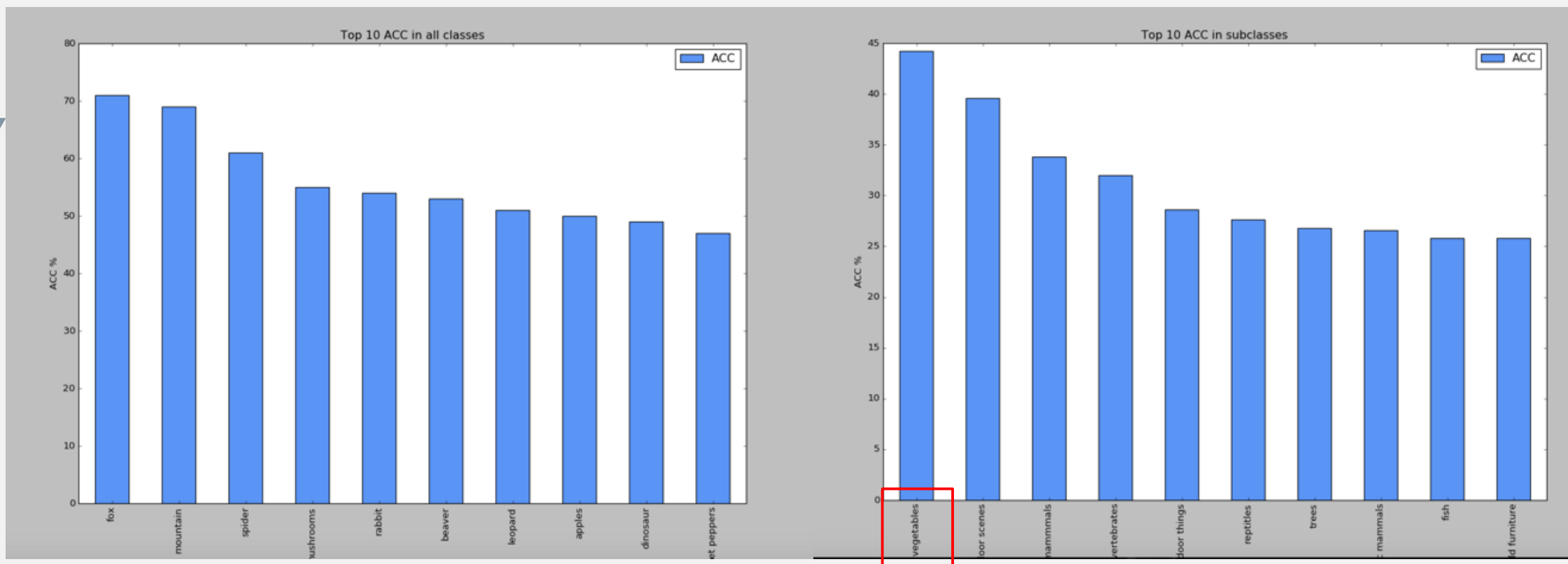
        elif (label >= 25) and (label < 30):
```

# MLP in PyTorch - Result



It didn't show any saturated spots outside of diagonal, which means there is no a specific misclassification.

# MLP in PyTorch - Result



Fox	mountain	Spider	Mushrooms	rabbit	beaver	leopard	apple	dinosaur	Sweet pepper
medium-sized mammals	large natural outdoor scenes	non-insect invertebrates	fruit and vegetables	small mammals	aquatic mammals	large carnivores	fruit and vegetables	reptiles	fruit and vegetables

**03**

## **CNN in Pytorch**

# CNN in PyTorch

		CV_1	CV_2	CV_3	CV_4
	batch size	200	200	200	100
	epoch	20	20	20	40
Conv1	nn.Conv2d(in_channels=3, out_channels=6, kernel_size=5)	v			
	nn.Conv2d(in_channels=3, out_channels=30, kernel_size=3)			v	
	nn.Conv2d(in_channels=3, out_channels=30, kernel_size=5)		v		
	nn.Conv2d(in_channels=3, out_channels=30, kernel_size=8)				v
pool1	nn.MaxPool2d(kernel_size=2, stride=2)	v	v	v	v
Conv2	nn.Conv2d(in_channels=6, out_channels=16, kernel_size=5)	v			
	nn.Conv2d(in_channels=30, out_channels=80, kernel_size=3)			v	
	nn.Conv2d(in_channels=30, out_channels=80, kernel_size=5)		v		
	nn.Conv2d(in_channels=30, out_channels=80, kernel_size=8)				v
pool2	nn.MaxPool2d(kernel_size=2, stride=2)	v	v	v	v
ip	nn.Linear(**, 120)	v	v	v	v
	nn.Linear(**, 100)	v	v	v	v
	Accuracy	16%	22%	20%	17%
	training time(s)	191	242	230	229

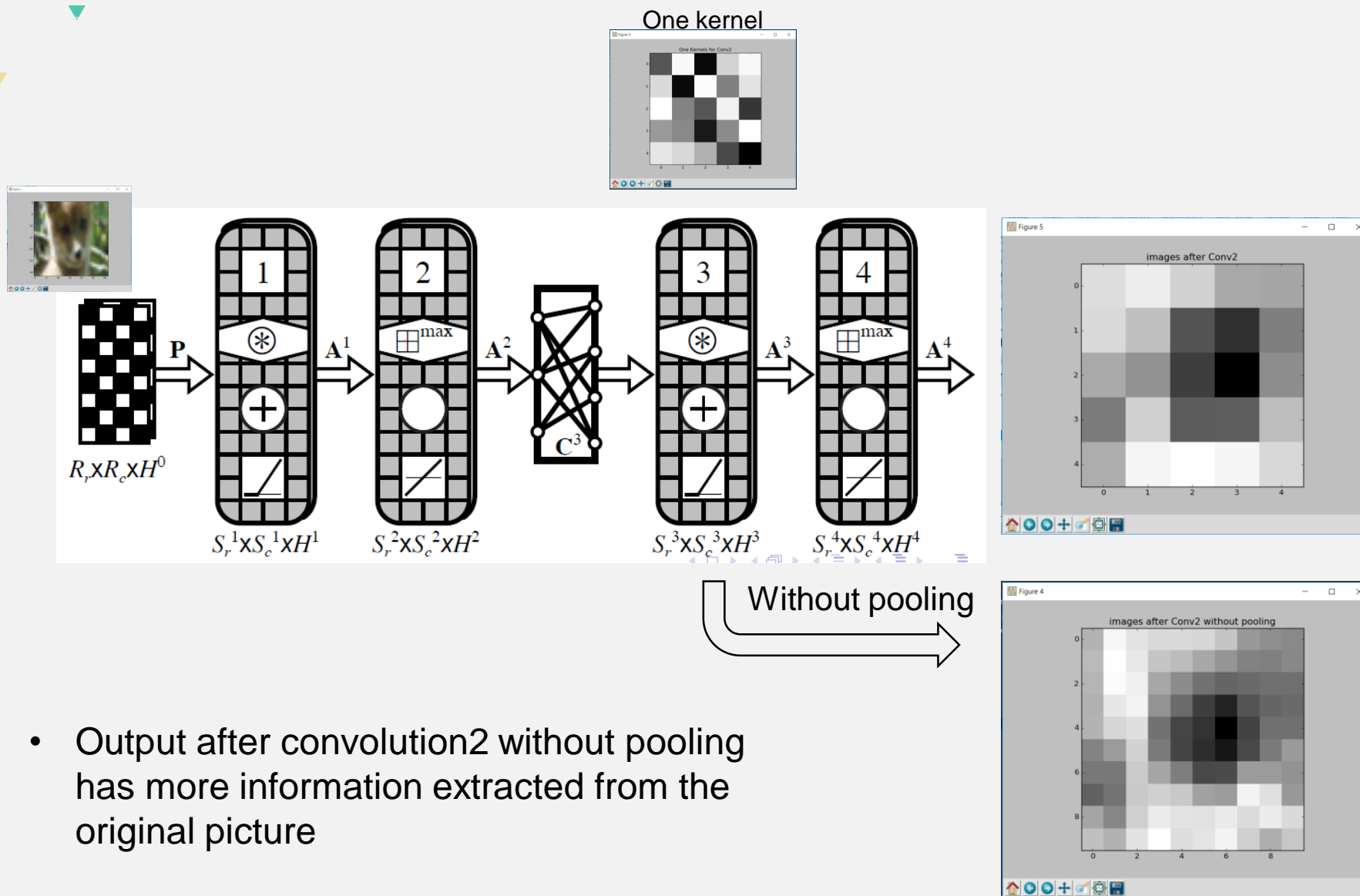
- Increasing the number of kernels increases the accuracy.
- Kernel size =5 has the best performance in terms of accuracy.

# CNN in PyTorch

		CV_2	CV_5	CV_6
	batch size	200	200	200
	epoch	20	20	20
Conv1	nn.Conv2d(in_channels=3, out_channels=30, kernel_size=5)	v		v
	nn.Conv2d(in_channels=3, out_channels=30, kernel_size=5, stride=3)		v	
pool1	nn.MaxPool2d(kernel_size=2, stride=2)	v	v	v
Conv2	nn.Conv2d(in_channels=30, out_channels=80, kernel_size=5)	v		v
	nn.Conv2d(in_channels=30, out_channels=80, kernel_size=5, stride=1)		v	
pool2	nn.MaxPool2d(kernel_size=2, stride=2)	v		
ip	nn.Linear(**, 120)	v	v	v
	nn.Linear(**, 100)	v	v	v
	Accuracy	22%	12%	28%
	training time(s)	242	186	246

- Changing the number of stride at convolution layer decreases with accuracy because FM did not sufficiently extract the feature of the picture.
  - The size of outputs of Conv2 down to 80x1x1
  - Suggest to increase the size of outputs of Conv2 layer by removing pool2 layer
- Model CV\_6 without pool2 layer has a better performance at accuracy

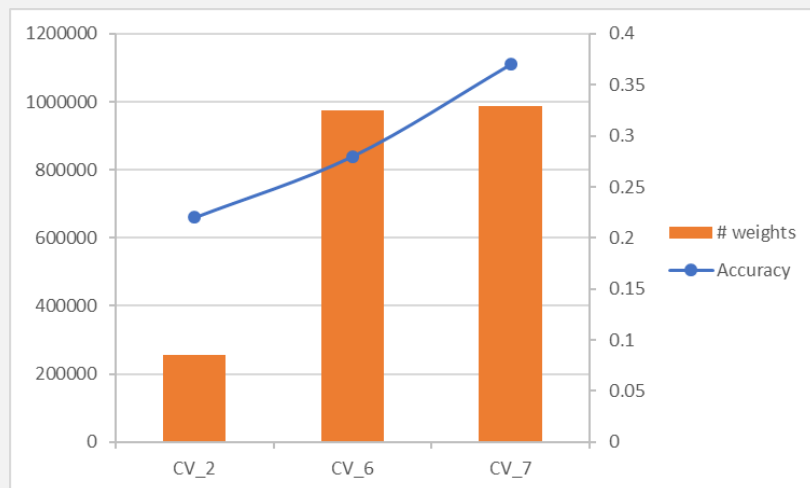
# CNN in PyTorch



- Output after convolution2 without pooling has more information extracted from the original picture

# CNN in PyTorch

		CV_2	CV_6	CV_7
	batch size	200	200	100
	epoch	20	20	40
Conv1	nn.Conv2d(in_channels=3, out_channels=30, kernel_size=5)	v	v	v
pool1	nn.MaxPool2d(kernel_size=2, stride=2)	v	v	v
Conv2	nn.Conv2d(in_channels=30, out_channels=80, kernel_size=5)	v	v	v
pool2	nn.MaxPool2d(kernel_size=2, stride=2)	v		
ip	nn.Linear(**, 120)	v	v	v
	nn.Linear(**, 110)			v
	nn.Linear(**, 100)	v	v	v
	Accuracy	22%	28%	37%
	training time(s)	242	246	500



- Increasing the number of neuron at fully connected layers (ip), the numbers of epoch, and decreasing batch size increases the accuracy from 28% to 37%.



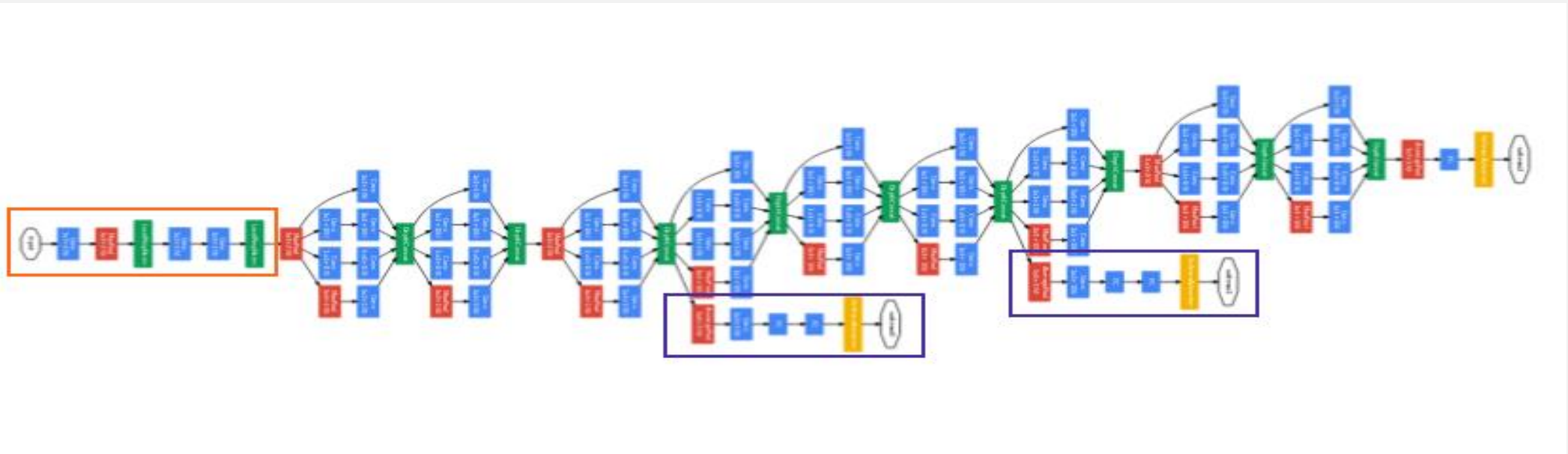
**04**

## **Transfer learning in TensorFlow**

# Transfer learning

- Transfer learning is to reuse a model that was trained in a prior task as a starting point for the new/current task
- GoogLeNet (InceptionV1) was used in this project as a starting point. It was originally developed as a submission to a competition by a group of scientists with Google

## Inception V1

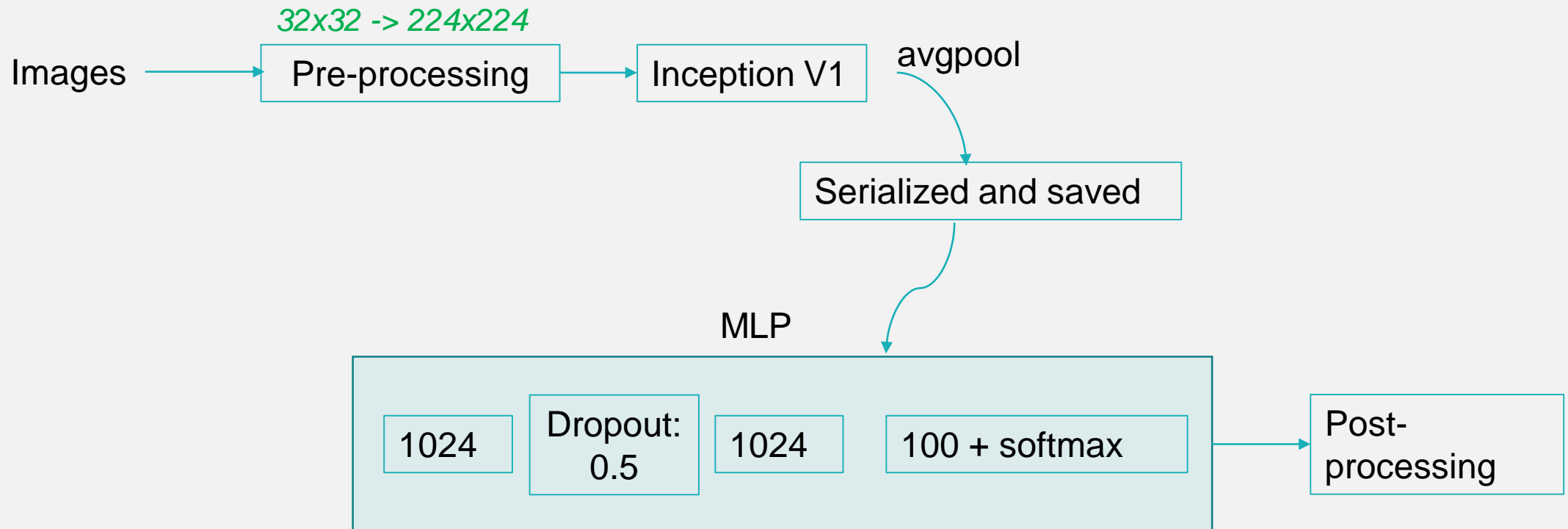


22 layers (27, including the pooling layers)

# Transfer learning in TensorFlow

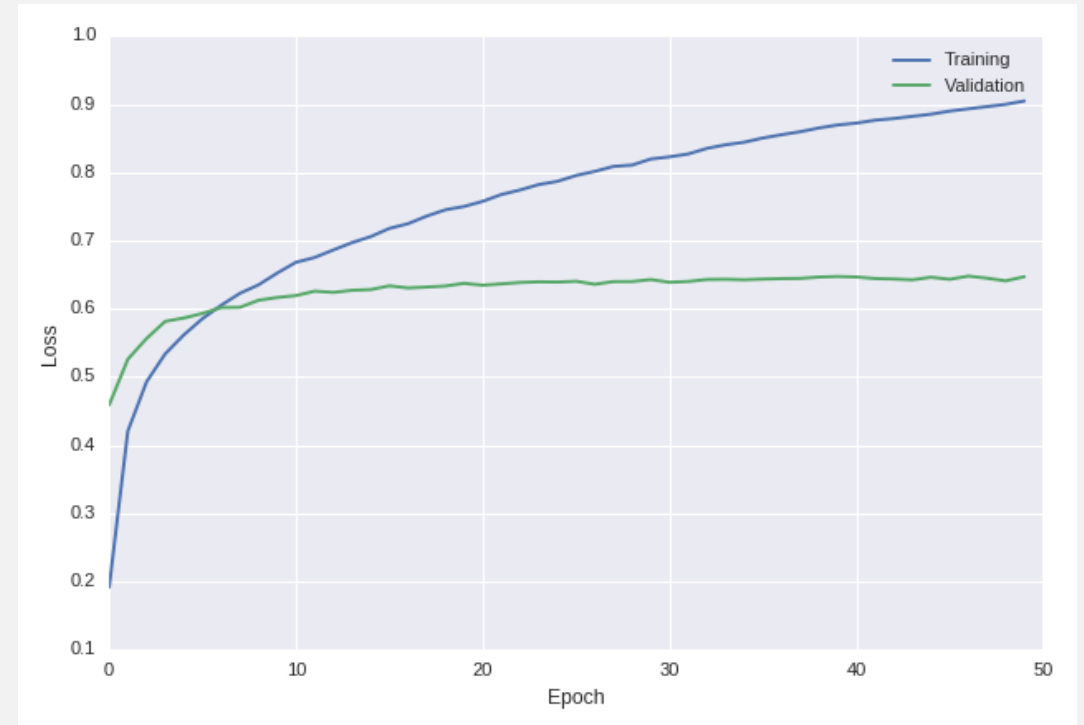
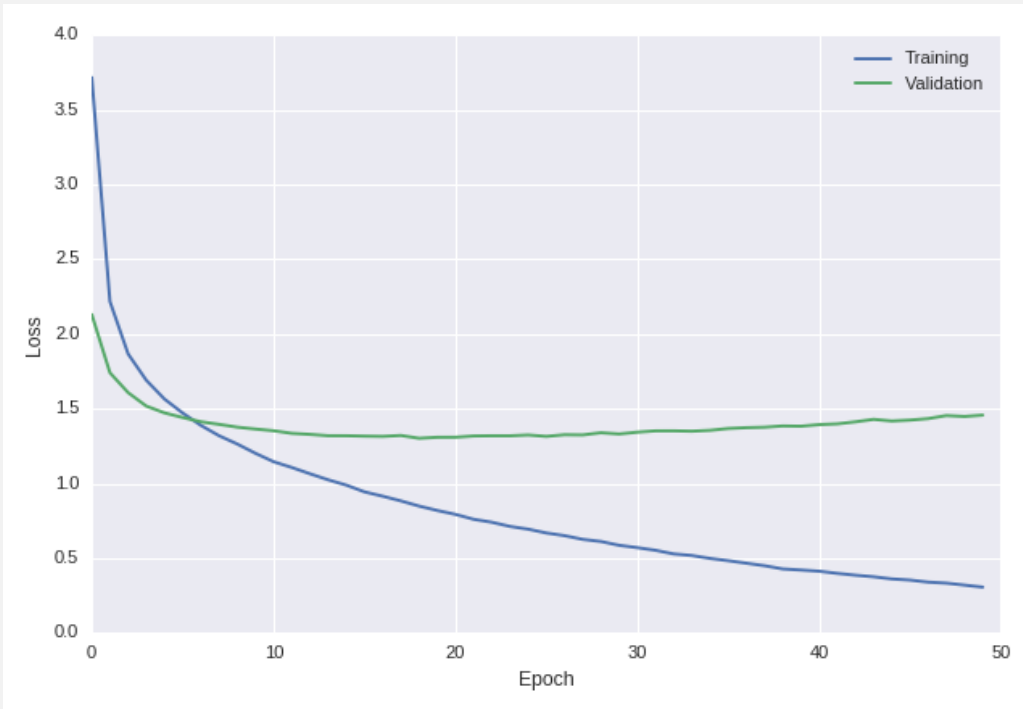
*Platform: tensorflow.keras*

*Data ingestion: tensorflow.keras.datasets.cifar100*

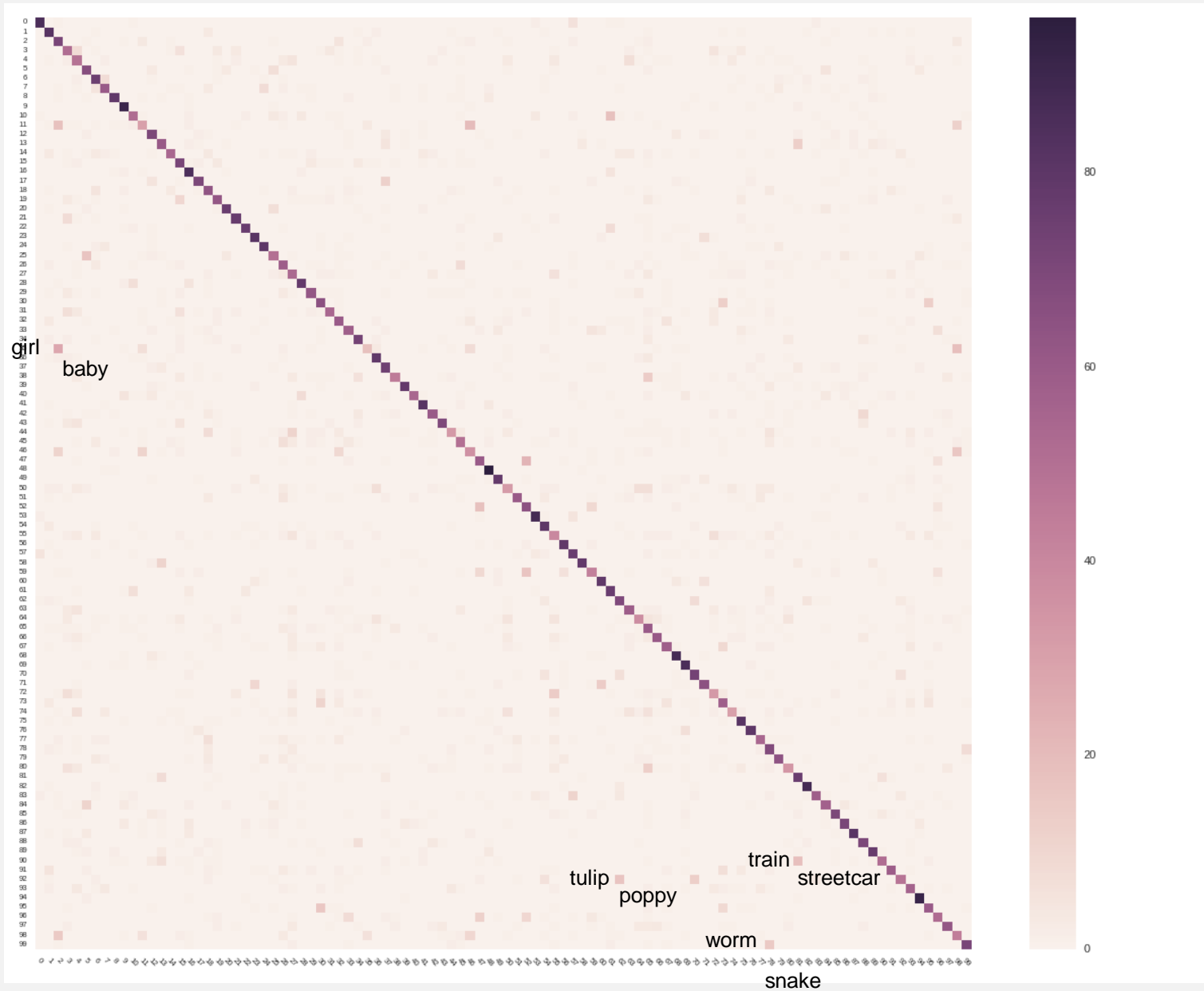


# Transfer learning in TensorFlow - Performance

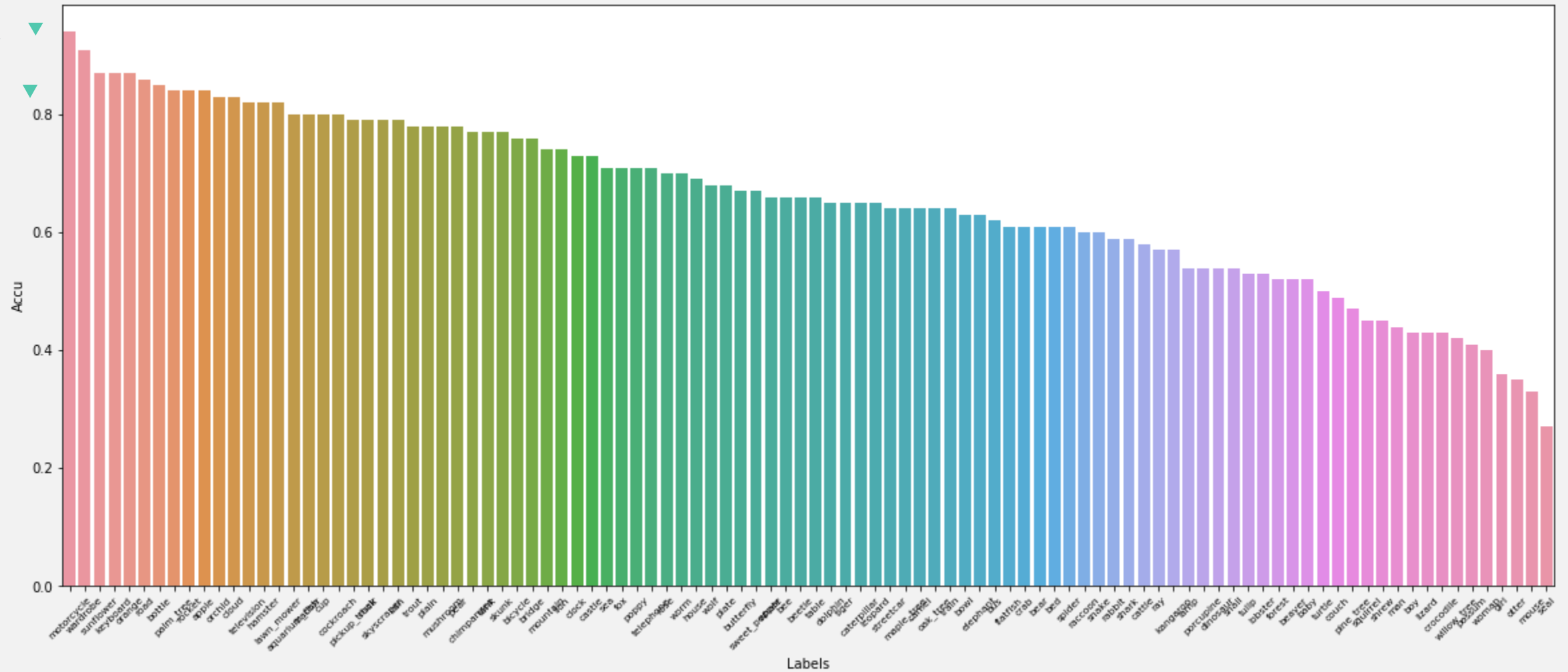
- Keras can conveniently set aside pre-defined portion of training data for validation purposes
- Training for more epochs will continuously lower the loss with the training set, but the loss on the validation set can be indicative of the optimal number of epochs
- The performance of this transfer learning net is dominated by the pre-trained model. MLP layers has marginal effects on the accuracy.



# Transfer learning in TensorFlow - Performance



# Transfer learning in TensorFlow - Performance





## Conclusion

- MLP is not a good model for CIFAR100 as the accuracy is only 27%. However, our analysis suggests that MLP model performs relatively better to classify fruit and vegetables and large natural outdoor scenes whose performance are over 40%
- The CNN model reaches its highest accuracy at 37%.
  - Control the size of output of FM is important to train the model
- Output from the Inception model + fully connected layers yields decent results (overall accuracy = 66%), but the class-specific accuracies range from 27% to 94%.



Question?



# Thank you

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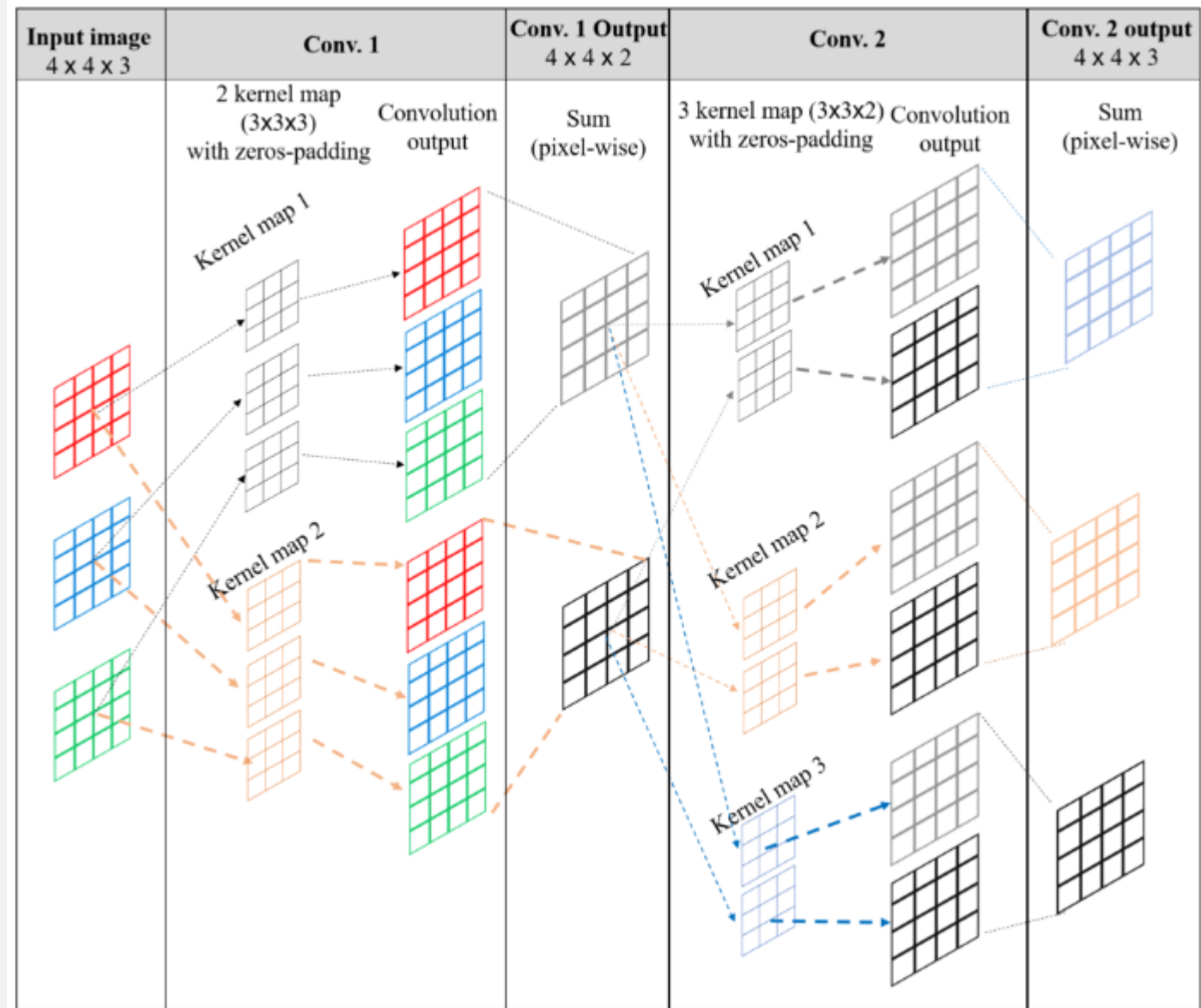
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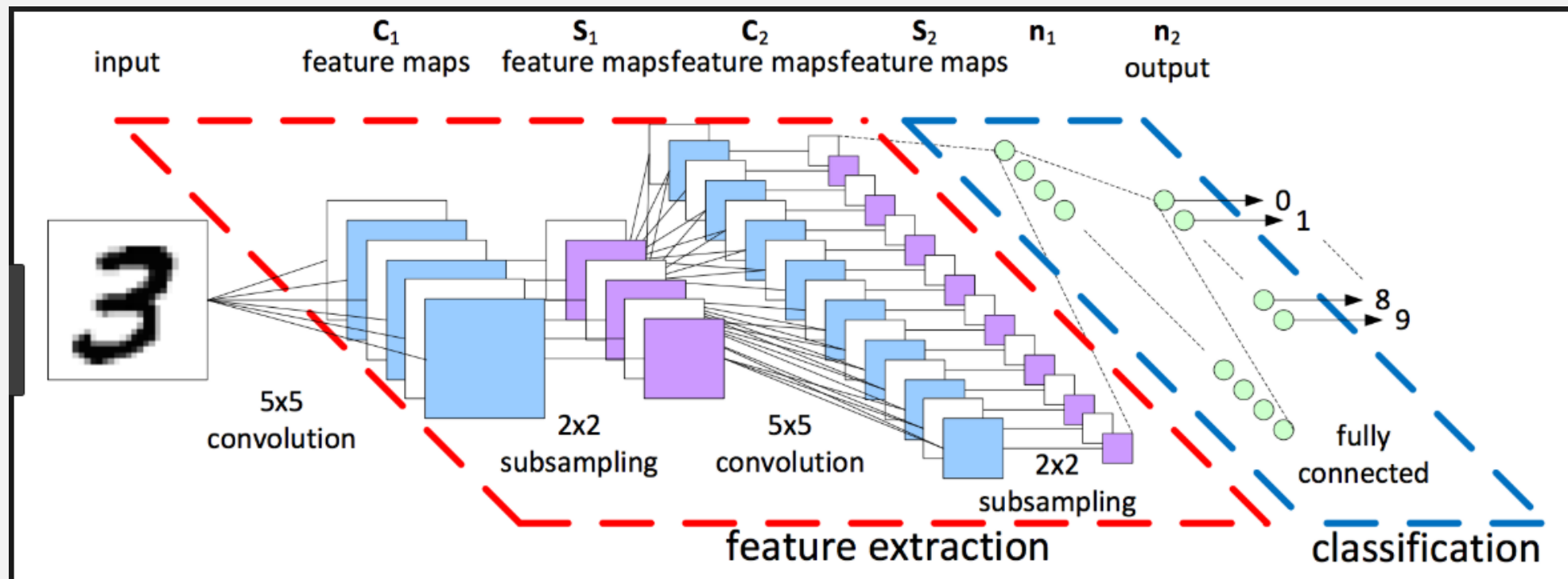
**05**

**Back Up**

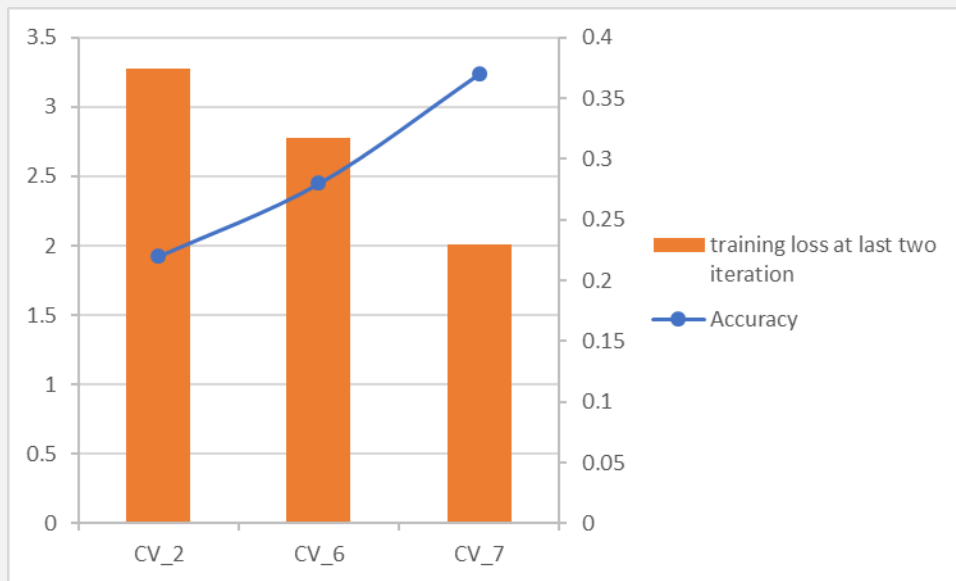
# CNN Calculation Process



# CNN Architecture



# CNN in Pytorch



- The result of training loss have not showed that the model suffer over-fitting

Backup

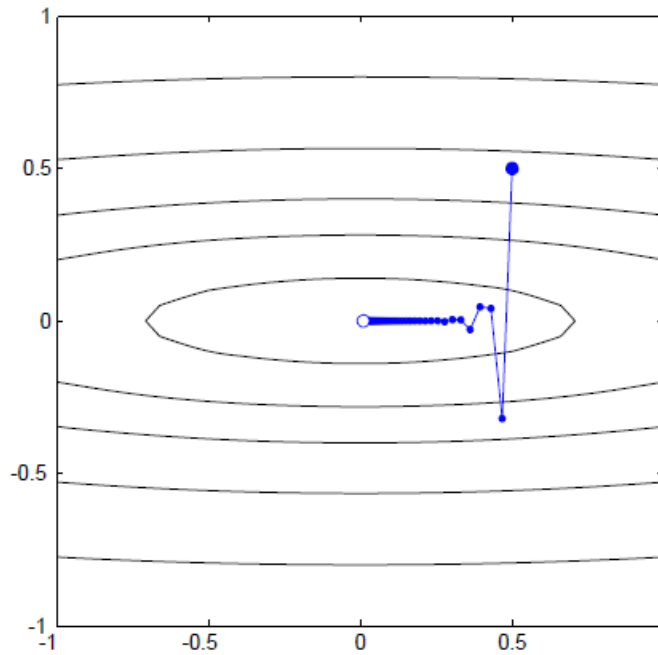


Figure P12.3 Trajectory for  $\alpha = 0.041$  and  $\gamma = 0.2$

# Backup

Accuracy	Learning rate	Batch size	epochs
20%	0.01	50	50
24%	0.01	200	50
25%	0.001	50	50
22%	0.001	200	50

	Layer 2 ACC
Drop = 0	20
Drop = 0.2	19.03
Drop = 0.4	17